

# A brief introduction to Bayesian Statistics through Astronomical Applications (Lecture 3)

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More Examples

# Coordinate Transformations

- ◆ Lets say we have a problem in which we know how to write our posterior  $P(x)$  in a variable  $x$ , but in reality we are interested in knowing the posterior  $P(y)$  for variable  $y=f(x)$
- ◆ We know the integral of the probability must be conserved

$$\int P(x)dx = \int P(y)dy \qquad P(x)dx = P(y)dy$$

- ◆ This makes it easy, we know how to change variables inside an integral

$$P(y) = \left| \frac{dx}{dy} \right| P(x)$$

← Jacobian of the transformation  $f(x)$

# The Parallax Example

- ◆ Lets illustrate this with an example. Say we have  $N$  measurements of the parallax for a star from Gaia
- ◆ Lets assume we have an error model and CU7/DPAC gives us an estimate on the parallax error and tells us that its safe to assume these errors are gaussian
- ◆ What we'd ultimately like to get is the posterior on the distance to the star



# The Parallax Example

- ◆ Lets write the posterior on the parallax first

$$P(\varpi|\{\varpi_i\}) = P(\{\varpi_i\}|\varpi)P(\varpi) \quad |I$$

- ◆ Our likelihood is

$$P(\{\varpi_i\}|\varpi) = \prod_{i=1}^N e^{-\frac{(\varpi - \varpi_i)^2}{2\sigma_{\varpi}^2}}$$

- ◆ So the posterior is

$$P(\varpi|\{\varpi_i\}) = \prod_{i=1}^N e^{-\frac{(\varpi - \varpi_i)^2}{2\sigma_{\varpi}^2}} P(\varpi) \quad |I$$

no coordinate transformations yet...

# The Parallax Example

- ◆ Now we want the posterior for the distance  $D=1/\varpi$

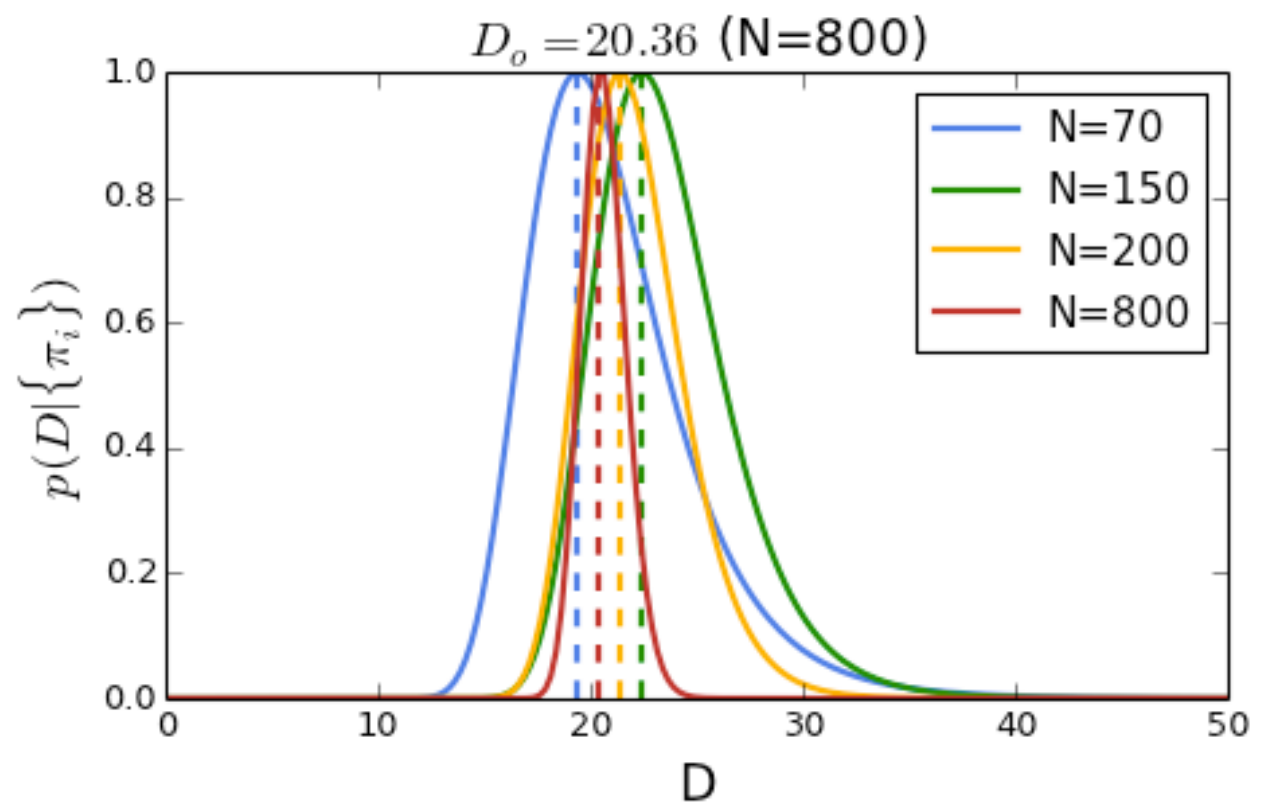
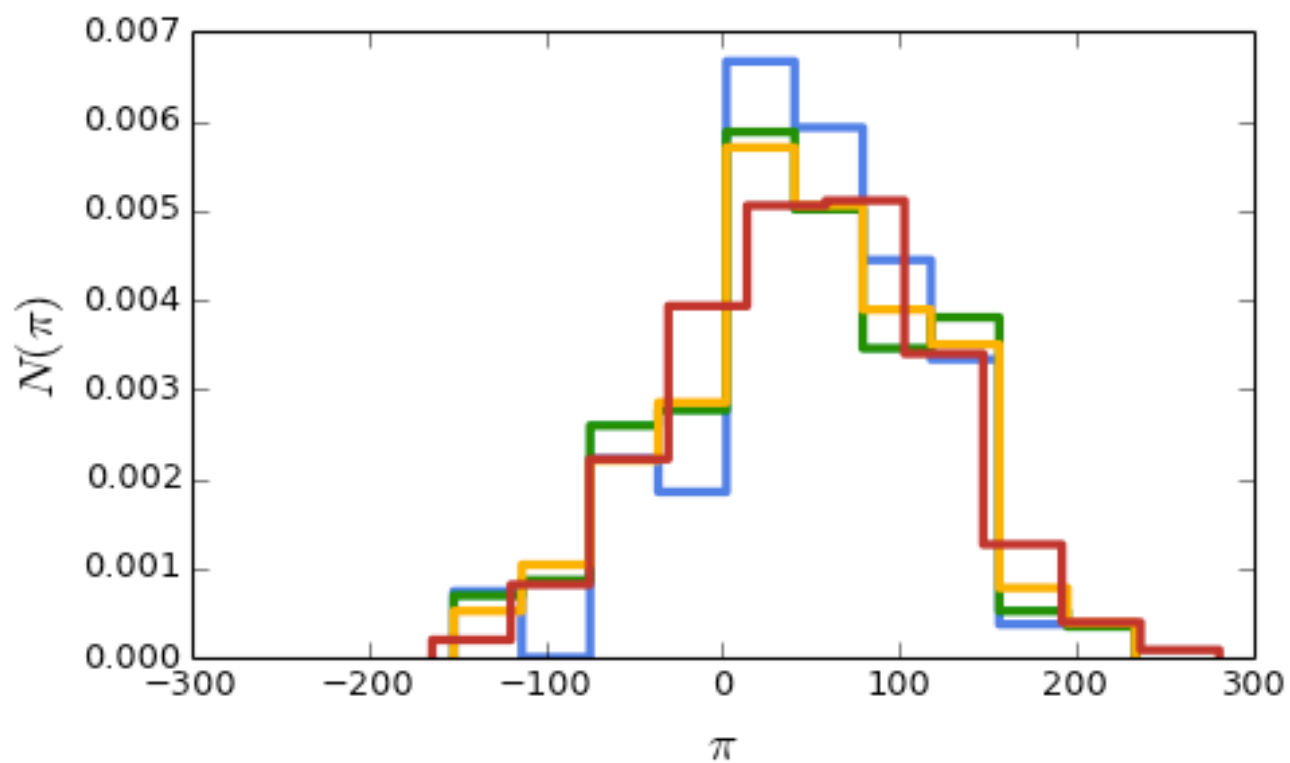
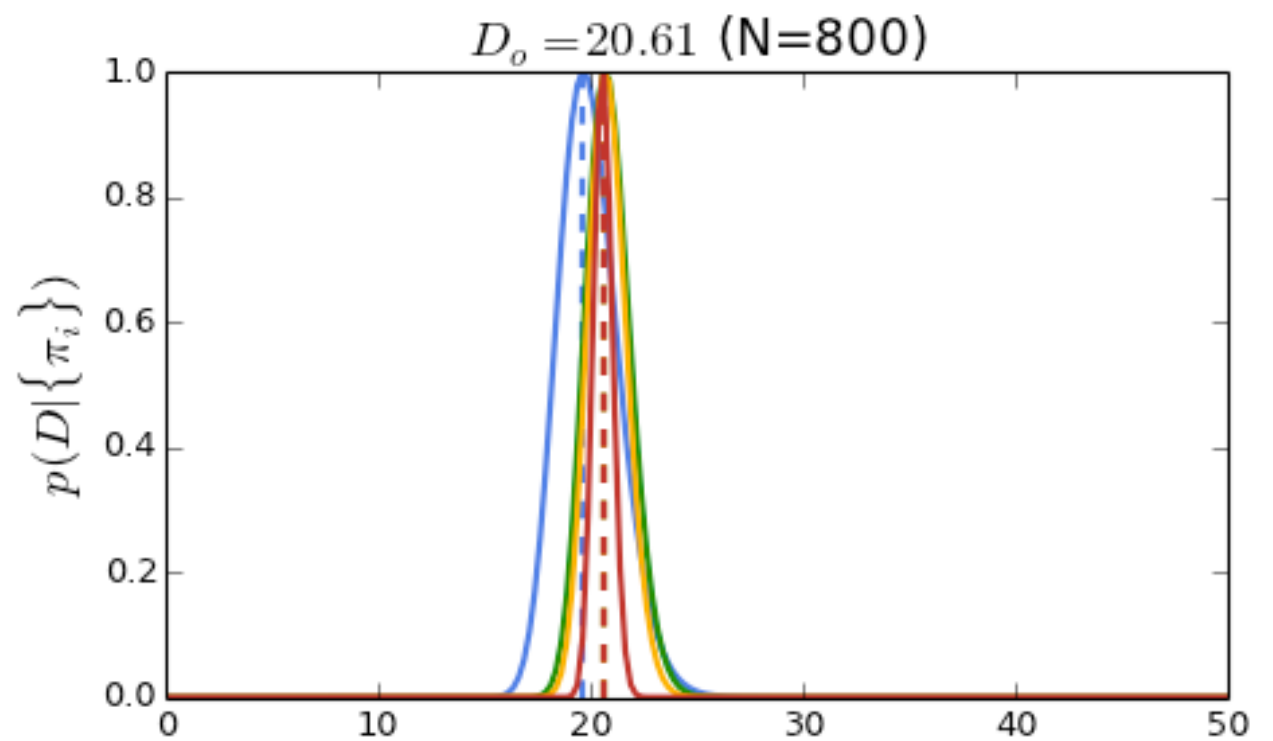
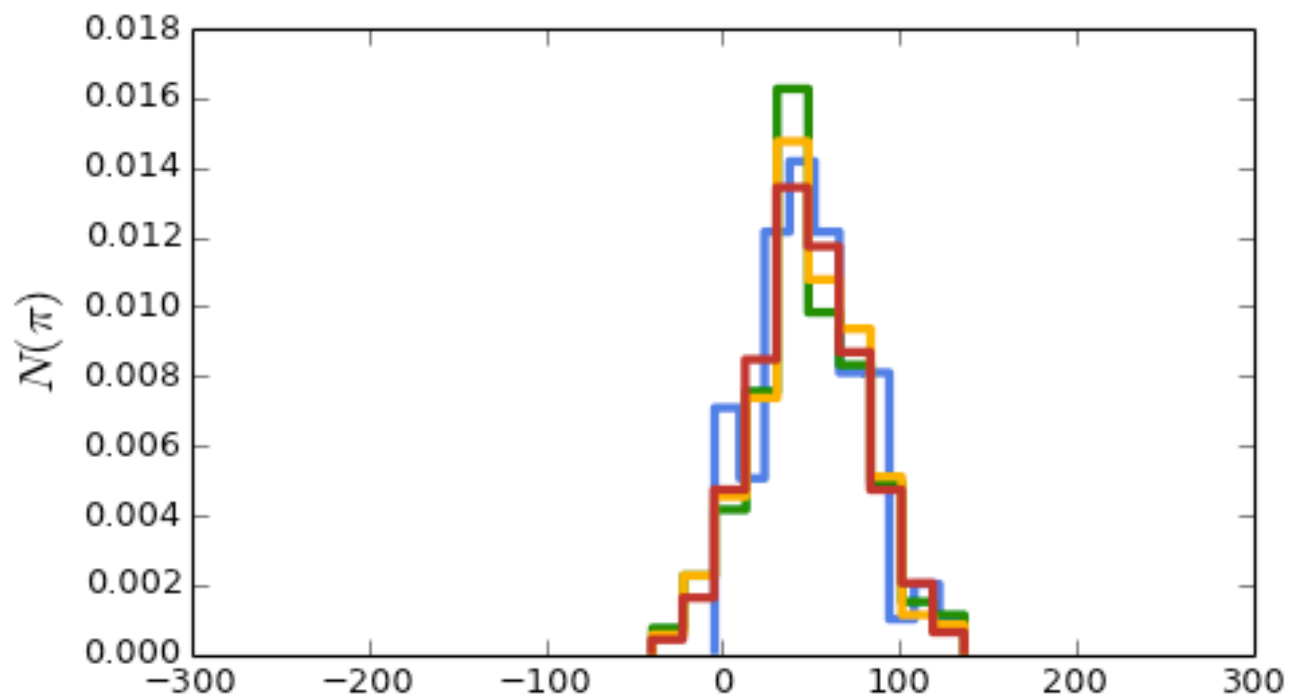
$$P(\varpi|\{\varpi_i\})d\varpi = P(D|\{\varpi_i\})dD$$

$$P(D|\{\varpi_i\}) = P(\varpi|\{\varpi_i\}) \left| \frac{d\varpi}{dD} \right|$$
$$P(\varpi|\{\varpi_i\}) = \prod_{i=1}^N e^{-\frac{(\varpi - \varpi_i)^2}{2\sigma_{\varpi}^2}} P(\varpi)$$

$$P(D|\{\varpi_i\}) = P(\varpi|\{\varpi_i\}) \frac{1}{D^2}$$

$$P(D|\{\varpi_i\}) = \prod_{i=1}^N e^{-\frac{(1/D - \varpi_i)^2}{2\sigma_{\varpi}^2}} \frac{1}{D^2} P(\varpi(D))$$

# The Parallax Example



# Error Propagation



# Error Propagation

- ◆ Lets say we know the PDF for two variables  $X$  and  $Y$

$$P(X) \quad p(Y) \quad |data, I$$

- ◆ Now we'd like to know what is the PDF for  $Z$ , where

$$Z = X + Y$$

- ◆ First, lets look at the case when  $X$  and  $Y$  are conditionally independent. If this is the case, the joint probability  $P(X,Y)=P(X)p(Y)$ , from the Marginalization rule this is:

$$P(Z) = \iint P(X)p(Y)dXdY \quad |data, I$$

for all  $X, Y$   
t.q.  $Z=X+y$

# Error Propagation

- ♦ First, let's look at the case when  $X$  and  $Y$  are conditionally independent. If this is the case, the joint probability  $P(X, Y) = P(X)p(Y)$ , from the Marginalization rule this is:


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for all  $X, Y$   
t.q.  $Z = X + Y$

$$P(Z) = \iint P(X)p(Y)\delta(Z - [X + Y])dXdY$$

$$P(Z) = \int P(X)p(Y = Z - X)dX$$

**note this is  
the  
convolution of  
 $P(X)$  and  $p(Y)$**



# Error Propagation

- ♦ If  $P(X)$  and  $p(y)$  are gaussians, e.g. lets say like yesterday we have a model with gaussian uncertainties and a uniform prior,

$$P(X) = \frac{1}{\sqrt{2\pi}\sigma_X} e^{-\frac{(X-X_o)^2}{2\sigma_X^2}} \quad P(Y) = \frac{1}{\sqrt{2\pi}\sigma_Y} e^{-\frac{(Y-Y_o)^2}{2\sigma_Y^2}}$$

then

$$P(Z) = \int P(X)p(Y = Z - X)dX \quad |data, I$$

is the convolution of these two gaussians

$$P(Z) = \frac{1}{2\pi\sigma_X\sigma_Y} \int_{-\infty}^{+\infty} e^{-\frac{(X-X_o)^2}{2\sigma_X^2}} e^{-\frac{(Z-X-Y_o)^2}{2\sigma_Y^2}} dX$$

# Error Propagation

- ◆ After completing squares and simplifying we get

$$P(Z) = \frac{1}{\sqrt{2\pi}\sigma_z} e^{-\frac{(Z-Z_o)^2}{2\sigma_z^2}}$$

where

$$Z_o = X_o + Y_o \quad \text{and} \quad \sigma_z^2 = \sigma_X^2 + \sigma_Y^2$$

so, the sum in quadrature rule is derived

- ◆ Lets go back to the general problem, where  $Z=f(X,Y)$

# Error Propagation

- ◆ In general, i.e. without assuming cond. independence of  $X, Y$  we have

$$P(Z) = \iint P(X, Y) dX dY$$

for all  $X, Y$   
t.q.  
 $Z=f(X, Y)$

- ◆ Since  $Z=f(X, Y)$  we have

$$P(Z) = \iint P(X, Y) \delta(Z - f(X, Y)) dX dY$$

# The Parallax Example

- ◆ Now we want the posterior for the distance  $D=1/\varpi$

$$P(\varpi|\{\varpi_i\})d\varpi = P(D|\{\varpi_i\})dD$$

$$P(D|\{\varpi_i\}) = P(\varpi|\{\varpi_i\}) \left| \frac{d\varpi}{dD} \right|$$
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More Examples

# Fitting a density profile to data

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- Another example. Lets say you have a catalogue of a particular stellar tracer, e.g. RR Lyrae stars, Red Clump stars, Cepheids or whatever.
- We'd like to use these tracers to study how stars are distributed in space in the different components in the Galaxy, i.e. their density profile  $\rho$
- How do we compare and fit this function to a sample of stars?

# Thick Disc and Halo RRL Density Profiles

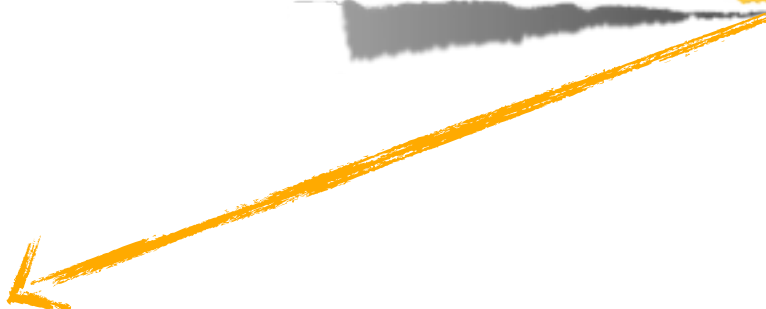
♦ Thick Disc density profile

♦ Halo density profile

$$\rho_{\text{DG}} = C_{\text{DG}} e^{-\frac{R-R}{h_R}} e^{-\frac{|z|}{h_z}}$$

$$\rho_{\text{H}} = \frac{C_{\text{H}}}{R_{\odot}^n} \left[ R^2 + \left( \frac{z}{q} \right)^2 \right]^{n/2}$$

... but the directly observable quantity is not the density  $\rho$ , but the number  $N_{\text{RR}}$  of RRLs in the survey volume  $V_{\text{S}}$


$$N_{\text{RR}} = \iiint_{V_{\text{S}}} \rho(\vec{r}) dV = \iiint_{V_{\text{S}}} [\rho_{\text{H}}(R, z) + \rho_{\text{DG}}(R, z)] R dR dz d\varphi$$

# Density Profiles: A Bayesian approach

- ◆ Our free parameters are:

$$\vec{\theta} = (h_z, h_r, C_{tkd}, n, C_h)$$

- ◆ We build an imaginary grid restricted *only* to the survey volume  $V_S$
- ◆ Our likelihood function is then

$$L \equiv p(\{\eta\}|\vec{\theta}) = \prod_{i \in V_S} p(\eta_i|\vec{\theta}) = \prod_{i \in V_S} \frac{\mu_i^{\eta_i} e^{-\mu_i}}{\eta_i!}$$

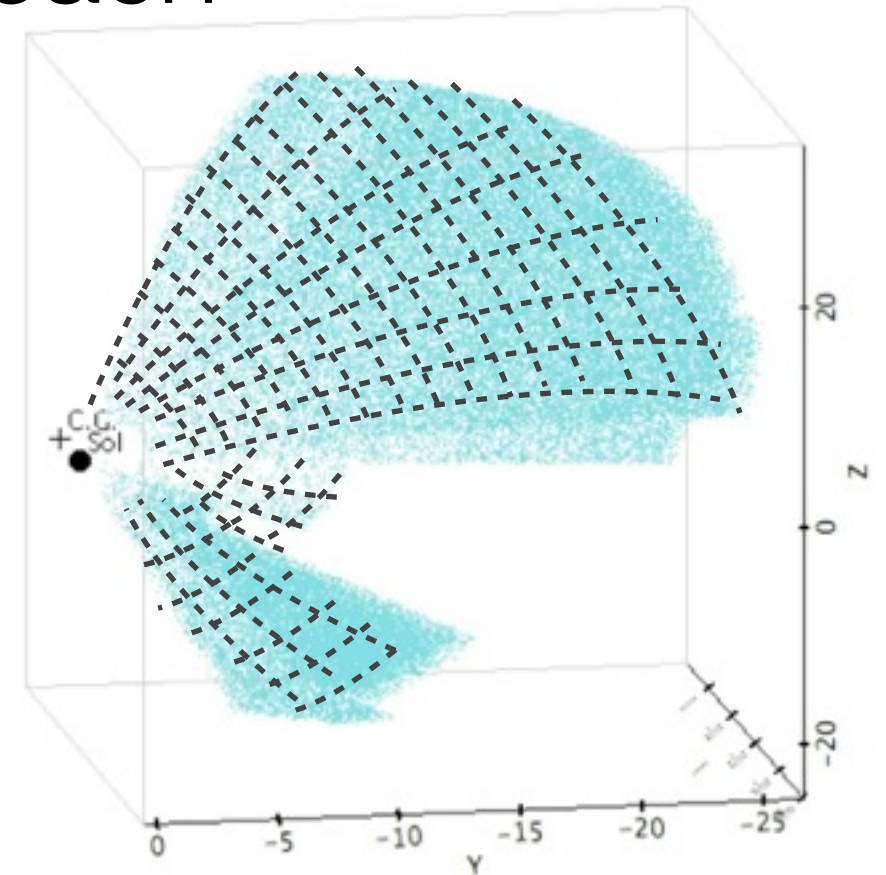
$$\ln L = \sum_{i \in V_S} \eta_i \ln \mu_i - \mu_i$$

- ◆ If now we make the grid cell size tend to 0

$$\mu_i(\vec{\theta}, \vec{r}_i^{RRLS}) \rightarrow \rho(\vec{\theta}, \vec{r}_i^{RRLS})$$

- ◆ We finally get

$$\ln L = \sum_{i=1}^{N_{obs}^{RRL}} \ln \rho(\vec{\theta}, \vec{r}_i^{RRLS}) - N_{model}^{RRL}(\vec{\theta})$$



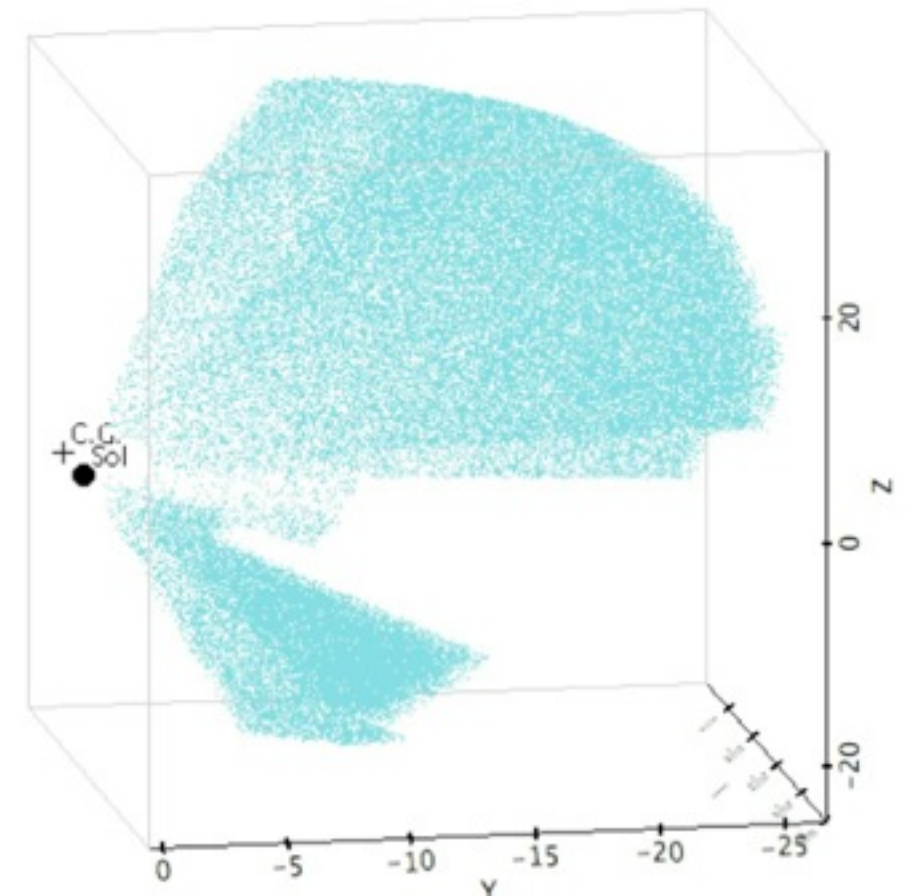
$\eta_i$  - *observed* number or RRLS on  $i$ -th bin

$\mu_i$  - *predicted* number or RRLS on  $i$ -th bin

# Density Profiles: A Bayesian approach

- ◆ This framework allows us to account for the inhomogeneities of the survey volume due to the variable extinction
- ◆ We could also include an incompleteness function for example

$$\ln L = \sum_{i=1}^{N_{obs}^{RRL}} \ln \rho(\vec{\theta}, \vec{r}_i^{RRLS}) - N_{model}^{RRL}(\vec{\theta})$$



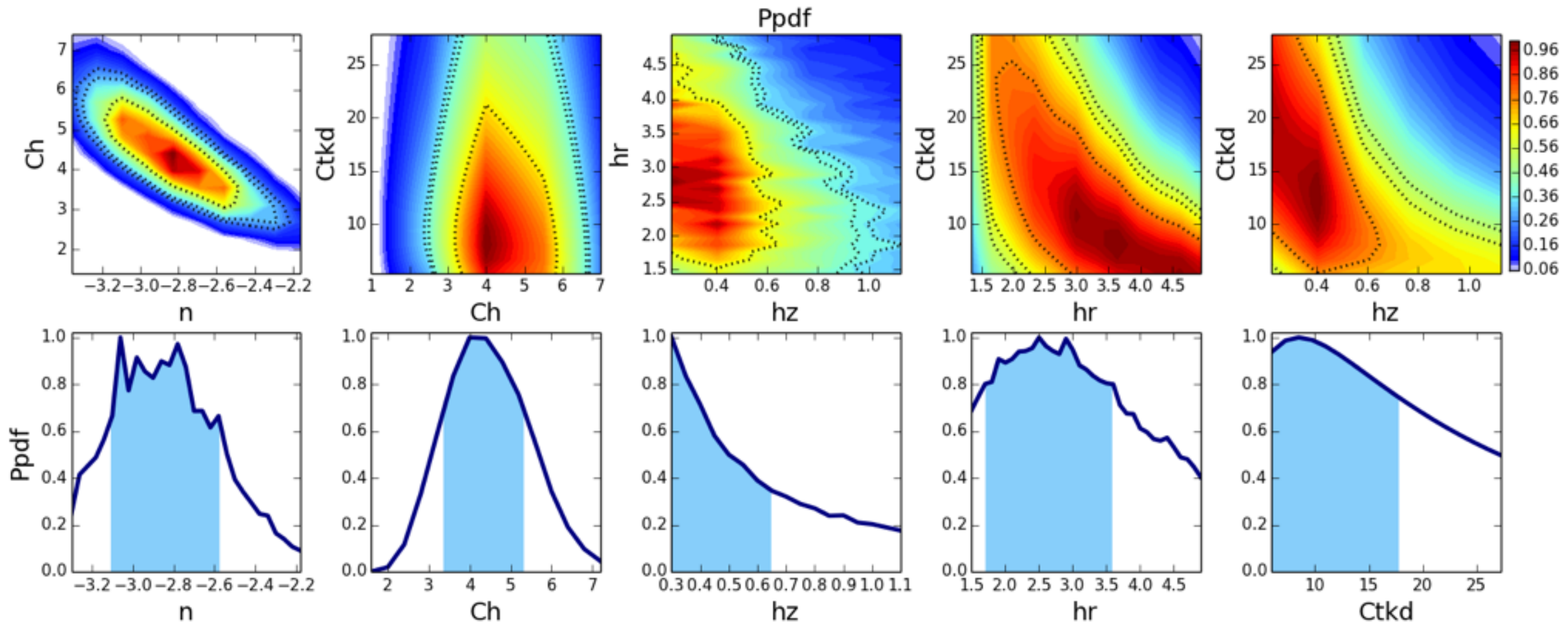
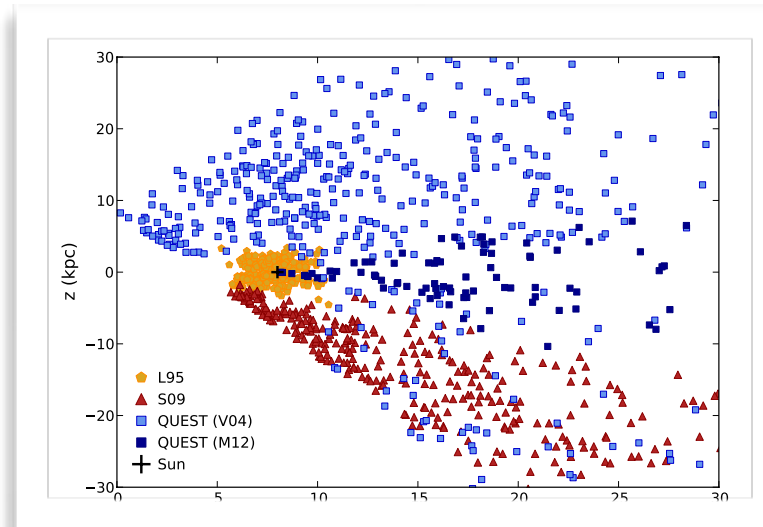
**This is the computationally intensive part**

$$N_{RR} = \iiint_{V_S} \rho(\vec{r}) dV = \iiint_{V_S} [\rho_H(R, z) + \rho_{DG}(R, z)] R dR dz d\varphi$$



# Density Profiles: One sample at a time

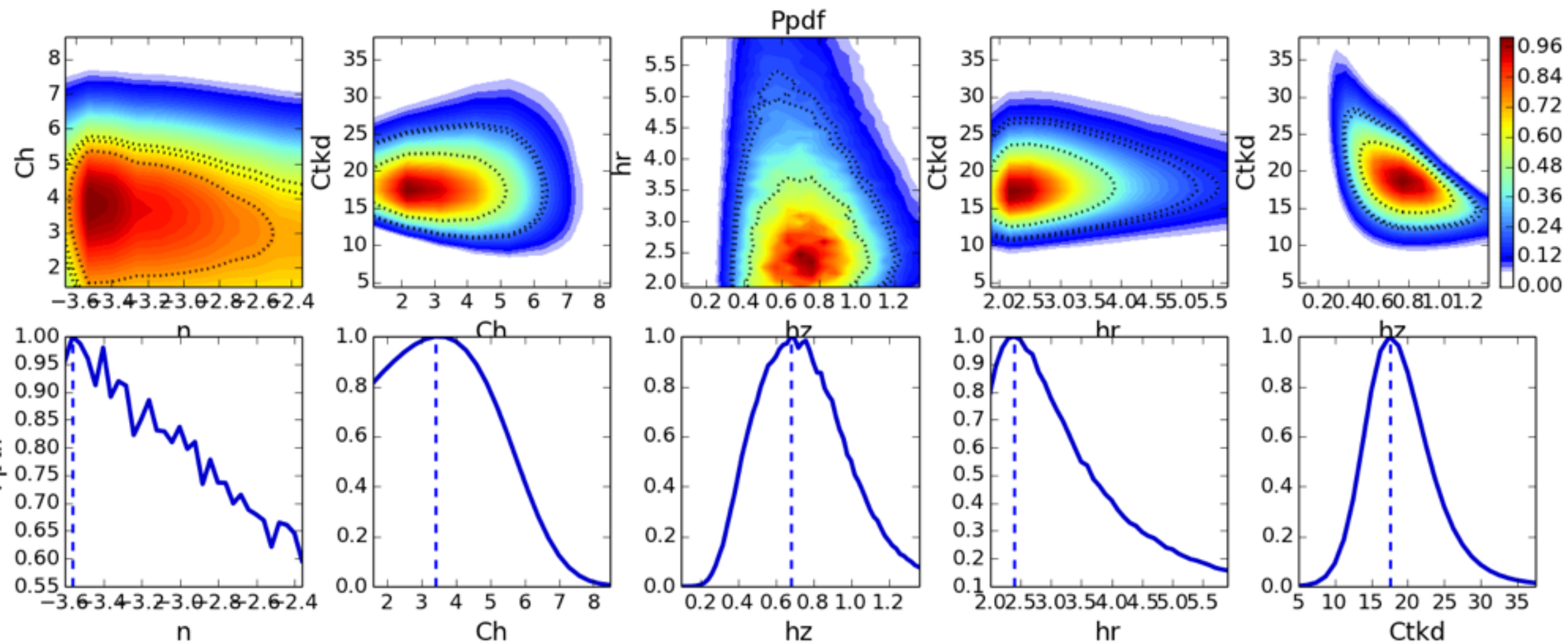
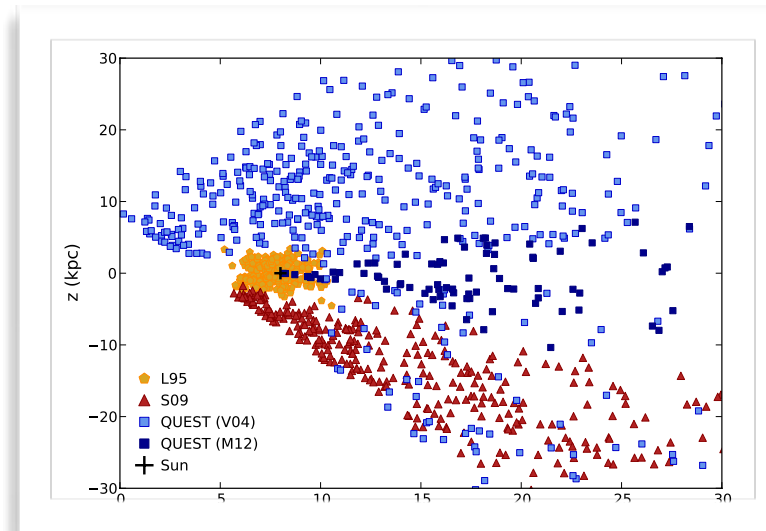
The marginal posteriors taking only the **QUEST** sample are as follows:





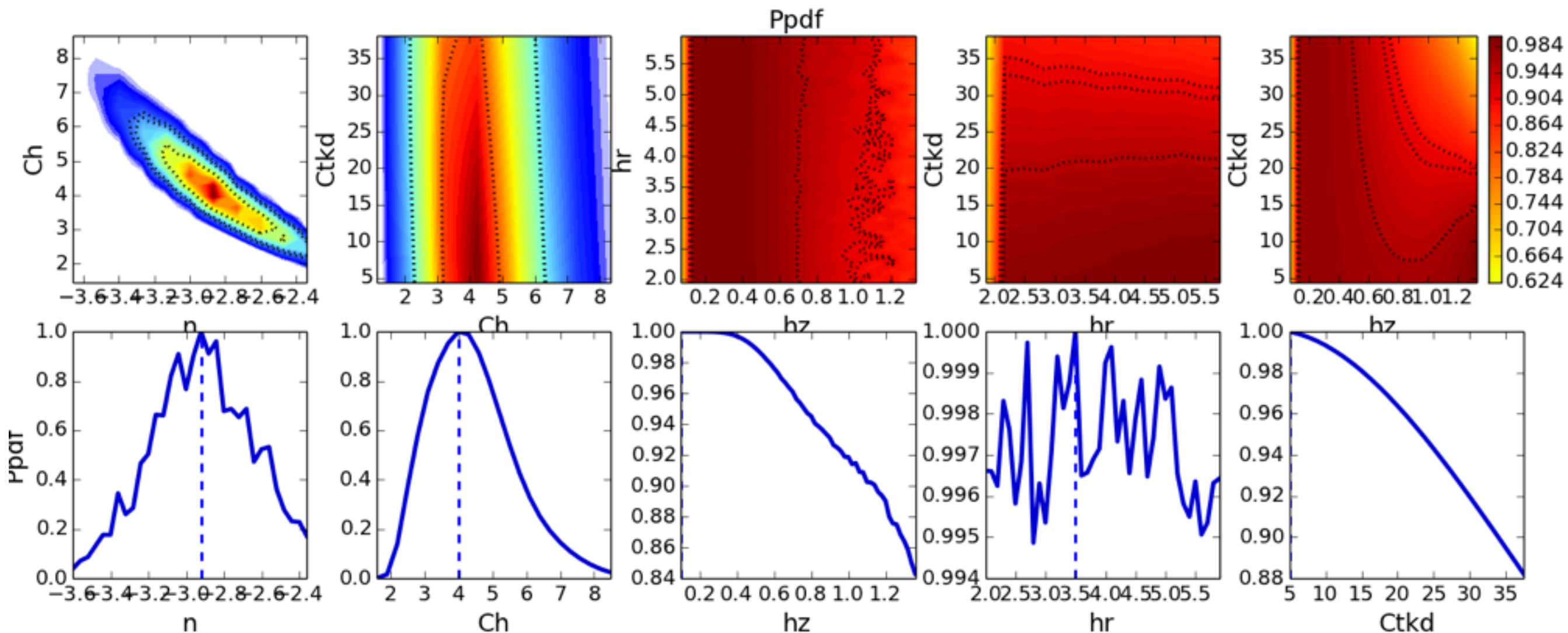
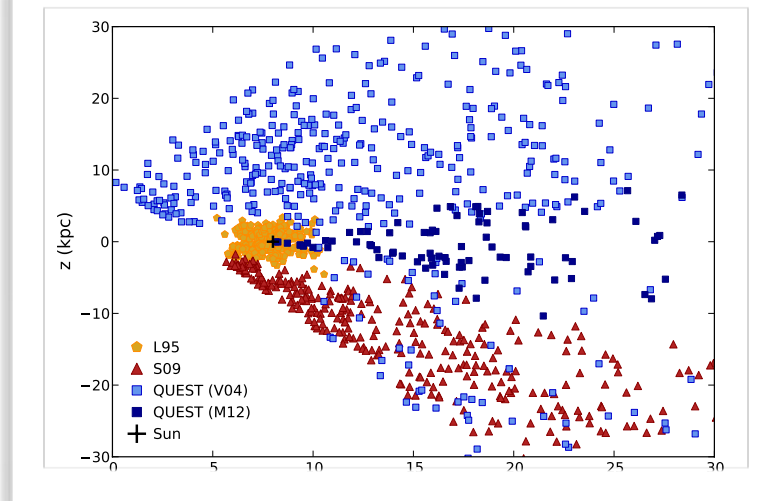
# Density Profiles: One sample at a time

The marginal posteriors taking only the **Layden sample** are as follows:



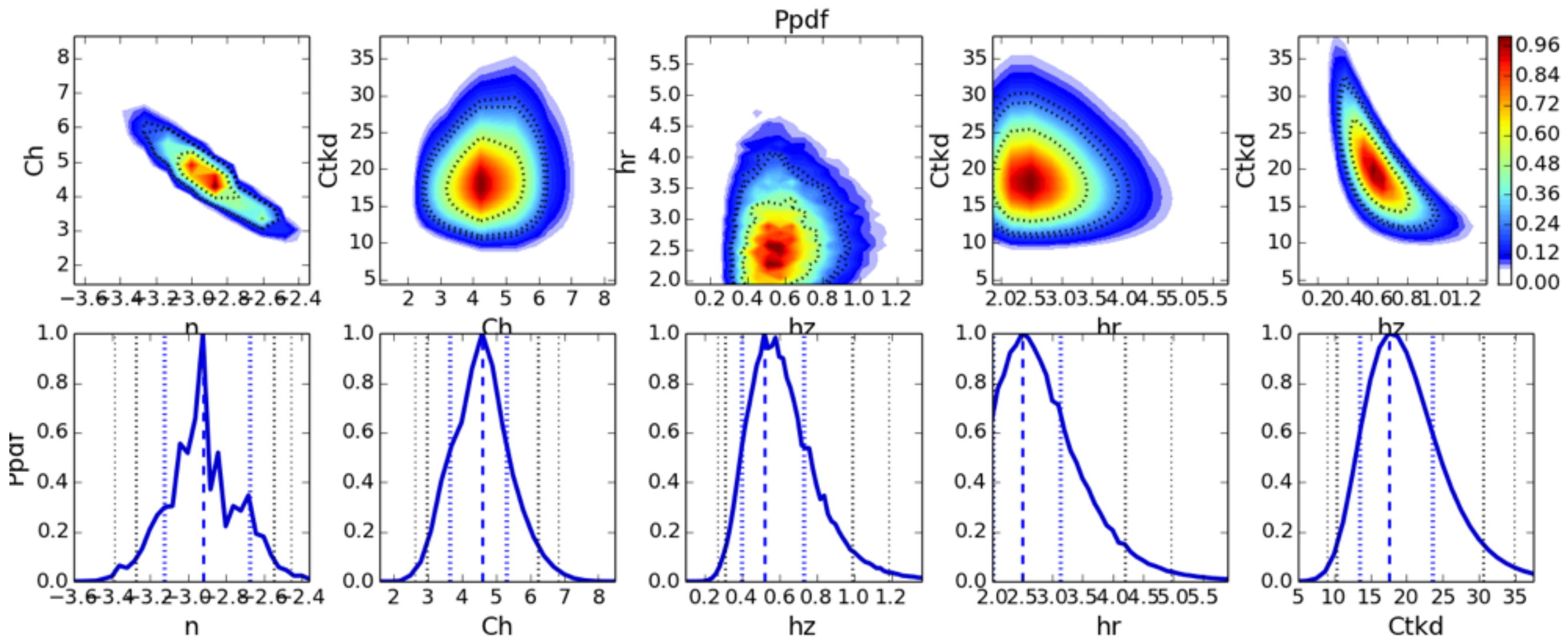
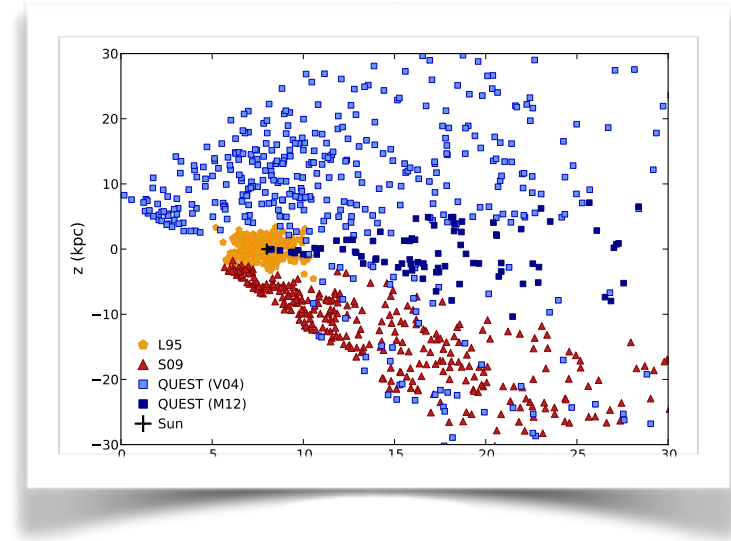
# Density Profiles: One sample at a time

The marginal posteriors taking only the **Sesar sample** are as follows:



# Density Profiles: Combined samples

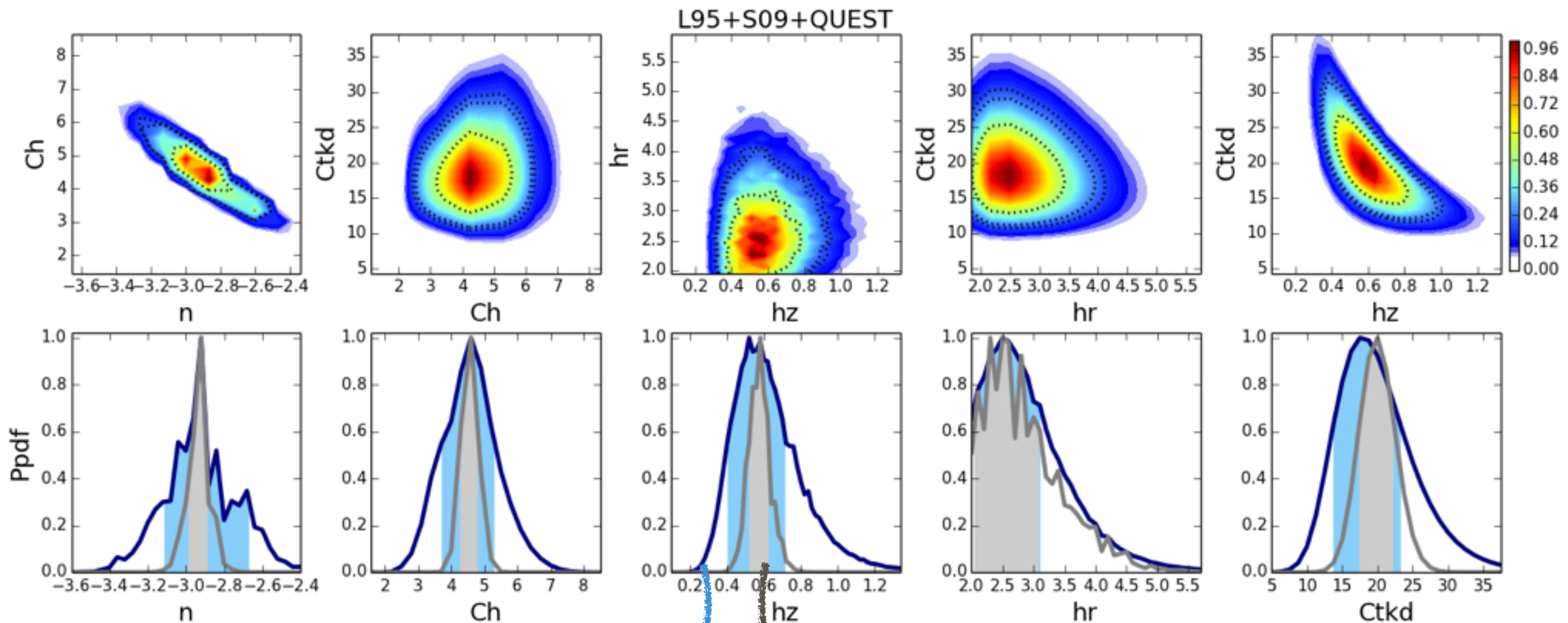
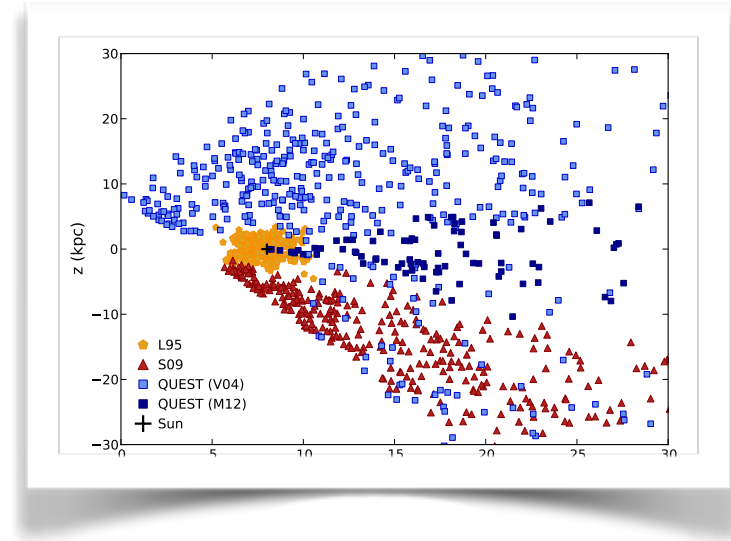
Combining three different samples we find these marginal posteriors (remember its the product of the individual pdfs in 5-D space, and then marginalizing):





# Density Profiles: Combined samples

Combining three different samples we find these marginal posteriors (remember its the product of the individual pdfs in 5-D space, and then marginalizing):



marginal distribution

joint distribution