

# An introduction to Bayesian Statistics through Astronomical Applications (Lecture 2)

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# The Coin Example



# GitHub Repository

- \* Classes and programs are available in the following GitHub repository

[https://github.com/cmateur/intro\\_to\\_bayes\\_UB](https://github.com/cmateur/intro_to_bayes_UB)

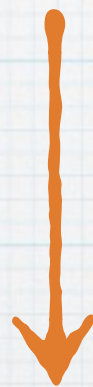


# The Coin Example

- \* Lets recap

- \*  $N$  and  $N_h$  are our data (known)

- \* Our goal is to get  $P(h|N, N_h, I)$  remember this is a function of  $h$



The full posterior IS the answer to our problem

$$P(h|N, N_h, I) = C h^{N_h} (1-h)^{N-N_h} P(h|I)$$



# The Coin Example

The full posterior IS the answer to our problem

$$P(h|N, N_h, I) = C h^{N_h} (1-h)^{N-N_h} P(h|I)$$

- \* anything else we may want can be calculated from it, e.g.
  - \* the most probable value of  $h$
  - \* credible regions (Bayesian term for confidence intervals)
  - \* The probability that  $p > 0.5$ 
    - \*  $\int P(p|N, n, I) dp$
  - \* ... more on this ...



# The Coin Example

The full posterior IS the answer to our problem

$$P(w|N, N_h, I) = C w^{N_h} (1-w)^{N-N_h} P(w|I)$$

\* Question:

- \* is it equivalent to take the data as a whole or to take a subset and add new data as it comes?



# Updating Information



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- \* Lets consider the case of having two independent data points  $D_1$  and  $D_2$ . Bayes' Theorem states

$$P(H|D,I) \propto \prod_{i=1,2} P(D_i|H,I) P(H|I)$$

- \* Expanding the product in the likelihood term:

$$P(H|D,I) \propto P(D_2|H,I) P(D_1|H,I) P(H|I)$$

$$P(H|D_1,I)$$



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$$P(H|D_1, D_2, I) \propto P(D_2|H, I) P(H|D_1, I)$$

- \* Here  $P(H|D_1)$  the posterior on  $H$  given  $D_1$  is acting as an updated prior!



# The Coin Example

The full posterior IS the answer to our problem

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  - \* ... more on this ...



# More examples

The full posterior **IS** the answer to our problem

$$P(h|N, N_H, I) \propto h^{N_H} (1-h)^{N-N_H} P(h|I)$$

- \* The probability that the coin is biased:

- \* Lets say if  $0.45 < h < 0.55$  we can safely take the coin as fair

$$P_{fair} = \int_{0.45}^{0.55} P(h|N, N_H, I) dh$$

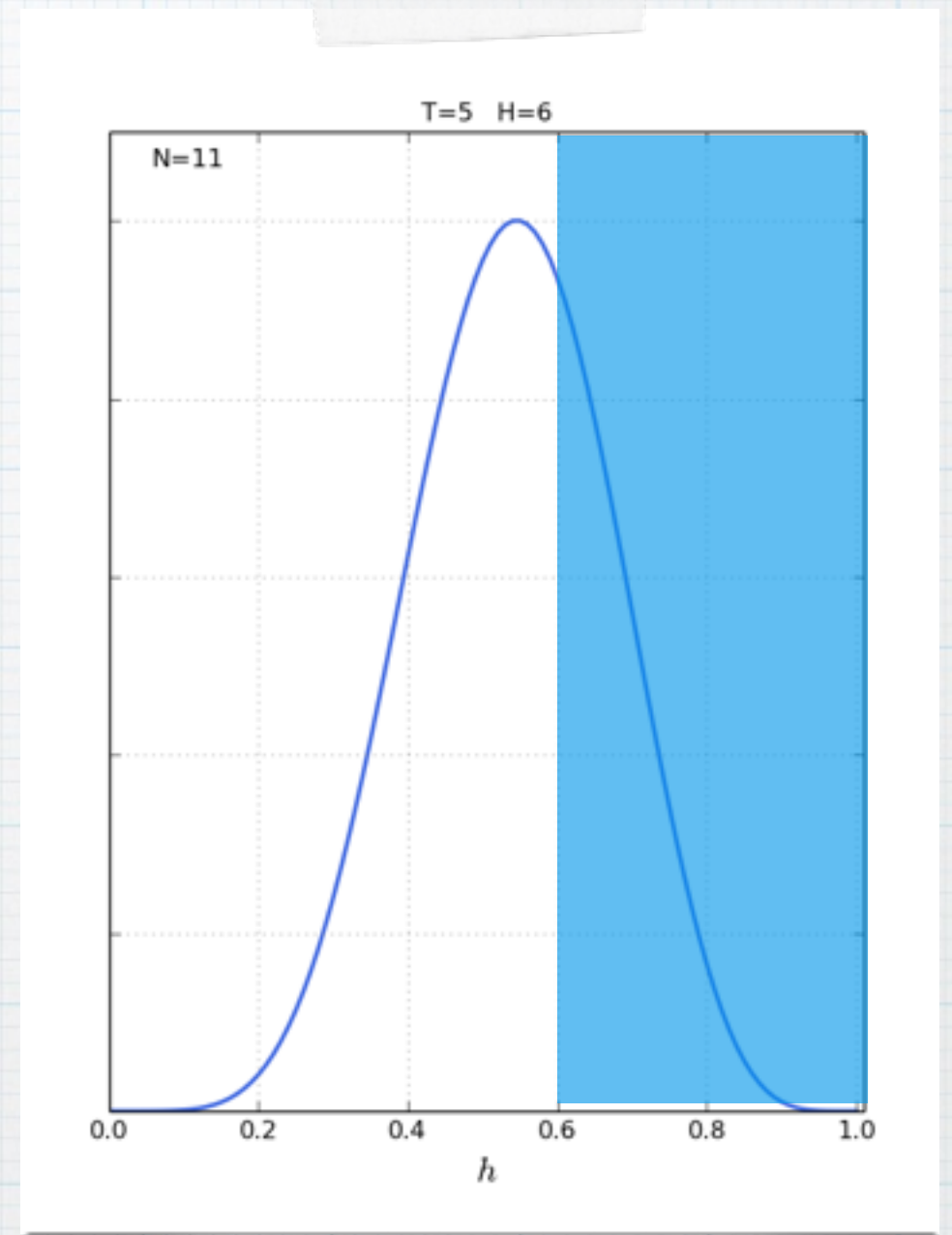
- \* so, the probability that it is biased is  $P_{biased} = 1 - P_{fair}$

$$P_{biased} = \int_0^{0.45} P(h|N, N_H, I) dh + \int_{0.55}^1 P(h|N, N_H, I) dh$$



# Marginalization

- \* We want to compute the probability that the coin is biased towards heads
- \* Lets say by this, we mean  $h > 0.6$
- \* We have to integrate the posterior over the desired range of  $h$



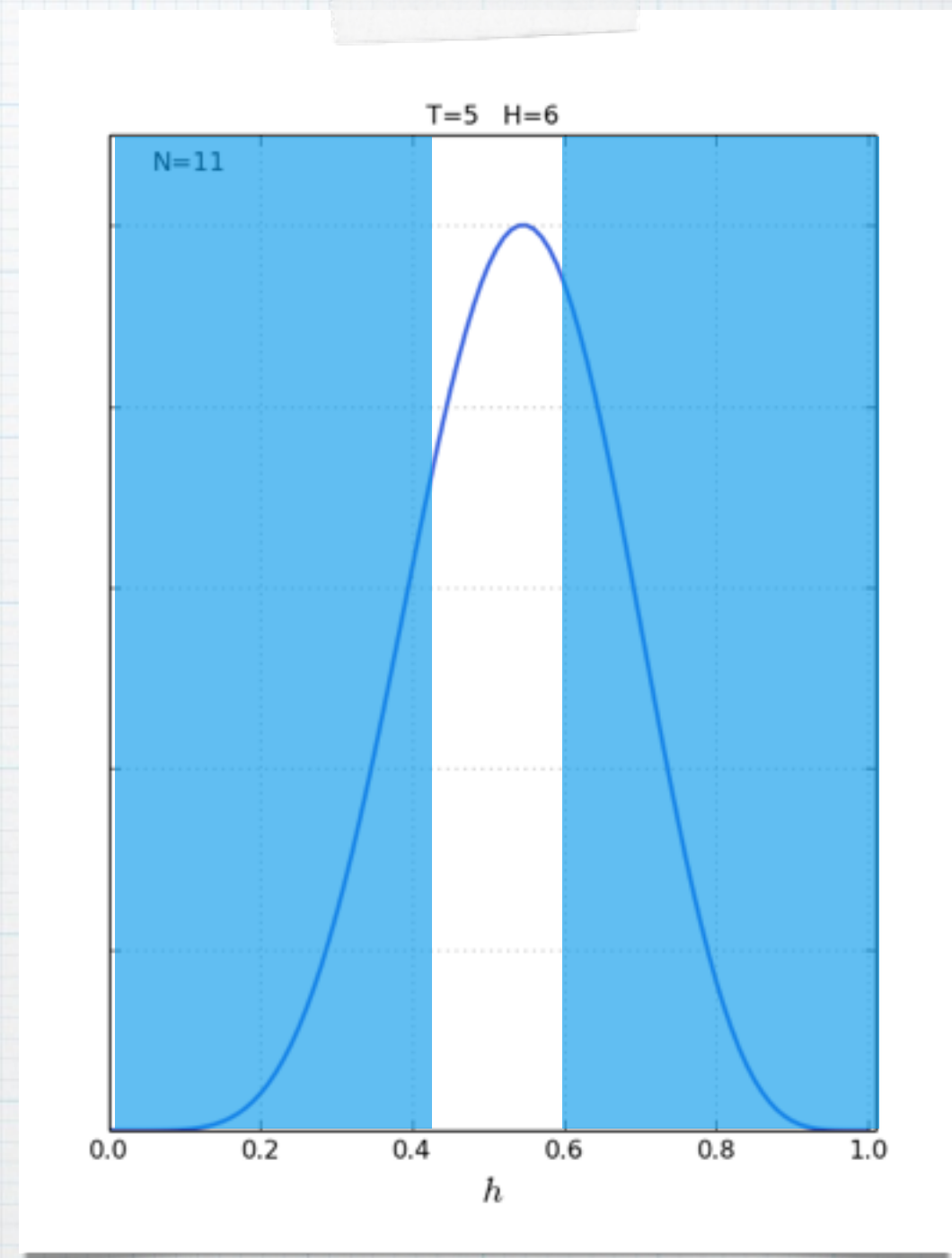
$$P(h > 0.6 | N_h, N) = \int_{0.6}^1 P(h | N_h, N) dh$$



# Marginalization

- \* Now, Lets compute the probability that the coin is fair
- \* Lets say by fair we mean  $h=0.5 \pm x$ , where  $x$  could be e.g.  $x=0.05$

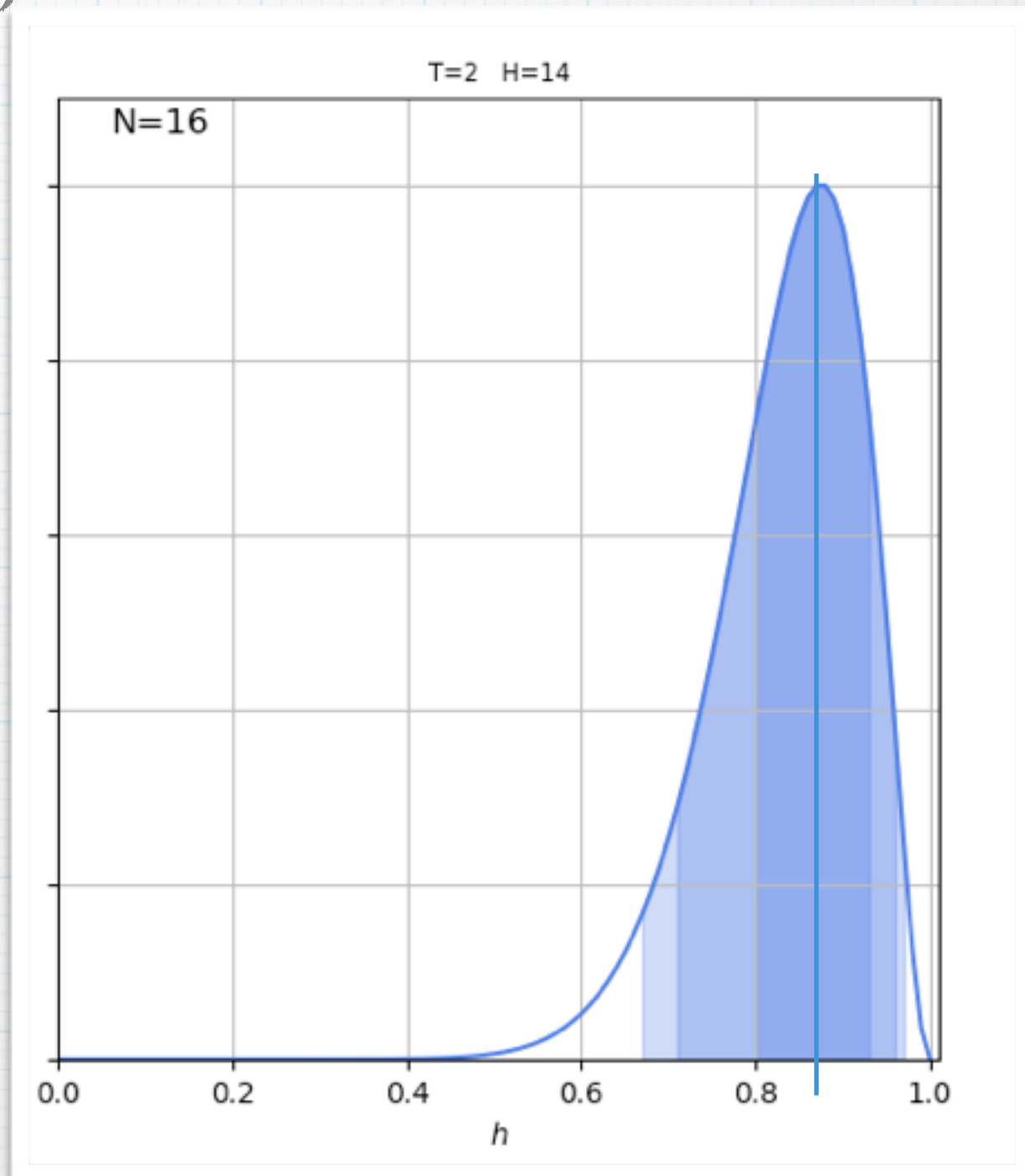
$$P(|h - 0.5| < x | N_h, N)$$
$$= \int_{0.5-x}^{0.5+x} P(h | N_h, N) dh$$





# More Things to compute

- \*  $h_0$  = Most probable value of  $h$ ,  
i.e.  $h$  where  $P(h|N_h, N)$  is  
maximum
- \* Credible regions:
  - \* An  $X\%$  credible region  
contains  $X\%$  of the area of  
the posterior
  - \* e.g.  $1\sigma$  intervals are a 68%  
credible region for a  
gaussian posterior

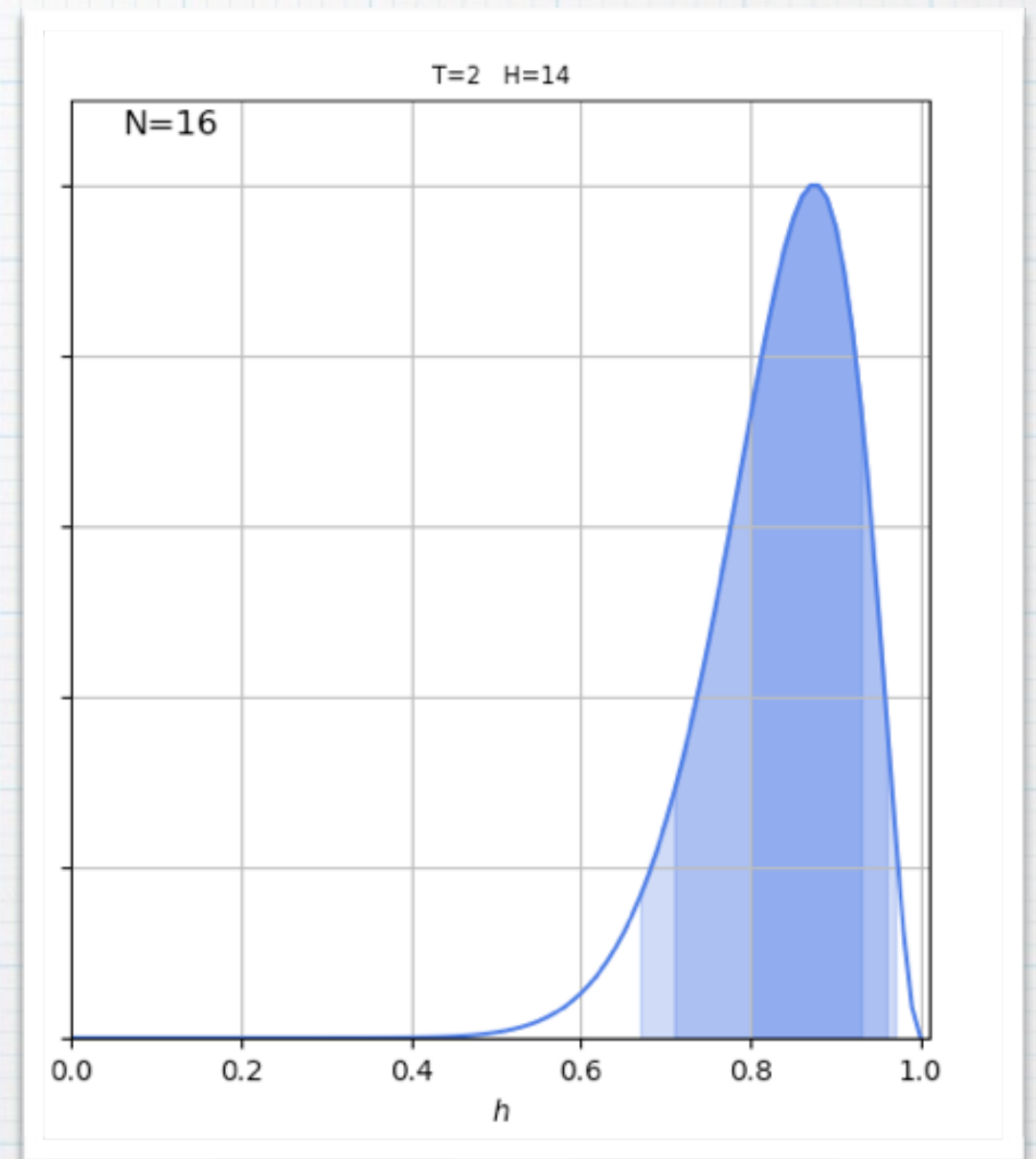




# More Things to compute

- \* Lets report as an error bar, the 68% credible region

- \* The most probable value is  $Nh/N$ , the usual answer, but there's a natural way of computing the error bars



- \* This is specially important for extremely low or extremely high values of  $h$



# The Coin Example in an astrophysical context



# Disk Fractions

- \* The Coin is just one example of a Binomial problem
- \* This describes anything that can be expressed as a two-state problem, a 'success' occurring with probability  $p$  and 'failure' with probability  $(1-p)$ , for example  $p$  could be:
  - \* The fraction of radio-loud quasars in a sample
  - \* The fraction of stars having disks
  - \* The fraction of early/late type galaxies
  - \* ....



# Disk Fractions

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# A simple Real Life example

- \* Lets take an example from Downes et al. (2015)
- \* We have a sample with a total of  $N_{VLMS}=77$  very low mass stars (VLMS) and  $N_{BD}=16$  brown dwarfs (BD) from the 25 Ori cluster ( $\sim 10$  Myr)
- \* Out of these, 6 VLMS and 4 BDs have disks (infrared excesses observed)
- \* The key scientific question is

Do VLMS and BDs have the same disk fraction?



# VLMS and BD disk Fractions

- \* The data are conditionally independent, thus from the product rule we have

$$P(f_{disk}^{VLMS}, f_{disk}^{BD} | data) = P(f_{disk}^{VLMS} | data) P(f_{disk}^{BD} | data)$$

i.e. the multiplication of the disk fraction posteriors for VLMS and BDs. Each of these is given by the Binomial distribution as in the coin example

$$P(f_{disk} | data) = f_{disk}^{N_{disk}} (1 - f_{disk})^{N - N_{disk}}$$

in this case we have assumed a uniform prior

$$P(f_{disk}^{VLMS}, f_{disk}^{BD}) = 1$$



\* In this case our posterior is a two-dimensional function that depends upon  $f_{disk}^{VL}$  and  $f_{disk}^{BD}$



$$P(f_{disk}^{V L M S}, f_{disk}^{B D} | data)$$

again, remember the posterior is the 'Holy Grail'



# Marginalization

- \* If we want the posterior dependent upon just one of the parameters we need to marginalise over the other one
- \* For  $f_{disk}^{BD}$  we get

$$P(f_{disk}^{BD} | data) = \int P(f_{disk}^{V LMS}, f_{disk}^{BD} | data) df_{disk}^{V LMS}$$

- \* similarly for  $f_{disk}^{VL}$

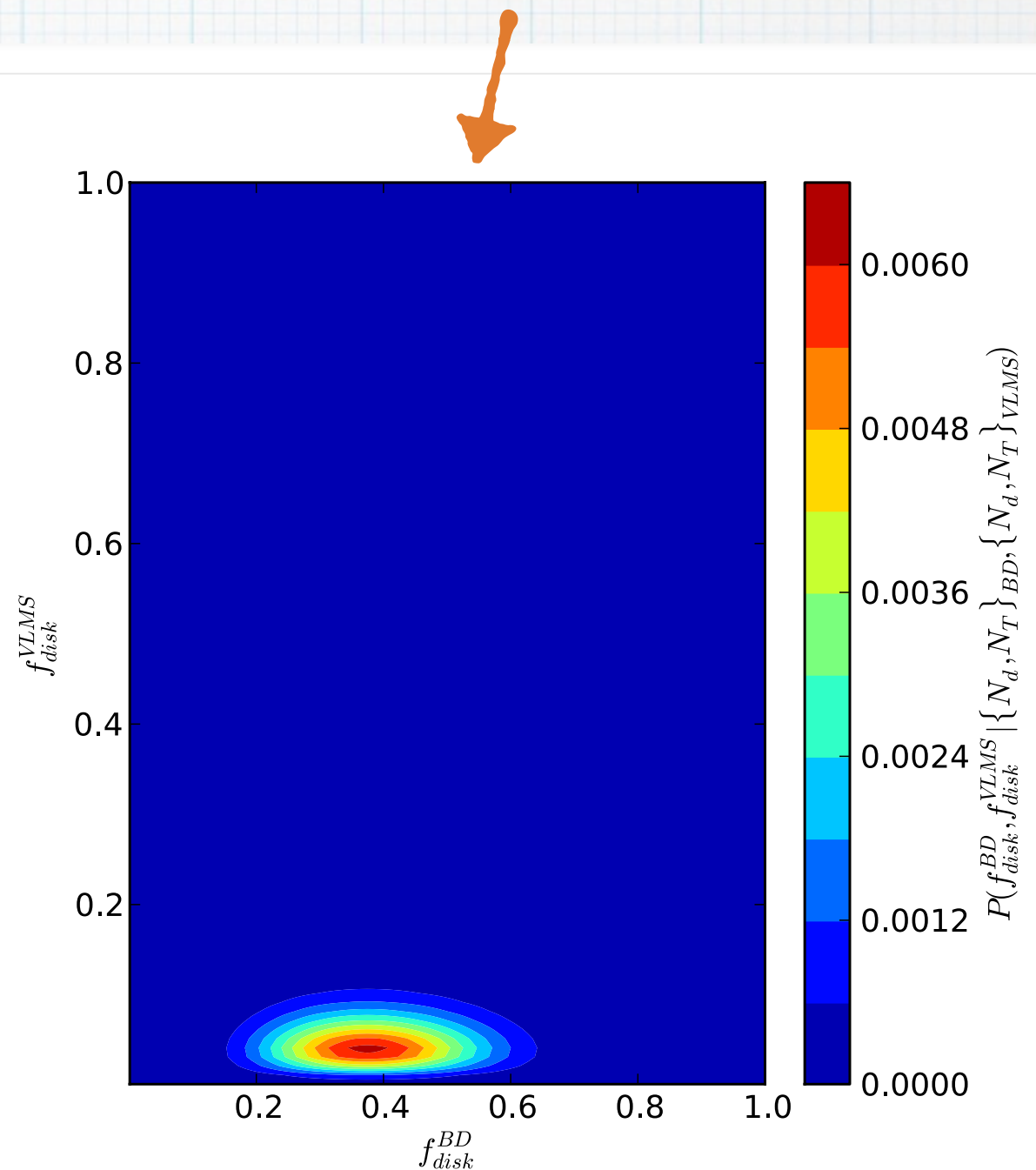
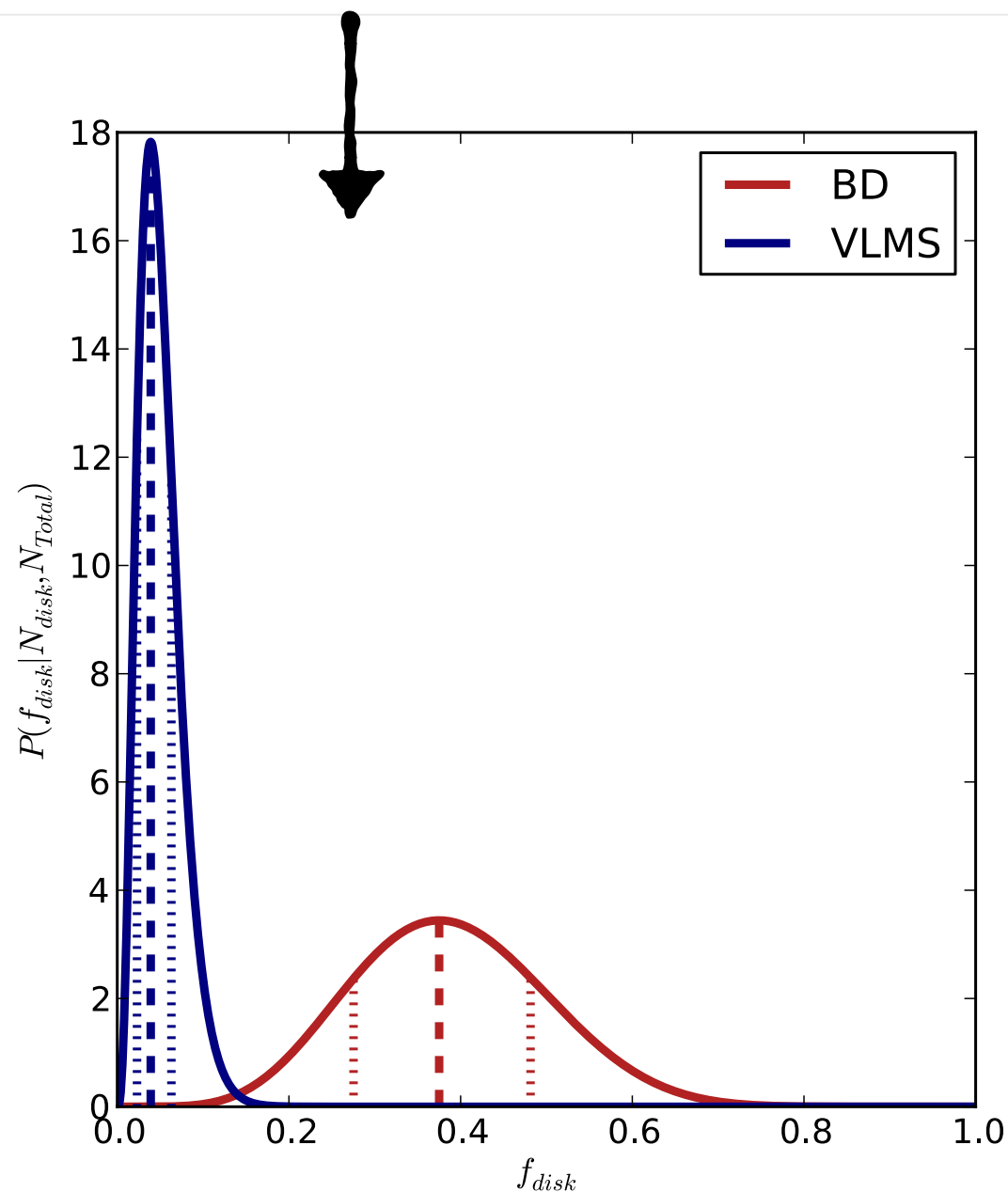
$$P(f_{disk}^{V LMS} | data) = \int P(f_{disk}^{V LMS}, f_{disk}^{BD} | data) df_{disk}^{BD}$$



# VLMS and BD disk Fractions

Marginal posteriors (integrated upon  $f_{disk}^{VL}$  or  $f_{disk}^{BD}$ )

$$P(f_{disk}^{VLMS}, f_{disk}^{BD} | data)$$

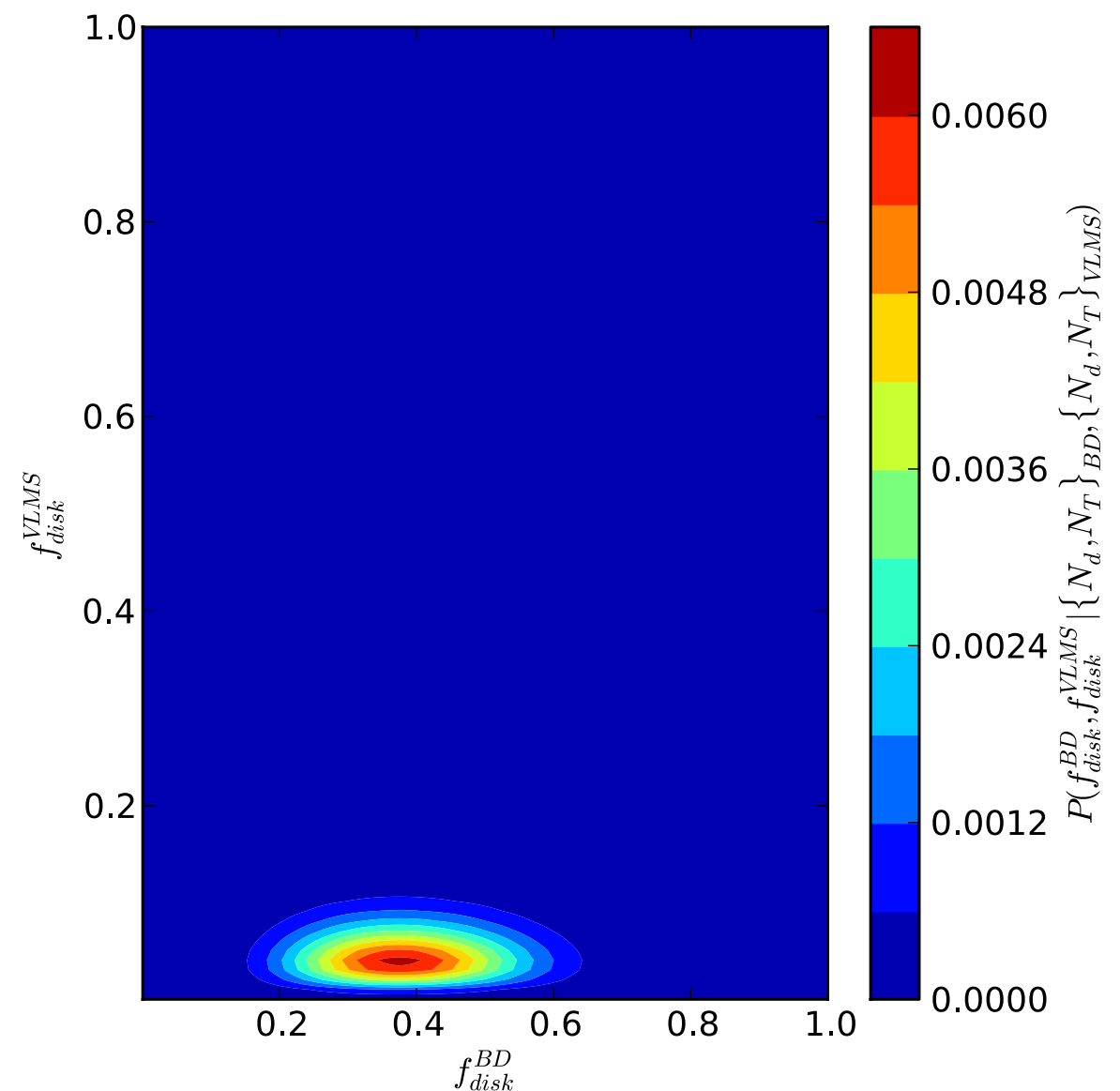
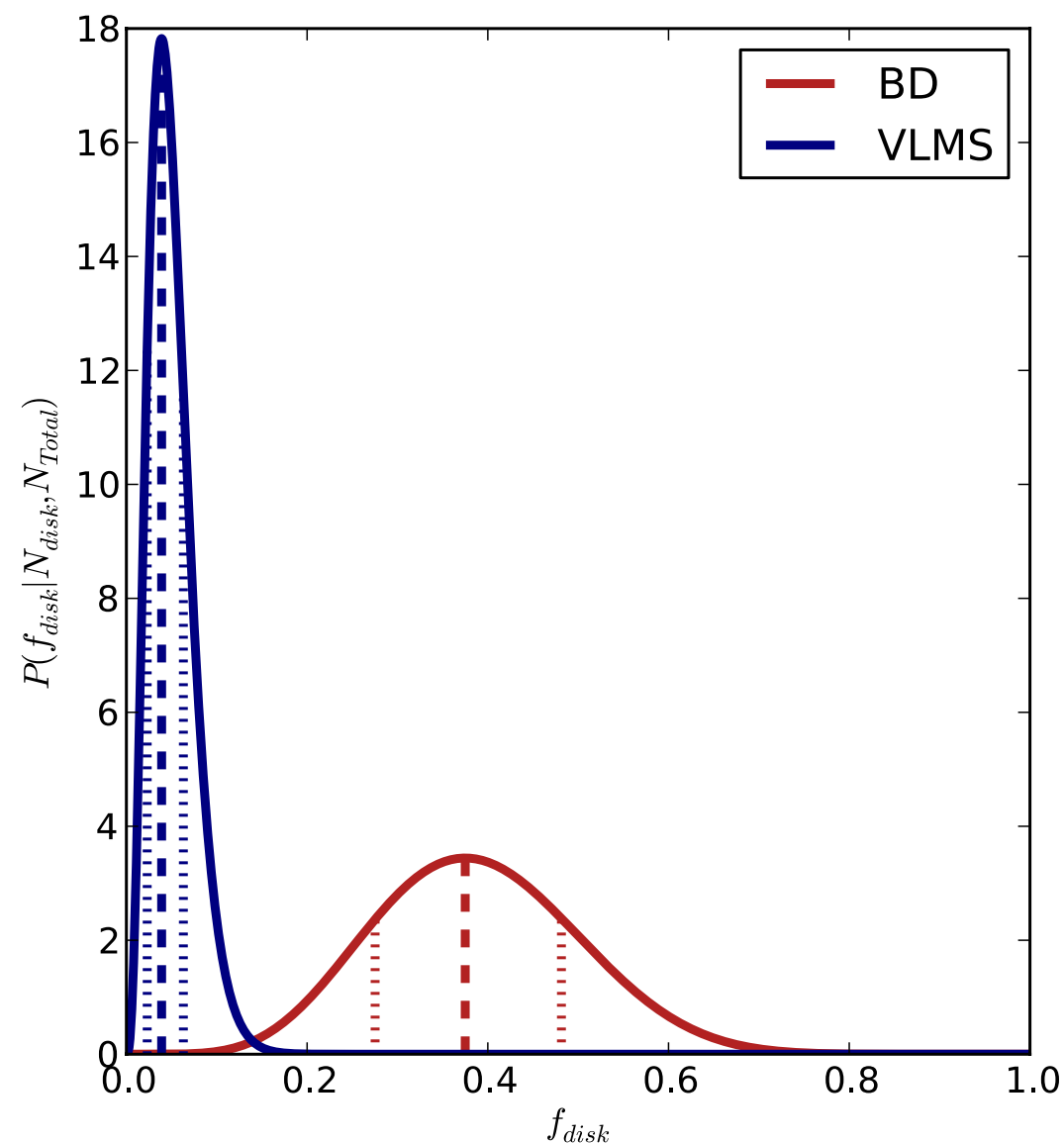


$$N_{VLMS} = 77, N_{VLMS}^{disk} = 4; N_{BD}^{disk} = 16, N_{BD} = 6$$



# VLMS and BD disk Fractions

How do we answer the initial question: do VLMS and BDs have the same disk fraction?



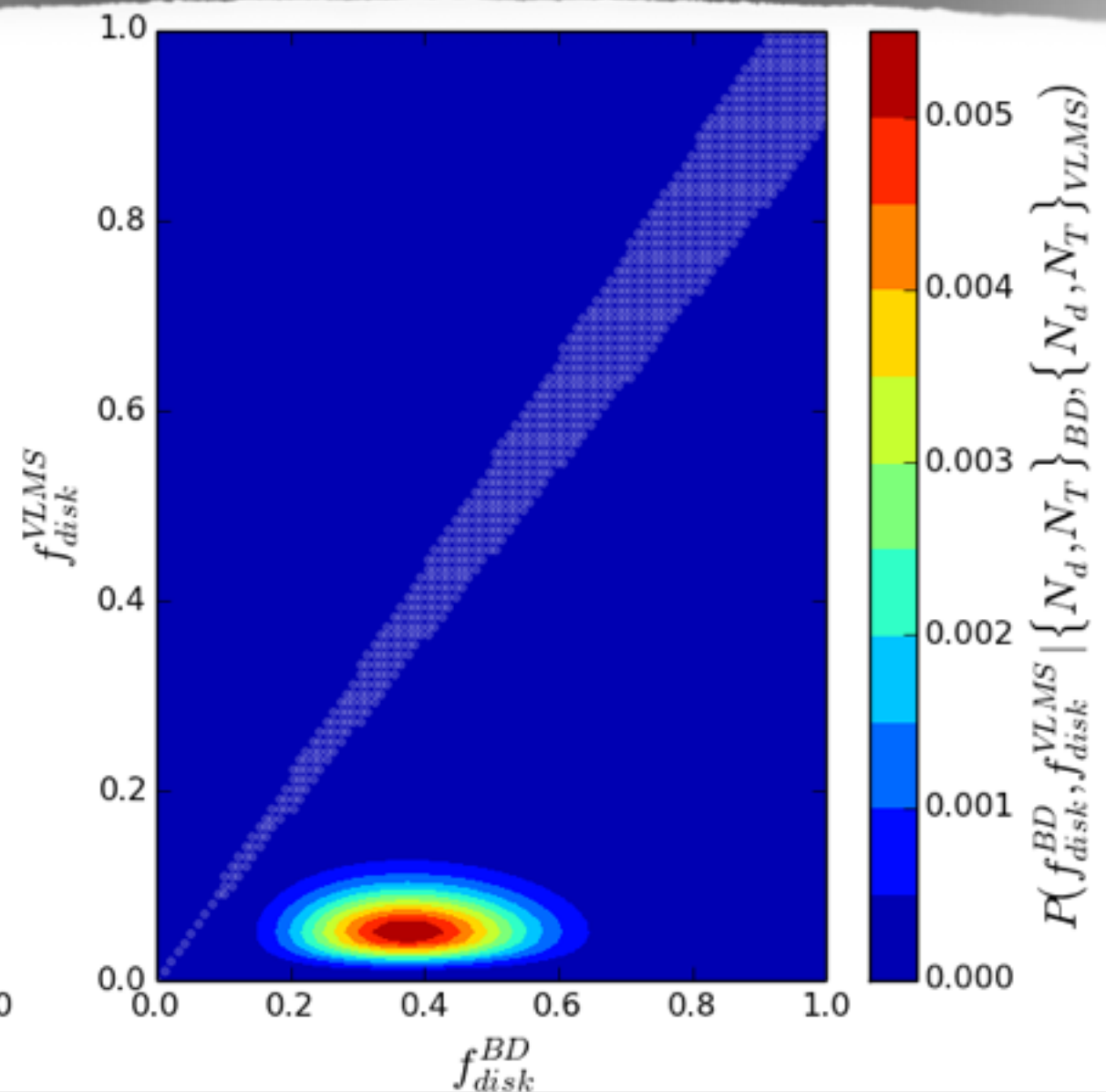
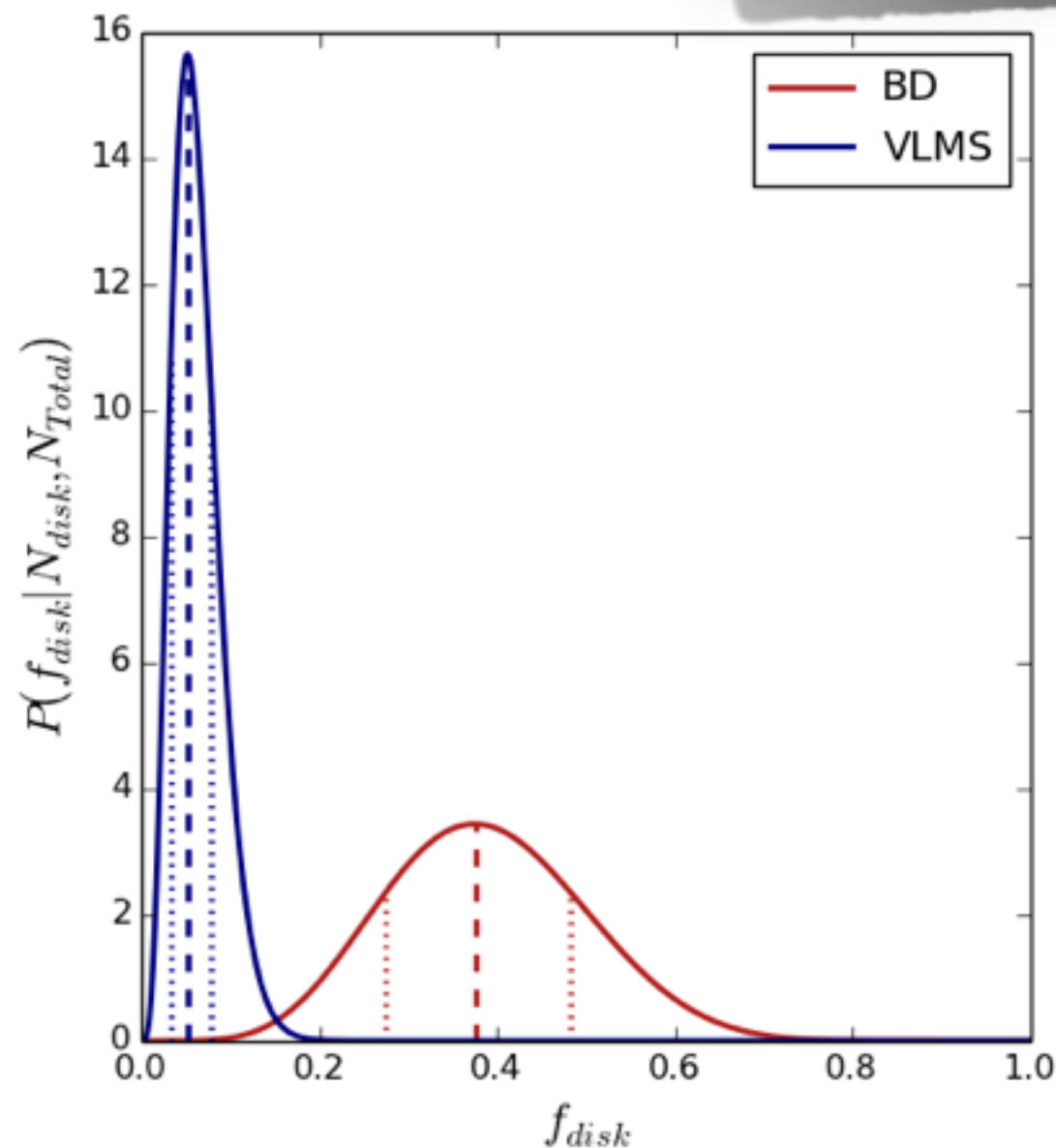


# VLMS and BD disk Fractions

Integrate the posterior in the region where

$$f_{\text{disk}}^{\text{VL}} \neq f_{\text{disk}}^{\text{BD}}$$

this gives the probability that the two disk fractions are different!



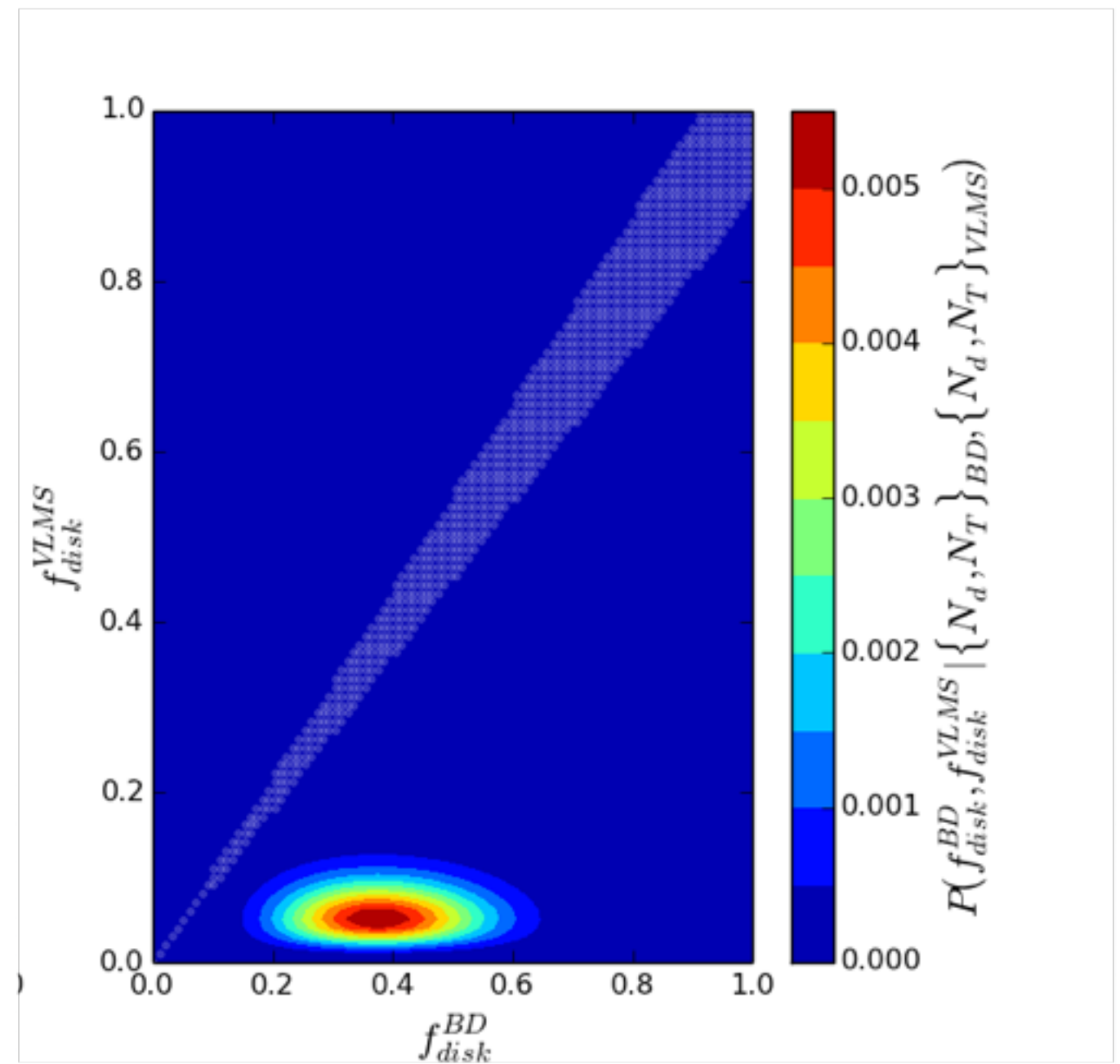


# VLMS and BD disk Fractions

Better to integrate the posterior in the region where the disk fractions differ by 10% e.g.

In this example we get that the probability that the two disk fractions are different is

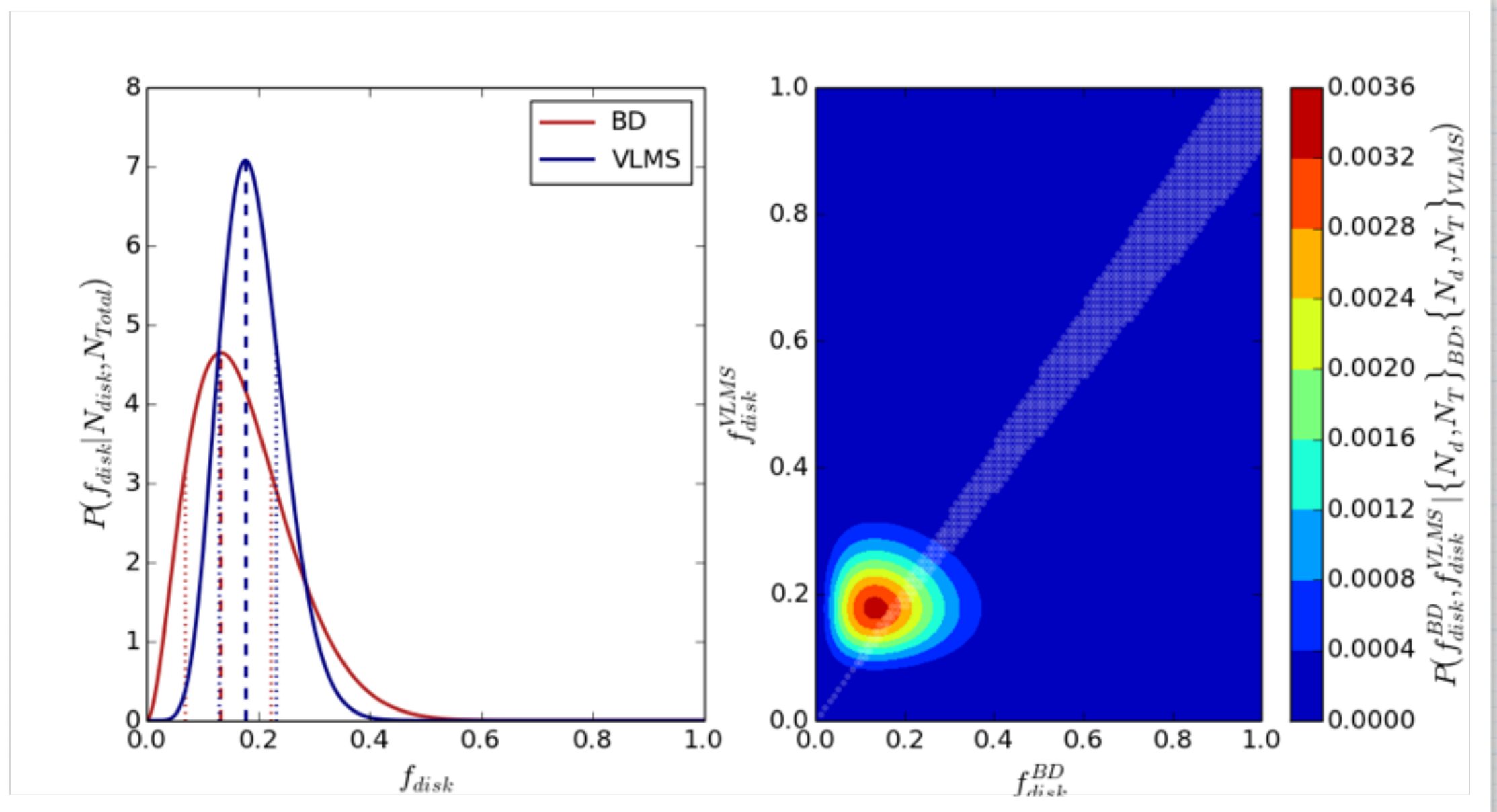
$$P_{>10\%} = 99.95\%$$





# VLMS and BD disk Fractions

This is even more useful in more uncertain cases, e.g. for transitional disk fractions in this same cluster we have:



$$N_{VLMS} = 12, N_{VLMS}^{disk} = 45, N_{BD} = 8, N_{BD}^{disk} = 15$$

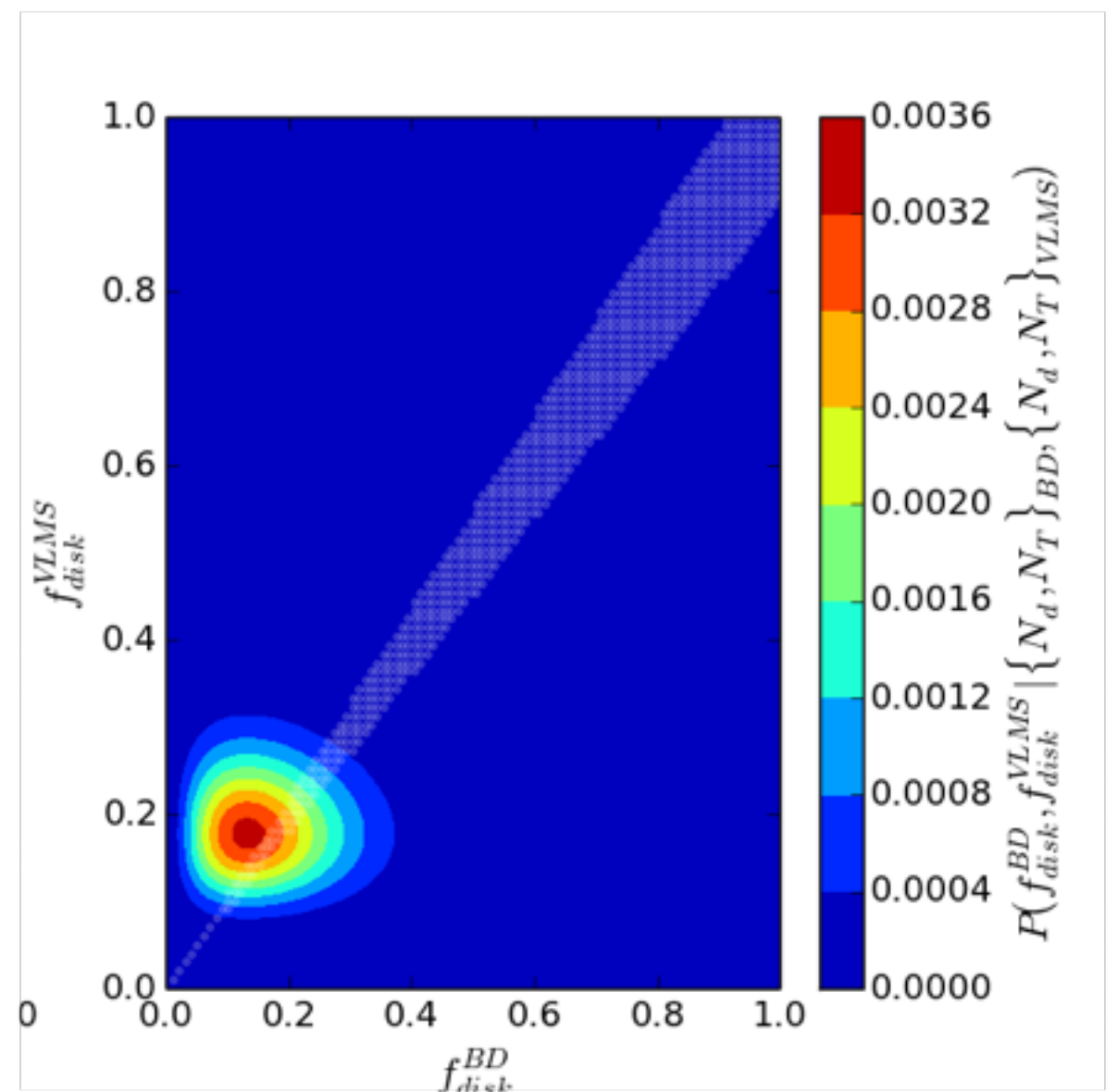


# VLMS and BD disk Fractions

This is even more useful in more uncertain cases, e.g. for transitional disk fractions in this same cluster we have:

Here we get that the probability that the two disk fractions are different is

$$P_{>10\%} = 89.7\%$$



$$N_{VLMS} = 8, N_{VLMS}^{disk} = 45, N_{BD} = 2, N_{BD}^{disk} = 15$$



# Least Squares



# Gaussian Uncertainties: Least Squares derived

- \* In a problem, whatever it may be, where our model differs from our observations because of gaussian uncertainties, the posterior is simply:

$$P(model|data, I) = \prod_{i=1}^N e^{-\frac{(x_i - x_{model})^2}{2\sigma_i^2}} P(model|I)$$
$$= e^{-\frac{1}{2} \sum_{i=1}^N \frac{(x_i - x_{model})^2}{\sigma_i^2}}$$

- \* For a uniform prior we have

$$P(model|data, I) = e^{-\frac{1}{2} \chi^2}$$

The least squares or  $\chi^2$  minimisation method derived !!!!  
(assumptions are explicit!)



# Very short bibliography

- \* Highly recommended introductory bibliography:
- \* Sivia & Skilling book
- \* Giulio D'Agostini's notes available at Tom Loredo's BIPS web page:

<http://www.astro.cornell.edu/staff/loredo/bayes/>

