MECE-410: Flight Dynamics Spring 2014-2015 (2145)

Due: April 2nd, 2015

Project #3

Instructions: Use Matlab to solve all problems. Save your work in an m-file.

Assume the following aerodynamic aircraft model:

$$\begin{split} &C_{X} = C_{X_{0}} + C_{X_{u}}u + C_{X_{w}}w + \frac{\overline{c}}{2u}C_{X_{q}}q\frac{180}{\pi} + C_{X_{\delta\epsilon}}\delta e \\ &C_{Y} = C_{Y_{0}} + C_{Y_{v}}v + \frac{b}{2u}\Big(C_{Y_{p}}p + C_{Y_{r}}r\Big)\frac{180}{\pi} + C_{Y_{\delta a}}\delta a + C_{Y_{\delta r}}\delta r \\ &C_{Z} = C_{Z_{0}} + C_{Z_{u}}u + C_{Z_{w}}w + \frac{\overline{c}}{2u}C_{Z_{q}}q\frac{180}{\pi} + C_{Z_{\delta\epsilon}}\delta e \\ &C_{I} = C_{I_{0}} + C_{I_{v}}v + \frac{b}{2u}\Big(C_{I_{p}}p + C_{I_{r}}r\Big)\frac{180}{\pi} + C_{I_{\delta a}}\delta a + C_{I_{\delta r}}\delta r \\ &C_{m} = C_{m_{0}} + C_{m_{u}}u + C_{m_{w}}w + \frac{\overline{c}}{2u}C_{m_{q}}q\frac{180}{\pi} + C_{m_{\delta\epsilon}}\delta e \\ &C_{n} = C_{n_{0}} + C_{n_{v}}v + \frac{b}{2u}\Big(C_{n_{p}}p + C_{n_{r}}r\Big)\frac{180}{\pi} + C_{n_{\delta a}}\delta a + C_{n_{\delta r}}\delta r \end{split}$$

The external forces and moments acting on the aircraft are:

$$\begin{split} F_{A_x} &= \overline{q}SC_X; F_{A_y} = \overline{q}SC_Y; F_{A_z} = \overline{q}SC_Z; F_{T_x} = T; F_{T_y} = 0; F_{T_z} = 0 \\ M_{e_y} &= \overline{q}SbC_l; M_{e_y} = \overline{q}S\overline{c}C_m; M_{e_z} = \overline{q}SbC_n \end{split}$$

and:

$$\begin{split} &C_{X_0} = -2.135364 \text{E-}02 \ ; C_{X_u} = 1.289018 \text{E-}04 \ ; C_{X_w} = -2.17775 \text{E-}03 \ ; C_{X_q} = 2.1928052 \text{E-}04 \\ &C_{X_{\delta e}} = 1.386632 \text{E-}03 \\ &C_{Y_0} = 0 \ ; C_{Y_v} = -6.4490425 \text{E-}02 \ ; C_{Y_p} = 1.33481 \text{E-}03 \ ; C_{Y_r} = 9.401418 \text{E-}03 \ ; \\ &C_{Y_{\delta u}} = 4.618436 \text{E-}04 \ ; C_{Y_{\delta r}} = 2.991717 \text{E-}03 \\ &C_{Z_0} = 5.092263 \text{E-}02 \ ; C_{Z_u} = -4.3444023 \text{E-}04 \ ; C_{Z_w} = -1.9946051 \text{E-}03 \ ; C_{Z_q} = -5.3473522 \text{E-}02 \ ; \\ &C_{Z_{\delta e}} = -1.2167892 \text{E-}02 \\ &C_{I_0} = 0 \ ; C_{I_v} = -1.75539 \text{E-}03 \ ; C_{I_p} = -7.392626 \text{E-}03 \ ; C_{I_r} = 5.910111 \text{E-}05 \\ &C_{I_{\delta u}} = -2.089358 \text{E-}03 \ ; C_{I_{\delta r}} = 4.7651867 \text{E-}04 \\ &C_{m_0} = -1.39985 \text{E-}02 \ ; C_{m_u} = -1.15335756 \text{E-}04 \ ; C_{m_w} = -1.16313463 \text{E-}03 \ ; C_{m_q} = -6.08086182 \text{E-}01 \ ; \\ &C_{m_{\delta v}} = -4.632495451 \text{E-}02 \end{split}$$

with units (/deg) expect for the "not" terms which are dimensionless and u, v, w which are (/ft/sec)

 $C_{n_0} = 0$; $C_{n_v} = 5.1988574$ E-03; $C_{n_v} = -4.29454$ 8E-04; $C_{n_v} = -8.6047784$ E-03

 $C_{n_{s_{-}}} = -1.955539\text{E}-04$; $C_{n_{s_{-}}} = -5.50282873\text{E}-03$

Assume $\bar{q} = 0.5 \rho u^2$

The aircraft properties are:

$$I_{xx} = 8691.46164$$
, $I_{yy} = 70668.585$, $I_{zz} = 70418.67355$, $I_{xz} = 151.43836$, $I_{xy} = I_{yz} = 0.0$ (slug-ft²) $S = 300$ (ft²), $\overline{c} = 11.32$ (ft), $b = 30$ (ft), $m = mass = 756.5262463$ (slugs)

assume air density is constant: $\rho = 0.0012669984$ (slugs/ ft³) and g = 32.17561865 (ft/sec²)

The initial "trim" conditions are:

$$u(0) = 670.360471$$
 (ft/sec), $w(0) = 40.362171$ (ft/sec), $\theta(0) = \tan^{-1} \left[w(0) / u(0) \right]$ (rad), $T = thrust = 3767.207337$ (lbs), $\delta e = -2.9846046$ (deg), all others variable IC's are zero

In your m-file, program the nine nonlinear differential equations (axial velocity, u; side velocity, v; normal velocity, w; roll rate, p; pitch rate, q; yaw rate, r; bank angle, ϕ ; pitch angle, θ ; heading angle, ψ) for aircraft dynamics and:

- 1. Using the "ode45" command, simulate the response of the aircraft model for the time interval of $\begin{bmatrix} 0,10 \end{bmatrix}$ sec with $\Delta t = 0.01$ sec using the "trim" conditions shown above. Plot Axial Velocity (ft/sec) vs time; Side Velocity (ft/sec) vs time; Normal Velocity (ft/sec) vs time; Roll Rate (deg/sec) vs time; Pitch Rate (deg/sec) vs time; Yaw Rate (deg/sec) vs time; Bank Angle (deg) vs time; Pitch Angle (deg) vs time; and Heading Angle (deg) vs time for the trim condition. Verify the aircraft is trimmed!
- 2. Using the "ode45" command, simulate the response of the aircraft model for the time interval of $\begin{bmatrix} 0,10 \end{bmatrix}$ sec with $\Delta t = 0.01$ sec for a step "delta" input to the elevator with the step starting at time 1 sec and with a magnitude of "delta" -0.5 deg so that the total elevator deflection at 1 sec is -3.4846046 deg and equal to the trim condition before 1 sec. Plot Axial Velocity (ft/sec) vs time; Side Velocity (ft/sec) vs time; Normal Velocity (ft/sec) vs time; Roll Rate (deg/sec) vs time; Pitch Rate (deg/sec) vs time; Yaw Rate (deg/sec) vs time; Bank Angle (deg) vs time; Pitch Angle (deg) vs time; and Heading Angle (deg) vs time for the trim condition for the step response. The aileron and rudder position should be set fixed to their trim condition for this part.
- 3. Using the "ode45" command, simulate the response of the aircraft model for the time interval of $\begin{bmatrix} 0,10 \end{bmatrix}$ sec with $\Delta t = 0.01$ sec for a step input to the aileron with the step starting at time 1 sec and with a magnitude of -0.5 deg. Plot Axial Velocity (ft/sec) vs time; Side Velocity (ft/sec) vs time; Normal Velocity (ft/sec) vs time; Roll Rate (deg/sec) vs time; Pitch Rate (deg/sec) vs time; Yaw Rate (deg/sec) vs time; Bank Angle (deg) vs time; Pitch Angle (deg) vs time; and Heading Angle (deg) vs time for the trim condition for the step response. The elevator and rudder position should be set fixed to their trim condition for this part.
- 4. Using the "ode45" command, simulate the response of the aircraft model for the time interval of $\begin{bmatrix} 0,10 \end{bmatrix}$ sec with $\Delta t=0.01$ sec for a step input to the rudder with the step starting at time 1 sec and with a magnitude of -2.0 deg. Plot Axial Velocity (ft/sec) vs time; Side Velocity (ft/sec) vs time; Normal Velocity (ft/sec) vs time; Roll Rate (deg/sec) vs time; Pitch Rate (deg/sec) vs time; Yaw Rate (deg/sec) vs time; Bank Angle (deg) vs time; Pitch Angle (deg) vs time; and Heading Angle (deg) vs time for the trim condition for the step response. The elevator and aileron position should be set fixed to their trim condition for this part.