sos2tf

Convert digital filter second-order section data to transfer function form

Syntax

```
[b,a]=sos2tf(sos)
[b,a] = sos2tf(sos,g)
```

Description

sos2tf converts a second-order section representation of a given digital filter to an equivalent transfer function representation.

[b,a] = sos2tf(sos) returns the numerator coefficients b and denominator coefficients a of the transfer function that describes a discrete-time system given by sos in second-order section form. The second-order section format of H(z) is given by

$$H(z) = \prod_{k=1}^L H_k(z) = \prod_{k=1}^L \frac{b_{0k} + b_{1k}z^{-1} + b_{2k}z^{-2}}{1 + a_{1k}z^{-1} + a_{2k}z^{-2}}$$

sos is an *L*-by-6 matrix that contains the coefficients of each second-order section stored in its rows.

$$sos = \begin{bmatrix} b_{01} & b_{11} & b_{21} & 1 & a_{11} & a_{21} \\ b_{02} & b_{12} & b_{22} & 1 & a_{12} & a_{22} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ b_{0L} & b_{1L} & b_{2L} & 1 & a_{1L} & a_{2L} \end{bmatrix}$$

Row vectors b and a contain the numerator and denominator coefficients of H(z) stored in descending powers of z.

$$H(z) = \frac{B(z)}{A(z)} = \frac{b_1 + b_2 z^{-1} + \dots + b_{n+1} z^{-n}}{a_1 + a_2 z^{-1} + \dots + a_{m+1} z^{-m}}$$

[b,a] = sos2tf(sos,g) returns the transfer function that describes a discrete-time system given by sos in second-order section form with gain g.

$$H(z) = g \prod_{k=1}^L H_k(z)$$

Examples

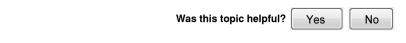
Compute the transfer function representation of a simple second-order section system:

Algorithms

sos2tf uses the <u>conv</u> function to multiply all of the numerator and denominator second-order polynomials together. For higher order filters (possibly starting as low as order 8), numerical problems due to roundoff errors may occur when forming the transfer function.

See Also

latc2tf | sos2ss | sos2zp | ss2tf | tf2sos | zp2tf



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