

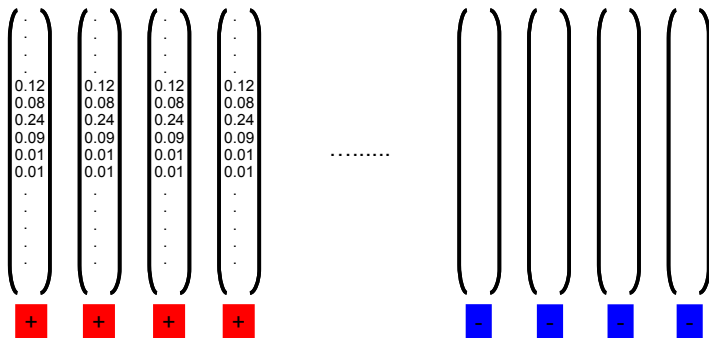
Support Vector Machines for Multiple-Instance Learning

S. Andrews, I. Tsochantaridis and T. Hofmann

presented by Y. Chai

June 7, 2011

Supervised Learning



- Given: a training set of labeled patterns, $(\mathbf{x}_i, y_i) \in \mathbb{R}^d \times Y$, i.i.d.
- Target: a classifier, i.e., a function to map patterns to labels $f: \mathbb{R}^d \rightarrow Y$

Multiple Instance Learning (MIL)

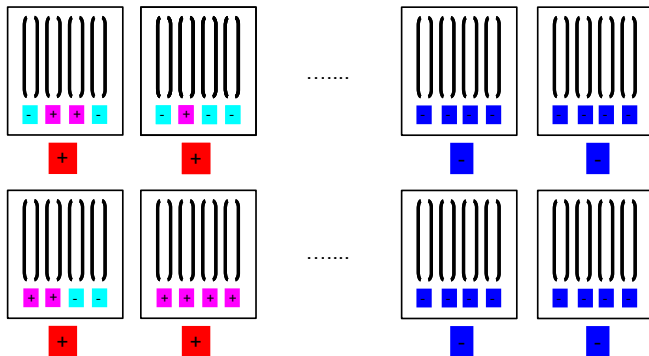
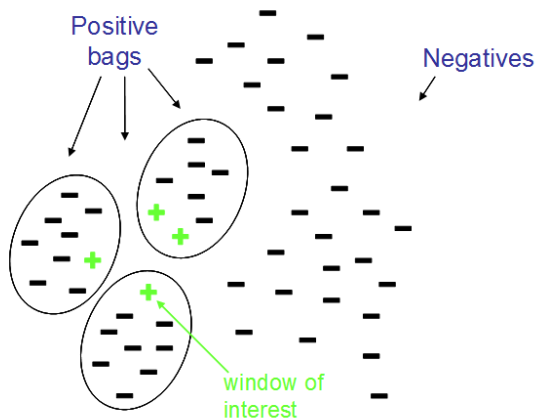


Figure: Plus(red), minus(blue). Hidden plus(purple), hidden minus(cyan)

Multiple Instance Learning (MIL)



Multiple Instance Learning (MIL)

Given:

- a training set of **patterns** $\mathbf{x}_1, \dots, \mathbf{x}_n$, grouped into **bags** $\mathbf{B}_1, \dots, \mathbf{B}_m$, with $\mathbf{B}_I = \{\mathbf{x}_i : i \in I\}$ for $I \subset \{1, \dots, n\}$.
- each of the bags has a label \mathbf{Y}_I .
- if $\mathbf{Y}_I = -1$, all patterns in the particular bag have -1 .

$$\sum_{i \in I} \frac{y_i + 1}{2} = 0$$

- if $\mathbf{Y}_I = 1$, **at least** one pattern in the particular bag has 1.

$$\sum_{i \in I} \frac{y_i + 1}{2} \leq 1$$

Multiple Instance Learning (MIL)

Some application areas:

- drug design: molecule conformations
- image retrieval
- information retrieval from documents

Multiple Instance Learning (MIL)

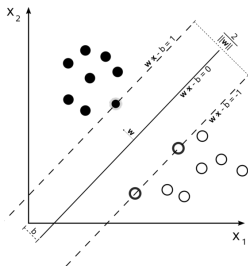
Some application areas:

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The authors introduced two MIL formulations:

- Maximum Pattern Margin Formulation (mi-SVM)
- Maximum Bag Margin Formulation (MI-SVM)

Support-Vector-Machine (SVM)



SVM with ℓ^2 -regularizer and hinge loss:

$$\min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i$$

$$\text{s.t. } \forall i : y_i(\langle \mathbf{w}, \mathbf{x} \rangle + b) \geq 1 - \xi_i, \xi_i \geq 0, y_i \in \{-1, 1\}$$

Maximum Pattern Margin Formulation (mi-SVM)

We look for a discriminant, where:

- all patterns from negative bags are on the negative halfspace.
- at least one pattern from every positive bag is on the positive halfspace.
- maximized the margin with respect to the entire set with some patterns from every positive bag turning to negative.

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$$\min_{y_i} \min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i$$

s.t. $\forall i : y_i(\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1 - \xi_i$, $\xi_i \geq 0$, $y_i \in \{-1, 1\}$, and the conditions for MIL hold.

Maximum Pattern Margin Formulation (mi-SVM)

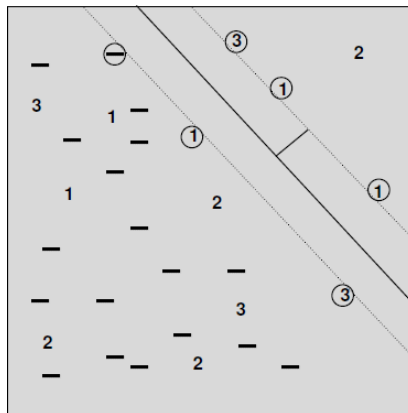


Figure: '-': patterns from negative bags. 'i': patterns from the i-th bag, which is positive.

Maximum Bag Margin Formulation (MI-SVM)

We look for a discriminant, where:

- all patterns from negative bags are on the negative halfspace.
- for positive bag, only the pattern with the largest margin has an impact on training. Rest is ignored.
- maximized the bag margin instead of pattern margin.

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$$\min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_I \xi_I$$

$$\text{s.t. } \forall I : Y_I \max_{i \in I} (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1 - \xi_I, \xi_I \geq 0$$

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- all patterns from negative bags are on the negative halfspace.
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- maximized the bag margin instead of pattern margin.

$$\min_s \min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_I \xi_I$$

$$\text{s.t. } \forall I \quad \begin{array}{ll} Y_I = -1 & \bigwedge \quad -\langle \mathbf{w}, \mathbf{x}_i \rangle - b \geq 1 - \xi_I, \\ Y_I = 1 & \bigwedge \quad \langle \mathbf{w}, \mathbf{x}_{s(I)} \rangle + b \geq 1 - \xi_I, \end{array} \quad \begin{array}{l} \forall i \in I \text{ and } \xi_I \geq 0 \\ \text{and } \xi_I \geq 0 \end{array}$$

Maximum Bag Margin Formulation (MI-SVM)

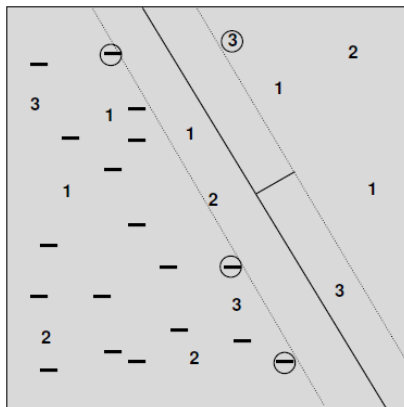


Figure: '-': patterns from negative bags. 'i': patterns from the i-th bag, which is positive.

Optimization Heuristics

For mi-SVM:

$$\min_{y_i} \min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i$$

s.t. $\forall i : y_i(\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1 - \xi_i$, $\xi_i \geq 0$, $y_i \in \{-1, 1\}$, and the conditions for MIL hold.

```

initialize  $y_i = Y_I$  for  $i \in I$ 
REPEAT
  compute SVM solution  $\mathbf{w}, b$  for data set with imputed labels
  compute outputs  $f_i = \langle \mathbf{w}, \mathbf{x}_i \rangle + b$  for all  $\mathbf{x}_i$  in positive bags
  set  $y_i = \text{sgn}(f_i)$  for every  $i \in I$ ,  $Y_I = 1$ 
  FOR (every positive bag  $B_I$ )
    IF  $(\sum_{i \in I} (1 + y_i)/2 == 0)$ 
      compute  $i^* = \arg \max_{i \in I} f_i$ 
      set  $y_{i^*} = 1$ 
    END
  END
  WHILE (imputed labels have changed)
  OUTPUT  $(\mathbf{w}, b)$ 

```


Optimization Heuristics

For MI-SVM:

$$\min_s \min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_I \xi_I$$

$$\text{s.t. } \forall I \quad \begin{array}{ll} Y_I = -1 & \bigwedge \quad -\langle \mathbf{w}, \mathbf{x}_i \rangle - b \geq 1 - \xi_I, \\ Y_I = 1 & \bigwedge \quad \langle \mathbf{w}, \mathbf{x}_{s(I)} \rangle + b \geq 1 - \xi_I, \end{array} \quad \begin{array}{l} \forall i \in I \text{ and } \xi_I \geq 0 \\ \text{and } \xi_I \geq 0 \end{array}$$

```

initialize  $\mathbf{x}_I = \sum_{i \in I} \mathbf{x}_i / |I|$  for every positive bag  $B_I$ 
REPEAT
  compute QP solution  $\mathbf{w}, b$  for data set with
    positive examples  $\{\mathbf{x}_I : Y_I = 1\}$ 
  compute outputs  $f_i = \langle \mathbf{w}, \mathbf{x}_i \rangle + b$  for all  $\mathbf{x}_i$  in positive bags
  set  $\mathbf{x}_I = \mathbf{x}_{s(I)}$ ,  $s(I) = \arg \max_{i \in I} f_i$  for every  $I$ ,  $Y_I = 1$ 
WHILE (selector variables  $s(I)$  have changed)
OUTPUT  $(\mathbf{w}, b)$ 

```

To take home

- the multiple-instance-learning model
- the ideas behind the mi-SVM and MI-SVM formulation
- optimization heuristics towards mi-SVM and MI-SVM

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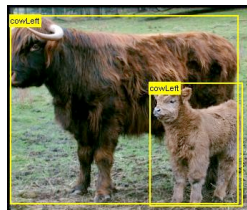
Oh God, this presentation is toooo short!!!

Felzenszwalb et al. [CVPR08]

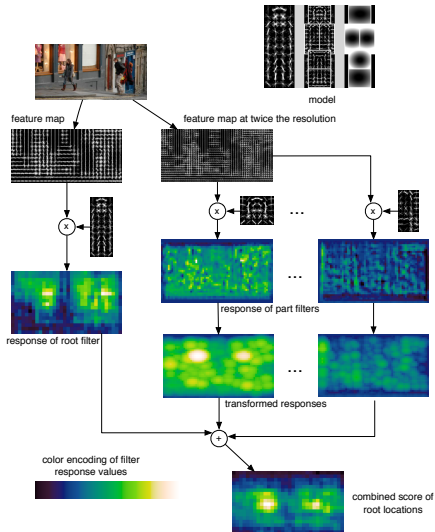
A Discriminatively Trained, Multiscale, Deformable Part Model

(images are taken from Felzenszwalb et al.'s slides)

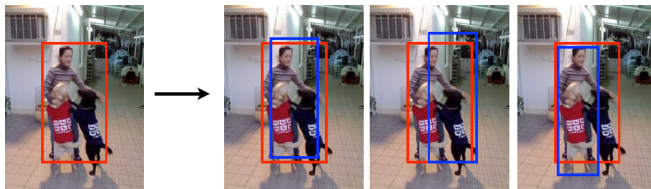
- PASCAL Challenge (object detection)
- objects are provided with labeled bounding boxes
- won the PASCAL VOC "Lifetime Achievement" prize



Felzenszwalb et al. [CVPR08]



Felzenszwalb et al. [CVPR08]



Training algorithm (where MIL comes into play):

- root filter initialization
- root filter update (in a MIL fashion)
- part initialization
- model update (in a MIL fashion)

Babenko et al. [CVPR09]

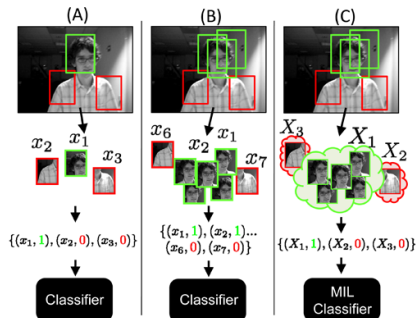
Visual Tracking with Online Multiple Instance Learning

- tracking by detection
- discriminative classifier in an online manner to separate the object from the background
- MIL involved in the training

Babenko et al. [CVPR09]

Visual Tracking with Online Multiple Instance Learning

(image is taken from Babenko et al.'s project page)



Nguyen et al. [ICCV09]

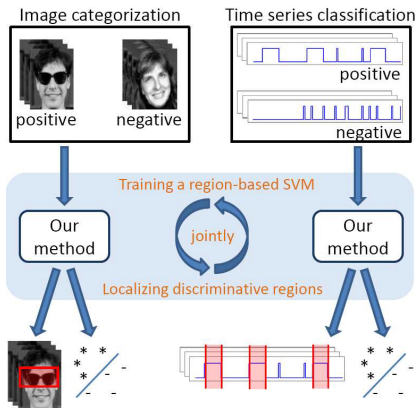
Weakly supervised discriminative localization and classification: a joint learning process

- localization-classification SVM
- training set consists of weakly supervised images with only labels given
- subwindows of each image correspond to patterns with images being the bags
- algorithm tries to jointly segment and classify the images
- Lampert, Blaschko and Hofmann [ECCV2008] have made this method computationally possible

Nguyen et al. [ICCV09]

Weakly supervised discriminative localization and classification: a joint learning process

(image is taken from Nguyen et al.'s paper)



Conclusion continued

We have seen:

- high applicability of MIL in many computer vision areas, e.g. detection, tracking and segmentation
- hot topic in the recent years
- besides MI-SVM, MIL can be also applied to boosting, e.g. Galleguillos et al. [ECCV08] and Viola et al. [NIPS07]