Problem 1. Consider $V=\mathbb{C}$, the complex numbers, as a \mathbb{C} -vector space. Define a function $\Re:\mathbb{C}\to\mathbb{C}$ by

$$\Re(x+iy) = x$$

Is \Re a linear map? If so, prove it. If not, explain why not.

No it is not

Proof. No as it does not satisfy homogeneity. Consider $(1+i) \cdot \Re(1+i) = 1+i$ but $\Re((1+i) \cdot (1+i)) = \Re(2i) = 0$ so it does not satisfy homogeneity.

Problem 2. Extending a linear map. Let V be a finite-dimensional \mathbb{K} -vector space, W a \mathbb{K} -vector space, and U as U as U as U as U be a finite-dimensional U as U as

$$\{\mathbf{u_1}, \dots, \mathbf{u_m}\}$$
 be a basis for U and $\{\mathbf{u_1}, \dots, \mathbf{u_m}, \mathbf{v_{m+1}}, \dots, \mathbf{v_n}\}$ be the (extended) basis for V .

Taking $T:U\to W$ to be any linear map, define a function $f:V\to W$ by

$$f(a_1\mathbf{u_1} + \dots + a_m\mathbf{u_m} + a_{m+1}\mathbf{v_{m+1}} + \dots + a_n\mathbf{v_n}) = T(a_1\mathbf{u_1} + \dots + a_m\mathbf{u_m}).$$

- (a) Is f a linear map? If so, prove it. If not, explain why not.
- (b) What happens if the definition of f is changed to the following?

$$f(\mathbf{x}) = \begin{cases} T(\mathbf{x}) & \text{if } \mathbf{x} \in U \\ \mathbf{0} & \text{otherwise} \end{cases}$$

- (a) Proof. Let $\lambda \in \mathbb{K}$ and $a_1\mathbf{u_1} + a_2\mathbf{u_2} + ... + a_m\mathbf{u_m}$
- (b)

Problem 3. Prove that the following is a subspace of $\mathcal{L}(\mathbb{K}^2)$:

$$U = \left\{ f \in \mathcal{L}(\mathbb{K}^2) : \begin{array}{l} a, b, c \in \mathbb{K} \text{ and} \\ f(x, y) = (ax + by, bx + cy) \end{array} \right\}$$

Proof.

Problem 4. For any linear map $T \in \mathcal{L}(V)$, we say that a subspace $U \subseteq V$ is an invariant subspace of T if and only if $T(U) \subset U$.

Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be the linear map given by

$$T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} 7x - 3y + 5z \\ 12x - 4y + 12z \\ -x + y + z \end{bmatrix}.$$

Show that each of the following subspaces of \mathbb{R}^3 are invariant subspaces of T.

$$U_1 = \operatorname{Span}\left(\begin{bmatrix} -2\\ -3\\ 1 \end{bmatrix}\right)$$
 and $U_2 = \operatorname{Span}\left(\begin{bmatrix} -1\\ 0\\ 1 \end{bmatrix}, \begin{bmatrix} 1\\ 2\\ 0 \end{bmatrix}\right)$

Proof.

Problem 5. Let U_1, U_2 be the subspaces from Problem 4. Prove that

$$\mathbb{R}^3 = U_1 \oplus U_2.$$

Proof.