Design (Purpose) GPSAHR Mk.IV (General Purpose Semi-Autonomous Cargo Handling Robot)

13 **Total Volume:** 3,150.00 **Apparent Stats** Volume Left: 2,155.50 158 STR DEX 15 **Total Power:** 1,000.00 INT 9 Power Left: 56.50 **EDU** 4(9) **Total Weight:** 6,339.20 **Chassis Damage Points** Thrust: 9,000.00 Incap 630.00 Manevuer Left: Destroyed 0.42 1,575.00 Mesh Endurance (d): 36 hours ops Fuel (L): **Total Cost:** 895,125.00 Life Span: 55.00 Effective Cost Per Year: 32,550.00 Bank Loan Term: 27.00 Monthly Payment: 66,305.56

URP		Vol (Litres	Power	Wt (kg)	Price (Cr)	Notes
1. Chassis Size: D		3,000.0	<u> </u>	300.0		Chassis Type VIIb
Configuration:	1					Box/ Wedge, Mesh Armour Base
_						
Armour:		0.000.0		200.0	0.000.0	Mesh
		3,000.0	-	300.0	6,000.0	
2. Powerplant System:	9	- 750.0	1,000.0	3,000.0	225,000.0	2MW
Fuel Tank:	ŭ	- 43.2	.,000.0	3.0	,	36 hours ops
		- 793.2	1,000.0		225,000.0	
					·	-
3. Locomotion	D	- 180.0	- 900.0	- 108.0	18,000.0	9,000kg thrust UHVY
4. Appendages Head:		150.0				
Rt Arm:			- 1.0		·	Very Light, +0 STR
Lt Arm:			- 1.0			_Very Light, +0 STR
		150.0	- 32.0	17.0	3,800.0	
5 Sandanant						
5. Equipment			- 4.0	3.0	1 700 0	2 Optical, 2 Audio, 1 Olfactory
Basic Sensor Package Voder			- 2.0		1,200.0	2 Optical, 2 Addio, 1 Ollactory
Radio, Distant Range			- 0.5		•	5km
Visual Spectrum Spotlight			- 1.0		200.0	OKITI
Video Recorder			- 3.0		600.0	
		-	- 10.5		3,775.0	
					·	
<u>URP</u>		<u>CPU</u>	Storage		<u>Price</u>	<u>Notes</u>
6. Software						
Low Autonomous	2	15.0	20.0		·	+2 Dext
Basic Command	2	3.0	5.0		5,000.0	+2 INT
Another Language-1			8.0		600.0	
Prg: Cargo Handling-1	i	18.0	2.0		200.0	
		10.0	35.0		12,800.0	
URP		Vol (Litres	Power	Wt (kg)	Price (Cr)	Notes
7. Brain			, <u></u>	··· (··· <u>s</u>)	<u> (0.)</u>	
8x Synaptic CPU		- 0.8	- 1.0	0.8	400,000.0	8 CPU, +4 INT
10x Parallel CPU		- 5.0	-	1.0	·	10 CPU, +2 INT
Synaptic Storage		- 0.5	-	0.3	·	5 Units, +5 EDU
Standard Storage		- 15.0	-	3.0		_30 Units
		- 21.3	- 1.0	5.1	625,750.0	