

$dk$

$$dk = 2\pi / (b-a)$$

$$2\pi / (N \cdot dx)$$

$k_0$

If no input value given

$$k_0 = -\frac{N \times dk}{2}$$

$$= -\frac{N}{2} \times \frac{2\pi}{N \cdot dx}$$

$$= \pi / dx$$

$k$

$$k = [k_0, k_0 + dk, k_0 + 2dk, \dots, k_0 + (N-1)dk]$$

$$= [\pi/dx, \pi/dx + \frac{2\pi}{N \cdot dx}, \pi/dx + \frac{4\pi}{N \cdot dx}, \dots, \pi/dx + \frac{(N-1)2\pi}{N \cdot dx}]$$

$\uparrow_{b-a}$

$\Psi$

$\psi_x$

$$\text{initialization } \psi_x = \psi_{x0}$$

$$\psi_x = \left[ e^{i k_0 x} \times \frac{(2\pi)^{\frac{1}{2}}}{dx} \right] * -\psi_{\text{discrete}_x}$$

$\uparrow$

$$\psi_x = \left[ e^{i k_0 x} \times \frac{(2\pi)^{\frac{1}{2}}}{dx} \right] * -\psi_{\text{discrete}_x}$$

$$= \frac{(2\pi)^{\frac{1}{2}}}{dx} \left[ e^{ik_0 x[0]} * \hat{\Psi}[0], e^{ik_0 x[1]} * \hat{\Psi}[1], \dots, e^{ik_0 x[N-1]} * \hat{\Psi}[N-1] \right]$$

$\hat{\Psi}$

$\text{psi\_direct\_xL}$

$$\hat{\Psi} = \hat{\Psi} * e^{-i \times k_0 \times x} * \frac{dx}{(2\pi)^{\frac{1}{2}}}.$$

$$= \frac{dx}{(2\pi)^{\frac{1}{2}}} \left[ e^{-ik_0 x[0]} \Psi[0], e^{-ik_0 x[1]} \Psi[1], \dots, e^{ik_0 x[N-1]} \Psi[N-1] \right]$$

$$= [\hat{\Psi}[0], \hat{\Psi}[1], \dots, \hat{\Psi}[N-1]].$$

-get\_dt

Returns -dt.

-set\_dt

Takes an in-value\_dt.

If different from -dt

- Sets -dt = in\_value\_dt

- Sets -x\_evolve\_hbar =  $e^{-\frac{V_x \times -dt \times i}{2 \hbar}}$

$$= \left[ e^{-\frac{V_x[0] \times -dt \times i}{2 \hbar}}, \dots, e^{-\frac{V_x[N-1] \times -dt \times i}{2 \hbar}} \right]$$

$$= \left[ e^{\frac{-V_x[0] dt \times i}{2 \hbar}}, \dots, e^{\frac{-V_x[N-1] dt \times i}{2 \hbar}} \right]$$

$$\bullet \text{set } -\alpha_{\text{evolve}} = e^{-\frac{\hbar \omega_0^2 \times hbar \times dt}{2m}}$$

$$= \left[ e^{-\frac{\hbar \omega_0^2 \times hbar \times dt \times i}{2m}}, \dots, e^{-\frac{\hbar \omega_0^2 \times hbar \times dt \times (N-1)}{2m}} \right]$$

$$= \left[ e^{-\frac{\hbar \omega_0^2 t \times dt \times i}{2m}}, \dots, e^{-\frac{\hbar \omega_0^2 t \times dt \times (N-1)}{2m}} \right]$$

time-step

Signature : time-step (self, dt, Nsteps = 1) ignored for simplicity

$$\text{self. } dt = dt.$$

for  $i = 0, 1, \dots, Nsteps - 1$ :

Step 1  $\hat{\Psi} = \hat{\Psi} * \alpha_{\text{evolve\_half}}$

$$= \hat{\Psi} * e^{-\frac{V_{xc} \times dt \times i}{2hbar}}$$

$$= \left[ \hat{\Psi}[0] * e^{-\frac{V_{xc}[0] \times dt \times i}{2hbar}}, \dots, \hat{\Psi}[N-1] * e^{-\frac{V_{xc}[N-1] \times dt \times i}{2hbar}} \right]$$

$$= \left[ \hat{\Psi}[0] e^{-\frac{V_{xc}[0] dt \times i}{2\hbar}}, \dots, \hat{\Psi}[N-1] e^{-\frac{V_{xc}[N-1] dt \times i}{2\hbar}} \right]$$

$\hat{k}$

psi-discrete\_h

Step 2  $\text{psi\_discrete\_h} = \text{fft}(\hat{\Psi})$ .

i.e.  $\hat{k} = \text{fft}(\hat{\Psi})$ .

Step 3

$$\hat{h} = \hat{h} * h\text{-evolve}$$

$$= \left[ \hat{h}[0] * e^{-\frac{k[0]^2 \hbar dt i}{2m}}, \dots, \hat{h}[N-1] * e^{-\frac{k[N-1]^2 \hbar dt i}{2m}} \right]$$

Step 4

$$\hat{\Psi} = \text{Ifft}(\hat{h})$$

Step 5

$$\hat{\Psi} = \hat{\Psi} * x\text{-evolve-half}$$

$$= \left[ \hat{\Psi}[0] e^{-\frac{V_x[0] dt i}{2\hbar}}, \dots, \hat{\Psi}[N-1] e^{-\frac{V_x[N-1] dt i}{2\hbar}} \right]$$

$$t = t + \text{Ntsteps} \times dt -$$

$$\text{soft.t} = \text{soft.t} + \text{Ntsteps} \times \text{soft.dt}$$

$$\text{gauss\_x}(\alpha, a, x_0, k_0)$$

Returns:  $(a * \pi^{\frac{1}{2}})^{-\frac{1}{2}} * e^{-\left(\frac{x-x_0}{a}\right)^2 + k_0 * x^i}$

$$= (a * \pi^{\frac{1}{2}})^{-\frac{1}{2}} \left[ e^{-\left(\frac{x[0]-x_0}{a}\right)^2 + k_0 * x[0]i}, \dots, e^{-\left(\frac{x[N-1]-x_0}{a}\right)^2 + k_0 * x[N-1]i} \right]$$

Variables