

# Auto Segmentation

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## Background

- ▶ used U.S. car market generates over \$100 billion annually and is quickly growing
- ▶ used car matching process is inefficient because selective online searches require car attributes to be manually labeled (e.g. color)

## Goal

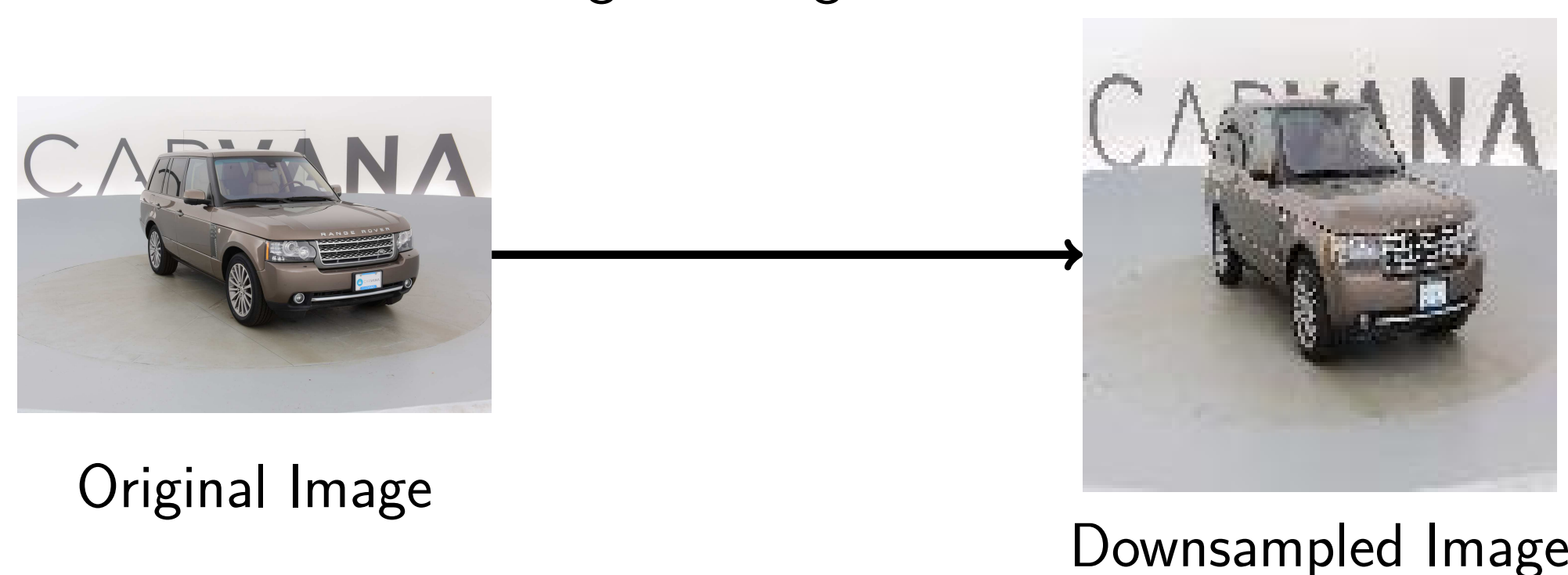
- ▶ reduce inefficiency present in the process of searching in the online used car market, improve user experience
- ▶ develop method to isolate an image of a car from its surrounding background
- ▶ train model to cluster groups of cars based off certain features (e.g. color) to expedite the used car searching process

## Issues and Where We'd Like To Go

- ▶ would purchase extra compute power so that we could maintain image quality of the cars
  - ▷ couldn't do that for this project because of limited computing power and financial resources
  - ▷ instead downsampled from the images (more information below)
- ▶ would extend the clustering algorithm to instead be a recommendation system
  - ▷ couldn't do that for this project due to the inavailability of user-preference data

## Data Downsampling

- ▶ we were limited by memory and computing power
- ▶ to remedy these issues, we downsampled all the input images and labels from 1918x1280 to 128x128 using Pillow's default image resizing



## UNet

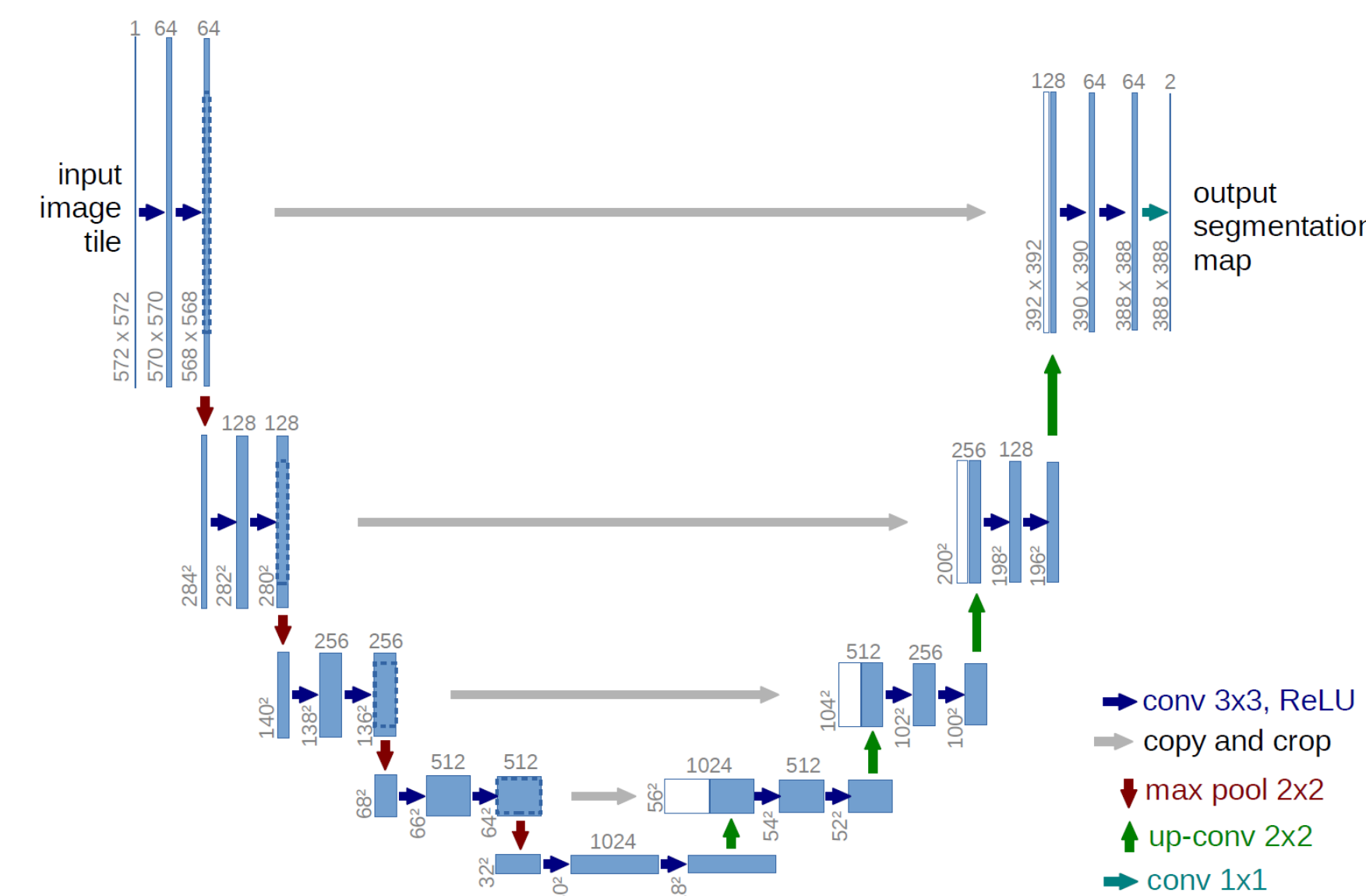


Figure: UNet Architecture

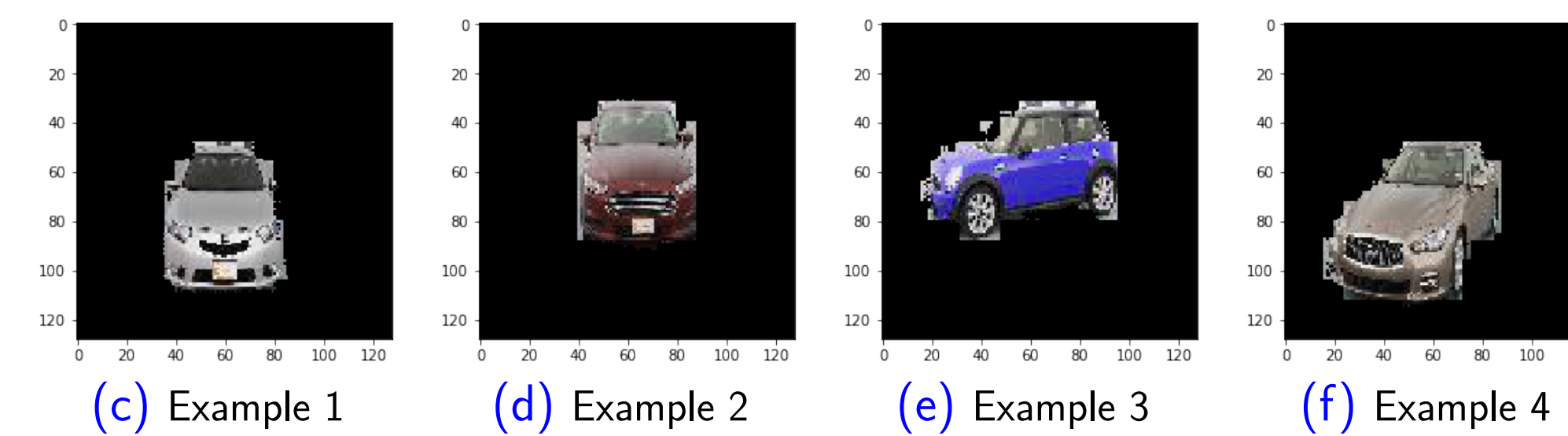
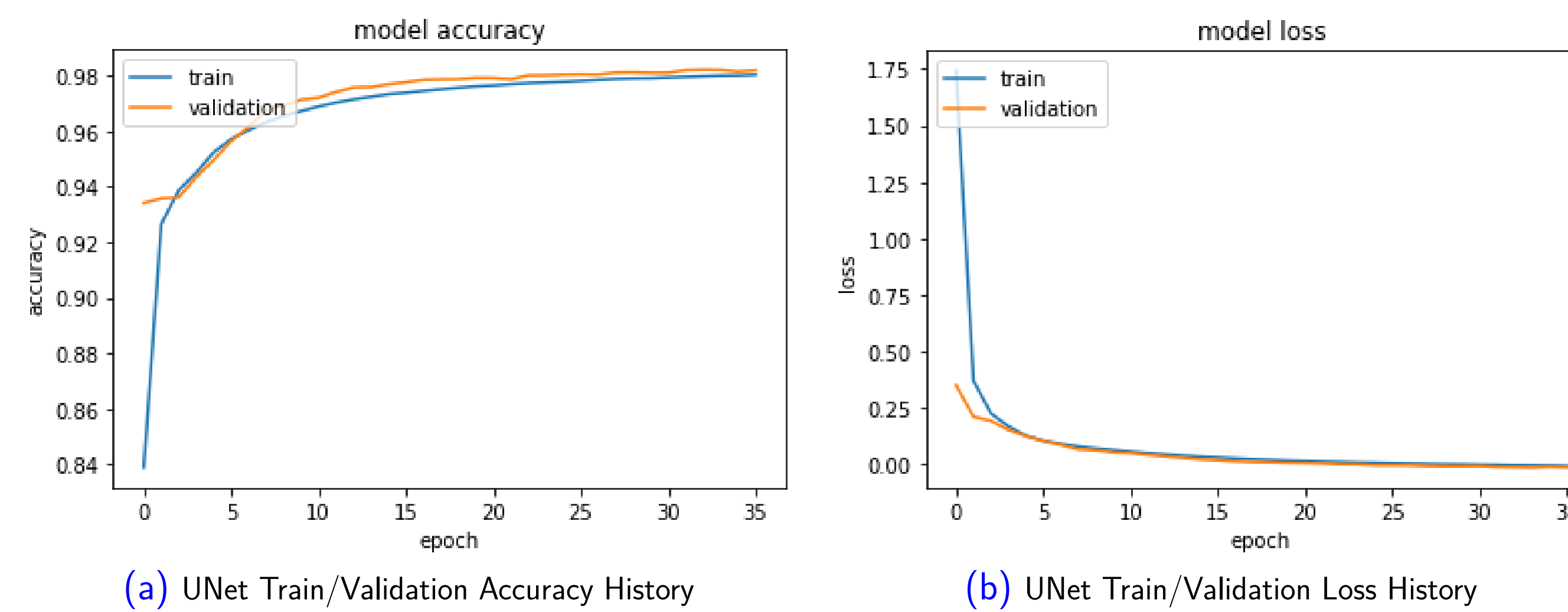


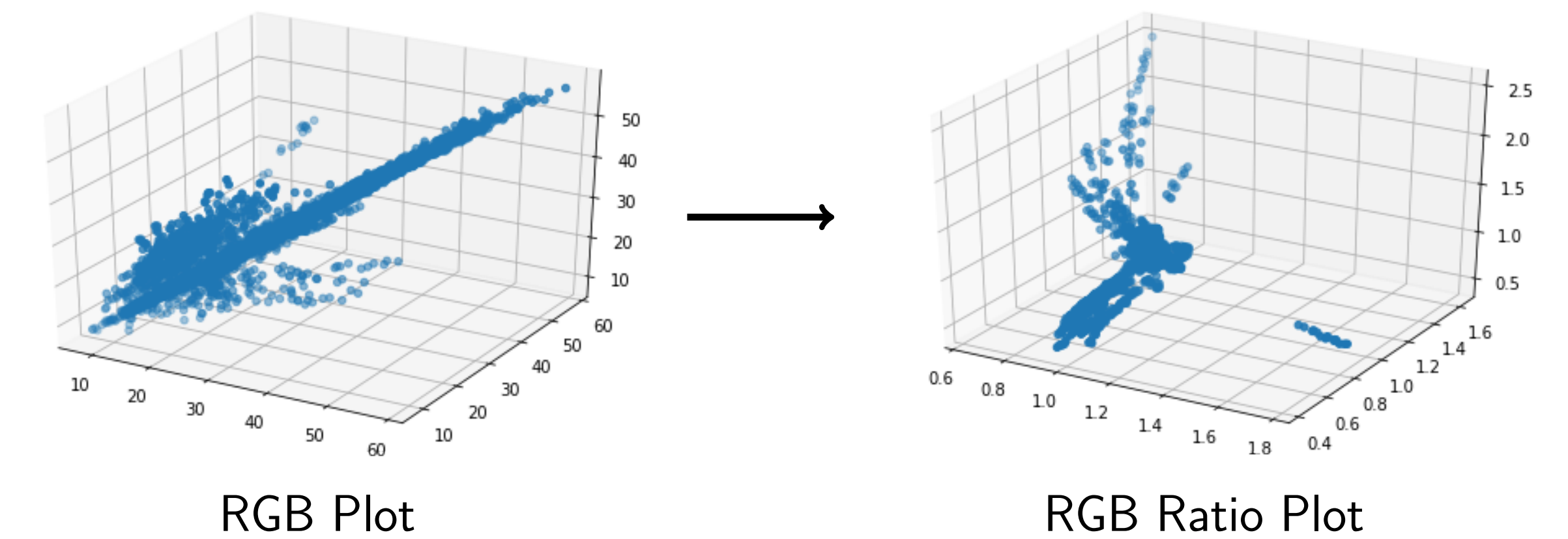
Figure: UNet Output Examples

## UNet Modifications

- ▶ added Early Stopping callback with patience of 3
- ▶ added 9 dropout layers with hyperparameter of .5 (per suggestion of Geoff Hinton) to reduce overfitting
  - ▷ Train F1: 0.966
  - ▷ Test F1: 0.966
- ▶ added batch normalization to all 2D convolution blocks to unify feature scales
  - ▷ training F1
    - ▶ without batch normalization: 0.876
    - ▶ with batch normalization: 0.966
  - ▷ testing F1
    - ▶ without batch normalization: 0.831
    - ▶ with batch normalization: 0.966

## Example Clustering Method: Automobile Color

- ▶ Goal: cluster automobiles based on RGB values. Used car sites provide search narrowing through color selection, so we would like to provide a service that autonomously identifies the color of the car
- ▶ Issue: RGB values are distributed in lines radiating from the origin
- ▶ Solution: Cluster based off of RGB ratios



## Clustering Approach

- ▶ we used DBSCAN on the RGB ratios
  - ▷ we wanted the algorithm to be able to select the number of colors because we were unsure of how many colors there were in the dataset
  - ▷ we wanted the algorithm to be able to identify when a data point is noise to alert the user that they must label the color of the car because the algorithm is unsure
- ▶ Number of Clusters: 12
- ▶ Number of Noise Points: 699 out of 5088

## Clustering Examples

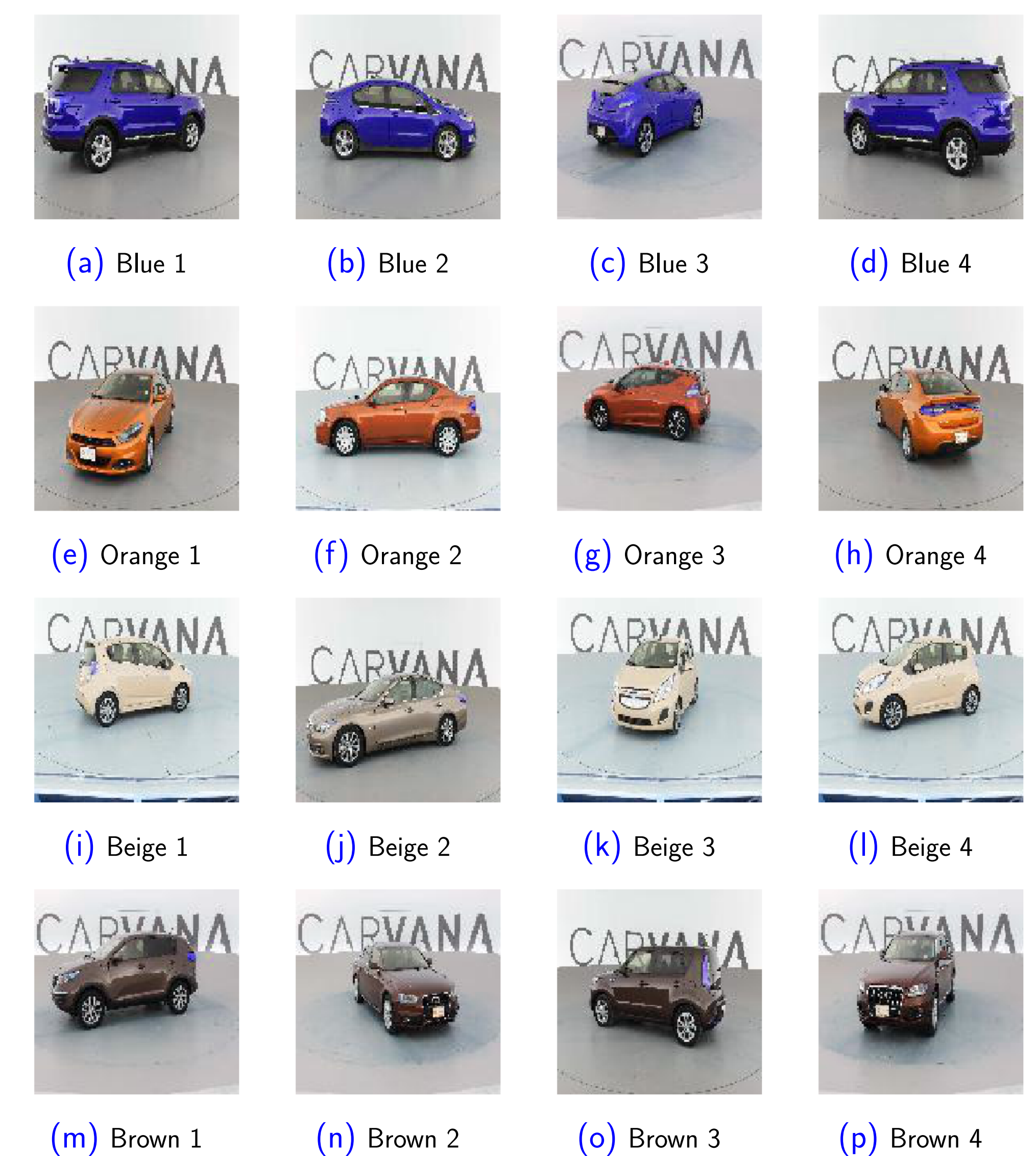


Figure: Example Color Clusters. Each row corresponds to a cluster