# Auto Segmentation

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#### Background

- ► used U.S. car market generates over \$100 billion annually and is quickly growing
- used car matching process is inefficient because selective online searches require car attributes to be manually labeled (e.g. color)

#### Goal

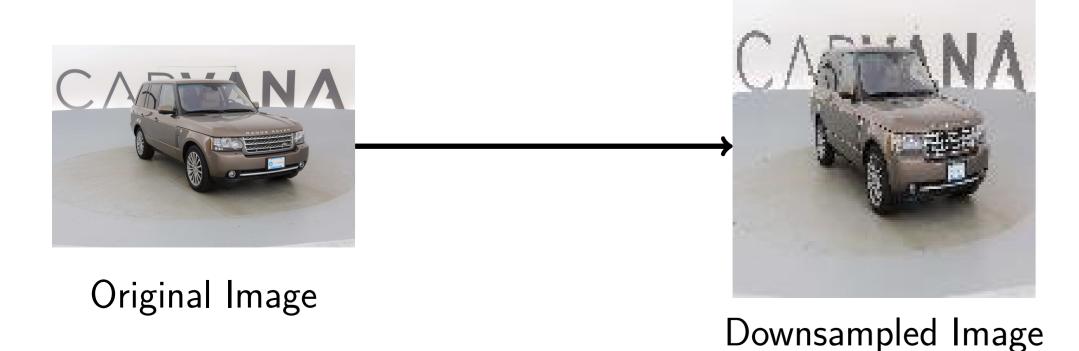
- reduce inefficiency present in the process of searching in the online used car market, improve user experience
- develop method to isolate an image of a car from its surrounding background
- ➤ train model to cluster groups of cars based off certain features (e.g. color) to expedite the used car searching process

#### Issues and Where We'd Like To Go

- would purchase extra compute power so that we could maintain image quality of the cars
- □ couldn't do that for this project because of limited computing power and financial resources
- ▷ instead downsampled from the images (more information below)
- would extend the clustering algorithm to instead be a recommendation system
- ▷ couldn't do that for this project due to the inavailability of user-preference data

#### **Data Downsampling**

- ▶ we were limited by memory and computing power
- ➤ to remedy these issues, we downsampled all the input images and labels from 1918x1280 to 128x128 using Pillow's default image resizing



#### **UNet**

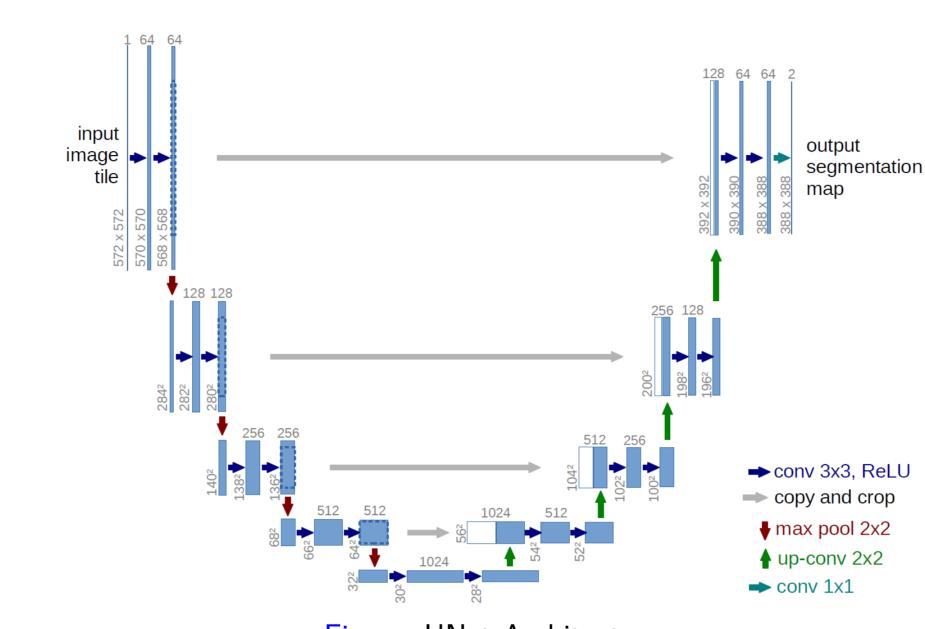
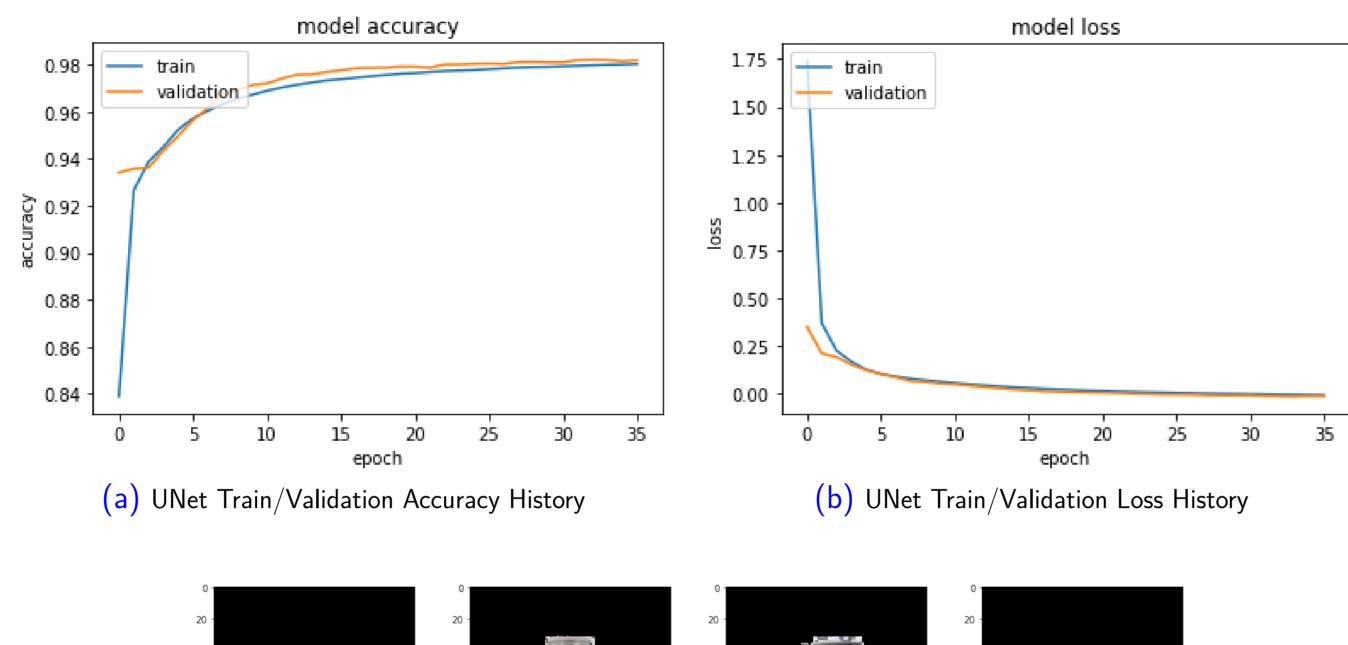
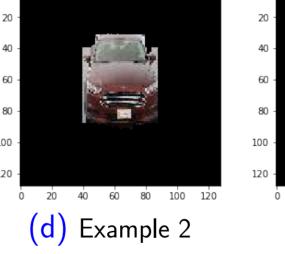
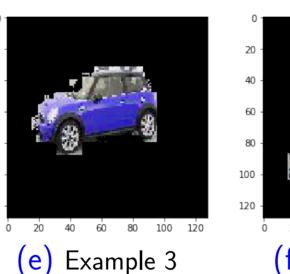


Figure: UNet Architecture



20 -40 -80 -100 -120 -(C) Example 1





20 -40 -80 -100 -120 -0 20 40 60 80 100 (f) Example 4

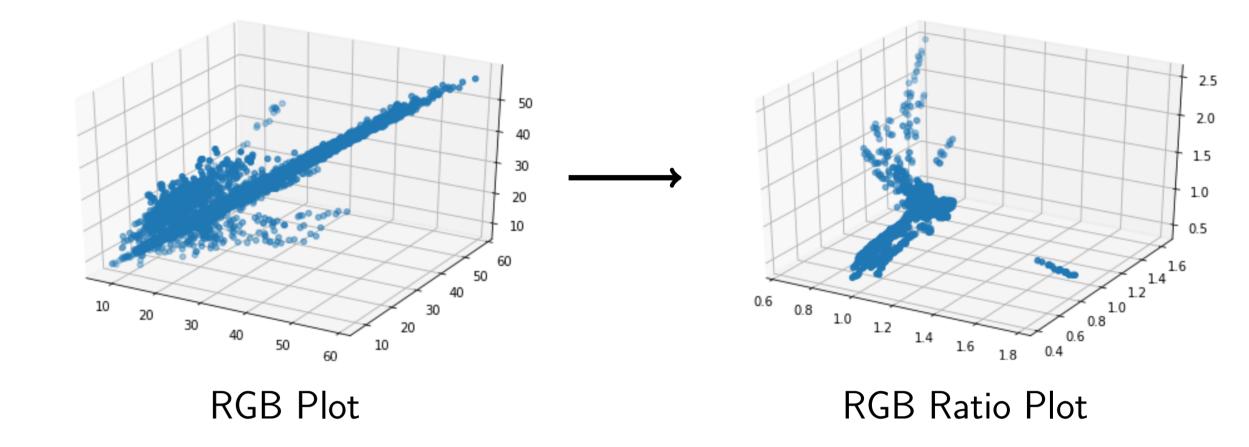
Figure: UNet Output Examples

## **UNet Modifications**

- ► added Early Stopping callback with patience of 3
- ► added 9 dropout layers with hyperparameter of .5 (per suggestion of Geoff Hinton) to reduce overfitting
  - ▶ Train F1: 0.966
- ▶ Test F1: 0.966
- ▶ added batch normalization to all 2D convolution blocks to unify feature scales
  - ▶ training F1
  - without batch normalization: 0.876
    with batch noramlization: 0.966
  - ▶ testing F1
  - without batch normalization: 0.831with batch noramlization: 0.966

# **Example Clustering Method: Automobile Color**

- ➤ Goal: cluster automobiles based on RGB values. Used car sites provide search narrowing through color selection, so we would like to provide a serivce that autonomously identifies the color of the car
- ► Issue: RGB values are distributed in lines radiating from the origin
- ► Solution: Cluster based off of RGB ratios



#### **Clustering Approach**

- ▶ we used DBSCAN on the RGB ratios
- ▶ we wanted the algorithm to be able to select the number of colors because we were unsure of how many colors there were in the dataset
- ▶ we wanted to the algorithm to be able to identify when a data point is noise to alert the user that they must label the color of the car because the algorithm is unsure
- ► Number of Clusters: 12
- ► Number of Noise Points: 699 out of 5088

### **Clustering Examples**

