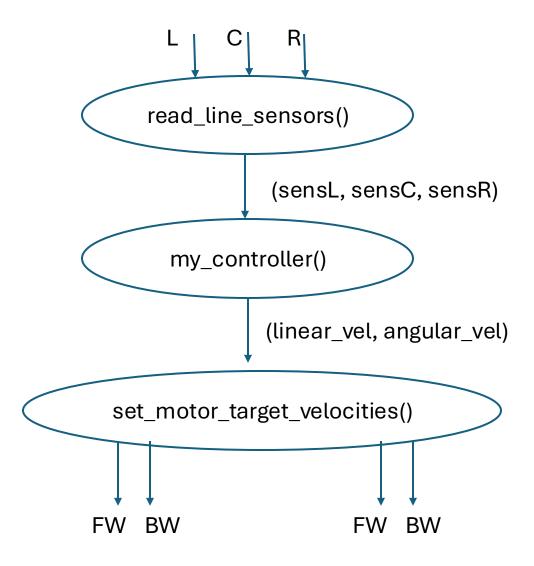
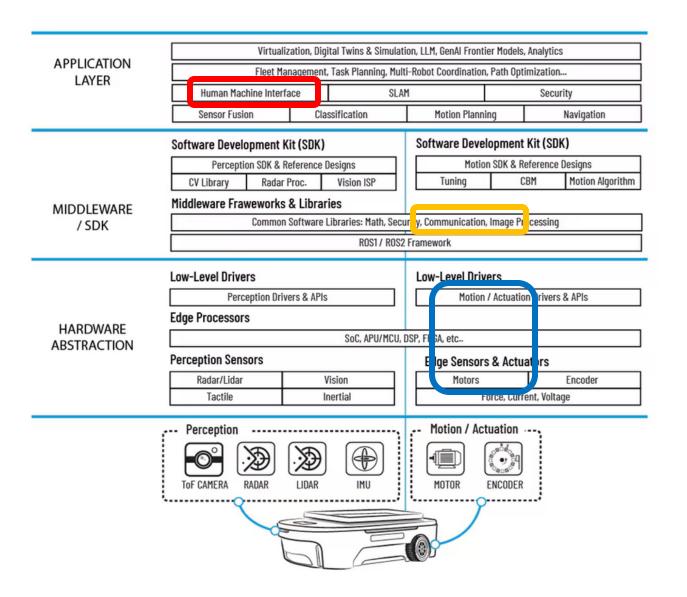
TurtleBot: Configuración básica

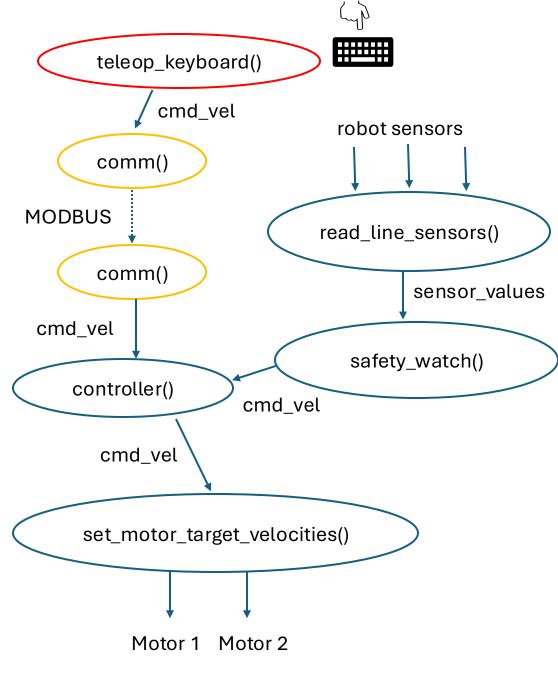
Sensores de línea **BUZZER** ESP32 FW BW FW BW Motor L Motor R Motores con inversor de giro

TurtleBot-base: Arquitectura de código (SPA)



TurtleBot-teleop: Arquitectura de software





TurtleBot-teleop: Arquitectura de software

