

Lorentz Force Simulator

Chares Moustakas

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1 Introduction

The current software is attempting to simulate the behaviour of a particle near a finite long charged wire. It is important to underline that the aforementioned software is just a fun, non-optimized project and as a consequence the reader can feel free to use, modify, improve and play with it. It is notable to mention that this software was developed in C++ using relatively low level APIs and Libraries such as modern OpenGL, custom fragment-vertex shaders through GLSL, Dear ImGui and CMake, while all the Objects-meshes were constructed through Blender. I would also like to thank <http://www.opengl-tutorial.org/> for their great explanations.

2 Mathematics

The concept of this simulation is to calculate the Lorentz Force that the wire exerts to the spherical particle, using primarily the current that flows through the wire as a datum. To begin with, it is crucial to visualize from the Mathematical perspective the goal, being said that the formula for the previous calculation is:

$$\vec{F}_L = q(\vec{E} + \vec{u} \times \vec{B})$$

Where q is Coulomb charge of the particle, \mathbf{E} the electric field, \mathbf{u} particle's velocity and \mathbf{B} the magnetic's field flux density.

2.1 **B** calculation

The calculation of **B** is based on Ampere's formula:

$$\oint_C \vec{B} d\vec{l} = \mu I$$

Due to **B** and **dl** parallelism, the equation above is tranformed as:

$$|\vec{B}| \oint_C dl = \mu I$$

$$|\vec{B}| 2\pi r = \mu I$$

$$|\vec{B}| = \frac{\mu I}{2\pi r}$$

$$\vec{B} = \frac{\mu I}{2\pi r} \hat{\phi} \quad (1)$$

Cylindrical Coordinates:

$$\hat{\phi} = -\frac{z}{r} \hat{x} + \frac{x}{r} \hat{z}$$

It is notable that the direction of **B** is tangent to the closed circle-loop C. Consequently **B** calculation is possible if the position of the particle and the current are known magnitudes.

2.2 **E** calculation

Regarding Electric field calculation, patience is the key... So lets construct the main acceptance, first of all lets assume that the wire has **L** length. An infinitesimal charged part of the wire **dq** that is **y** units away from the end of the cable causes Electric field **dE** for a random point P that it is **r** units away from the wire:

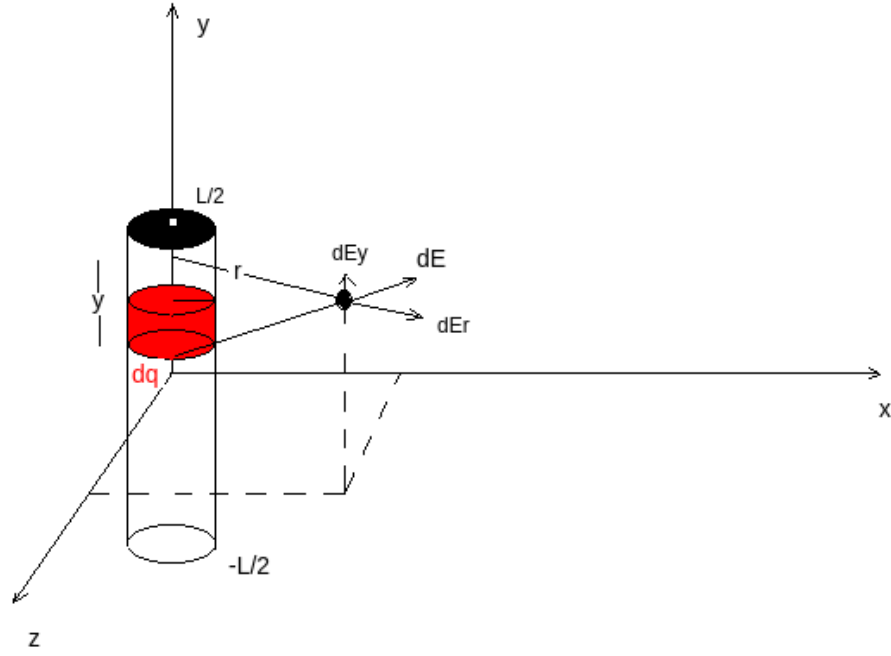


Figure 1: Calculation of Electric field

$$\frac{dq}{dy} = \frac{Q}{L}$$

$$dq = \frac{Q}{L} dy$$

$$\vec{dE} = dE_y \sin\theta \hat{y} + dE_r \cos\theta \hat{r} \quad (2)$$

$$\sin\theta = \frac{y}{\sqrt{y^2 + r^2}}, \cos\theta = \frac{r}{\sqrt{y^2 + r^2}} \quad (3)$$

$$dE = k \frac{dq}{y^2 + r^2}$$

Based on the above:

$$dE_y = k \frac{Q}{L} \frac{y}{\sqrt{(y^2 + r^2)^3}} dy$$

$$\int_0^{E_y} dE_y = k \frac{Q}{L} \int_{-L/2}^{L/2} \frac{y}{\sqrt{(y^2 + r^2)^3}} dy = k \frac{Q}{L} \left(-\frac{1}{\sqrt{(r^2 + \frac{L^2}{4})}} + \frac{1}{\sqrt{(r^2 + \frac{L^2}{4})}} \right)$$

$$E_y = 0$$

The only non zero coordinate is the coordinate of \mathbf{r} unit vector, based on the (1) ! Lets calculate the r coordinate.

$$dE_r = k \frac{Q}{L} \frac{r}{\sqrt{(y^2 + r^2)^3}} dy$$

$$\int_0^{E_r} dE_r = k \frac{Q}{L} \int_{-L/2}^{L/2} \frac{r}{\sqrt{(y^2 + r^2)^3}} dy = k \frac{Q}{L} \left(\frac{L/2}{r \sqrt{(r^2 + \frac{L^2}{4})}} + \frac{L/2}{r \sqrt{(r^2 + \frac{L^2}{4})}} \right)$$

$$E_r = k \frac{Q}{r \sqrt{r^2 + \frac{L^2}{4}}}$$

Consequently, the expression (1) can be written as:

$$\vec{E} = k \frac{Q}{r \sqrt{r^2 + \frac{L^2}{4}}} \hat{r} \quad (4)$$

Cylindrical coordinates:

$$\hat{r} = \frac{x}{r} \hat{x} + \frac{z}{r} \hat{z}$$

It is crucial to keep in mind that the Coulomb charge \mathbf{Q} is not constant in time, therefore on each OpenGL iteration the expression (1) and (4), concerning the Electric field and Magnetic flux density calculation, is taken into account:

$$I = \frac{dQ}{dt}$$

2.3 Force Calculation

As a result of the above, for known initial velocity it is possible to calculate the Lorentz force for the \mathbf{q} particle. Consequently, on each OpenGL iteration it is critical to calculate classic motion differential equations for the velocity. So, for the aforementioned known force for a specific timestamp in the timeline $\mathbf{t}=\mathbf{t}_i$:

$$\vec{F}_{Li} = m \vec{a}_i$$

$$\vec{F}_{Li} = m \frac{d\vec{u}_i}{dt}$$

$$\vec{F}_{Li} \approx m \frac{\Delta \vec{u}_i}{\Delta t}$$

$$\vec{u}_i \approx \frac{\Delta t}{m} \vec{F}_{Li} + \vec{u}_{i-1}$$

Therefore, in order for the inductive calculation above to be successful, knowledge of the initial velocity is a capable and necessary condition.