

Classical p -brane

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1 Point particle: 0-brane

1.1 Linear action

$$S_1[x^M] := -m \int_{\gamma} ds = -m \int_{\gamma} d\lambda \sqrt{-g_{MN} \dot{x}^M \dot{x}^N}. \quad (1)$$

1.2 Quadratic action

$$S_2[e, x^M] := \frac{1}{2} \int_{\gamma} d\lambda e (e^{-2} g_{MN} \dot{x}^M \dot{x}^N - m^2). \quad (2)$$

2 Classical bosonic string: 1-brane

[5] contains a

2.1 Nambu–Goto action

The action reads [6, 4]

$$S_{\text{NG}}[X^M] := -T \int_{\Sigma} dA = -T \int_{\Sigma} d^2\sigma \sqrt{-\tilde{\psi}}, \quad (3)$$

where

$$\tilde{\psi} := \det \psi_{\alpha\beta} \equiv \psi_{11}\psi_{22} - \psi_{12}\psi_{21} \quad (4)$$

is the metric determinant, $\alpha, \beta, \dots = 1, 2$ are the world-sheet indices, (Σ^α) are the world-sheet coordinates,

$$\psi_{\alpha\beta} := g_{MN} X^M_{,\alpha} X^N_{,\beta}, \quad (5)$$

is the induced metric on the world-sheet, $P, N, \dots = 0, 1, \dots, d$ are the target-space indices, $X^M = X^M(\Sigma^\alpha)$ are the world-sheet [8] coordinates. The immersion map $X^M(\sigma^\alpha)$ are the dynamical variables.

The inverse metric can also be expressed in a closed form

$$\begin{aligned}\psi^{\alpha\beta} &= \frac{1}{(2-1)!} \tilde{\epsilon}^{\alpha\gamma} \tilde{\epsilon}^{\beta\delta} \tilde{\psi}^{-1} \psi_{\gamma\delta} \\ &= \tilde{\epsilon}^{\alpha\gamma} \tilde{\epsilon}^{\beta\delta} \tilde{\psi}^{-1} \psi_{\gamma\delta} = \epsilon^{\alpha\gamma} \epsilon^{\beta\delta} \psi_{\gamma\delta}\end{aligned}\tag{6}$$

$$= \tilde{\epsilon}^{\alpha\gamma} \tilde{\epsilon}^{\beta\delta} \tilde{\psi}^{-1} g_{P\Sigma} X^P{}_{,\gamma} X^\Sigma{}_{,\delta} = \epsilon^{\alpha\gamma} \epsilon^{\beta\delta} g_{P\Sigma} X^P{}_{,\gamma} X^\Sigma{}_{,\delta}\tag{7}$$

$$\equiv \frac{1}{\tilde{\psi}} \begin{pmatrix} \psi_{22} & -\psi_{12} \\ -\psi_{21} & \psi_{11} \end{pmatrix}^{\alpha\beta}.\tag{8}$$

Unfortunately this is not useful.

Variation of the induced metric determinant can be expressed in terms of that of the induced metric

$$\delta \tilde{\psi} = \tilde{\psi} \psi^{\alpha\beta} \delta \psi_{\alpha\beta}.\tag{9}$$

Variation of the induced metric in terms of the world-sheet coordinates reads

$$\delta \psi_{\alpha\beta} = X^N{}_{,\alpha} (2g_{N\Lambda} \delta X^\Lambda{}_{,\beta} + X^P{}_{,\beta} g_{NP,\Lambda} \delta X^\Lambda).\tag{10}$$

Variation of the area element reads

$$\begin{aligned}\delta \sqrt{-\tilde{\psi}} &= \frac{1}{2} \sqrt{-\tilde{\psi}} \psi^{\alpha\beta} \delta \psi_{\alpha\beta} \\ &= \frac{1}{2} \sqrt{-\tilde{\psi}} \psi^{\alpha\beta} X^N{}_{,\alpha} (2g_{N\Lambda} \delta X^\Lambda{}_{,\beta} + X^P{}_{,\beta} g_{NP,\Lambda} \delta X^\Lambda) \\ &= -\frac{1}{T} \left\{ (\dots)_{\text{NG},\beta}^\beta + \mathcal{L}_{\text{NG},X^\Lambda} \delta X^\Lambda \right\},\end{aligned}\tag{11}$$

where

$$\frac{1}{T} (\dots)_{\text{NG}}^\beta := -\sqrt{-\tilde{\psi}} \psi^{\alpha\beta} X^N{}_{,\alpha} g_{N\Lambda} \delta X^\Lambda,\tag{12}$$

is a boundary term,

$$\begin{aligned}\frac{\mathcal{L}_{\text{NG},X^\Lambda}}{T\sqrt{-\tilde{\psi}}} &= \square_\psi X^M g_{M\Lambda} + \psi^{\alpha\beta} X^N{}_{,\alpha} g_{N\Lambda,P} X^P{}_{,\beta} - \frac{1}{2} \psi^{\alpha\beta} X^N{}_{,\alpha} X^P{}_{,\beta} g_{NP,\Lambda} \\ &= \square X^M g_{M\Lambda} + \frac{1}{2} \psi^{\alpha\beta} X^N{}_{,\alpha} X^P{}_{,\beta} (-g_{NP,\Lambda} + g_{P\Lambda,N} + g_{\Lambda N,P}) \\ &= g_{M\Lambda} (\square_\psi X^M + \Gamma^M{}_{NP} \psi^{\alpha\beta} X^N{}_{,\alpha} X^P{}_{,\beta})\end{aligned}\tag{13}$$

gives the Euler–Lagrange derivative, in which

$$\square_\psi X^M := \frac{1}{\sqrt{-\tilde{\psi}}} \left(\sqrt{-\tilde{\psi}} \psi^{\alpha\beta} X^M{}_{,\alpha} \right)_{,\beta}\tag{14}$$

is a d’Alembertian on the world-sheet with respect to $\psi_{\alpha\beta}$.

2.2 External symmetry

If ξ^M is a Killing vector, one can show

$$\left(\sqrt{-\tilde{\psi}} \psi^{\alpha\beta} X^M{}_{,\alpha} \xi_M \right)_{,\beta} = 0. \quad (15)$$

Geometrically, this corresponds to

$$\text{div } \xi^\top = 0. \quad (16)$$

Since one also has

$$\mathbb{L}_X \omega = (\text{div } X) \omega, \quad (17)$$

where ω is the volume form on Σ , one has

$$\mathbb{L}_{\xi^\top} \omega = 0, \quad (18)$$

i.e. the volume form is invariant under diffeomorphism generated by ξ^\top .

2.3 Polyakov action

The action reads [3, 2, 7]

$$S_P[h_{\alpha\beta}, X^M] = -\frac{T}{2} \int_\Sigma d^2\sigma \sqrt{-\tilde{h}} h^{\alpha\beta} \psi_{\alpha\beta}. \quad (19)$$

Variation of the integrand reads

$$\begin{aligned} \delta \left(\sqrt{-\tilde{h}} h^{\alpha\beta} \psi_{\alpha\beta} \right) &= \delta_h \left(\sqrt{-\tilde{h}} h^{\alpha\beta} \right) \psi_{\alpha\beta} + \left(\sqrt{-\tilde{h}} h^{\alpha\beta} \right) \delta_X \psi_{\alpha\beta} \\ &= -\frac{2}{T} \left\{ (\dots)_{P,\beta}^\beta + \mathcal{L}_{P,h^{\alpha\beta}} \delta h^{\alpha\beta} + \mathcal{L}_{P,X^\Lambda} \delta X^\Lambda \right\}, \end{aligned} \quad (20)$$

where

$$\frac{2}{T} (\dots)_{P,\beta}^\beta := -2 \sqrt{-\tilde{h}} h^{\alpha\beta} X^N{}_{,\alpha} g_{N\Lambda} \delta X^\Lambda, \quad (21)$$

is a boundary term,

$$\frac{2\mathcal{L}_{P,h^{\alpha\beta}}}{T\sqrt{-\tilde{h}}} = \left(\frac{1}{2} h^{\gamma\delta} h_{\alpha\beta} - \delta^\gamma_\alpha \delta^\delta_\beta \right) X^M{}_{,\gamma} X^N{}_{,\delta} g_{MN} \quad (22)$$

gives the Euler–Lagrange derivative with respect to $h^{\alpha\beta}$,

$$\frac{2\mathcal{L}_{P,X^\Lambda}}{T\sqrt{-\tilde{h}}} = 2g_{M\Lambda} (\Box_h X^M + \Gamma^M{}_{NP} X^N{}_{,\alpha} X^P{}_{,\beta} h^{\alpha\beta}) \quad (23)$$

gives the Euler–Lagrange derivative with respect to X^Λ , and

$$\Box_h X^M := \frac{1}{\sqrt{-\tilde{h}}} \left(\sqrt{-\tilde{h}} h^{\alpha\beta} X^M{}_{,\alpha} \right)_{,\beta} \quad (24)$$

is another d’Alembertian on the world-sheet with respect to $h_{\alpha\beta}$.

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[1]

References

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