Tool-kit for the coframe formalism

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1 Introduction

This note is intended to be pragmatic, collecting a set of toolkits for the calculation of field theories without and with gravitation. The physical motivation will be discussed elsewhere.

2 Complex scalar field

The action reads

$$S = \int -\mathbf{d}\phi^* \wedge \star \mathbf{d}\phi - m^2 \phi^* \wedge \star \phi \tag{1}$$

$$= \int -\frac{1}{2} (\mathrm{d} \phi^* \wedge \star \mathrm{d} \phi + \mathrm{d} \phi \wedge \star \mathrm{d} \phi^*) - \frac{1}{2} m^2 (\phi^* \wedge \star \phi + \phi \wedge \star \phi^*) \tag{2}$$

Variation commutes with exterior derivative

$$[\delta, \mathbf{d}]\phi = 0. \tag{3}$$

In the absence of gravitation, variation also commutes with Hodge star. A generic variation of the kinetic terms therefore reads

$$\delta(\mathrm{d}\phi^* \wedge \star \mathrm{d}\phi) = \mathrm{d}(\delta\phi^* \wedge \star \mathrm{d}\phi + \delta\phi \wedge \star \mathrm{d}\phi^*)$$

$$+ \delta\phi^* \wedge \star \mathrm{d}^{\dagger}\mathrm{d}\phi + \delta\phi \wedge \star \mathrm{d}^{\dagger}\mathrm{d}\phi^*.$$

$$(4)$$

where the codifferential is defined in eq. (52). A generic variation of the action reads

$$\delta S = \int d(-\delta\phi^* \wedge \star d\phi - \delta\phi \wedge \star d\phi^*)$$
$$-\delta\phi^* \wedge \star (d^{\dagger}d + m^2)\phi - \delta\phi \wedge \star (d^{\dagger}d + m^2)\phi^*. \tag{5}$$

2.1 U(1) Noether current

The action is invariant

$$\delta_{\lambda} S \equiv 0 \tag{6}$$

under the rigid transformation

$$\phi \to e^{-ie\lambda}\phi$$
, $\phi^* \to e^{+ie\lambda}\phi^*$. (7)

When the equations of motion are satisfied, infinitesimal transformation leads to

$$0 = \int \lambda \, d\mathfrak{J}_0 \,,$$

$$\mathfrak{J}_0 := ie(\phi^* \wedge \star d\phi - \phi \wedge \star d\phi^*) \,, \tag{8}$$

which is the Noether current, a twisted 3-form, satisfying the continuity equation

$$d\mathfrak{J}_0 = 0. (9)$$

2.2 T(D) Noether current

The action is invariant up to a total differential

$$\begin{split} \delta_{\lambda} S &= \int -\lambda \, \mathrm{d}(z \, \lrcorner \, \mathfrak{L}) \\ &= \int \lambda \, \frac{1}{2} \, \mathrm{d} \big\{ +z \, \lrcorner \, \big[\mathrm{d}\phi^* \wedge \star \mathrm{d}\phi + \mathrm{d}\phi \wedge \star \mathrm{d}\phi^* + m^2 (\phi^* \, \star \phi + \phi \, \star \phi^*) \big] \big\} \,, \end{split} \tag{10}$$

under the rigid infinitesimal transformation

$$\delta\phi = -\lambda \,\pounds_z \phi = -\lambda \,z \, \neg \, \mathrm{d}\phi \,, \qquad \delta\phi^* = -\lambda \,\pounds_z \phi^* = -\lambda \,z \, \neg \, \mathrm{d}\phi^* \,. \tag{11}$$

Note the minus sign, which has to do with our mostly-positive metric convention $(-,+,\dots,+)$.

When the equations of motion are satisfied, infinitesimal transformation leads to

$$\delta_{\lambda}S = \int \lambda \, \mathrm{d}\{+(z - \mathrm{d}\phi^*) \wedge \star \mathrm{d}\phi + (z - \mathrm{d}\phi) \wedge \star \mathrm{d}\phi^*\} \,. \tag{12}$$

Taking the difference with eq. (10) and setting $z=e_{\alpha}$ yield

$$0 = \int \lambda \, d\mathfrak{T}_{\alpha},\tag{13}$$

$$\begin{split} 2\mathfrak{T}_{\alpha} &:= +(e_{\alpha} \dashv \mathrm{d}\phi^*) \wedge \star \mathrm{d}\phi + \mathrm{d}\phi^* \wedge (e_{\alpha} \dashv \star \mathrm{d}\phi) \\ &\quad + (e_{\alpha} \dashv \mathrm{d}\phi) \wedge \star \mathrm{d}\phi^* + \mathrm{d}\phi \wedge (e_{\alpha} \dashv \star \mathrm{d}\phi^*) \\ &\quad - m^2 (\phi^* \, e_{\alpha} \dashv \star \phi + \phi \, e_{\alpha} \star \phi^*) \,. \end{split} \tag{14}$$

The continuity equation reads

$$d\mathfrak{T}_{\alpha} = 0. \tag{15}$$

In components,

$$\mathfrak{T}_{\alpha} = + \left[e_{\alpha}(\phi^*) e^{\beta}(\phi) + e_{\alpha}(\phi) e^{\beta}(\phi^*) \right] \epsilon_{\beta} - \left[e^{\beta}(\phi^*) e_{\beta}(\phi^*) + m^2 \phi^* \phi \right] \epsilon_{\alpha} \,. \tag{16}$$

3 Pure electromagnetic field

The action reads

$$S = \int -\frac{1}{2}F \wedge \star F. \tag{17}$$

Variation of the Lagrangian reads

$$\delta(F \wedge \star F) = 2\,\delta F \wedge \star F \tag{18}$$

$$= 2 \operatorname{d}(\delta A \wedge \star F) + 2 \delta A \wedge \operatorname{d} \star F. \tag{19}$$

Note that this is not gauge invariant.

3.1 Lorenz gauge

The Laplace–de Rham operator, or in our Lorentzian metric signature the d'Alembertian

$$\Box^2 \coloneqq \left(\mathbf{d} + \mathbf{d}^\dagger \right)^2 = \mathbf{d} \mathbf{d}^\dagger + \mathbf{d}^\dagger \mathbf{d} \,. \tag{20}$$

$$\mathrm{d} \star F = \mathrm{d} \star \mathrm{d} A = \star (-)^2 \star^{-1} \mathrm{d} \star \mathrm{d} A = \star \mathrm{d}^\dagger \mathrm{d} A = \star (\Box^2 - \mathrm{d} \mathrm{d}^\dagger) A \,. \tag{21}$$

One would like to have $dd^{\dagger}A = 0$, or $d^{\dagger}A = \text{const.}$ This would be fulfilled if

$$d^{\dagger}A = 0, \qquad (22)$$

which is the Lorenz gauge [2, 3, 6].

3.2 T(D) Noether current

The action is invariant up to a total differential

$$\delta_{\lambda}S = -\int \lambda \,\mathrm{d}(z \, \mathop{\neg} \mathfrak{L}) = \int \lambda \, \frac{1}{2} \,\mathrm{d}\{+z \, \mathop{\neg} (F \wedge \star F)\}\,, \tag{23}$$

under the rigid infinitesimal transformation combined with a gauge transformation [8, eq. 3.46]

$$\delta A = -\lambda \{z - d(A - dA) + d[z - (A - dA)]\}. \tag{24}$$

Choosing

$$d\Lambda = A(z) z^{\flat} \tag{25}$$

makes the second term vanish, yielding

$$\delta A = -\lambda \, z \, \neg \, dA = -\lambda \, z \, \neg \, F \,. \tag{26}$$

When the equations of motion are satisfied, infinitesimal transformation leads to

$$\delta_{\lambda} S = \int \lambda \, \mathrm{d} \{ +(z \, \neg \, F) \wedge \star F \} \,. \tag{27}$$

Taking the difference with eq. (23) and setting $z=e_{\alpha}$ yield

$$0 = \int \lambda \, d\mathfrak{T}_{\alpha},\tag{28}$$

$$2\mathfrak{T}_{\alpha} := +(e_{\alpha} - F) \wedge \star F - F \wedge (e_{\alpha} - \star F). \tag{29}$$

The continuity equation reads

$$d\mathfrak{T}_{\alpha} = 0. \tag{30}$$

In components, one needs

$$e_{\alpha} \, \neg \, F = F_{\alpha\beta} \, \vartheta^{\beta} \,, \tag{31}$$

$$e_{\alpha} \rightarrow \star F = \frac{1}{2} F^{\beta \gamma} \, \epsilon_{\beta \gamma \alpha} \, ; \tag{32} \label{eq:32}$$

equipped with eqs. (58) to (58), one arrives at

$$(e_{\alpha} - F) \wedge \star F = -F_{\alpha\gamma} F^{\gamma\beta} \epsilon_{\beta}, \qquad (33)$$

$$F \wedge (e_{\alpha} \, \neg \, \star F) = \frac{1}{2} F_{\beta \gamma} F^{\beta \gamma} \, \epsilon_{\alpha} + F_{\alpha \gamma} F^{\gamma \beta} \, \epsilon_{\beta} \, . \tag{34} \label{eq:34}$$

One finally has

$$\mathfrak{T}_{\alpha} = -F_{\alpha\gamma}F^{\gamma\beta}\,\epsilon_{\beta} - \frac{1}{4}F_{\beta\gamma}F^{\beta\gamma}\,\epsilon_{\alpha}\,. \tag{35}$$

4 U(1)-gauged complex scalar field theory

The action reads

$$S = \int -\mathbb{D}\phi^* \wedge \star \mathbb{D}\phi - m^2 \phi^* \wedge \star \phi - \frac{1}{2} F \wedge \star F, \qquad (36)$$

where the exterior covariant derivative is defined in eq. (63).

Variation does *not* commute with exterior covariant derivative.

$$[\delta, \mathbb{D}]\phi = -ie\delta A\phi. \tag{37}$$

Variation of the covariant kinetic term reads

$$\delta(\mathbb{D}\phi^* \wedge \star \mathbb{D}\phi) = d(\delta\phi^* \star \mathbb{D}\phi + \delta\phi \star \mathbb{D}\phi^*)
+ \delta\phi^* \wedge \star \mathbb{D}^{\dagger}\mathbb{D}\phi + \delta\phi \wedge \star \mathbb{D}^{\dagger}\mathbb{D}\phi^* + \delta A \wedge \mathfrak{J}_A,$$
(38)

where the covariant codifferential is defined in eq. (66), and

$$\mathfrak{J}_A := \mathrm{i} e(\phi^* \star \mathbb{D} \phi - \phi \star \mathbb{D} \phi^*) \,. \tag{39}$$

A generic variation of the action then reads

$$\delta S = \int d(-\delta\phi^* \wedge \star \mathbb{D}\phi - \delta\phi \wedge \star \mathbb{D}\phi^* - \delta A \wedge \star F)$$
$$-\delta\phi^* \wedge \star (\mathbb{D}^{\dagger}\mathbb{D} + m^2)\phi - \delta\phi \wedge \star (\mathbb{D}^{\dagger}\mathbb{D} + m^2)\phi^*$$
$$-\delta A \wedge (d\star F - \mathfrak{J}_A). \tag{40}$$

4.1 Noether's invariances

The action is invariant under the generic transformation

$$\phi \to e^{-ie\Lambda}\phi$$
, $\phi^* \to e^{+ie\Lambda}\phi^*$, $A \to A - d\Lambda$. (41)

There are two scenarios [1].

If the transformation is rigid, $d\Lambda = 0$, one obtains \mathfrak{J}_A as the Noether current from the boundary term as before, which satisfies the continuity equation $d\mathfrak{J}_A = 0$

If the transformation is gauge with a compact support, the boundary term can be dropped, and one obtains a Noether identity, which is under construction.

[1]

A Differential geometry

A.1 Basic operations

Following the style of [4], it is attempted to define the operations *inductively*, instead of giving explicit expressions, which is much less effective than the former in practice.

Interior product Let z be a vector, ω be a 1-form, χ be a k-form. The interior product is defined inductively as the bilinear map satisfying

$$z - 1 = 0, \tag{42}$$

$$z - \omega := \omega(z) \,, \tag{43}$$

$$z \rightharpoonup (\omega \wedge \chi) := (z \rightharpoonup \omega) \wedge \chi - \omega \wedge (z \rightharpoonup \chi). \tag{44}$$

Equation (44) is also known as the anti-product rule.

By induction one can show that for a p-form ϕ ,

$$z - (\phi \land \chi) = (z - \phi) \land \chi + (-)^p \chi \land (z - \chi). \tag{45}$$

Hodge star Let ω be an 1-form, χ be a k-form. The Hodge star \star is defined inductively as the linear map

$$\star 1 := \text{vol}\,,\tag{46}$$

$$\star(\chi \wedge \omega) := \omega^{\sharp} - \star \chi \,. \tag{47}$$

Non-gravitational theories features $[\delta, \star] = 0$, which means [7, sec. 3.2]

$$\delta g_{\mu\nu} = -2\omega_{(\mu\nu)}, \qquad \delta\vartheta^{\mu} = \omega_{\nu}^{\ \mu}\,\vartheta^{\nu}\,; \tag{48}$$

for an orthonormal coframe, the allowed variations are $\omega_{(\alpha\beta)} = 0$.

Identity Inspired by [9, eq. (3.167)], for a 1-form ω , k-form χ , one can derive

$$\omega \wedge \star \chi = (-)^{D-k} \star \chi \wedge \omega = (-)^{D-k} \star^{-1} \left(\omega^{\sharp} \to \star \chi\right)$$

$$= (-)^{D-k} (-)^{(D-k-1)(k+1)+s} \star \left(\omega^{\sharp} \to (-)^{k(D-k)+s} \star^{-1} \star \chi\right)$$

$$= (-)^{k+1} \star \left(\omega^{\sharp} \to \chi\right). \tag{49}$$

This will be useful in eqs. (58) to (60).

Codifferential The *codifferential* \mathbb{d}^{\dagger} is defined as follows. Let ϕ be a k-form, χ be a (k-1)-form.

$$d(\chi^* \wedge \star \phi) \equiv d\chi^* \wedge \star \phi - (-)^k \chi^* \wedge d \star \phi =: d\chi^* \wedge \star \phi - \chi^* \wedge \star d^{\dagger} \phi \tag{50}$$

$$= d\chi^* \wedge \star \phi - \chi^* \wedge \star (-)^k \star^{-1} d \star \phi.$$
 (51)

In other words,

$$\boxed{\mathbf{d}^{\dagger}\phi = (-)^k \star^{-1} \mathbf{d} \star \phi .} \tag{52}$$

If $\int d(\chi^* \wedge \star \phi) = 0$, then d^{\dagger} is the adjoint of the exterior derivative d in functional sense.

A.2 Coframe bases

Coframes come into play if an explicit expression in components is wanted, or if gravitation comes into play.

For a detailed discussion about the meaning of untwisted (describing extensions) and twisted (describing densities) differential forms, see e.g. [4, sec. 22, 28].

Untwisted orthonormal k-cobases Let $\{\vartheta^{\alpha}\}$ be an orthonormal coframe. The orthonormal basis for untwisted k-form is defined inductively as

$$1, (53)$$

$$\vartheta^{\alpha_1 \alpha_2 \dots \alpha_k} := \vartheta^{\alpha_1} \wedge \vartheta^{\alpha_2 \dots \alpha_k} . \tag{54}$$

Twisted orthonormal k**-cobases** Let $\{\vartheta^{\alpha}\}$ be an orthonormal coframe. The orthonormal basis for twisted (D-k)-form is defined inductively as

$$\epsilon := \text{vol}\,,\tag{55}$$

$$\epsilon_{\alpha_1 \alpha_2 \dots \alpha_k} \coloneqq e_{\alpha_k} - \epsilon_{\alpha_1 \dots \alpha_{k-1}}. \tag{56}$$

By using eq. (47) and induction, one can show that

$$\epsilon_{\alpha_1 \alpha_2 \dots \alpha_k} = \star \vartheta_{\alpha_1 \alpha_2 \dots \alpha_k} \,. \tag{57}$$

Identities The following identities come from eq. (49)

$$\vartheta^{\alpha} \wedge \epsilon_{\beta\gamma} = -\delta^{\alpha}_{\beta} \, \epsilon_{\gamma} + \delta^{\alpha}_{\gamma} \, \epsilon_{\beta} \,, \tag{58}$$

$$\vartheta^{\alpha} \wedge \epsilon_{\beta\gamma\delta} = \delta^{\alpha}_{\beta} \, \epsilon_{\gamma\delta} - \delta^{\alpha}_{\gamma} \, \epsilon_{\beta\delta} + \delta^{\alpha}_{\delta} \, \epsilon_{\beta\gamma} \,. \tag{59}$$

One can further deduce that

$$\vartheta^{\alpha\beta} \wedge \epsilon_{\gamma\delta\epsilon} = + \left(\delta^{\alpha}_{\gamma} \delta^{\beta}_{\delta} - \delta^{\alpha}_{\delta} \delta^{\beta}_{\gamma} \right) \epsilon_{\epsilon} - \left(\delta^{\alpha}_{\gamma} \delta^{\beta}_{\epsilon} - \delta^{\alpha}_{\epsilon} \delta^{\beta}_{\gamma} \right) \epsilon_{\delta} + \left(\delta^{\alpha}_{\delta} \delta^{\beta}_{\epsilon} - \delta^{\alpha}_{\epsilon} \delta^{\beta}_{\delta} \right) \epsilon_{\gamma} .$$

$$(60)$$

Equations (58) to (60) are useful in constructing explicit expressions in components.

Translation Consider the rigid infinitesimal transformation

$$\delta_{\lambda} \chi = \lambda \, \pounds_{z} \chi = \lambda [z - d\chi + d(z - \chi)]; \tag{61}$$

'rigid' means

$$\delta_{\lambda}\vartheta^{\alpha} = 0. \tag{62}$$

A.3 Connection on the principal bundle

Exterior covariant derivative Let χ be a \mathbb{C} -valued k-form. The exterior covariant derivative of χ reads

$$\mathbb{D}\chi := (d - ieA)\chi, \qquad \mathbb{D}\chi^* := (d + ieA)\chi^*, \tag{63}$$

where A is a $\mathfrak{u}(1)$ -valued connection form.

Covariant codifferential The covariant codifferential \mathbb{D}^{\dagger} is defined as follows. Let ϕ be a \mathbb{C} -valued k-form, χ be a \mathbb{C} -valued (k-1)-form.

$$d(\chi^* \wedge \star \phi) \equiv d\chi^* \wedge \star \phi - (-)^k \chi^* \wedge d \star \phi =: \mathbb{D}\chi^* \wedge \star \phi - \chi^* \wedge \star \mathbb{D}^{\dagger} \phi$$

$$= \mathbb{D}\chi^* \wedge \star \phi - ieA \wedge \chi^* \wedge \star \phi - (-)^k \chi^* \wedge d \star \phi$$

$$= \mathbb{D}\chi^* \wedge \star \phi + \chi^* \wedge (-)^k ieA \star \phi - (-)^k \chi^* \wedge d \star \phi$$

$$= \mathbb{D}\chi^* \wedge \star \phi - \chi^* \wedge \star (-)^k \star^{-1} (d - ieA) \star \phi .$$
(65)

In other words,

$$\boxed{ \mathbb{D}^{\dagger} \phi = (-)^k \star^{-1} (\mathbf{d} - ieA) \star \phi \,. } \tag{66}$$

If $\int d(\chi^* \wedge \star \phi) = 0$, \mathbb{D}^{\dagger} becomes the adjoint of the exterior covariant derivative \mathbb{D} in the functional sense.

A.4 Variation of coframe bases

Upon variation of ϑ^{α} , $\vartheta^{\alpha_1\alpha_2...\alpha_k}$ goes under

$$\delta \vartheta^{\alpha_1 \alpha_2 \dots \alpha_k} = \delta \vartheta^{\alpha} \wedge (e_{\alpha} - \vartheta^{\alpha_1 \alpha_2 \dots \alpha_k}), \tag{67}$$

which can be proved by induction.

Upon variation of ϑ^{α} , $\epsilon_{\alpha_1\alpha_2...\alpha_k}$ goes under [7, sec. A.2]

$$\delta \epsilon_{\alpha_1 \alpha_2 \dots \alpha_k} = \delta \vartheta^{\alpha} \wedge \left(e_{\alpha} - \epsilon_{\alpha_1 \alpha_2 \dots \alpha_k} \right). \tag{68}$$

Variation of Hodge star In gravitational theories [7, sec. 3.2] with an orthonormal cobasis,

$$[\delta,\star]\phi = \delta\vartheta^\alpha \wedge (e_\alpha \, \lrcorner \, \star \phi) - \star (\delta\vartheta^\alpha \wedge (e_\alpha \, \lrcorner \, \phi)) \,. \tag{69}$$

Let χ be a p-form, ϕ another form [5, sec. 5].

$$\delta(\chi \wedge \star \phi) = \delta\chi \wedge \star \phi + \delta\phi \wedge \star \chi - \delta\vartheta^{\alpha} \wedge \Sigma_{\alpha}, \tag{70}$$

$$\Sigma_{\alpha} := \chi \wedge \left\{ \star (e_{\alpha} - \phi) - (-)^{p} (e_{\alpha} - \star \phi) \right\}. \tag{71}$$

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