

# Tool-kit for the coframe formalism

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## 1 Introduction

This note is intended to be pragmatic, collecting a set of toolkits for the calculation of field theories without and with gravitation. The physical motivation will be discussed elsewhere.

## 2 Complex scalar field

The action reads

$$S = \int -\mathrm{d}\phi^* \wedge \star \mathrm{d}\phi - m^2 \phi^* \wedge \star \phi \quad (1)$$

$$= \int -\frac{1}{2}(\mathrm{d}\phi^* \wedge \star \mathrm{d}\phi + \mathrm{d}\phi \wedge \star \mathrm{d}\phi^*) - \frac{1}{2}m^2(\phi^* \wedge \star \phi + \phi \wedge \star \phi^*) \quad (2)$$

Variation commutes with exterior derivative

$$[\delta, \mathrm{d}]\phi = 0. \quad (3)$$

For simplicity, one assumes that variation also commutes with Hodge star

$$[\delta, \star]\phi = 0. \quad (4)$$

In the absence of gravitation, variation also commutes with Hodge star. A generic variation of the kinetic terms therefore reads

$$\begin{aligned} \delta(\mathfrak{d}\phi^* \wedge \star \mathfrak{d}\phi) &= \mathfrak{d}(\delta\phi^* \wedge \star \mathfrak{d}\phi + \delta\phi \wedge \star \mathfrak{d}\phi^*) \\ &\quad + \delta\phi^* \wedge \star \mathfrak{d}^\dagger \mathfrak{d}\phi + \delta\phi \wedge \star \mathfrak{d}^\dagger \mathfrak{d}\phi^*, \end{aligned} \quad (5)$$

where the codifferential is defined in eq. (53). A generic variation of the action reads

$$\begin{aligned} \delta S &= \int \mathfrak{d}(-\delta\phi^* \wedge \star \mathfrak{d}\phi - \delta\phi \wedge \star \mathfrak{d}\phi^*) \\ &\quad - \delta\phi^* \wedge \star (\mathfrak{d}^\dagger \mathfrak{d} + m^2)\phi - \delta\phi \wedge \star (\mathfrak{d}^\dagger \mathfrak{d} + m^2)\phi^*. \end{aligned} \quad (6)$$

## 2.1 U(1) Noether current

The action is invariant

$$\delta_\lambda S \equiv 0 \quad (7)$$

under the rigid transformation

$$\phi \rightarrow e^{-ie\lambda} \phi, \quad \phi^* \rightarrow e^{+ie\lambda} \phi^*. \quad (8)$$

When the equations of motion are satisfied, infinitesimal transformation leads to

$$\begin{aligned} 0 &= \int \lambda \mathfrak{d}\mathfrak{J}_0, \\ \mathfrak{J}_0 &:= ie(\phi^* \wedge \star \mathfrak{d}\phi - \phi \wedge \star \mathfrak{d}\phi^*), \end{aligned} \quad (9)$$

which is the Noether current, a twisted 3-form, satisfying the continuity equation

$$\mathfrak{d}\mathfrak{J}_0 = 0. \quad (10)$$

## 2.2 T(D) Noether current

The action is invariant up to a total differential

$$\begin{aligned} \delta_\lambda S &= \int -\lambda \mathfrak{d}(z \lrcorner \mathfrak{L}) \\ &= \int \lambda \frac{1}{2} \mathfrak{d}\{+z \lrcorner [\mathfrak{d}\phi^* \wedge \star \mathfrak{d}\phi + \mathfrak{d}\phi \wedge \star \mathfrak{d}\phi^* + m^2(\phi^* \star \phi + \phi \star \phi^*)]\}, \end{aligned} \quad (11)$$

under the rigid infinitesimal transformation

$$\delta\phi = -\lambda \mathfrak{L}_z \phi = -\lambda z \lrcorner \mathfrak{d}\phi, \quad \delta\phi^* = -\lambda \mathfrak{L}_z \phi^* = -\lambda z \lrcorner \mathfrak{d}\phi^*. \quad (12)$$

Note the minus sign, which has to do with our mostly-positive metric convention  $(-, +, \dots, +)$ .

When the equations of motion are satisfied, infinitesimal transformation leads to

$$\delta_\lambda S = \int \lambda \mathfrak{d}\{+(z \lrcorner \mathfrak{d}\phi^*) \wedge \star \mathfrak{d}\phi + (z \lrcorner \mathfrak{d}\phi) \wedge \star \mathfrak{d}\phi^*\}. \quad (13)$$

Taking the difference with eq. (11) and setting  $z = e_\alpha$  yield

$$0 = \int \lambda \mathfrak{d}\mathfrak{T}_\alpha, \quad (14)$$

$$\begin{aligned} 2\mathfrak{T}_\alpha := & +(e_\alpha \lrcorner \mathfrak{d}\phi^*) \wedge \star \mathfrak{d}\phi + \mathfrak{d}\phi^* \wedge (e_\alpha \lrcorner \star \mathfrak{d}\phi) \\ & + (e_\alpha \lrcorner \mathfrak{d}\phi) \wedge \star \mathfrak{d}\phi^* + \mathfrak{d}\phi \wedge (e_\alpha \lrcorner \star \mathfrak{d}\phi^*) \\ & - m^2(\phi^* e_\alpha \lrcorner \star \phi + \phi e_\alpha \star \phi^*). \end{aligned} \quad (15)$$

The continuity equation reads

$$\mathfrak{d}\mathfrak{T}_\alpha = 0. \quad (16)$$

In components,

$$\mathfrak{T}_\alpha = +[e_\alpha(\phi^*)e^\beta(\phi) + e_\alpha(\phi)e^\beta(\phi^*)]\epsilon_\beta - [e^\beta(\phi^*)e_\beta(\phi^*) + m^2\phi^*\phi]\epsilon_\alpha. \quad (17)$$

### 3 Pure electromagnetic field

The action reads

$$S = \int -\frac{1}{2}F \wedge \star F. \quad (18)$$

Variation commutes with exterior derivative

$$[\delta, \mathfrak{d}]\phi = 0. \quad (3 \text{ rev.})$$

For simplicity, one assumes that variation also commutes with Hodge star

$$[\delta, \star]\phi = 0. \quad (4 \text{ rev.})$$

Variation of the Lagrangian reads

$$\delta(F \wedge \star F) = 2\delta F \wedge \star F \quad (19)$$

$$= 2\mathfrak{d}(\delta A \wedge \star F) + 2\delta A \wedge \mathfrak{d}\star F. \quad (20)$$

Note that this is not gauge invariant.

#### 3.1 Lorenz gauge

The Laplace–de Rham operator, or in our Lorentzian metric signature the d'Alembertian

$$\square^2 := (\mathfrak{d} + \mathfrak{d}^\dagger)^2 = \mathfrak{d}\mathfrak{d}^\dagger + \mathfrak{d}^\dagger\mathfrak{d}. \quad (21)$$

$$\mathfrak{d}\star F = \mathfrak{d}\star \mathfrak{d}A = \star(-)^2 \star^{-1} \mathfrak{d}\star \mathfrak{d}A = \star \mathfrak{d}^\dagger \mathfrak{d}A = \star(\square^2 - \mathfrak{d}\mathfrak{d}^\dagger)A. \quad (22)$$

One would like to have  $\mathfrak{d}\mathfrak{d}^\dagger A = 0$ , or  $\mathfrak{d}^\dagger A = \text{const.}$  This would be fulfilled if

$$\mathfrak{d}^\dagger A = 0, \quad (23)$$

which is the Lorenz gauge[2, 3, 6].

### 3.2 $\mathbb{T}(D)$ Noether current

The action is invariant up to a total differential

$$\delta_\lambda S = - \int \lambda \mathfrak{d}(z \lrcorner \mathfrak{L}) = \int \lambda \frac{1}{2} \mathfrak{d}\{+z \lrcorner (F \wedge \star F)\}, \quad (24)$$

under the rigid infinitesimal transformation combined with a gauge transformation [8, eq. 3.46]

$$\delta A = -\lambda\{z \lrcorner \mathfrak{d}(A - \mathfrak{d}A) + \mathfrak{d}[z \lrcorner (A - \mathfrak{d}A)]\}. \quad (25)$$

Choosing

$$\mathfrak{d}A = A(z) z^\flat \quad (26)$$

makes the second term vanish, yielding

$$\delta A = -\lambda z \lrcorner \mathfrak{d}A = -\lambda z \lrcorner F. \quad (27)$$

When the equations of motion are satisfied, infinitesimal transformation leads to

$$\delta_\lambda S = \int \lambda \mathfrak{d}\{+(z \lrcorner F) \wedge \star F\}. \quad (28)$$

Taking the difference with eq. (24) and setting  $z = e_\alpha$  yield

$$0 = \int \lambda \mathfrak{d}\mathfrak{T}_\alpha, \quad (29)$$

$$2\mathfrak{T}_\alpha := +(e_\alpha \lrcorner F) \wedge \star F - F \wedge (e_\alpha \lrcorner \star F). \quad (30)$$

The continuity equation reads

$$\mathfrak{d}\mathfrak{T}_\alpha = 0. \quad (31)$$

In components, one needs

$$e_\alpha \lrcorner F = F_{\alpha\beta} \vartheta^\beta, \quad (32)$$

$$e_\alpha \lrcorner \star F = \frac{1}{2} F^{\beta\gamma} \epsilon_{\beta\gamma\alpha}; \quad (33)$$

equipped with eqs. (59) to (59), one arrives at

$$(e_\alpha \lrcorner F) \wedge \star F = -F_{\alpha\gamma} F^{\gamma\beta} \epsilon_\beta, \quad (34)$$

$$F \wedge (e_\alpha \lrcorner \star F) = \frac{1}{2} F_{\beta\gamma} F^{\beta\gamma} \epsilon_\alpha + F_{\alpha\gamma} F^{\gamma\beta} \epsilon_\beta. \quad (35)$$

One finally has

$$\mathfrak{T}_\alpha = -F_{\alpha\gamma} F^{\gamma\beta} \epsilon_\beta - \frac{1}{4} F_{\beta\gamma} F^{\beta\gamma} \epsilon_\alpha. \quad (36)$$

## 4 U(1)-gauged complex scalar field theory

The action reads

$$S = \int -\mathbb{D}\phi^* \wedge \star \mathbb{D}\phi - m^2 \phi^* \wedge \star \phi - \frac{1}{2} F \wedge \star F, \quad (37)$$

where the exterior covariant derivative is defined in eq. (64).

Variation does *not* commute with exterior covariant derivative.

$$[\delta, \mathbb{D}]\phi = -ie\delta A\phi. \quad (38)$$

For simplicity, one assumes that variation also commutes with Hodge star

$$[\delta, \star]\phi = 0. \quad (4 \text{ rev.})$$

Variation of the covariant kinetic term reads

$$\begin{aligned} \delta(\mathbb{D}\phi^* \wedge \star \mathbb{D}\phi) &= \mathbb{d}(\delta\phi^* \star \mathbb{D}\phi + \delta\phi \star \mathbb{D}\phi^*) \\ &\quad + \delta\phi^* \wedge \star \mathbb{D}^\dagger \mathbb{D}\phi + \delta\phi \wedge \star \mathbb{D}^\dagger \mathbb{D}\phi^* + \delta A \wedge \mathfrak{J}_A, \end{aligned} \quad (39)$$

where the covariant codifferential is defined in eq. (67), and

$$\mathfrak{J}_A := ie(\phi^* \star \mathbb{D}\phi - \phi \star \mathbb{D}\phi^*). \quad (40)$$

A generic variation of the action then reads

$$\begin{aligned} \delta S &= \int \mathbb{d}(-\delta\phi^* \wedge \star \mathbb{D}\phi - \delta\phi \wedge \star \mathbb{D}\phi^* - \delta A \wedge \star F) \\ &\quad - \delta\phi^* \wedge \star (\mathbb{D}^\dagger \mathbb{D} + m^2)\phi - \delta\phi \wedge \star (\mathbb{D}^\dagger \mathbb{D} + m^2)\phi^* \\ &\quad - \delta A \wedge (\mathbb{d}\star F - \mathfrak{J}_A). \end{aligned} \quad (41)$$

### 4.1 Noether's invariances

The action is invariant under the generic transformation

$$\phi \rightarrow e^{-ie\Lambda}\phi, \quad \phi^* \rightarrow e^{+ie\Lambda}\phi^*, \quad A \rightarrow A - \mathbb{d}\Lambda. \quad (42)$$

There are two scenarios [1].

If the transformation is rigid,  $\mathbb{d}\Lambda = 0$ , one obtains  $\mathfrak{J}_A$  as the Noether current from the boundary term as before, which satisfies the continuity equation  $\mathbb{d}\mathfrak{J}_A = 0$ .

If the transformation is gauge with a compact support, the boundary term can be dropped, and one obtains a Noether identity, which is under construction. [1]

## A Differential geometry

### A.1 Basic operations

Following the style of [4], it is attempted to define the operations *inductively*, instead of giving explicit expressions, which is much less effective than the former in practice.

**Interior product** Let  $z$  be a vector,  $\omega$  be a 1-form,  $\chi$  be a  $k$ -form. The *interior product* is defined inductively as the bilinear map satisfying

$$z \lrcorner 1 = 0, \quad (43)$$

$$z \lrcorner \omega := \omega(z), \quad (44)$$

$$z \lrcorner (\omega \wedge \chi) := (z \lrcorner \omega) \wedge \chi - \omega \wedge (z \lrcorner \chi). \quad (45)$$

Equation (45) is also known as the anti-product rule.

By induction one can show that for a  $p$ -form  $\phi$ ,

$$z \lrcorner (\phi \wedge \chi) = (z \lrcorner \phi) \wedge \chi + (-)^p \chi \wedge (z \lrcorner \phi). \quad (46)$$

**Hodge star** Let  $\omega$  be an 1-form,  $\chi$  be a  $k$ -form. The Hodge star  $\star$  is defined inductively as the linear map

$$\star 1 := \text{vol}, \quad (47)$$

$$\star(\chi \wedge \omega) := \omega^\sharp \lrcorner \star \chi. \quad (48)$$

Non-gravitational theories features  $[\delta, \star] = 0$ , which means [7, sec. 3.2]

$$\delta g_{\mu\nu} = -2\omega_{(\mu\nu)}, \quad \delta \vartheta^\mu = \omega_\nu{}^\mu \vartheta^\nu; \quad (49)$$

for an orthonormal coframe, the allowed variations are  $\omega_{(\alpha\beta)} = 0$ .

**Identity** Inspired by [9, eq. (3.167)], for a 1-form  $\omega$ ,  $k$ -form  $\chi$ , one can derive

$$\begin{aligned} \omega \wedge \star \chi &= (-)^{D-k} \star \chi \wedge \omega = (-)^{D-k} \star^{-1} (\omega^\sharp \lrcorner \star \star \chi) \\ &= (-)^{D-k} (-)^{(D-k-1)(k+1)+s} \star \left( \omega^\sharp \lrcorner (-)^{k(D-k)+s} \star^{-1} \star \chi \right) \\ &= (-)^{k+1} \star (\omega^\sharp \lrcorner \chi). \end{aligned} \quad (50)$$

This will be useful in eqs. (59) to (61).

**Codifferential** The *codifferential*  $\mathfrak{d}^\dagger$  is defined as follows. Let  $\phi$  be a  $k$ -form,  $\chi$  be a  $(k-1)$ -form.

$$\mathfrak{d}(\chi^* \wedge \star \phi) \equiv \mathfrak{d}\chi^* \wedge \star \phi - (-)^k \chi^* \wedge \mathfrak{d} \star \phi =: \mathfrak{d}\chi^* \wedge \star \phi - \chi^* \wedge \star \mathfrak{d}^\dagger \phi \quad (51)$$

$$= \mathfrak{d}\chi^* \wedge \star \phi - \chi^* \wedge \star (-)^k \star^{-1} \mathfrak{d} \star \phi. \quad (52)$$

In other words,

$$\boxed{\mathfrak{d}^\dagger \phi = (-)^k \star^{-1} \mathfrak{d} \star \phi.} \quad (53)$$

If  $\int \mathfrak{d}(\chi^* \wedge \star \phi) = 0$ , then  $\mathfrak{d}^\dagger$  is the adjoint of the exterior derivative  $\mathfrak{d}$  in functional sense.

## A.2 Coframe bases

Coframes come into play if an explicit expression in components is wanted, or if gravitation comes into play.

For a detailed discussion about the meaning of untwisted (describing extensions) and twisted (describing densities) differential forms, see e.g. [4, sec. 22, 28].

**Untwisted orthonormal  $k$ -cobases** Let  $\{\vartheta^\alpha\}$  be an orthonormal coframe. The orthonormal basis for untwisted  $k$ -form is defined inductively as

$$1, \quad (54)$$

$$\vartheta^{\alpha_1 \alpha_2 \dots \alpha_k} := \vartheta^{\alpha_1} \wedge \vartheta^{\alpha_2 \dots \alpha_k}. \quad (55)$$

**Twisted orthonormal  $k$ -cobases** Let  $\{\vartheta^\alpha\}$  be an orthonormal coframe. The orthonormal basis for twisted  $(D - k)$ -form is defined inductively as

$$\epsilon := \text{vol}, \quad (56)$$

$$\epsilon_{\alpha_1 \alpha_2 \dots \alpha_k} := \vartheta_{\alpha_k} \lrcorner \epsilon_{\alpha_1 \dots \alpha_{k-1}}. \quad (57)$$

By using eq. (48) and induction, one can show that

$$\epsilon_{\alpha_1 \alpha_2 \dots \alpha_k} = \star \vartheta_{\alpha_1 \alpha_2 \dots \alpha_k}. \quad (58)$$

**Identities** The following identities come from eq. (50)

$$\vartheta^\alpha \wedge \epsilon_{\beta\gamma} = -\delta_\beta^\alpha \epsilon_\gamma + \delta_\gamma^\alpha \epsilon_\beta, \quad (59)$$

$$\vartheta^\alpha \wedge \epsilon_{\beta\gamma\delta} = \delta_\beta^\alpha \epsilon_{\gamma\delta} - \delta_\gamma^\alpha \epsilon_{\beta\delta} + \delta_\delta^\alpha \epsilon_{\beta\gamma}. \quad (60)$$

One can further deduce that

$$\begin{aligned} \vartheta^{\alpha\beta} \wedge \epsilon_{\gamma\delta\epsilon} = & + (\delta_\gamma^\alpha \delta_\delta^\beta - \delta_\delta^\alpha \delta_\gamma^\beta) \epsilon_\epsilon \\ & - (\delta_\gamma^\alpha \delta_\epsilon^\beta - \delta_\epsilon^\alpha \delta_\gamma^\beta) \epsilon_\delta \\ & + (\delta_\delta^\alpha \delta_\epsilon^\beta - \delta_\epsilon^\alpha \delta_\delta^\beta) \epsilon_\gamma. \end{aligned} \quad (61)$$

Equations (59) to (61) are useful in constructing explicit expressions in components.

**Translation** Consider the rigid infinitesimal transformation

$$\delta_\lambda \chi = \lambda \mathcal{L}_z \chi = \lambda [z \lrcorner d\chi + d(z \lrcorner \chi)]; \quad (62)$$

‘rigid’ means

$$\delta_\lambda \vartheta^\alpha = 0. \quad (63)$$

### A.3 Connection on the principal bundle

**Exterior covariant derivative** Let  $\chi$  be a  $\mathbb{C}$ -valued  $k$ -form. The *exterior covariant derivative* of  $\chi$  reads

$$\mathbb{D}\chi := (d - ieA)\chi, \quad \mathbb{D}\chi^* := (d + ieA)\chi^*, \quad (64)$$

where  $A$  is a  $\mathfrak{u}(1)$ -valued *connection form*.

**Covariant codifferential** The *covariant codifferential*  $\mathbb{D}^\dagger$  is defined as follows. Let  $\phi$  be a  $\mathbb{C}$ -valued  $k$ -form,  $\chi$  be a  $\mathbb{C}$ -valued  $(k-1)$ -form.

$$\mathbb{d}(\chi^* \wedge \star \phi) \equiv \mathbb{d}\chi^* \wedge \star \phi - (-)^k \chi^* \wedge \mathbb{d} \star \phi =: \mathbb{D}\chi^* \wedge \star \phi - \chi^* \wedge \star \mathbb{D}^\dagger \phi \quad (65)$$

$$\begin{aligned} &= \mathbb{D}\chi^* \wedge \star \phi - ieA \wedge \chi^* \wedge \star \phi - (-)^k \chi^* \wedge \mathbb{d} \star \phi \\ &= \mathbb{D}\chi^* \wedge \star \phi + \chi^* \wedge (-)^k ieA \star \phi - (-)^k \chi^* \wedge \mathbb{d} \star \phi \\ &= \mathbb{D}\chi^* \wedge \star \phi - \chi^* \wedge \star (-)^k \star^{-1} (\mathbb{d} - ieA) \star \phi. \end{aligned} \quad (66)$$

In other words,

$$\boxed{\mathbb{D}^\dagger \phi = (-)^k \star^{-1} (\mathbb{d} - ieA) \star \phi.} \quad (67)$$

If  $\int \mathbb{d}(\chi^* \wedge \star \phi) = 0$ ,  $\mathbb{D}^\dagger$  becomes the adjoint of the exterior covariant derivative  $\mathbb{D}$  in the functional sense.

## A.4 Variation of coframe bases

Upon variation of  $\vartheta^\alpha$ ,  $\vartheta^{\alpha_1 \alpha_2 \dots \alpha_k}$  goes under

$$\delta \vartheta^{\alpha_1 \alpha_2 \dots \alpha_k} = \delta \vartheta^\alpha \wedge (e_\alpha \lrcorner \vartheta^{\alpha_1 \alpha_2 \dots \alpha_k}), \quad (68)$$

which can be proved by induction.

Upon variation of  $\vartheta^\alpha$ ,  $\epsilon_{\alpha_1 \alpha_2 \dots \alpha_k}$  goes under [7, sec. A.2]

$$\delta \epsilon_{\alpha_1 \alpha_2 \dots \alpha_k} = \delta \vartheta^\alpha \wedge (e_\alpha \lrcorner \epsilon_{\alpha_1 \alpha_2 \dots \alpha_k}). \quad (69)$$

**Variation of Hodge star** In gravitational theories [7, sec. 3.2] with an orthonormal cobasis,

$$[\delta, \star] \phi = \delta \vartheta^\alpha \wedge (e_\alpha \lrcorner \star \phi) - \star (\delta \vartheta^\alpha \wedge (e_\alpha \lrcorner \phi)). \quad (70)$$

Let  $\chi$  be a  $p$ -form,  $\phi$  another form [5, sec. 5].

$$\delta(\chi \wedge \star \phi) = \delta \chi \wedge \star \phi + \delta \phi \wedge \star \chi - \delta \vartheta^\alpha \wedge \Sigma_\alpha, \quad (71)$$

$$\Sigma_\alpha := \chi \wedge \{ \star (e_\alpha \lrcorner \phi) - (-)^P (e_\alpha \lrcorner \star \phi) \}. \quad (72)$$

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