Notes on Canonical Singular Dynamics

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1 Classical formalism

Lagrangian with velocity

$$L^{\mathbf{v}} := L|_{\dot{a}=v} \tag{1.1}$$

Equations of motion

$$\sum_{j} M_{ij} \dot{v}_{j} = K_{i}^{\text{v}}, \quad \dot{q}_{i} = v_{i}. \tag{1.2}$$

where

$$M_{ij}(q,v)\coloneqq \frac{\partial^2 L^{\rm v}}{\partial v_i\,\partial v_j}. \tag{1.3}$$

Adding

$$p_i := \frac{\partial L^{\mathbf{v}}}{\partial v_i}.\tag{1.4}$$

Variation of

$$S[q,p;v] := \int \mathrm{d}t \left[L^{\mathrm{v}} + \sum_i p_i (\dot{q}_i - v_i) \right]. \tag{1.5}$$

gives the extended Euler-Lagrange equations

$$\dot{q}_i = v_i, \quad \dot{p}_i = \frac{\partial L^{\rm v}}{\partial q_i}, \quad p_i = \frac{\partial L^{\rm v}}{\partial v_i}. \tag{1.6}$$

Hamiltonian with velocity

$$H^{\mathbf{v}}(q,p;v) \coloneqq \sum_{i} p_{i}v_{i} - L^{\mathbf{v}}. \tag{1.7} \label{eq:1.7}$$

Identities

$$\frac{\partial H^{\rm v}}{\partial q_i} \equiv -\frac{\partial L^{\rm v}}{\partial q_i}, \quad \frac{\partial H^{\rm v}}{\partial p_i} \equiv v_i, \quad \frac{\partial H^{\rm v}}{\partial v_i} \equiv p_i - \frac{\partial L^{\rm v}}{\partial v_i}. \tag{1.8}$$

Variation of

$$S[q,p;v] \coloneqq \int \mathrm{d}t \left[\sum_i p_i \dot{q}_i - H^\mathrm{v} \right] \tag{1.9}$$

gives the extended canonical equations

$$\dot{q}_i = [q_i, H^{\mathbf{v}}]_{\mathbf{p}}, \quad \dot{p}_i = [p_i, H^{\mathbf{v}}]_{\mathbf{p}}, \quad \frac{\partial H^{\mathbf{v}}}{\partial v_i} = 0,$$
 (1.10)

where the Poisson bracket is defined as

$$[f^{\mathbf{v}}, g^{\mathbf{v}}]_{\mathbf{p}} := \sum_{i} \left(\frac{\partial f^{\mathbf{v}}}{\partial q_{i}} \frac{\partial g^{\mathbf{v}}}{\partial p_{i}} - \frac{\partial f^{\mathbf{v}}}{\partial p_{i}} \frac{\partial g^{\mathbf{v}}}{\partial q_{i}} \right). \tag{1.11}$$

 $v_a=\overline{v}_a(q,p;\{v_\alpha\})$ can be solved, $a=1,2,\ldots,r_M;\,v_\alpha$ cannot be solved, $\alpha=r_M+1,\ldots,n,$ where $r_M=\operatorname{rank} M.$

(need to show $v_a = \overline{v}_a(q, p_a)$)

Primary constraints in the standard form

$$\Phi_{\alpha}(q,p) \coloneqq \left. \frac{\partial H^{\mathrm{v}}}{\partial v_{\alpha}} \right|_{\{v_{\alpha} = \overline{v}_{\alpha}\}} \equiv p_{\alpha} - \overline{p}_{\alpha}(q,\{p_{a}\}), \tag{1.12}$$

where

$$\overline{p}_{\alpha}(q, \{p_a\}) := \left. \frac{\partial L^{\mathbf{v}}}{\partial v_{\alpha}} \right|_{\{v_a = \overline{v}_a\}}. \tag{1.13}$$

Total Hamiltonian

$$H^{\rm t} \coloneqq \left. H^{\rm v} \right|_{\{v_a = \overline{v}_a\}} \equiv H^{\rm v}(q,p;\{\overline{v}^a(q,p_a;\{v_\alpha\}),v_\alpha\}). \tag{1.14} \label{eq:1.14}$$

Subspace of primary constraints

$$\Gamma_{\mathbf{P}} = \{ (q, p) \mid \Phi_{\alpha}(q, p) = 0, \forall \alpha \}$$
(1.15)

Since

$$\left. \frac{\partial H^{\rm t}}{\partial v_{\alpha}} = \left. \frac{\partial H^{\rm v}}{\partial v_{\alpha}} \right|_{\{v_{\alpha} = \overline{v}_{\alpha}\}} = \Phi_{\alpha} \equiv p_{\alpha} - \overline{p}_{\alpha}(q, \{p_{a}\}), \tag{1.16}$$

 H^{t} is linear in v_{α} . One writes

$$H^{\rm t}(q,\{p_a\};\{p_\alpha\},\{v_\alpha\}) = H(q,\{p_a\}) + \sum v_\alpha \Phi_\alpha, \eqno(1.17)$$

where H^{c} is the *canonical Hamiltonian* or simply *Hamiltonian*.

Proposition H^{c} is independent of $\{p_{\alpha}\}.$

Proposition Canonical equations with primary constraints

$$\dot{q}_{i}=\left[q_{i},H\right]_{\mathrm{P}}+\sum_{\beta}v_{\beta}\left[q_{i},\phi_{\beta}\right]_{\mathrm{P}},\tag{1.18}$$

$$\dot{\boldsymbol{p}}_{i}=\left[\boldsymbol{p}_{i},\boldsymbol{H}\right]_{\mathrm{P}}+\sum_{\beta}\boldsymbol{v}_{\beta}\left[\boldsymbol{p}_{i},\boldsymbol{\phi}_{\beta}\right]_{\mathrm{P}},\tag{1.19}$$

$$\Phi_{\alpha}(q,p) = 0, \tag{1.20}$$

where v_{β} 's are undetermined. Note that eq. (1.18) for $i=\alpha$ holds identically: $\dot{q}_{\alpha}=\dot{q}_{\alpha}$.

Weak equality: $f_1 pprox f_2 \text{ iff } \left. f_1 \right|_{\Gamma_{\mathsf{p}}} = \left. f_2 \right|_{\Gamma_{\mathsf{p}}}.$

Proposition if f and g are two functions over the phase space Γ , and $f \approx h$, then

$$\frac{\partial}{\partial q_i} \left(f - \sum_{\beta} \phi_{\beta} \frac{\partial f}{\partial p_{\beta}} \right) \approx \frac{\partial}{\partial q_i} \left(h - \sum_{\beta} \phi_{\beta} \frac{\partial h}{\partial p_{\beta}} \right), \tag{1.21}$$

$$\frac{\partial}{\partial p_i} \left(f - \sum_{\beta} \phi_{\beta} \frac{\partial f}{\partial p_{\beta}} \right) \approx \frac{\partial}{\partial p_i} \left(h - \sum_{\beta} \phi_{\beta} \frac{\partial h}{\partial p_{\beta}} \right). \tag{1.22}$$

Corollary $\forall H_1 \approx H$,

$$\dot{q}_i \approx [q_i, H]_p, \qquad \dot{p}_i \approx [p_i, H]_p.$$
 (1.23)

Primary and second constraints $\phi_{\mu}^{(1,)},\phi_{\omega}^{(2,)};$ first and second class constraints $\phi_{u}^{(,1)},\phi_{w}^{(,2)}.$

2 Examples

2.1 Toy examples

Example 0

Gitman and Tyutin 1990, sec. 1.2

$$L = \frac{1}{2}(\dot{x} - y)^2 \tag{2.1}$$

Example 1

$$L = \frac{1}{2}\dot{x}^2 + \dot{x}y - \frac{1}{2}(x - y)^2.$$
 (2.2)

One has

$$L^{\mathbf{v}} = \frac{1}{2}v_x^2 + v_x y - \frac{1}{2}(x - y)^2, \tag{2.3}$$

so that

$$p_x = \frac{\partial L^{\mathbf{v}}}{\partial v_-} = v_x + y, \qquad p_y = 0, \tag{2.4}$$

thus

$$\overline{v}_x = p_x - y. \tag{2.5}$$

So that \boldsymbol{v}_y is the primary inexpressible velocity.

The Hamiltonian with velocity reads

$$H^{\mathrm{v}}(q,p;v) = v_{x}p_{x} + v_{y}p_{y} - \frac{1}{2}v_{x}^{2} - v_{x}y + \frac{1}{2}(x-y)^{2}, \tag{2.6}$$

whilst the total Hamiltonian is

$$H^{\mathsf{t}}\big(q,p;\overline{v}_{x},v_{y}\big) = \frac{1}{2}(p_{x}-y)^{2} + \frac{1}{2}(x-y)^{2} + v_{y}p_{y}. \tag{2.7}$$

Example 2

$$L = \frac{1}{2}\dot{x}^2 + \dot{x}y + \frac{1}{2}(x - y)^2$$
 (2.8)

Primary constraint

$$p_y = 0; (2.9)$$

total Hamiltonian

$$H^{\mathsf{t}} = \frac{1}{2}p_x^2 - p_x y - \frac{1}{2}x^2 + xy + v_y p_y. \tag{2.10}$$

Example 3

$$L = \frac{1}{2}(\dot{q}_2 - e^{q_1})^2 + \frac{1}{2}(\dot{q}_3 - q_2)^2.$$
 (2.11)

2.2 Parametrised systems

Non-relativistic point particle

Kiefer 2012, sec. 3.1.1

$$S[q(t)] := \int_{t_1}^{t_2} \mathrm{d}t \, L\!\left(q, \frac{\mathrm{d}q}{\mathrm{d}t}\right) \tag{2.12}$$

Relativistic charged point particle

Landau and Lifshitz 1975, sec. 16, Kiefer 2012, sec. 3.1.2

$$S := \int -m \, \mathrm{d}s + e A_{\mu}(x) \, \mathrm{d}x^{\mu} =: \int \mathrm{d}\tau \, L, \tag{2.13}$$

where the Lagrangian reads

$$L = -m\sqrt{-\eta_{\mu\nu}\dot{x}^{\mu}\dot{x}^{\nu}} + q\dot{x}^{\mu}A_{\mu}(x). \tag{2.14}$$

$$M_{\mu\nu} := \frac{\partial^2 L^{\mathbf{v}}}{\partial v^{\mu} \partial v^{\nu}} = m \frac{-\eta_{\mu\nu}\eta_{\alpha\beta} + \eta_{\mu\alpha}\eta_{\nu\beta}}{\left(-\eta_{\rho\sigma}v^{\rho}v^{\sigma}\right)^{3/2}} v^{\alpha}v^{\beta}, \tag{2.15}$$

which has one and only one eigenvector with null eigenvalue

$$v^{\mu}M_{\mu\nu} = 0. {(2.16)}$$

Momenta

$$p_{\mu} = \frac{\partial L^{\mathbf{v}}}{\partial v^{\mu}} = \frac{m\eta_{\mu\nu}v^{\nu}}{\sqrt{-\eta_{\rho\sigma}v^{\rho}v^{\sigma}}} + qA_{\mu}. \tag{2.17}$$

If one chooses v^0 to be the primary inexpressible velocity, then eliminating p_0 in eq. (2.17) yields

$$v^{i} = \frac{\xi \eta^{ij} (p_{j} - qA_{j}) v^{0}}{\sqrt{m^{2} + \eta^{kl} (p_{k} - qA_{k}) (p_{l} - qA_{l})}},$$
(2.18)

where $\xi = \operatorname{sgn} v^0$. In the following $\xi = +1$ will be chosen.

Inserting eq. (2.18) into the Hamiltonian with velocity

$$H^{\rm v} = v^{\mu} p_{\mu} - L^{\rm v} = m \sqrt{-\eta_{\mu\nu} v^{\mu} v^{\nu}} + v^{\mu} (p_{\mu} - q A_{\mu}(x)), \tag{2.19}$$

one obtains the total Hamiltonian

$$H^{\rm t} = v^0 \left(p_0 - qA_0 + \sqrt{m^2 + \eta^{kl} (p_k - qA_k)(p_l - qA_l)} \right), \tag{2.20}$$

where only a primary constraint survives, which is obviously a first-class constraint

$$\phi^{(1,1)} = p_0 - qA_0 + \sqrt{m^2 + \eta^{kl}(p_k - qA_k)(p_l - qA_l)}, \tag{2.21}$$

and the canonical Hamiltonian vanishes

$$H^{c} = 0. (2.22)$$

To compare, note in the non-covariant formalism (Landau and Lifshitz 1975, sec. 8)

$$S = \int dt L, \qquad L = -m\sqrt{1 - \dot{\vec{x}}^2} - q\phi + q\dot{\vec{x}} \cdot \vec{A},$$
 (2.23)

the system is regular, and the canonical Hamiltonian reads

$$H^{c} = \sqrt{m^2 + (\vec{p} - q\vec{A})^2} + q\phi,$$
 (2.24)

which corresponds to setting $\phi^{(1,1)}=0,$ $p_0\to -H^{\rm c}$ $(p_\mu=(-E,\vec p))$, and noting $A_\mu=\left(-\phi,\vec A\right)$.

Relativistic point particle with einbein

Blumenhagen, Lüst, and Theisen 2013, sec. 2.1

$$L := \frac{1}{2} \left(e^{-1} \eta_{\mu\nu} \dot{x}^{\mu} \dot{x}^{\nu} - m^2 e \right) \tag{2.25}$$

$$p_{\mu}=\frac{\partial L^{\mathrm{v}}}{\partial v^{\mu}}=e^{-1}\eta_{\mu\nu}v^{\nu}, \qquad p_{e}=0. \tag{2.26}$$

Choosing v^e to be the primary inexpressible velocity, one has

$$v^{\mu} = e\eta^{\mu\nu}p_{\mu}.\tag{2.27}$$

Hamiltonian with velocity

$$H^{\rm v} = v^{\mu} p_{\mu} + v^{e} p_{e} + \frac{1}{2} \left(-e^{-1} \eta_{\mu\nu} v^{\mu} v^{\nu} + m^{2} e \right); \tag{2.28}$$

total Hamiltonian

$$H^{\rm t} = \frac{e}{2} \big(\eta^{\mu\nu} p_{\mu} p_{\nu} + m^2 \big) + v^e p_e; \tag{2.29} \label{eq:2.29}$$

canonical Hamiltonian

$$H^{\rm c} = \frac{e}{2} (\eta^{\mu\nu} p_{\mu} p_{\nu} + m^2). \tag{2.30}$$

The only primary constraint

$$\Phi^{(1,)} = p_e; \tag{2.31}$$

its time evolution

$$\begin{split} \left[\Phi^{(1,)}, H^{\mathsf{t}}\right]_{\mathsf{p}} &= \left[p_{e}, e\right]_{\mathsf{p}} \frac{1}{2} \left(\eta^{\mu\nu} p_{\mu} p_{\nu} + m^{2}\right) \\ &= -\frac{1}{2} \left(\eta^{\mu\nu} p_{\mu} p_{\nu} + m^{2}\right). \end{split} \tag{2.32}$$

Choose

$$\Phi^{(2,)} = \eta^{\mu\nu} p_{\mu} p_{\nu} + m^2, \qquad (2.33)$$

whose Possion bracket with H^{t} vanishes; furthermore,

$$\left[\Phi^{(1,)}, \Phi^{(2,)}\right]_{\mathbf{p}} \equiv 0. \tag{2.34}$$

Thus one ends up with two first-class constraints.

2.2.1 Neutral scalar field

Kiefer 2012, sec. 3.3

2.3 Maxwell-Proca theory

$$\mathcal{L} = -\frac{1}{4}F_{\mu\nu}F^{\mu\nu} - \frac{1}{2}m^2A_{\mu}A^{\mu} + \frac{1}{2}F_{\mu\nu}S^{\mu\nu} + A_{\mu}J_{\rm f}^{\mu}, \tag{2.35}$$

where m>0 corresponds to the Proca theory Gitman and Tyutin 1990, sec. 2.3, and m=0 the Maxwell theory H. J. Rothe and K. D. Rothe 2010, sec. 3.3.3 Gitman and Tyutin 1990, sec. 2.4.

2.4 String theories

Nambu-Gotō action

Generalising the kinetic part of (2.13), one has

$$S_{\text{NG}} := -T \int_{\Sigma} dA =: -T \int_{\Sigma} d^2 \sigma \mathcal{L}, \qquad (2.36)$$

where the Lagrangian density

$$\mathcal{L} = \sqrt{-\Gamma}, \quad \Gamma \coloneqq \det \Gamma_{\alpha\beta}, \quad \Gamma_{\alpha\beta} \coloneqq \frac{\partial X^{\nu}}{\partial \sigma^{\alpha}} \frac{\partial X_{\nu}}{\partial \sigma^{\alpha}}. \tag{2.37}$$

Historically Gotō 1971; Nambu 1970; Reference e.g. Blumenhagen, Lüst, and Theisen 2013 Kiefer 2012, sec. 3.2

Polyakov action

Generalising (2.25)

$$S_{\mathbf{P}}[X^{\mu}, h\alpha\beta] = -\frac{T}{2} \int_{\Sigma} \mathcal{L}, \qquad (2.38)$$

where

$$\mathcal{L} := \sqrt{-h} h^{\alpha\beta} \Gamma_{\alpha\beta}. \tag{2.39}$$

Historically Brink, Di Vecchia, and Howe 1976; Deser and Zumino 1976; Polyakov 1981; Reference Kiefer 2012, sec. 3.2

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