Wightman function of Klein-Fock-Gordon field

Yi-Fan Wang

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Covariant differential 1

 ϕ a C-valued 0-form

$$\mathbb{D}\phi \coloneqq (\mathbf{d} - ieA) \wedge \phi, \qquad \mathbb{D}\phi^* \coloneqq (\mathbf{d} + ieA) \wedge \phi^*, \tag{1.0.1}$$

(2.0.3)

A the $\mathfrak{u}(1)$ -valued connection form.

$\mathbf{2}$ Covariant codifferential

Define the covariant codifferential of a \mathbb{C} -valued k-form ζ as follows. Let η be an arbitrary \mathbb{C} -valued (k-1)-form.

$$\int d(\eta^* \wedge \star \zeta) \equiv \int d\eta^* \wedge \star \zeta - (-)^k \eta^* \wedge d \star \zeta =: \int \mathbb{D}\eta^* \wedge \star \zeta - \eta^* \wedge \star \mathbb{D}^{\dagger} \zeta \quad (2.0.1)$$

$$= \int \mathbb{D}\eta^* \wedge \star \zeta - ieA \wedge \eta^* \wedge \star \zeta - (-)^k \eta^* \wedge d \star \zeta$$

$$= \int \mathbb{D}\eta^* \wedge \star \zeta + \eta^* \wedge (-)^k ieA \wedge \star \zeta - (-)^k \eta^* \wedge d \star \zeta$$

$$= \int \mathbb{D}\eta^* \wedge \star \zeta - \eta^* \wedge \star (-)^k \star^{-1} (d - ieA) \wedge \star \zeta . \quad (2.0.2)$$

$$\boxed{\mathbb{D}^{\dagger} \zeta = (-)^k \star^{-1} (d - ieA) \wedge \star \zeta .}$$

3 Maxwell-Klein-Fock-Gordon theory

$$S = \int -\mathbb{D}\phi^* \wedge \star \mathbb{D}\phi - m^2 \phi^* \wedge \star \phi - \frac{1}{2} F \wedge \star F. \tag{3.0.1}$$

$$\delta \mathbb{D} \phi = -ie\delta A \phi + \mathbb{D} \delta \phi. \tag{3.0.2}$$

$$\begin{split} \delta(\mathbb{D}\phi^* \wedge \star \mathbb{D}\phi) &= \mathbb{d}(\delta\phi^* \wedge \star \mathbb{D}\phi + \delta\phi \wedge \star \mathbb{D}\phi^*) \\ &+ \delta\phi^* \wedge \star \mathbb{D}^\dagger \mathbb{D}\phi + \delta\phi \wedge \star \mathbb{D}^\dagger \mathbb{D}\phi^* \\ &+ \delta A \wedge \left(\mathrm{i}e(\phi^* \star \mathbb{D}\phi - \phi \star \mathbb{D}\phi^*) \right), \end{split} \tag{3.0.3}$$

$$\delta(F \wedge \star F) = 2d(\delta A \wedge \star F) - 2\delta A \wedge d \star F. \tag{3.0.4}$$

$$\begin{split} \delta S &= \int -\mathrm{d}(\delta \phi^* \wedge \star \mathbb{D} \phi + \delta \phi \wedge \star \mathbb{D} \phi^* + \delta A \wedge \star F) \\ &+ \delta \phi^* \wedge \star (\mathbb{D}^\dagger \mathbb{D} - m^2) \phi + \delta \phi \wedge \star (\mathbb{D}^\dagger \mathbb{D} - m^2) \phi^* + \\ &+ \delta A \wedge (-\mathrm{d} \star F + \mathrm{i} e(\phi^* \star \mathbb{D} \phi - \phi \star \mathbb{D} \phi^*)). \end{split} \tag{3.0.5}$$

3.1 Lorenz gauge

$$\Box^2 \coloneqq \left(\mathrm{d} + \mathrm{d}^\dagger\right)^2 = \mathrm{d}\mathrm{d}^\dagger + \mathrm{d}^\dagger\mathrm{d}. \tag{3.1.1}$$

$$d \star F = d \star dA = \star (-)^2 \star^{-1} d \star dA = \star d^{\dagger} dA = \star (\Box^2 - dd^{\dagger}) A. \tag{3.1.2}$$

One would like to have $dd^{\dagger}A = 0$, or $d^{\dagger}A = \text{const.}$ This would be fulfilled if

$$\mathbf{d}^{\dagger} A = 0 \,, \tag{3.1.3}$$

which is the Lorenz gauge[1, 2, 4].

4 Free Klein–Fock–Gordon equation in (d+1)dimensions

In the absence of external electromagnetic field and Cartesian coordinates,

$$0 = (\mathbb{D}^{\dagger} \mathbb{D} - m^2) \phi = (-\partial_t^2 + \partial_x^2 - m^2) \phi. \tag{4.0.1}$$

Linearly independent solutions are

$$\exp\left(\pm\mathrm{i}\!\left(-\omega_{\vec{k}}t+\vec{k}\cdot\vec{x}\right)\right),\qquad \omega_{\vec{k}}=\sqrt{\vec{k}^2+m^2}\,. \tag{4.0.2}$$

One uses the Noether charge to normalise, which reads

$$(\phi_1, \phi_2) = \int d^d x \, j^0 \tag{4.0.3}$$

gives

$$\phi_{+}\left(\omega_{\vec{k}}, \vec{k}; t, x\right) = \frac{1}{\sqrt{2\omega_{\vec{k}}}} \exp\left\{+\mathrm{i}\left(-\omega_{\vec{k}}t + \vec{k} \cdot \vec{x}\right)\right\},$$

$$\phi_{-}\left(\omega_{\vec{k}}, \vec{k}; t, x\right) = \frac{1}{\sqrt{2\omega_{\vec{k}}}} \exp\left\{-\mathrm{i}\left(-\omega_{\vec{k}}t + \vec{k} \cdot \vec{x}\right)\right\},$$
(4.0.4)

For $d \geq 2$,

$$\int \frac{\mathrm{d}^d k}{\left(2\pi\right)^d} \frac{1}{2\omega_{\vec{k}}} \mathrm{e}^{+\mathrm{i}\left(-\omega\,\Delta t + \vec{k}\cdot\Delta\vec{x}\right)} = \int_0^{+\infty} \frac{\mathrm{d} k}{\left(2\pi\right)^d} \frac{k^{d-1} \mathrm{e}^{-\mathrm{i}\omega_{\vec{k}}\,\Delta t}}{2\omega_{\vec{k}}} \int \mathrm{e}^{\mathrm{i}k\,\Delta x\cos\phi_1}\,\mathrm{d}\Omega_{d-1}\,, \tag{4.0.5}$$

where

$$\begin{split} & \int \mathrm{d}\Omega_{d-1} \\ & \coloneqq \int_0^{2\pi} \mathrm{d}\phi_{d-1} \int_0^\pi \sin^{d-2}\phi_1 \sin^{d-3}\phi_2 \dots \sin^1\phi_{n-2} \, \mathrm{d}\phi_1 \, \mathrm{d}\phi_2 \dots \, \mathrm{d}\phi_{d-2} \,. \end{split} \tag{4.0.6}$$

Equipped with

$$\int_0^\pi \sin^\nu \phi \, \mathrm{d}\phi = \pi^{\frac{1}{2}} \frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\Gamma\left(\frac{\nu}{2}+1\right)} \qquad \Re\nu > -1 \,, \tag{4.0.7}$$

one has

$$\int \mathrm{d}\Omega_{d-1} = \frac{2\pi^{\frac{d-1}{2}}}{\Gamma(\frac{d-1}{2})} \int_0^\pi \sin^{d-2}\phi_1 \mathrm{d}\phi_1 \,. \tag{4.0.8}$$

The inner integral in eq. (4.0.5) turns to be

$$\begin{split} \int \mathrm{e}^{\mathrm{i}k\,\Delta x\cos\phi_1}\,\mathrm{d}\Omega_{d-1} &= \frac{2\pi^{\frac{d-1}{2}}}{\Gamma\left(\frac{d-1}{2}\right)}\int_0^\pi \mathrm{e}^{\mathrm{i}k\,\Delta x\cos\phi_1}\sin^{d-2}\phi_1\,\mathrm{d}\phi_1 \\ &= \frac{2\pi^{\frac{d-1}{2}}}{\Gamma\left(\frac{d-1}{2}\right)}\int_0^\pi \cos(k\,\Delta x\cos\phi_1)\sin^{d-2}\phi_1\,\mathrm{d}\phi_1 \\ &= \frac{2\pi^{\frac{d-1}{2}}}{\Gamma\left(\frac{d-1}{2}\right)}\frac{\pi^{\frac{1}{2}}\Gamma\left(\frac{d-1}{2}\right)}{\left(\frac{k\,\Delta x}{2}\right)^{\frac{d}{2}-1}}J_{\frac{d}{2}-1}(k\,\Delta x) \\ &= (2\pi)^{\frac{d}{2}}\frac{J_{\frac{d}{2}-1}(k\,\Delta x)}{(k\,\Delta x)^{\frac{d}{2}-1}} \end{split} \tag{4.0.9}$$

using [3, eq. (10.9.4)]. Now eq. (4.0.5) turns to be

$$\int_{0}^{+\infty} \frac{\mathrm{d}k}{(2\pi)^{\frac{d}{2}}} \frac{k^{d-1} \mathrm{e}^{-\mathrm{i}\omega_{\vec{k}}} \Delta t}{2\omega_{\vec{k}}} \frac{J_{\frac{d}{2}-1}(k \Delta x)}{(k \Delta x)^{\frac{d}{2}-1}} \,. \tag{4.0.10}$$

For $\Delta t > \Delta x$, choose a frame in which $\Delta x = 0$. Using [3, eq. (10.2.2)], one has

$$\lim_{x \to 0} \frac{J_{\nu}(k \Delta x)}{\left(k \Delta x\right)^{\nu}} = \frac{1}{2^{\nu} \Gamma(\nu + 1)}$$

$$(4.0.11)$$

References

References

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