

CMPT231

Lecture 13: ch34

Tractability, Semester Review

1 Corinthians 1:18-21 (ESV)

For the word of the **cross** is **folly** to those who are perishing,
but to us who are being saved it is the **power** of God.

19 For it is written, “I will destroy the **wisdom** of the wise,
and the **discernment** of the discerning I will thwart.”

20 Where is the one who is **wise**? Where is the **scribe**?
Where is the **debater** of this age?
Has not God made **foolish** the wisdom of the world?

Outline for today

- **All-pairs** shortest path
 - **Johnson** (reweighted Dijkstra):
 $O(|V|^2 \log |V| + |V||E|)$
- **Tractability**
 - Complexity **classes**: **P**, **EXP**, **R**
 - **Non-deterministic** verification: **NP**
 - NP-**hard** and NP-**complete**
- Semester **review**

All-pairs shortest path

- **Bellman-Ford** on each vertex: $O(|V|^2|E|)$
- Dyn prog by **path length**: $O(|V|^3 \log|V|)$
- **Floyd-Warshall** (by **subset** of **V**): $O(|V|^3)$
- **Johnson** (**Dijkstra** on each vertex):
 $O(|V|^2 \log|V| + |V||E|)$
 - **Reweight** edges for positive weights

Johnson's reweighting

- Johnson's trick: Add a **new** vertex s
 - Add **zero-weight** edges from s to all vertices:
 - $V' = V \cup \{s\}$,
 - $E' = E \cup \{(s,v) : v \in V\}$, and $w(s,v) = 0 \forall v$
 - **Compute** $y(s,v) \forall v$ (e.g., with Bellman-Ford)
 - **Reweight** edges using $h(v) = y(s,v)$



Johnson reweight, Fig-25-6(ab)

Johnson's reweighting

- Why does this eliminate **negative weights**?
 - **Triangle inequality**: $y(s,v) \leq y(s,u) + w(u,v)$
 - Substitute **defn** of h : $h(v) \leq h(u) + w(u,v)$
 - Apply **reweighting**: $w'(u,v) = w(u,v) + h(u) - h(v) \geq 0$



Johnson reweight, Fig-25-6(ab)

Johnson all-pairs

```
def Johnson( G, w ):  
    create G' = (V', E') with new vertex s  
    BellmanFord( G', w, s )  
  
    # find dlt[ s, v ]: O(VE)  
    if returned FALSE, quit  
  
    # net-neg cycle  
    w'[ u, v ] = w[ u, v ] + dlt[ s, u ] - dlt[ s, v ]  
    for u in V:  
        Dijkstra( G, w', u )  
  
    # find dlt'[ u, v ]: O(VlgV + E)  
    for v in V:  
        d[ u, v ] = dlt'[ u, v ] - dlt[ s, u ] + dlt[ s, v ]  
    return d
```

- Innermost loop **converts** back to original weighting
- **Complexity**: $O(|V|^2 \log|V| + |V||E|)$

All-pairs shortest path: summary

- **Negative** edges allowed (but not net-negative **cycles**)
- **Floyd-Warshall**: $O(|V|^3)$
 - Dyn prog by **subset** of vertices for intermediate nodes
- **Johnson**: $O(|V|^2 \log|V| + |V||E|)$
 - **Bellman Ford** from new source **s**
 - **Reweight**: $h(v) = y(s,v)$ and $w'(u,v) = w(u,v) + h(u) - h(v)$
 - Run **Dijkstra** from each vertex

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Decision problems


- Phrase problem as yes/no **decision**:
 - **Input**: a string s (e.g., encoded in binary)
 - **Problem**: a set of strings X
 - **Algorithm** A returns boolean:
$$A(s) = \text{true} \Leftrightarrow s \in X$$
- **Complexity** of A in terms of **length** n of s
- e.g., given graph (V, E, w) , is there a **path** of weight ≤ 4 between nodes u and v ?
 - **Input** s includes entire **graph** spec, “4“, u , and v
 - **Floyd-Warshall**: $O(|V|^3) = O(n^3)$
- e.g., given an integer j , is it **prime**?

Turing machine model

- General model of **computation**
 - Infinite **tape** using finite **symbol** set (plus blank)
 - **Head** can read, write, and move left/right
 - Machine has a finite **state space** and **transitions**:
 - Instructions for when to **change** internal states
- ![Alan Turing] ![Turing machine]
static/img/alan-turing.jpg) (static/img/turing-machine-
2.png)

Complexity classes

- **P**: decision problems for which **polynomial-time** algorithms exist (“tractable”)
 - **Most** of the algorithms in this course! $O(n^c)$
- **EXP**: problems solvable in **exponential** time: $O(2^{n^c})$
- **R**: problems solvable in **finite** time
 - **R** = “**recursive**” (Turing 1936, Church 1941)



P, EXP, and
R

Examples

- Does a weighted graph have a **net-negative cycle**?
 - In **P**: e.g., **Bellman-Ford** $O(|V||E|) = O(n^2)$
- Given a **chess** board configuration ($n \times n$), can White **win**?
 - In **EXP** (exhaustive search) but **not** in **P**
- Given a **Tetris** board + seq of pieces, can you **survive**?
 - In **EXP** but not **known** whether in **P**
- Given a computer **program** and **input**, does it **halt**?
 - Automated **infinite loop** checker
 - **Uncomputable!** ($\notin R$)
 - **Cannot** solve in **finite** time for **all** programs, for

Halting problem

- Assume $\text{Halt}(P, s)$ solves the **halting problem**:
 - Input two strings: a **program** P and an **input** s to P
 - Outputs $\text{TRUE} \Leftrightarrow P(s)$ **halts**
- Now, consider the following **program**:

```
def Koan( X ):  
    if Halt( X, X ):  
        loop forever  
Koan( Koan )
```

- Case 1: $\text{Koan}(\text{Koan})$ **halts**.
 - $\Rightarrow \text{Halt}(\text{Koan}, \text{Koan}) = \text{TRUE}$ (by correctness of Halt)

$\text{Koan}(\text{Koan})$ loops forever (by code of Koan)

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NP

- **Certification** algorithm: instead of saying whether $s \in X$,
 - Check a proposed **proof** t that $s \in X$:
- $C(s,t)$ is a **certifier** for problem X if for every s :
 - $s \in X \Leftrightarrow \exists$ **certificate** t such that $C(s,t) = \text{TRUE}$
- **NP** (nondeterministic polynomial): all problems X which have a **polynomial**-time **certifier**:
 - $C(s,t)$ runs in polynomial time
 - Certificate t is of polynomial size: $|t| \in O(|s|^c)$
- **Nondeterministic** Turing machine:
 - Can make lucky **guesses** of t and **check** in

Examples of NP

e.g., **Tetris** \in NP:

- Given sequence of moves, can easily **check** if survive
- **Rules** are simple; **strategy** is hard

Most **games**: checkers, Minesweeper, Sudoku, etc.

Travelling salesman problem (TSP):

- **Shortest** path visiting **every** vertex in weighted graph
- **Decision** version: is min weight $\leq x$?

Satisfiability (3-SAT):

- Boolean formula in **conjunctive normal form** (CNF):
 - $(x_1 \text{ or } x_2 \text{ or } x_3)$ and $(x_4 \text{ or } x_5 \text{ or } x_6)$ and $(x_7 \text{ or } x_8)$
 - Each **clause** is an **OR** of up to 3 Boolean variables

cnf formula is an **AND** of all clauses

P vs NP

- $P \subseteq NP \subseteq EXP$
 - For any P problem, can **solve** \Rightarrow can find **certificate t**
 - For any NP problem, can try **every string t** with $|t| < n$
- Million-dollar question (Clay prize): $P = ? NP$
 - Is it easier to **check** a proof than **construct** one?
 - Can't “**engineer luck**”

Reductions

- **Convert** your problem into one with a known solution
 - **unweighted** shortest path \rightarrow **weighted** shortest path:
 - set all **edge weights** to 1
 - **longest** path \rightarrow **shortest** path (**negate** weights)
- Problem **X reduces** (poly, Cook) to **Y**, ($X \geq_p Y$) iff:
 - Can solve **X** using a polynomial number of **calls** to a solution of **Y**, plus polynomial additional work
 - Model of **computation** (**subroutines**)
 - **X is at least as hard as Y**

NP-hard and NP-complete

- $X \in \text{NP-hard} \Leftrightarrow X \geq_p Y$ for all $Y \in \text{NP}$
 - “at least as hard as NP”
- $\text{NP-complete} = \text{NP} \cap \text{NP-hard}$
 - all NP-complete problems are “the same” difficulty (mod poly)
 - If any one is in P, then they all are, and $P = \text{NP}$

NP
complete

Examples of NP-complete

- 3-SAT, TSP, 0-1 knapsack (pseudo-poly)
- 3-partition: split n integers into triples of equal sum?
- 3-colouring of graphs (no adj nodes share colour)
- Find largest clique in a graph (fully connected subset)
- Shortest path in 3D avoiding obstacles
- Factoring integers is NP but unknown if NP-hard
- Chess (generalised to $n \times n$) is EXP-complete
- Protein folding, urban traffic flow equilibrium, optimal meshing for FEM, max social welfare in Nash equilib, ...
- Foundational textbook: Garey + Johnson,

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Semester overview

- **Complexity:** V O I o ω , recurrence, induction (ch1-5)
- **Sorting** (ch4-8)
 - Comparison sorts: insert, merge, heap, quick
 - Linear sorts: counting, radix, bucket
- **Data Structures** (ch10-12, 18)
 - Hash tables, linked lists, BST*s, *B-trees
- **Divide and Conquer** (ch15-16)
 - Dynamic prog: rod cut, matrix-chain, LCS, opt BST
 - Greedy: act sel, list merge, Huffman, frac knapsack

Lecture 1: ch1-3

- **Insertion** sort and its **analysis**
- Discrete **math** review
 - **Logic** and proofs
 - Monotonicity, limits, iterated functions
 - **Fibonacci** sequence and golden ratio
 - Factorials and **Stirling's** approximation
- **Asymptotic** notation: V , O , Θ , o , ω
 - **Proving** asymptotic bounds

Lecture 2: ch4-5

- **Divide and conquer** (ch4)
 - **Merge** sort and its **analysis**
 - Recursion trees + proof by **induction**
 - Maximum **subarray**
 - Matrix multiply vs **Strassen**'s method
 - **Master method** of solving recurrences
- **Probabilistic Analysis** (ch5)
 - **Hiring** problem and analysis
 - **Randomised** algorithms and PRNGs

Lecture 3: ch6-7

- **Heapsort** (ch6) :
 - Trees, binary **heaps**, **max-heap** property
 - **Heapify()** function on a node
 - **Heapsort**: build a max-heap, use it for sorting
 - **Priority queue** using max-heap: operations, complexity
- **Quicksort** (ch7) :
 - Regular quicksort with **fixed** (Lomuto) partitioning
 - **Randomised** pivot
 - Analysis of randomised pivot: **expected** time

Lecture 4: ch8,11

- **Linear**-time sorts (ch8) (**assumptions!**)
 - **Decision-tree** model, why comparison sorts are $\Theta(n \lg n)$
 - **Counting** sort: census + move: $\Theta(n+k)$, **stability**
 - **Radix** sort (with r -bit digits): $\Theta(d(n+k))$
 - **Bucket** sort: $\Theta(n)$ **expected** time
- **Hash** tables (ch11):
 - Hash **function**, hash **collisions**, **chaining**
 - **Load factor** $v = n/\text{num_buckets}$
 - **Search** in $\Theta(1+v)$
 - **Hashes**: div, mul, universal hashing
 - **Open addressing**: linear, quad, double-hash

Lecture 5-6: ch10,12,18

- **Linked lists** (ch10):
 - Singly/**doubly**-linked, **circular**
- **Stacks** and **queues** (ch10):
 - Operations, implementation with linked-lists
- **Trees** and Binary search trees (**BST**) (ch12):
 - Tree **traversals**: inorder, preorder, postorder
 - **Search**, **Min**/max and **successor**/pred
 - **Insert** and **delete**
 - **Randomised** BST
- **Skip lists**: implementation, complexity
- **B-Trees** (ch18)

Lecture 8: ch15

- **Dynamic programming**
 - **Rod-cutting** problem
 - Proving optimal **substructure**
 - Recursive, top-down, **bottom-up** solutions
- **Fibonacci** sequence
- **Matrix-chain** multiplication
- Longest common **subsequence**
- Shortest unweighted **path**
- Optimal **binary search tree**

Lecture 9: ch16

- **Greedy** algorithms
 - Proving optimal **substructure**
 - Proving **greedy property**
- **Activity selection** problem
- **List merging** problem
- **Huffman** coding
- **Knapsack** problem: **fractional** and **0-1**
- Optimal offline **caching**

Lecture 10: ch22

- **Graph** representation:
 - Edge list, **adjacency list**, adjacency matrix
- **Breadth-first** graph traversal
- **Depth-first** graph traversal
 - **Parenthesis** structure
 - Edge **classification**
 - Topological **sort**
 - Finding **strongly-connected** components

Lecture 11-12: ch23-25

- **Minimum spanning tree (MST)**
 - **Kruskal** (disjoint-set forest): $O(|E|\log|E|)$
 - **Prim** (priority queue): $O(|V|\log|V| + |E|)$
- **Single-source** shortest paths
 - **Bellman-Ford**: $O(|V||E|)$
 - Special case for **DAG** (no cycles)
 - **Dijkstra** (weights ≥ 0): $O(|V|\log|V| + |E|)$
- **All-pairs** shortest paths
 - **Dynamic** programming by path length: $O(|V|^4)$
 - **Exponential** speedup: $O(|V|^3 \log|V|)$
 - **Floyd-Warshall** (dyn prog by vertex subset):

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