

The background of the slide is a photograph of several hands holding various autumn leaves. The leaves are in shades of yellow, orange, and red. The hands are positioned around the central text, with some fingers holding the stems of the leaves. The overall lighting is soft, and the colors are muted, giving it a calm, seasonal feel.

CMPT231

Lecture 8: ch15

Dynamic Programming

Ephesians 4:1-3 (NASB)

Therefore I, the **prisoner** of the Lord, implore you
to **walk** in a manner **worthy of the calling**
with which you have been called,
with all **humility** and **gentleness**, with **patience**,
showing **tolerance** for one another in love,
being diligent to preserve the **unity** of the Spirit
in the bond of **peace**.

Outline for today

- **Dynamic programming**
 - **Rod-cutting** problem
 - Optimal **substructure**
 - Recursive, top-down, **bottom-up** solutions
- **Fibonacci** sequence
- **Matrix-chain** multiplication
- Longest common **subsequence**
- Shortest unweighted **path**
- Optimal **binary search tree**

Optimisation

- Large class of **real-world** problems consisting of
 - Finding the **max** (or min) value of some **goal** (cost) function over some **search space**
- **Search space**: may be **discrete** or **continuous**
 - **Dimension** of space may be **low** or very **high** (10^6 or more)
- **Goal** function: may be **analytic** or a **black-box**
 - Are its **derivatives** computable?

Exhaustive search is usually way too **slow**

![Saddle point between maxima, [Wikin

Dynamic programming

- “Programming” here means **tables**
 - (e.g., linear “programming”)
- A form of **divide-and-conquer**, but
 - Store solutions to **sub-problems** for reuse
- Efficiency depends on:
 - Optimal **substructure**
 - **Overlapping** sub-problems
- Thought **process** to design solution:
 - **Recurrence** yields a recursive **top-down** solution (inefficient)
 - Top-down with **memoisation** (save **sub-results**)
 - **Bottom-up** (solve **smaller** sub-problems first.)

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Rod-cutting problem

- Steel **rods** of length i sell for $\$p_i$ each ($1 \leq i \leq n$)
- **Cut** a rod of length n so as to maximise **revenue**
 - Assume **cuts** are free
- Input: **price table** $p = [1, 5, 8, 9]$
 - So in this case rod **length** $n = 4$
 - **Exhaustive**: $\$9, 8+1, 1+8, 5+5, 5+1+1, 1+5+1, 1+1+5, 1+1+1+1$
 - **Optimal** solution: two pieces of length 2: $\$5+5$
- For fixed p , let r_n be the optimal **revenue** for length n
 - In this case, $r_n = 10$

Rod-cut: example

	i:	1	2	3	4	5	6	7	8
	p:	1	5	8	9	10	17	17	20
n:	0	1	2	3	4	5	6	7	8
r[n]:	0	1	5	8	10	13	17	18	22
cuts:	0	1	2	3	2+2	2+3	6	1+6, 2+2+3	2+6

May have **multiple** optimal solutions, with **same** r_n

Rod-cut: substructure

- Optimise **one cut** at a time, left to right
 - Assume the first piece **won't** be cut again
- Optimise **revenue** r_n by considering possible cuts:
 - cut of length **1**: $r_n = p_1 + r_{n-1}$
 - cut of length **2**: $r_n = p_2 + r_{n-2}$
 - ...
 - cut of length **n**, i.e., **no** cuts: $r_n = p_n$
- **Recurrence** relation: $r_n = \max_{i=1 \dots n} (p_i + r_{n-i})$
- Decomposes overall task into **subproblems** r_i
- Translates directly into a **recursive** solution

Requirements for dyn prog

- To use **dynamic programming**, we need two properties:
- **Optimal substructure:**
 - Optimal solution to **subproblem** results in optimal solution to **overall** problem
 - I.e., any optimal solution can be **composed** of solutions to subproblems
- **Overlapping subproblems:**
 - Subproblems appear in **multiple** branches of recursion tree
 - Allows **reuse** of solutions, giving us efficiency

Rod-cut: optim substruct

- Let A_n be an optimal solution for **entire** length n
 - Let i be location of **first** cut in A_n
 - Let A_{n-i} be the **remaining** cuts in A_n
- **Claim:** A_{n-i} is optimal for length $n-i$
 - Assume **not**: let B_{n-i} be a **better** solution for $n-i$
 - $\text{revenue}(B_{n-i}) > \text{revenue}(A_{n-i})$
 - Then we can **improve** on A_n by combining this with i :
 - Let $B_n = [i, B_{n-i}]$, then
 - $\text{rev}(B_n) = p[i] + \text{rev}(B_{n-i}) > p[i] + \text{rev}(A_{n-i}) = \text{rev}(A_n)$

Overlapping subproblems

- Optimal substructure shows recursive solution is **correct**
- To get **efficiency** of dynamic programming, we also need to **reuse** subproblems
- **Taxonomy** of subproblems:
 - Index subproblems by **length** of rod (n)
- **Reuse** solutions to subproblems:
 - A solution for length 5 works **anywhere** within longer rods
 - Only depends on **length**, not **location**
 - So solutions to **small** rods like $n=2$ can be reused

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(1) Recursive top-down

```
def cutRod( p, n ):
    if ( n < 1 ): return 0
    q = -infinity
    for i = 1 .. n:
        q = max( q, p[ i ] + cutRod( p, n-i ) )
    return q
```

- **Naive** implementation of recurrence
- Recursion **tree**?
- $T(n) = 2^n$ (#15.1-1)
 - Increase **n** by 1 \Rightarrow **double** run time!
- E.g., **cutRod(p, 2)** run many times

(2) Top-down w/memoisation

```
revenue = array[ 0 .. n ] of -infinity
revenue [ 0 ] = 0
def cutRod( p, n ):
    if revenue[ n ] != -infinity:
        return revenue[ n ]
    for i = 1 .. n:
        revenue[ n ] = max( revenue[ n ], p[ i ] + cutRod( p, n-i ) )
    return revenue[ n ]
```

- **Memoisation**: cache previously-computed results
 - Need to **reset** cache for each new price table p
- $\text{cutRod}(p, n)$ only computed **once** for each n
 - if result not in cache, takes $\Theta(n)$ to compute
 - **Complexity**: $\sum_i \Theta(i) = \Theta(n^2)$
- Can we eliminate the **recursion**?

(3) Bottom-up (dyn prog)

```
def cutRod( p, n ):
    revenue = array[ 0 .. n ] of -infinity
    revenue[ 0 ] = 0
    for j = 1 .. n:
        for i = 1 .. j:
            revenue[ j ] = max( revenue[ j ], p[ i ] + revenue[ j-i ] )
    return revenue[ n ]
```

- Start from **smaller** subproblems, caching as we go
- Doubly-nested **for** loop computes each **cutRod(j)**
- **Sequence** subproblems to satisfy dependencies
- **Complexity:** $\sum_i \Theta(j) = \Theta(n^2)$

Subproblem graph

- **Nodes** are the subproblems (e.g., `cutRod(j)`)
- **Arrows** show dependencies:
 - Other nodes ****needed**** to compute this node
 - Like recursion **tree**, but collapsing reused nodes
- **Top-down**: performs a **depth-first** search down to leaves
- **Bottom-up**: must **sequence** nodes to resolve dependencies before reaching a node

![[node graph]
(static/img/Fig-
15-4.svg)

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Fibonacci sequence

Recall: $F_n = F_{n-1} + F_{n-2}$, with $F_0 = F_1 = 1$

Closed-form solution: $\Theta(1)$

```
def fib( n ):
    return round( pow( phi, n ) )
```

Naive top-down: $\Theta(2^n)$

```
def fib( n ):
    if ( n < 2 ): return 1
    return fib( n-1 ) + fib( n-2 )
```

Fibonacci: dynamic prog

Top-down with memo: $\Theta(n)$

```
c = array[ 0 .. n ] of -1
c[ 0 ] = c[ 1 ] = 1
def fib( n ):
    if ( c[ n ] > 0 ): return c[ n ]
    c[ n ] = fib( n-1 ) + fib( n-2 )
    return c[ n ]
```

Bottom-up (dynamic programming): $\Theta(n)$

```
def fib( n ):
    c = array[ 0 .. n ] of -1
    c[ 0 ] = c[ 1 ] = 1
    for j = 2 .. n:
        c[ j ] = c[ j-1 ] + c[ j-2 ]
    return c[ n ]
```

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Matrix-chain multiplication

- Given a **chain** of n matrices to multiply:
 - $A_1 * A_2 * A_3 * \dots * A_n$
 - num **columns** of **left** matrix = num **rows** of **right** matrix
 - $(p_0 \times p_1)(p_1 \times p_2) \dots (p_{n-1} \times p_n)$
- All **parenthesisations** are equivalent, but which **minimises** number of operations?
 - Recall dimensions of product matrix:

$$(p \times q)(q \times r) = (p \times r)$$
- Input** is a list of matrix dimensions: $\{p_i\}_0^n$
- e.g.: $(5 \times 500) (500 \times 2) (2 \times 50)$:

$$(A_1 A_2) A_3: (5)(500)(2) + (5)(2)(50) = 5500 \text{ ops}$$

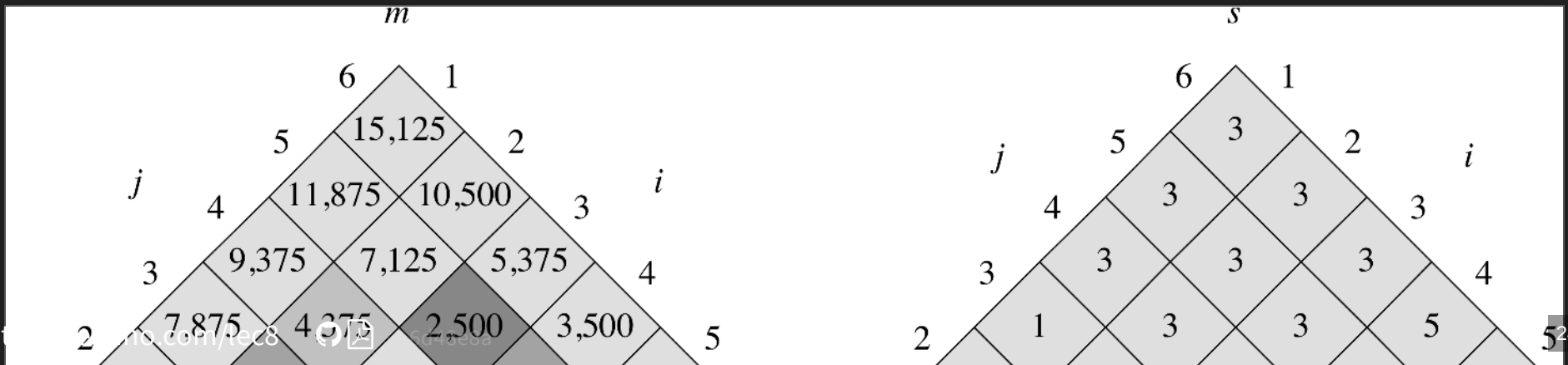
Optimal substructure

- Let $c(i, j)$ be min **cost** to multiply A_i, \dots, A_j
- Consider one **split** at a time (like **rod-cut**)
- If the chain from i to j is split at k , the cost is:
$$c(i, j) = c(i, k) + c(k + 1, j) + p_{i-1}p_kp_j$$
- **Naive** solution uses $2n$ recursive calls per loop: $\Theta(2^n)$

```
def matChain( p, i, j ):
    if (i == j): return 0
    cost = infinity
    for k = i .. j-1:
        cost = min( cost,
                    matChain( p, i, k ) + matChain( p, k+1, j ) + p[ i-1 ] * p[
    return cost
```


Bottom-up solution

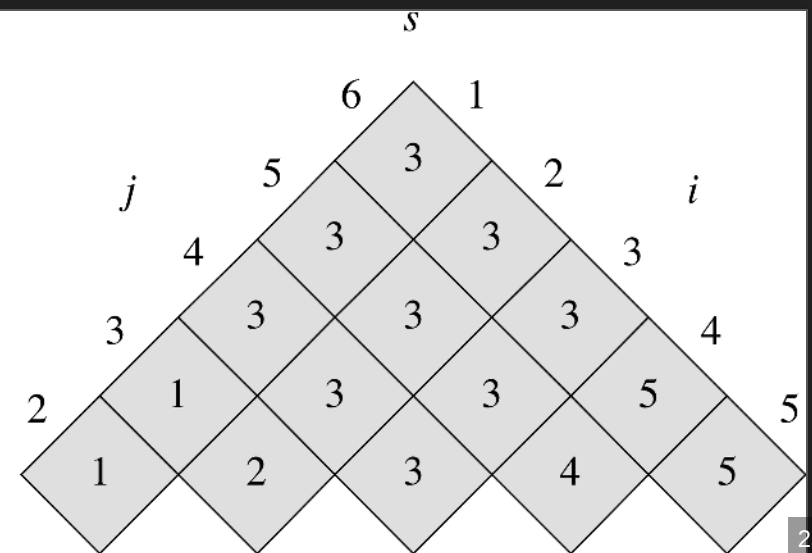
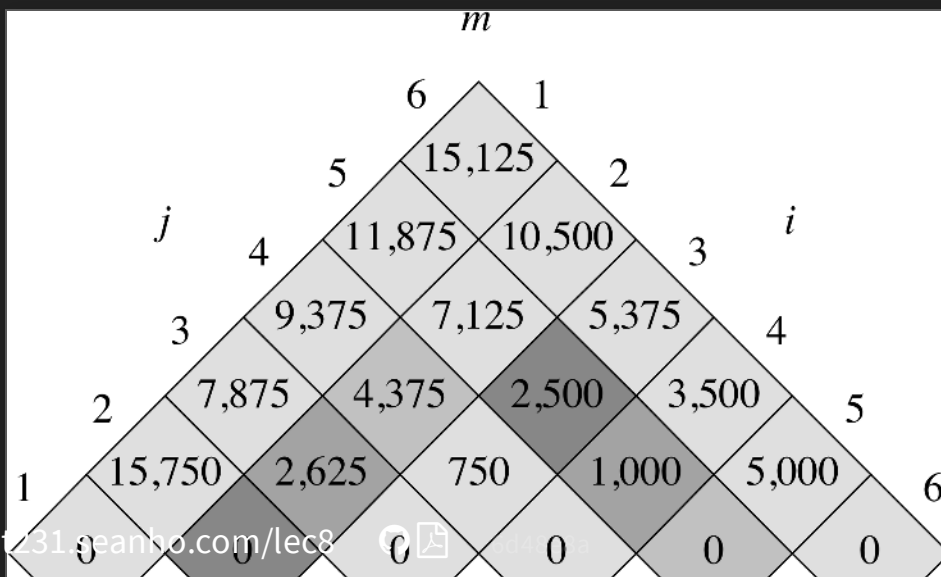
- Index subproblems by both **start** (i) and **end** (j):
 - Taxonomy is a 2D **grid** of nodes, not 1D line
- Save minimal **cost** in matrix $c[i, j]$
 - Save **split** point k in matrix $s[i, j]$
- $p = [30, 35, 15, 5, 10, 20, 25]$ ($n=7$)
 - at $(i, j) = (2, 5)$, $k = 3$: $c[2, 5] = c[2, 3] + c[4, 5] + 35 \times 5 \times 20 = 7125$



```

def matChain( p ):
    n = length(p) - 1
    c = array[ 1 .. n ][ 1 .. n ] of 0
    s = array[ 1 .. n-1 ][ 2 .. n ]
    for len = 2 .. n:
        for i = 1 .. n - len + 1:
            j = i + len - 1
            c[ i, j ] = infinity
            for k = i .. j-1:
                q = c[ i, k ] + c[ k+1, j ] + p[ i-1 ] * p[ k ] * p[ j ]
                if q < c[ i, j ]:
                    c[ i, j ] = q
                    s[ i, j ] = k

```



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Longest common subsequence

- Given two **sequences**: $X = \{x_i\}_1^m, Y = \{y_i\}_1^n$
 - Find longest **subsequence** common to both X and Y
 - Need not be **consecutive**, but must be in **order**
- E.g.: $\text{LCS}(\text{"springtime"}, \text{"pioneer"}) = \text{"pine"}$
 - $\text{LCS}(\text{"horseback"}, \text{"snowflake"}) = \text{"oak"}$
 - $\text{LCS}(\text{"heroically"}, \text{"scholarly"}) = \text{"holly"}$
- **Exhaustive** check:
 - for each of the 2^m **subsequences** of X ,
 - **check** (in $\Theta(n)$ time) if it's a subsequence of Y

LCS: optimal substructure

- Let $X_k = \{x_i\}_1^k$ represent a **prefix** of X
- Let $Z = \{z_i\}_1^k$ be any **LCS** of X and Y
- **Theorem (part 1)**: If $x_m = y_n$,
then (a) $z_k = x_m = y_n$
and (b) Z_{k-1} is an **LCS** of X_{m-1} and Y_{n-1}
- **Theorem (part 2)**: If $x_m \neq y_n$ and $z_k \neq x_m$,
then Z is an **LCS** of X_{m-1} and Y
- **Theorem (part 3)**: If $x_m \neq y_n$ and $z_k \neq y_n$,
then Z is an **LCS** of X and Y_{n-1}
- This theorem says that an LCS of two sequences contains (as prefix) an LCS of prefixes of the two sequences

Proof of optimal substruct (part 1)

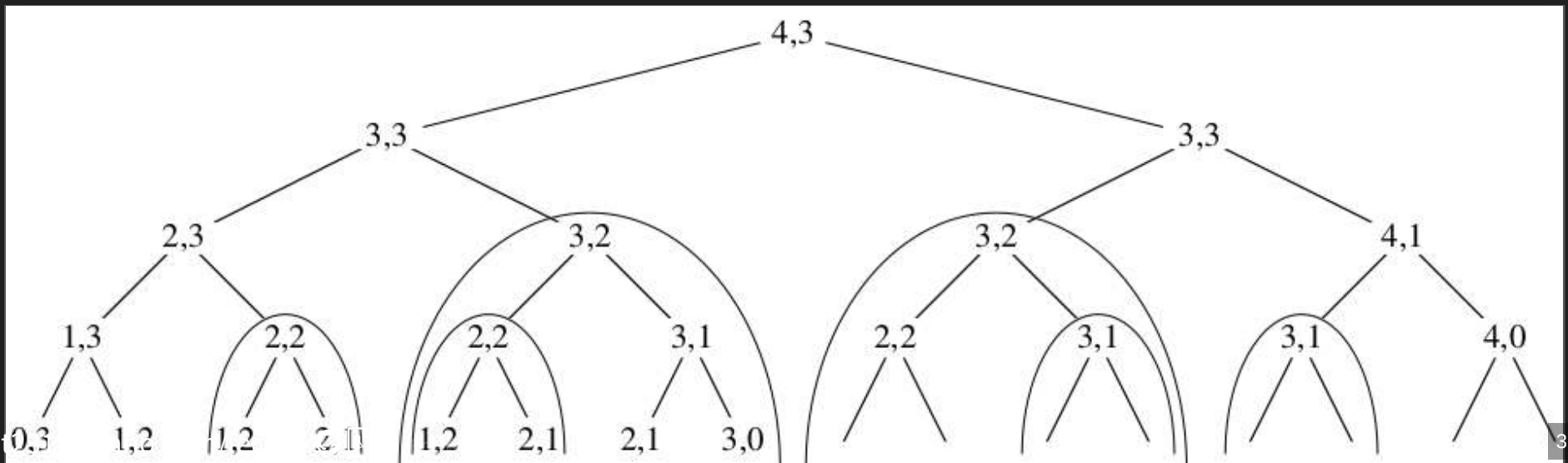
- Assume Z is an **LCS** of X and Y , and $x_m = y_n$
- **Part 1a**: Show $z_k = x_m = y_n$:
 - Assume **not**: then create Z' by **appending** x_m to Z :
 - i.e., let $Z' = (z_1, \dots, z_k, x_m)$
 - Z' is also a subsequence of X and Y , and it's **longer** than Z
 - This **contradicts** assumption that Z was an LCS of X and Y
- **Part 1b**: Show Z_{k-1} is an **LCS** of X_{m-1} and Y_{n-1} :
 - It's certainly a **subseq** of X_{m-1} and Y_{n-1} (it just

Proof of opt substruct (parts 2-3)

- Assume Z is an **LCS** of X and Y , and $x_m \neq y_n$
- **Part 2** ($z_k \neq x_m$): Show Z is an LCS of X_{m-1} and Y .
 - Let W be a subseq of X_{m-1} and Y , with length $> k$
 - Then W is also a subseq of X and Y , **longer** than Z
 - This **contradicts** assumption that Z was an LCS of X and Y
- **Part 3** ($z_k \neq y_n$) is **symmetric**
- Thus in all cases, any **LCS** of X and Y has a **prefix** which is an **LCS** of prefixes of X and Y

LCS recurrence

- Let $c[i, j]$ = length of LCS of X and Y . Then
- $$c[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ c[i - 1, j - 1] + 1 & \text{if } (i, j) > 0 \text{ and } x_i = y_j \\ \max(c[i - 1, j], c[j, i - 1]) & \text{if } (i, j) > 0 \text{ and } x_i \neq y_j \end{cases}$$
- LCS only gets **extended** by a character in case 2
- e.g., LCS("bozo", "bat") [(3,3) on rhs should be (4,2)]



LCS solution

```
def LCSLength( x, y ):
    ( m, n ) = length( x, y )
    b[ 1 .. m ][ 1 .. n ] = new array
    c[ 0 .. m ][ 0 .. n ] = 0
```

```
for i = 1 .. m:
    for j = 1 .. n:
        if x[ i ] == y[ j ]:
            c[ i, j ] = c[ i-1, j-1 ] + 1
            b[ i, j ] = "UL"
        elif c[ i-1, j ] >= c[ i, j-1 ]:
            c[ i, j ] = c[ i-1, j ]
            b[ i, j ] = "U"
        else:
            c[ i, j ] = c[ i, j-1 ]
            b[ i, j ] = "L"
```

Complexity: $\Theta(mn)$

What do "*spanking*" and
"*amputation*" have in
common?

	a	m	p	u	t	a	t	i	o	n
	0	0	0	0	0	0	0	0	0	0
s	0	0	0	0	0	0	0	0	0	0
p	0	0	0	1	1	1	1	1	1	1
a	0	1	1	1	1	1	2	2	2	2
n	0	1	1	1	1	1	2	2	2	3
k	0	1	1	1	1	1	2	2	2	3
i	0	1	1	1	1	1	2	2	3	3
n	0	1	1	1	1	1	2	2	3	4
g	0	1	1	1	1	1	2	2	3	4

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Shortest/longest path

- Given an unweighted **graph** (nodes + edges)
 - Find **shortest** path between given nodes u and v
- Optimal **substructure**:
 - If path is **split** at node w , then
 - **Concatenating** shortest paths $u \rightarrow w$ and $w \rightarrow v$
 - Yields a **shortest** path from u to v through w
- What about **longest** path $u \rightarrow v$?
 - Obviously need to rule out **cycles**
- **Concatenate** $\text{longest}(u, w) + \text{longest}(w, v)$?
 - **Doesn't work!** Might not be **longest** $u \rightarrow v$

! [Counter-example for longest path]
(static/img/Fig-15-6.svg)

Optimal BST

- Given sorted **keys** $\{k_i\}_1^n$ and **probabilities** $\{p_i\}_1^n$
 - Build tree to minimise expected **search cost**
- Recall cost for **successful** search is $\Theta(h(k))$ (depth of key)
- To handle **unsuccessful** searches:
 - Add **dummy** keys $\{d_i\}_0^n$ as leaves
 - Dummy key d_i represents entire **interval** (k_{i-1}, k_i)
 - Input q_i as **probability** of d_i
- **Probabilities** over all search keys: $\sum p_i + \sum q_i = 1$
- Expected **search cost**:

$$\sum (h(k_i) + 1)p_i + \sum (h(d_i) + 1)q_i$$

Optimal substructure

- Consider one **split** at a time: choice of **root**
- Given keys k_i, \dots, k_j :
 - Consider making k_r the **root** ($i \leq r \leq j$)
 - Recurse on **left** subtree: k_i, \dots, k_{r-1}
 - Recurse on **right** subtree: k_{r+1}, \dots, k_j
- **Demoting** a subtree increments **depth** to each node
 - Increases **search cost** by

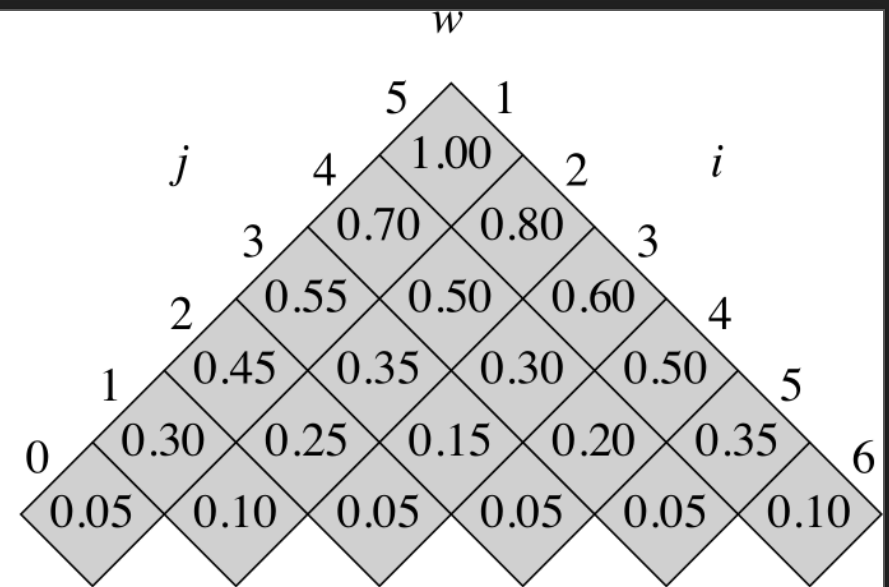
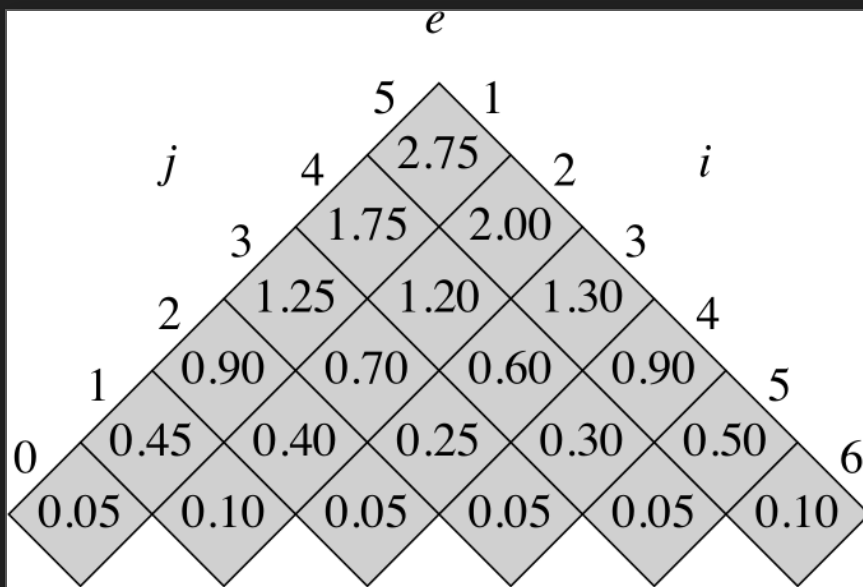
$$w(i, j) = \sum_{m=i}^j p_m + \sum_{m=i-1}^j q_m$$

- So **cost** is

$$e(i, j) = \min_{r=i \dots j} [e(i, r-1) + e(r+1, j) + w(i, j)]$$

Optimal BST example

i	0	1	2	3	4	5
p	-	0.15	0.10	0.05	0.10	0.20
q	0.05	0.10	0.05	0.05	0.05	0.10



root

Complexity of dyn prog

- Optimal substructure **varies** according to
 - **Structure** of subproblem taxonomy (1D, 2D, etc)
 - How many **subproblems** used in solution
 - How many **choices** to consider per task
- **Complexity**: count **edges** in subproblem graph
- **Rod-cut**: 1D graph, 1 subprob, n choices: $\Theta(n^2)$
 - **Fibonacci**: 1D graph, 2 subprobs, no choices (not opt): $\Theta(n)$
 - **Matrix-chain**: 2D graph, 2 subprobs, $j-i$ choices: $\Theta(n^3)$
 - **LCS**: 2D graph, 1 subprob, ≤ 2 choices: $\Theta(mn)$
 - **Optimal BST**: 2D graph, 2 subprobs, $j-i+1$

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