→ Exercise 1

We first load a dataset and examine its dimensions.

```
# If you are running this on Google Colab, uncomment and run the following lines; otherwise ignore this cell
# from google.colab import drive
# drive.mount('/content/drive')

import math
import numpy as np

xy_data = np.load('Ex1_polyreg_data.npy')
# If running on Google Colab change path to '/content/drive/MyDrive/IB-Data-Science/Exercises/Ex1_polyreg_data.npy'
x =np.shape(xy_data)
```

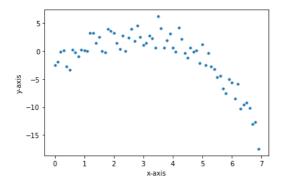
The matrix xy_data contains 70 rows, each a data point of the form (x_i, y_i) for $i = 1, \ldots, 70$.

▼ 1a) Plot the data in a scatterplot.

```
import matplotlib.pyplot as plt
# Your code for scatterplot here

data_x = xy_data[:,0]
data_y = xy_data[:,1]

plt.scatter(data_x, data_y, s=10)  # s can be used to adjust the size of the dots
plt.xlabel('x-axis')
plt.ylabel('y-axis')
plt.show()
```



▼ 1b) Write a function polyreg to fit a polynomial of a given order to a dataset.

The inputs to the function are a data matrix of dimension $N \times 2$, and $k \ge 0$, the order of the polynomial. The function should compute the coefficients of the polynomial $\beta_0 + \beta_1 x + \ldots + \beta_k x^k$ via least squares regression, and should return the coefficient vector, the fit, and the vector of residuals.

If specified the degree k is greater than or equal to N, then the function must fit an order (N-1) polynomial and set the remaining coefficients to zero.

NOTE: You are *not* allowed to use the built-in function <code>np.polyfit</code>.

```
def polyreg(data_matrix, k):
    # Your code here
    # The function should return the the coefficient vector beta, the fit, and the vector of residuals

data_x = data_matrix[:,0]  #First column of array
data_y = data_matrix[:,1]  #Second column of array

all_ones = np.ones(np.shape(data_x))

N = np.shape(data_matrix)[0]

if k >= N: # The condition for when k > or = N
    k = N - 1

else: # If k doesn't satisfy the equation above it equals itself
```

```
k = k
```

Use the tests below to check the outputs of the function you have written:

```
# Some tests to make sure your function is working correctly

xcol = np.arange(-1, 1.05, 0.1)
ycol = 2 - 7*xcol + 3*(xcol**2)  # We are generating data according to y = 2 - 7x + 3x^2
test_matrix = np.transpose(np.vstack((xcol,ycol)))
test_matrix.shape

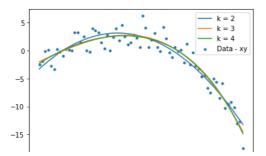
beta_test = polyreg(test_matrix, k=2)[0]
assert((np.round(beta_test[0], 3) == 2) and (np.round(beta_test[1], 3) == -7) and (np.round(beta_test[2], 3) == 3))
# We want to check that using the function with k=2 recovers the coefficients exactly

# Now check the zeroth order fit, i.e., the function gives the correct output with k=0
beta_test = polyreg(test_matrix, k=0)[0]
res_test = polyreg(test_matrix, k=0)[2]  #the last output of the function gives the vector of residuals

assert(np.round(beta_test, 3) == 3.1)
assert(np.round(np.linalg.norm(res_test), 3) == 19.937)
```

- ullet 1c) Use polyreg to fit polynomial models for the data in xy data for k=2,3,4:
 - Plot the fits for the three cases on the same plot together with the scatterplot of the data. The plots should be labelled and a legend included.
 - Compute and print the SSE and \mathbb{R}^2 coefficient for each of the three cases.
 - Which of the three models you would choose? Briefly justify your choice.

```
#Your code here
[beta_2, fit_2, resid_2] = polyreg(xy_data, 2)
[beta_3, fit_3, resid_3] = polyreg(xy_data, 3)
[beta_4, fit_4, resid_4] = polyreg(xy_data, 4)
all_ones = np.ones(np.shape(data_x))
fit_0 = np.mean(data_y) * all_ones # When k = 0
plt.scatter(data_x, data_y, s=10, label = 'Data - xy') # Plotting the scatter and the fit for different k values
plt.plot(data_x, fit_2, label = 'k = 2')
plt.plot(data_x, fit_3, label = 'k = 3')
plt.plot(data_x, fit_4, label = 'k = 4')
plt.legend()
plt.show()
SSE_0 = np.linalg.norm(data_y - fit_0)**2 # Calculating the SSE for different k values
SSE_2 = np.linalg.norm(data_y - fit_2)**2
SSE_3 = np.linalg.norm(data_y - fit_3)**2
SSE_4 = np.linalg.norm(data_y - fit_4)**2
R_2 = 1 - SSE_2 / SSE_0 \# Calculating R^2 for the corresponding k value
R_3 = 1 - SSE_3 / SSE_0
R_4 = 1 - SSE_4 / SSE_0
print("SSE_2 = ", np.round_(SSE_2, 2), "R_2^2 = ", np.round(R_2, decimals = 4))
print('SSE_3 = ', np.round_(SSE_3, 2), 'R_3^2 = ', np.round(R_3, decimals = 4))
print('SSE_4 = ', np.round_(SSE_4, 2), 'R_4^2 = ', np.round(R_4, decimals = 4))
```



State which model you choose and briefly justify your choice.

For the data range given, it can be seen that k = 4 is the best. This is because the error is the lowest (SSE), and the coefficient of determination (R^2) is the highest. This means that k = 4 is the best performing polynomial.

- ullet 1d) For the model you have chosen in the previous part (either k=2/3/4):
 - Plot the residuals in a scatter plot.
 - Plot a histogram of the residuals along with a Gaussian pdf with zero mean and the same standard deviation as the residuals.

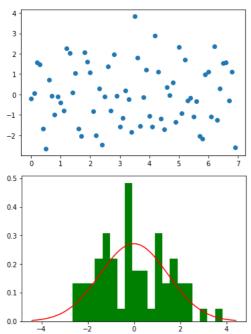
```
#Your code here
```

```
plt.scatter(data_x, resid_4) #Plotting a scatter of resid_4 from above
plt.show()

# Plot normed histogram of the residuals
n, bins, patches = plt.hist(resid_4, bins = 20, density = True, facecolor = 'green');

# Plot Gaussian pdf with same mean and variance as the residuals
from scipy.stats import norm

res_stdev = np.std(resid_4)  #standard deviation of residuals
xvals = np.linspace(-3 * res_stdev, 3 * res_stdev, 1000)
plt.plot(xvals, norm.pdf(xvals, loc = 0, scale = res_stdev), 'r')
plt.show()
```



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