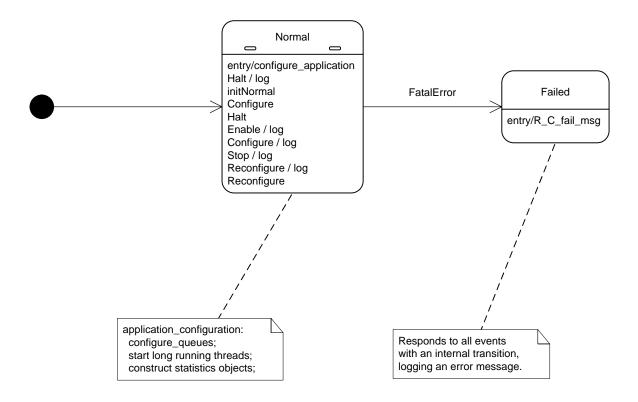
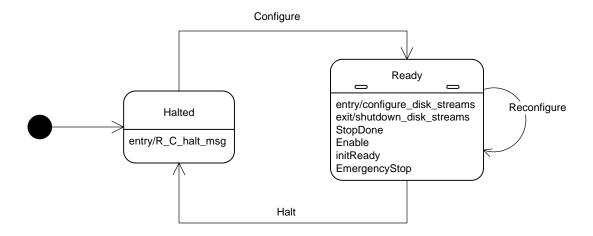
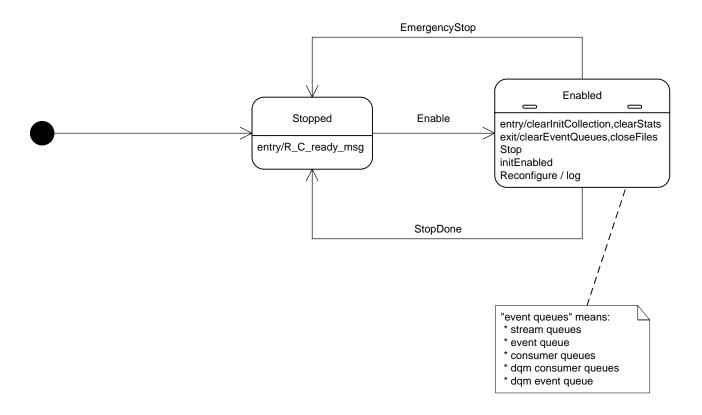
Top-level states



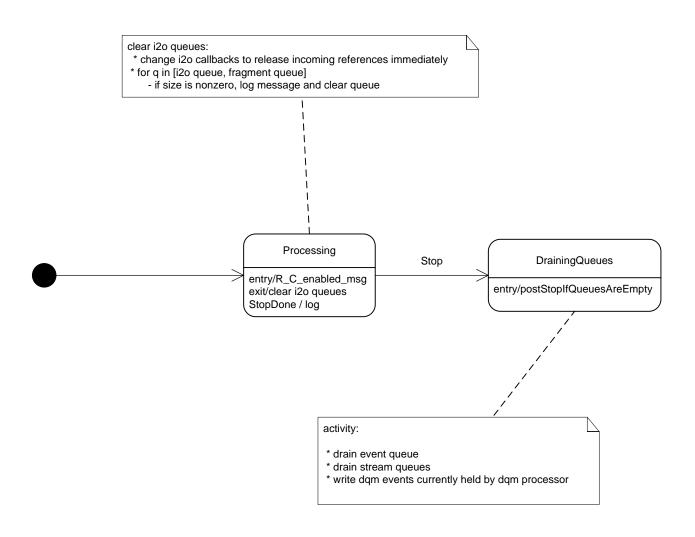
Substates for *Normal* state.

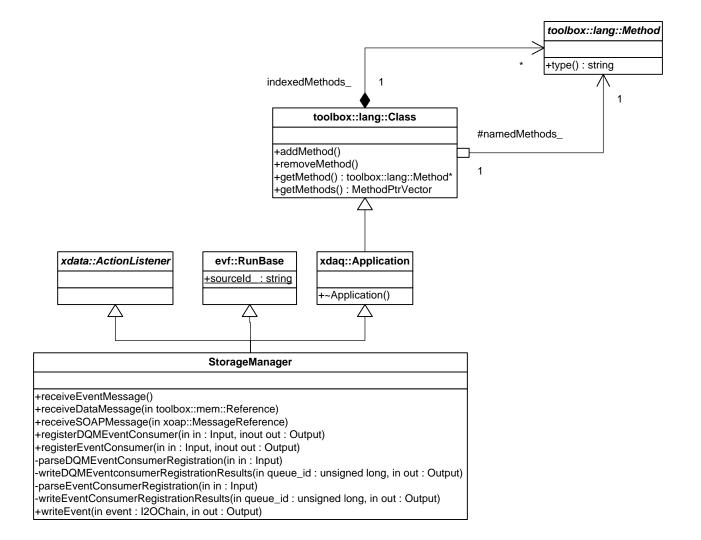


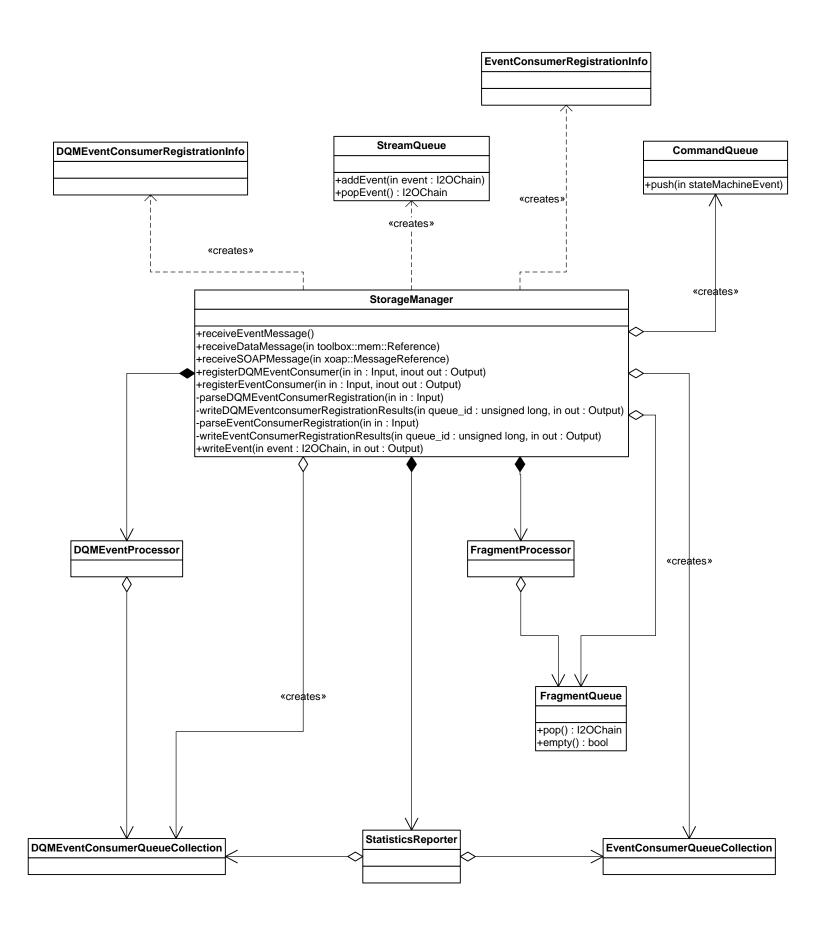
Substates for Ready state

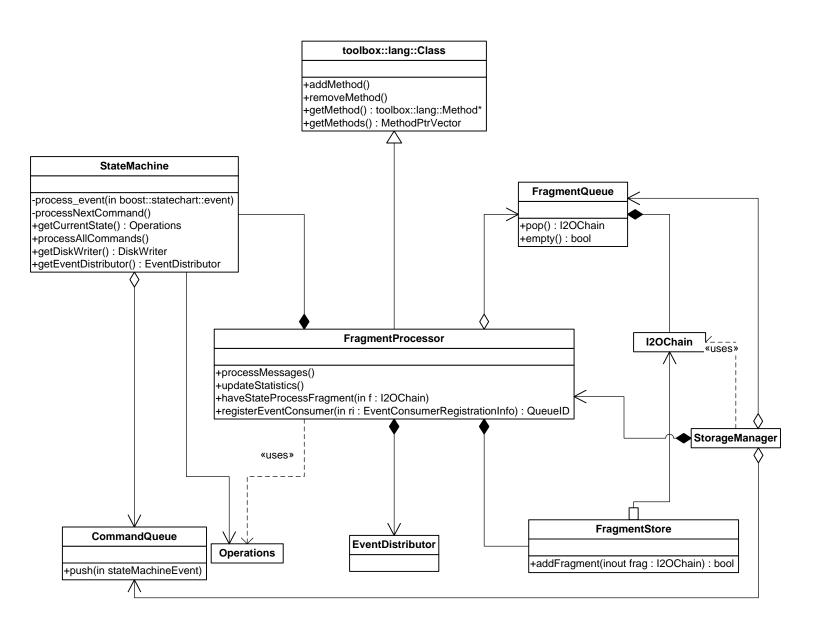


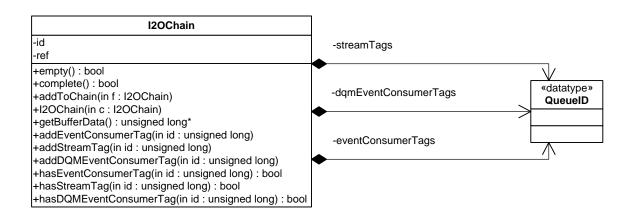
Substates for *Enabled* State





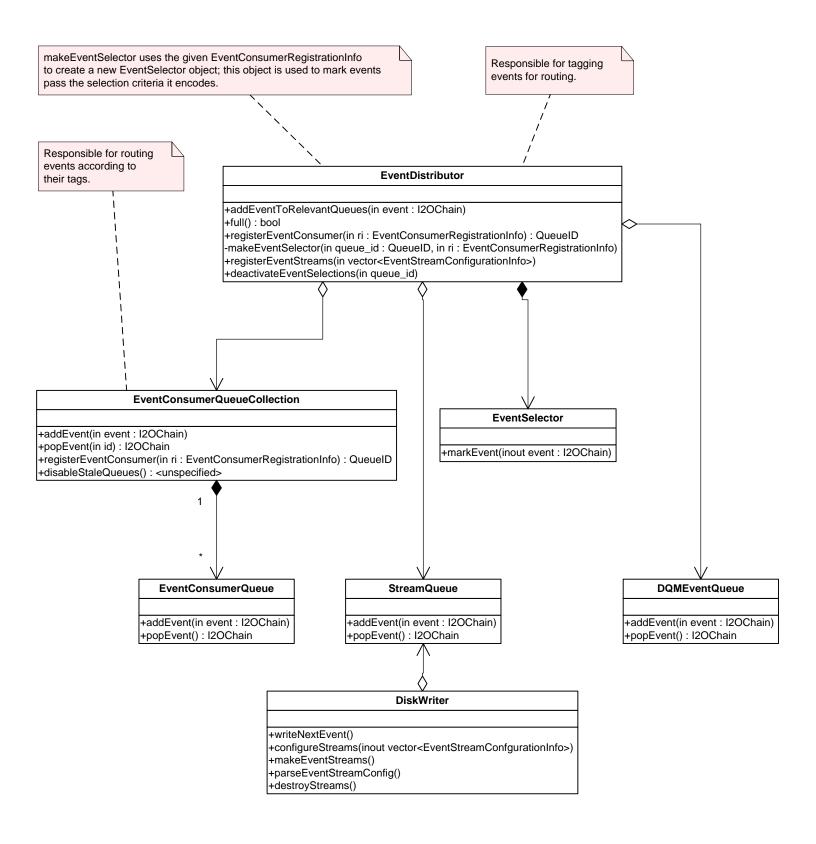


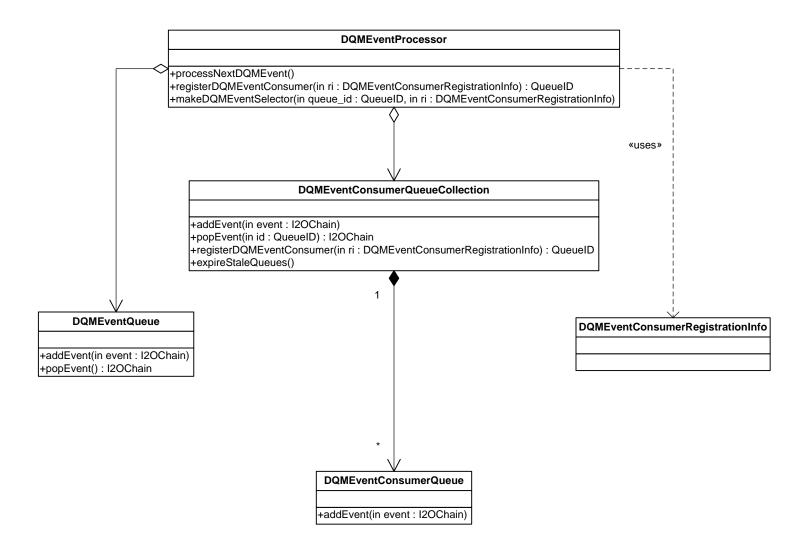




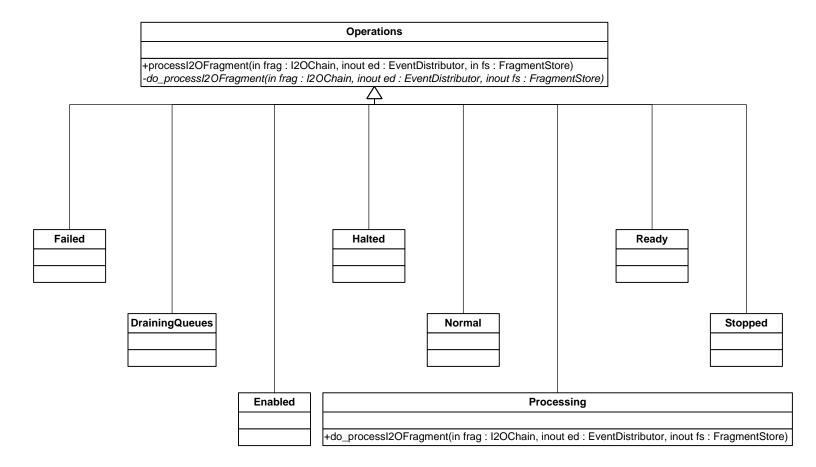
Configuration

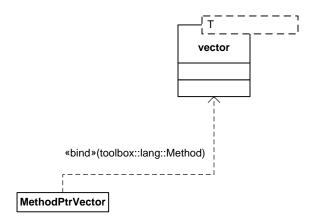
+getConfiguration() : <unspecified> +configurationHasChanged() : bool





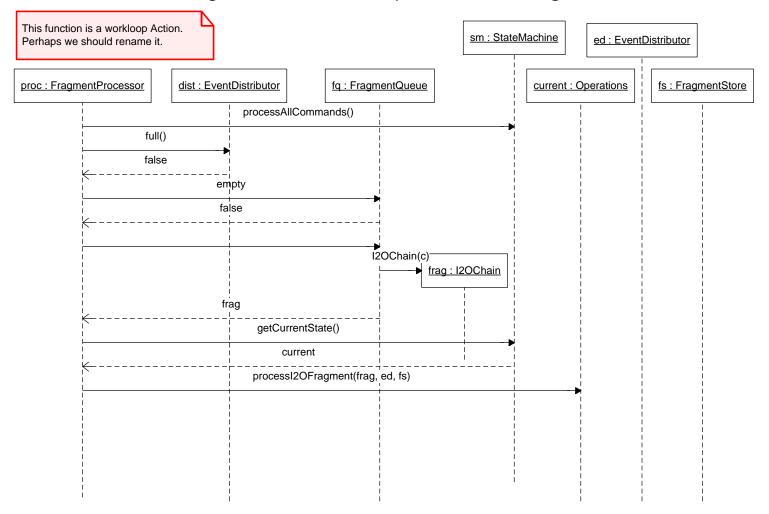
State classes show only the inheritance from Operations, not the inheritance from the Boost Statechart classes.



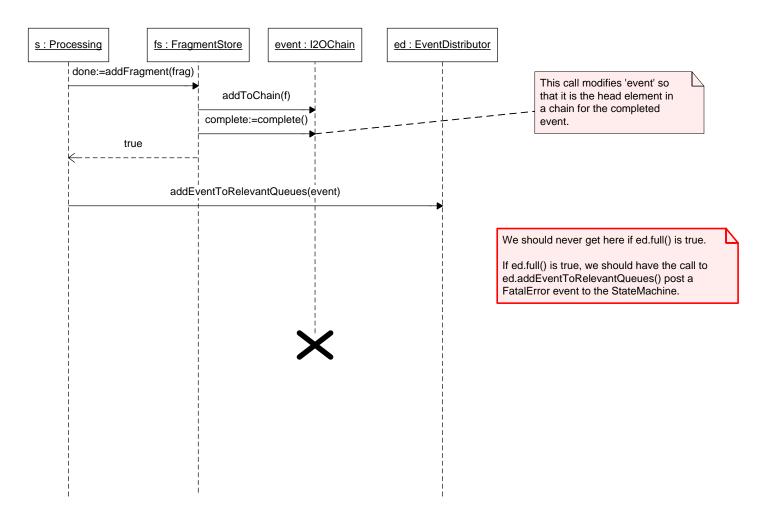


Input Output

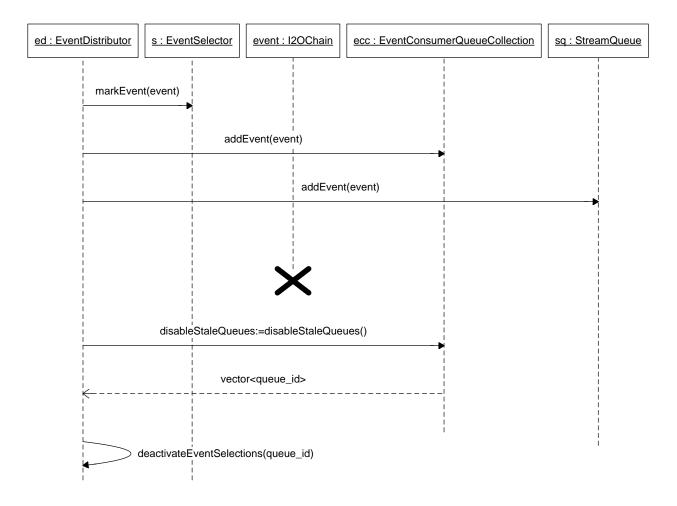
FragmentProcessor::processMessages



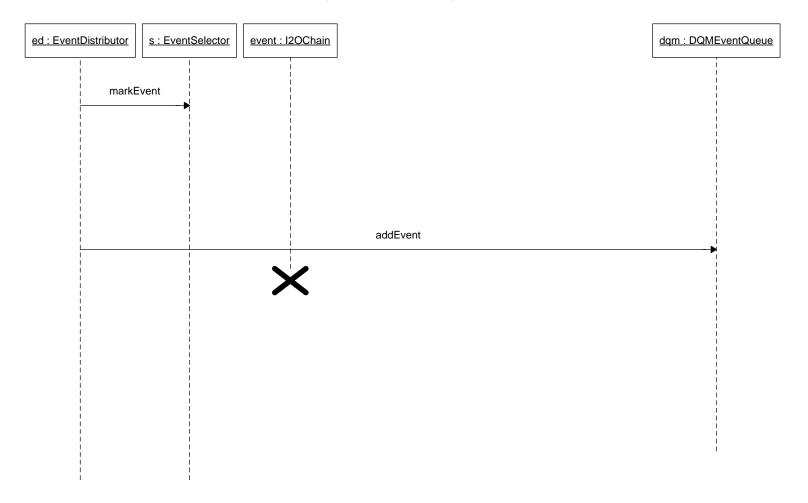
Processing State processing a fragment: last fragment case (do_processI2OFragment)



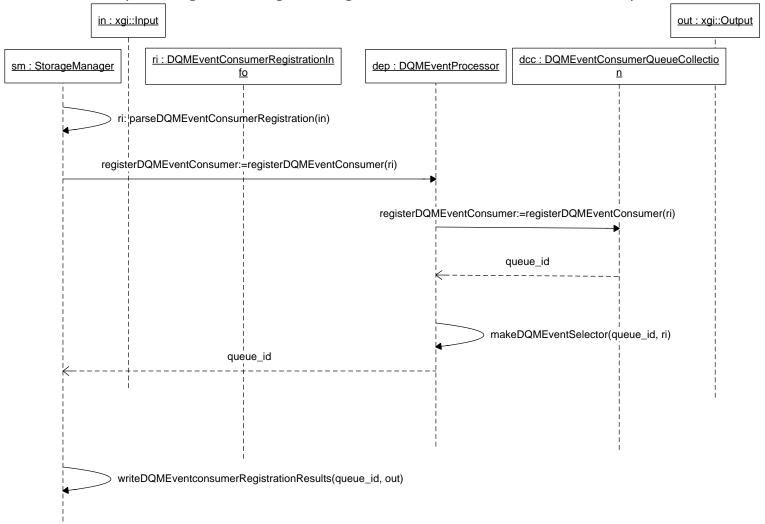
EventDistributor::addEventToRelevantQueues (collision event)



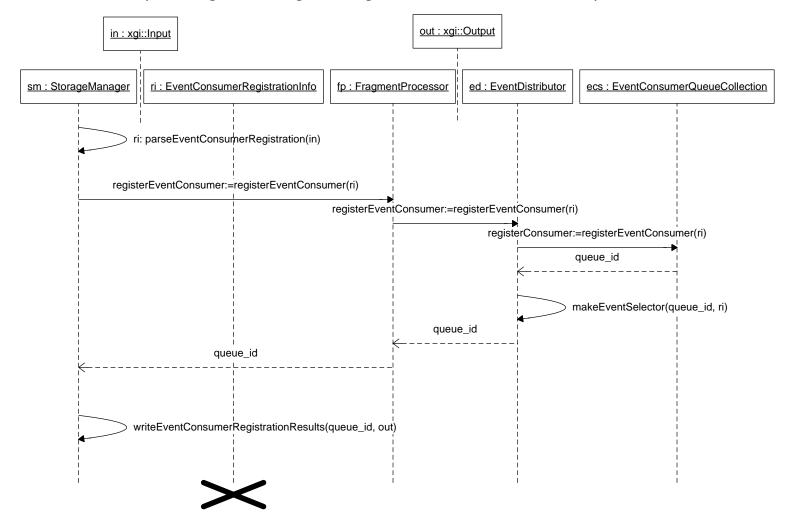
EventDistributor::addEventToRelevantQueues (DQM event)



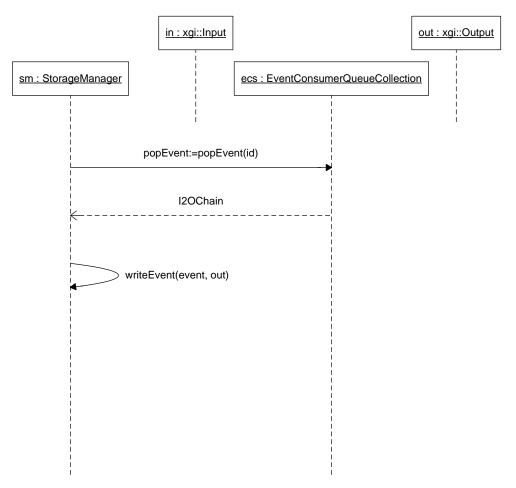
DQMEvent consumer registration (StorageManager::registerDQMEventConsumer)



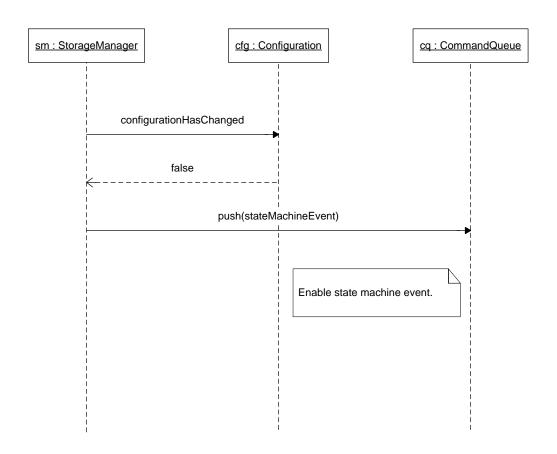
Event consumer registration (StorageManager::registerEventConsumer)



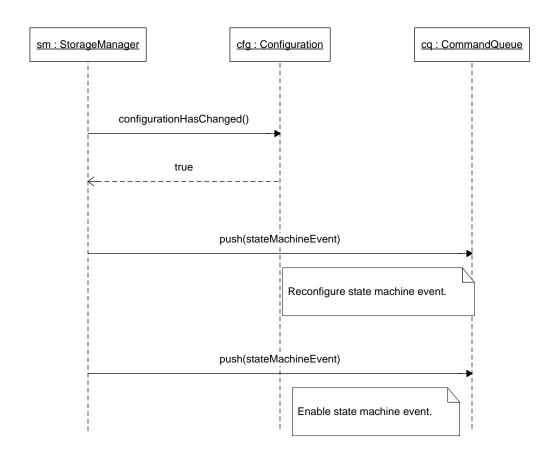
Event consumer event request (StorageManager::eventdataWebPage)

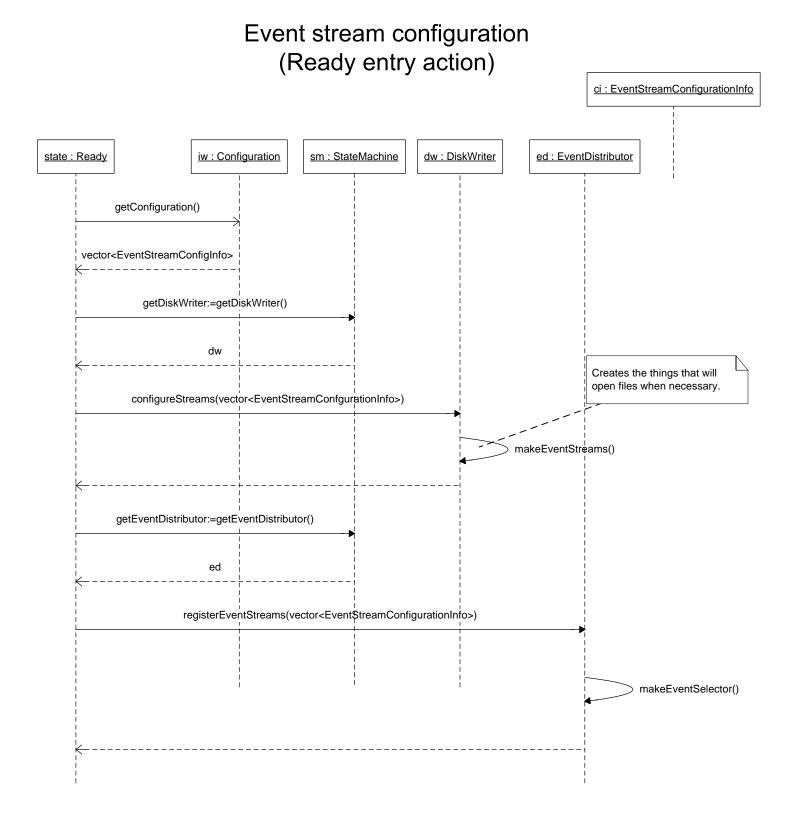


SM callback for Enable SOAP command (reconfiguration not needed)

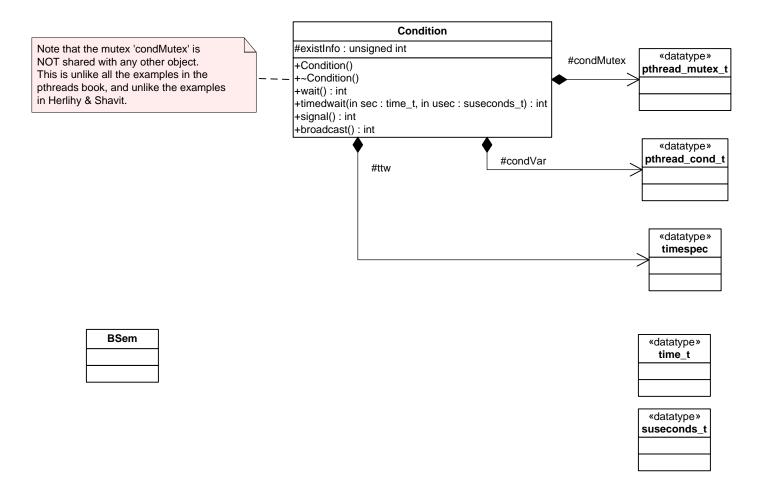


SM callback for Enable SOAP command (reconfiguration needed)





Toolbox classes for XDAQ: Linux implementations



T, DelayPolicy

ConcurrentQueue

+CommandQueue(in max : unsigned long)
+enq_wait(in item : T) : void
+deq_wait(out item : time_t) : void
+enq_wait_timeout(in item : T, in time : unsigned long) : bool
+deq_wait_timeout() : bool
+enq_nowait() : bool
+clear() : void
+empty() : bool