

**1**

Give decision trees to represent the following Boolean expressions

- (a)  $A \wedge \neg B$
  - (b)  $A \vee (\neg B \wedge C)$
  - (c)  $A \otimes B$
  - (d)  $(A \vee B) \wedge (\neg C \wedge D)$
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**2**

Consider the following set of training examples

Instance	Class	$A_1$	$A_2$
1	+	$T$	$T$
2	+	$T$	$T$
3	-	$T$	$F$
4	+	$F$	$F$
5	-	$F$	$T$
6	-	$F$	$T$

- (a) What is the entropy of this collection of training examples with respect to the target function classification?
  - (b) What is the information gain of  $A_2$  relative to these training examples?
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**3**

Suppose we generate a training set from a decision tree and then apply decision-tree learning to that training set. Is it the case that the learning algorithm will eventually return the correct tree as the training-set size goes to infinity? Why or why not?

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**4**

Suppose that an attribute splits the set of examples  $E$  into subsets  $E_k$  and that each subset has  $p_k$  positive examples and  $n_k$  negative examples. Show that the attribute has zero information gain if the ratio  $\frac{p_k}{p_k + n_k}$  is the same for all  $k$ .

**Extra credit:** Show that the attribute has strictly positive information gain unless the ratio  $\frac{p_k}{p_k + n_k}$  is the same for all  $k$ .

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**5**

A *decision graph* is a generalization of a *decision tree* that allows nodes (i.e., attributes used for splits) to have multiple parents, rather than just a single parent. The resulting graph must still be acyclic. Now, consider the XOR function of three binary input attributes, which produces the value 1 if and only if an odd number of the three input attributes has value 1.

- (a) Draw a minimal-sized *decision tree* for the three-input XOR function.
- (b) Draw a minimal-sized *decision graph* for the three-input XOR function.