

Blockers:

- Waiting for Computing Resource

Requirements:

- Hardware (few missing parts)
- Hard Drives

• Dataset - next step:

- Will decide the image size
 - how large does one pic cover
- Will decide the region size
 - conduct experiment on different region sizes to decide.
- Function to get Landsat data region

• Pipeline - next step:

- Stage 1: Region classifier
- Stage 2:
 - Landmark detection
 - End-to-end: image -> Longitude & latitude

Interfaces

Avionics:

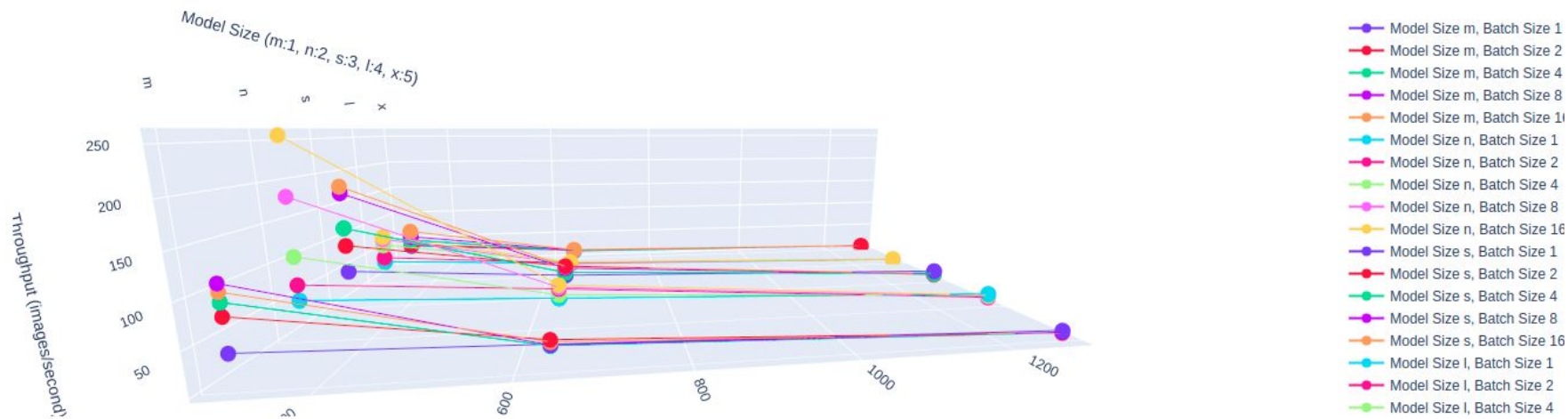
- Model prototype, size (MB), power consumption.

GNC:

- Previous longitude and latitude as priors for model

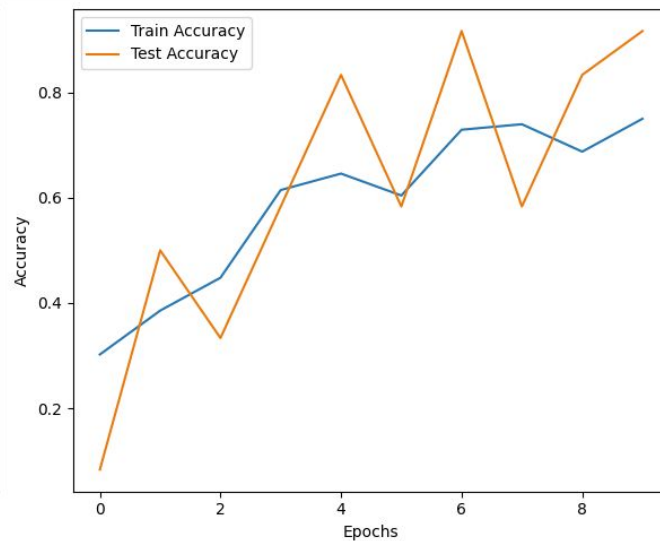
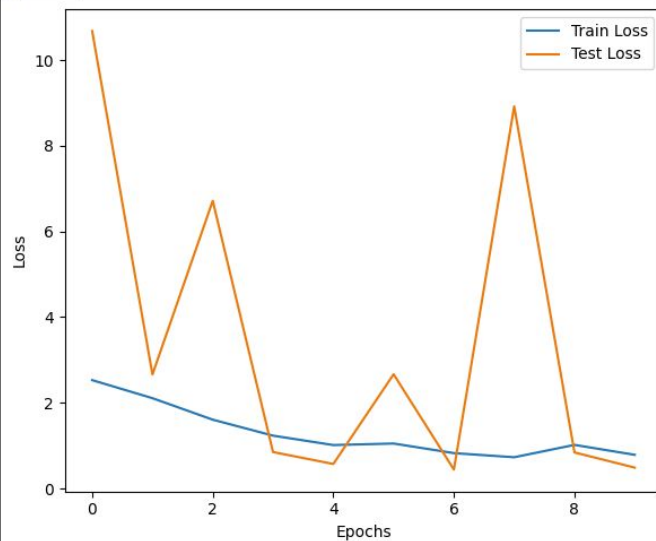
NVIDIA T4-GPU Throughput for YOLOv8

YOLOv8 Throughput Benchmark

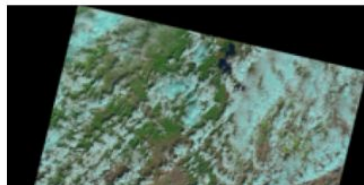


REGION CLASSIFICATION MODEL

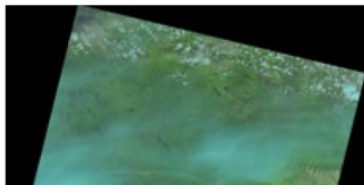
Epoch 9/10 Train Loss: 1.0182 Train Acc: 0.6875 Test Loss: 0.8423 Test Acc: 0.8333
Epoch 10/10 Train Loss: 0.7868 Train Acc: 0.7500 Test Loss: 0.4874 Test Acc: 0.9167



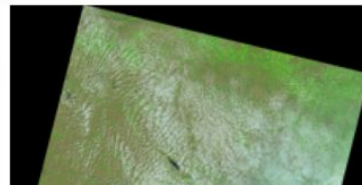
True: 10
Pred: 10



True: 0
Pred: 0



True: 5
Pred: 5



True: 4
Pred: 4

