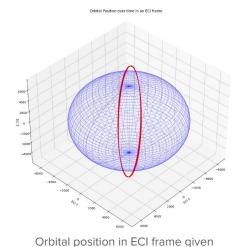
GNC Quad Chart

18 September 2024



initial keplerian orbital elements

Progress:

- 1. Developed a core dynamics model both on C++ & Python that does orbital dynamics and attitude dynamics simulations
 - a. Incorporates Harris-Priester model (without attitude/solar flux) and J2
 - b. Yet to be completely unit tested
- 2. Assigned subtask responsibilities to each member

Plan for the Upcoming Week:

- 1. Finalize the core dynamics algorithm and plan for algorithm validation against ground truth (STK, argus-1 sim etc.)
- 2. Define attitude control method (spin stable, 3 axis pointing etc.) and define actuator & sensor specs
- 3. Formulate non-linear optimization for orbit determination

External Tools Needed:

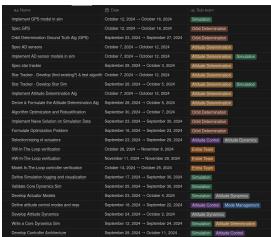
- STK access either on a lab PC / academic license
- 2. Pre-existing ground-truth simulation

Interfaces:

Interface with Avionics & Mechanical for actuator and sensor specs for attitude control

Timeline





General Task Flow:

- Problem Definition
- 2. Model-in-loop simulations Mid October
- 3. Software-in-loop simulations November
- 4. Hardware-in-loop simulations Mid November