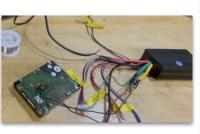
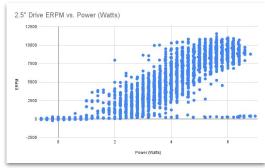
GNC Quad Chart

25 September 2024





ERPM vs Power for 2.5" Hard Drive 1000→10K ERPM Sweep

Progress:

- 1. Implemented more-accurate dynamics simulator (incorporated Brahe) and built out core simulation structure.
- 2. Implemented basic sensors, actuator models, and correspondence generation in simulation.
- 3. Measured hard drive power consumption with VESC (***5W** for 2.5" HDD). Projecting ***2W** for a 1.8" drive.
- 4. Further definition/discussion of the GNC configurations

Plan for the Upcoming Week:

- 1. Design and simulate different spacecraft configurations.
- 2. Refine camera sensor model interface for vision to implement with landsat images.
- 3. Optimize / debug sluggish components/models.

External Tools Needed:

- 1. STK access either on a lab PC / academic license
- 2. Pre-existing ground-truth simulation

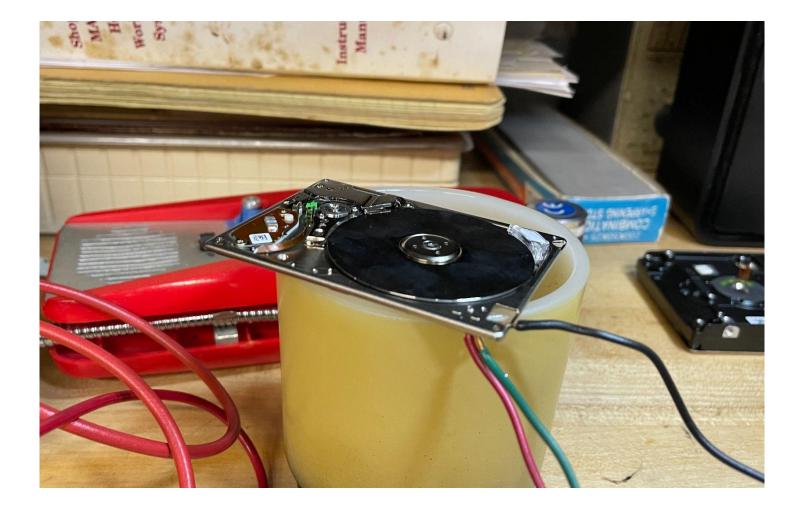
Nadir pointing with 3dof Attitude Control - getting nadir and orbital plane w/o GPS

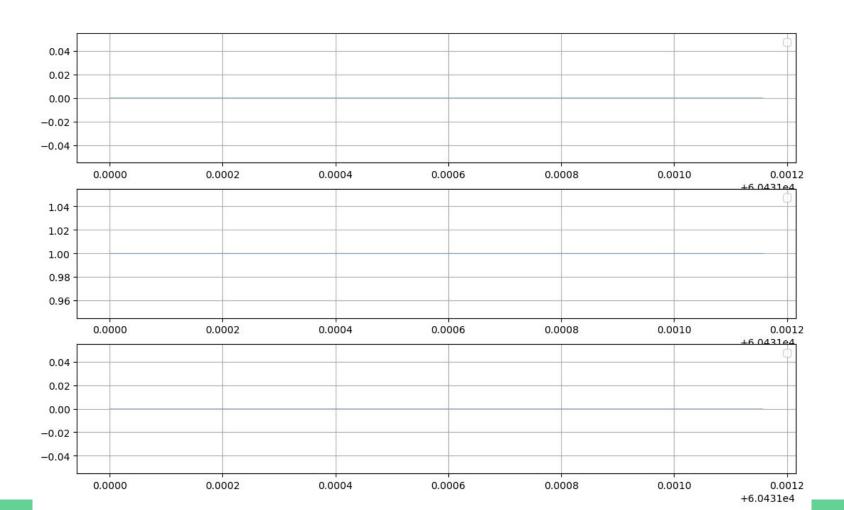
Interfaces:

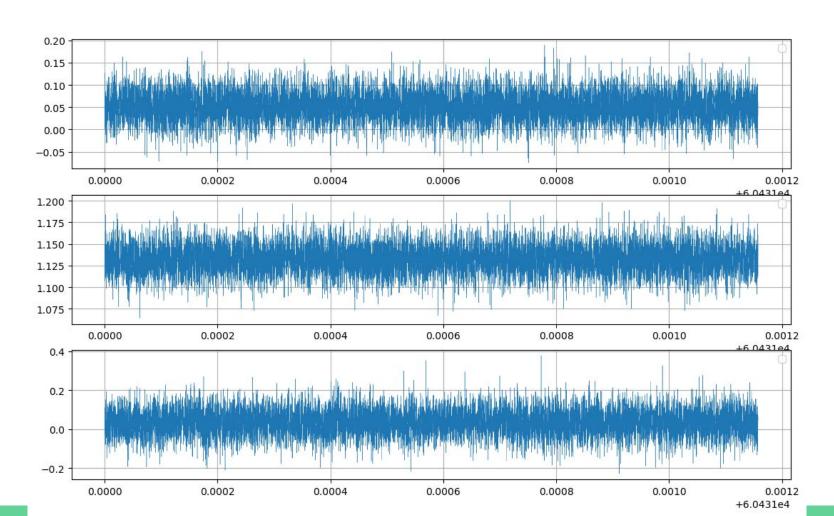
- 1. Mechanical: Custom reaction wheel design with more inertia?
- 2. Avionics: Can we afford a reaction wheel in our energy budget?
- 3. Vision: Camera specs and additional parameters for accurate correspondence generation and OD development?

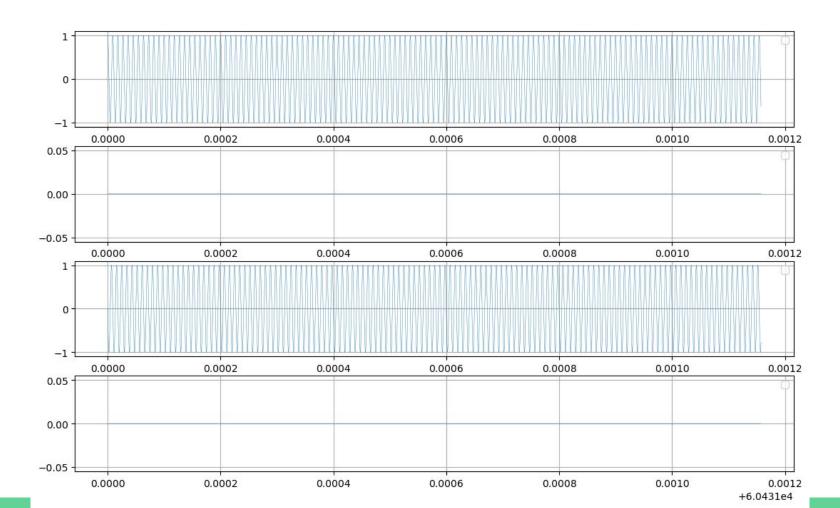
Sensors: IMU, star tracker, light sensors (mech)

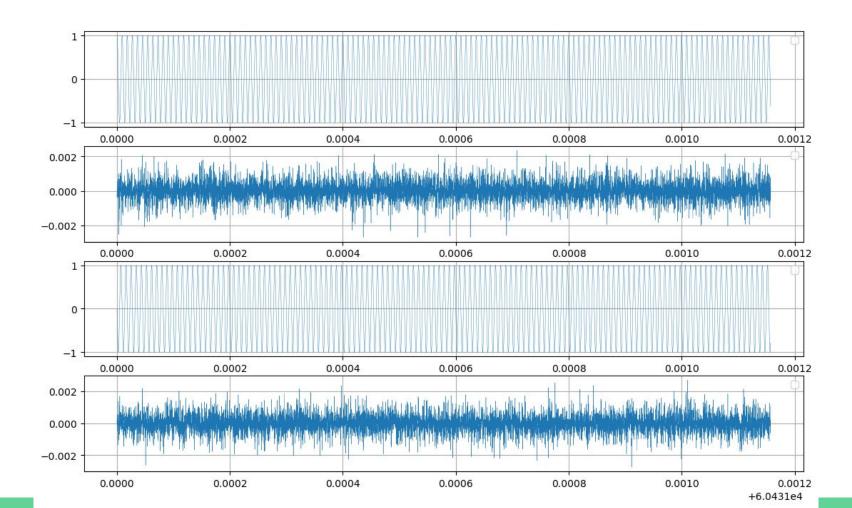
Actuators: RW, magnetorquer





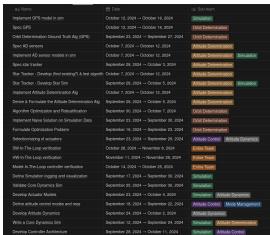






Timeline





General Task Flow:

- 1. Problem Definition
- 2. Model-in-loop simulations Mid October
- 3. Software-in-loop simulations November
- 4. Hardware-in-loop simulations Mid November