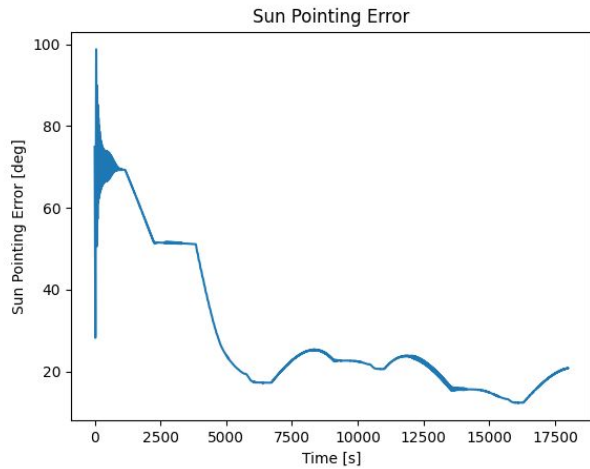


GNC Quad Chart

October 30 2024



Blockers:

None

Progress:

Simulation:

- Switch to C++ simulation nearly complete
- C++ simulation interfaced with PyCubed for HIL simulations
 - Only gives a 25:1 speedup and can't be used for MC simulations.
 - Can be used for controller verification

Control:

- *Spin-stabilized, Sun pointing controller implemented*

Orbit Determination:

Plan for the Upcoming Week:

1. Adding State Estimator to the simulation
2. Moving controllers from python sim to C++
3. Implementing RW controller

Interfaces:

Kanban

