Boot Average Power(mW) Boot Time(s) Boot Energy Consumption(mU) Execution Average Power(mW) Execution Time(s) Execution Energy Consumption (mU) Total Energy Consumption (Wh							• GNC: Solar Panel Simulation Data			
Orin Nano 8GB 7W (GUI	7704.886734 131.1654399	1010614.858		361.5218088	2748192.751	1.044113225				
Orin Nano 8GB Dev 7W		581751.003		328.4000478	2528297.922	0.8639024793				
Orin NX 16GB 10W (GU	9762.567927 67.01068119	654196.327		358.6316118	3374441.05	1.119065938	• GNC: Star Tracker is lower priority, may take a			
Orin Nano 8GB 15W (GL	JI) 8764.778801 64.74328156	High Powe 567460.5417		217,2475799	2232253.387	0.7776983136	1136			
Orin Nano 8GB Dev 15V		418536.5256		244.1522847	2212253.955	0.7307751334	month to get info.			
Orin NX 16GB 25W (GU	1) 10118.95126 60.77589629	614988.3321	12794.21726	179.9012141	2301695.22	0.8101898755	7755			
				100000000			 Waiting for PCB components and stencil arrivals for solar panel testing Busy for the midterms Accidentally burnt DRV8235 chip 			
 Milestones Achieved Camera board laid out. Argus-2 lx RP2040 Main Board schematics ConOps meeting with all the teams to figure out the mission details Finished preliminary jetson power testing Can save images to SD card for OpenMV camera 						 Interfaces Seems like 2-Camera solution is nigh (1 camera, 1 star tracker). GNC: Solar panel sim data GNC: Reaction wheel power data Mechanical: Finalize solar panel config 				
Looking										
 Argus-2 1x RP2040 Main Board layout 						· ·				
S S						· ·				
 X/Y board testing 						· ·				
 Deployable board design 						· ·				
, ş						· ·				
 Modifying/building state machines according to ConOps as we keep 						·				
						· ·				

Updates

building it

More Jetson power testing (Deep Sleep, no peripherals, etc)

Blockers

The CAN-Ban 🦅 🦅

