CMU DATA SCIENCE CLUB X CMU POKER CLUB PRESENTS...

# CMU POKER AI COMPETITION



## Welcome to the Poker Al Workshop!

### Poker Terminology

A hand: Cards dealt to a player (hidden information)



A board: community cards that are dealt face up. In no limit holdem, these consist of a flop (3 cards), turn (1 card), river (1 card).

SB/BB: Money put in by both players originally in each round (1 and 2). These alternate between rounds.

Showdown: Once no more community cards should be dealt, and all betting action has completed, the player with the better hand wins the pot.

Check: A bet of 0 (passing)

Bet X: Bet X chips. Your opponent can either **call** the X, **raise** to **Y**, or **fold**.

All In: A bet or raise that wagers all of your remaining chips.

#### **Contents**

- Basic poker terminology
- 2. What to code
- 3. All-In bot
- 4. A very *FLAWED* model
- 5. Why is this model flawed?
- 6. Further directions

#### **All-In Bot**

```
if RaiseAction in observation["legal_actions"]:
    return RaiseAction(observation["max_raise"])
if CheckAction in observation["legal_actions"]:
    return CheckAction()
return CallAction()
```

## A benchmark: Optimized All-In Bot

What if you only go all in with the *best* X% of hands and fold the rest? Or, what if instead of going all-in, you make a big preflop raise instead?

This bot can win money versus bots that call too wide. It can also win money versus bots that call too narrowly.



### A VERY FLAWED model ("Prob Bot")

1. Calculate **Equity** (showdown winning probability)

Consider all possible combinations of enemy cards, community cards to count the number of times we win. Equity = win\_num / total\_num

2. Calculate pot odds

```
pot_odds = continue_cost / (pot_size + continue_cost)
```

3. Use the calculations

```
if equity > 0.8 and RaiseAction in observation["legal_actions"]:
    action = RaiseAction(observation["max_raise"])
elif CallAction in observation["legal_actions"] and equity >= pot_odds:
    action = CallAction()
elif CheckAction in observation["legal_actions"]:
    action = CheckAction()
else:
    action = FoldAction()
```

prob\_bot Bankroll: 31605 allin bot Bankroll: -31605

## Why is this model *FLAWED*?

- 1. Over-Simplistic Equity Calculation (No attempts to narrow down hand range)
- 2. Inflexible Betting Amounts
- 3. Ignoring Contextual Information (Bet history, etc)
- 4. Lack of Bluffing Strategy

"In conclusion, while the given pseudocode is a basic representation of decision-making in poker, it lacks the sophistication and adaptability required for a robust poker-playing algorithm."

## **Utilizing Reinforcement Learning**

1. CFR (Counterfactual Regret Minimization) based methods

2. Policy Gradients

3. Genetic Algorithms

And much more.....

## **Utilizing Heuristic Algorithms (improving Prob Bot)**

- Evaluate your hand's Equity: the expected share of the pot your hand is worth.
   Multiple factors influence a hands equity:
  - a. Its current raw strength
  - Its ability to improve to a stronger hand on certain cards (i.e. flush draws or straight draws in NLH).
  - c. Its "blocking effect": in making very strong hands in the villains range less likely.
  - d. The position (the player who is last to act is mathematically known to have an advantage in almost all imperfect information games).

#### 2. When to bet?

- a. For "value": your hand has enough equity to want to inflate the size of the pot.
- b. As a "bluff": your hand will almost certainly lose if you give up and check.

#### And much more.....

#### With multiple bots

```
from engine.gym_env import PokerEnv

env = PokerEnv(num_rounds=1000)
  (obs1, obs2), info = env.reset()
  bot1, bot2 = random_bot, random_bot

done = False
  while not done:
    if obs1["is_my_turn"]:
        action = bot1(obs1)
    else:
        action = bot2(obs2)
        (obs1, obs2), (reward1, reward2), done, trunc, info = env.step(action)
```

#### With a single bot (enemy bot fixed)

```
env = PokerEnv(num_rounds=10, opp_bot=random_bot)
(obs1, obs2) = env.reset()
bot = random_bot

done = False
while not done:
    action = bot(obs)
    obs, reward, done, trunc, info = env.step(action)
```

# **GLHF!**