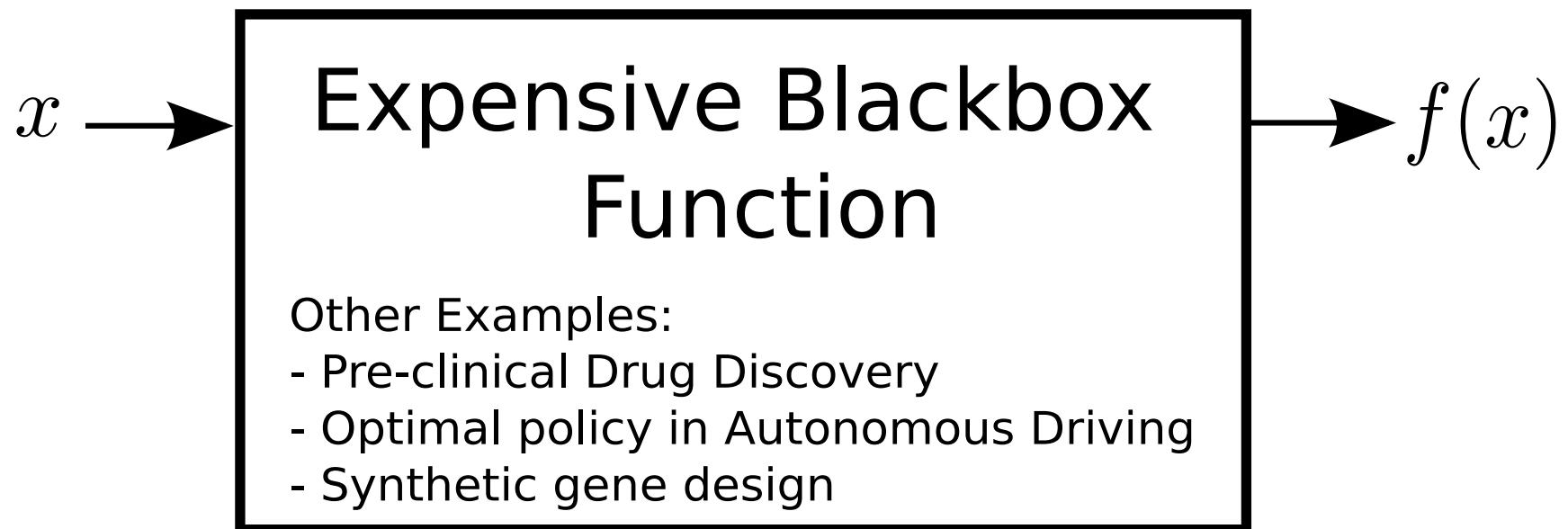


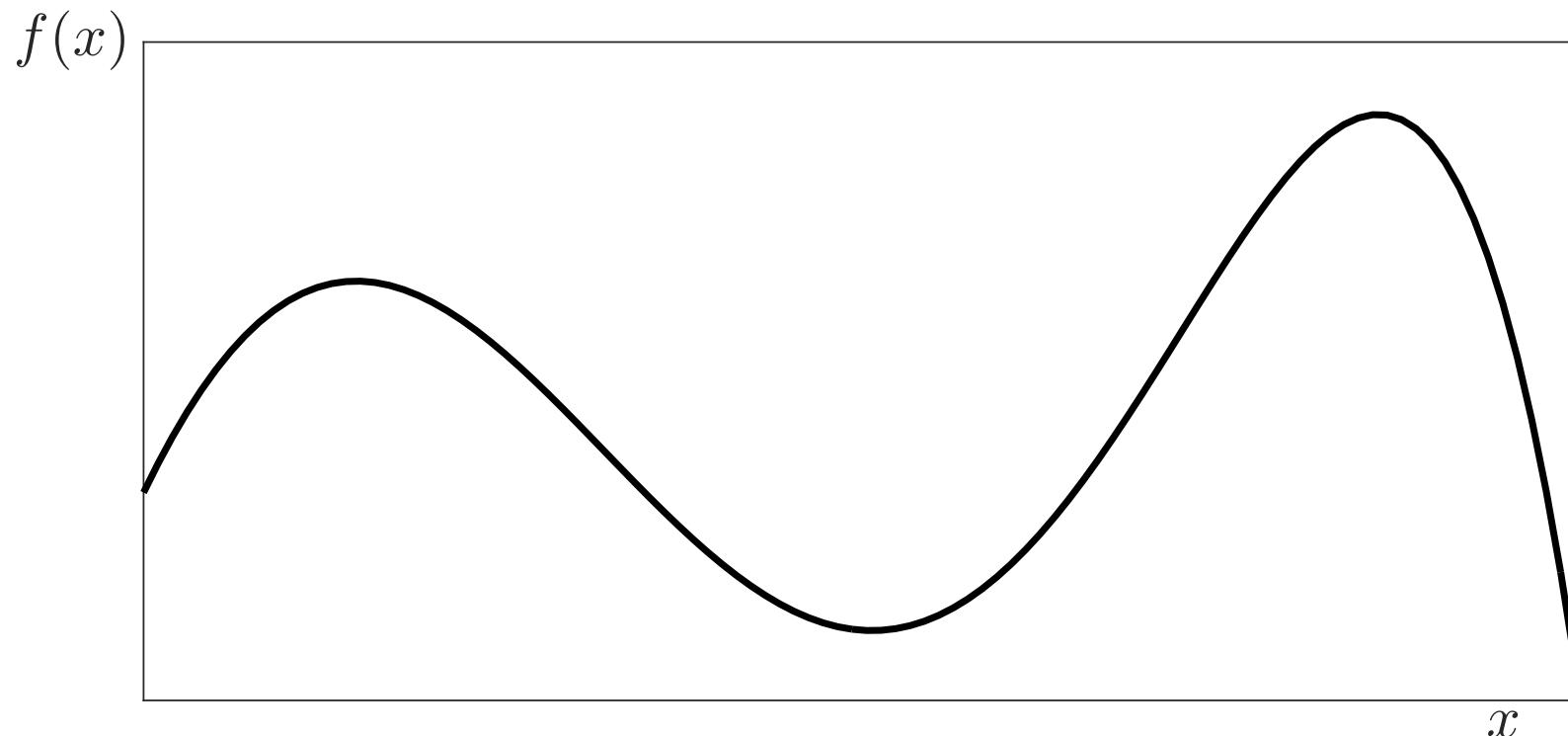
# Brief Overview of Bayesian Optimization and Gaussian Process

# Black-box Optimisation



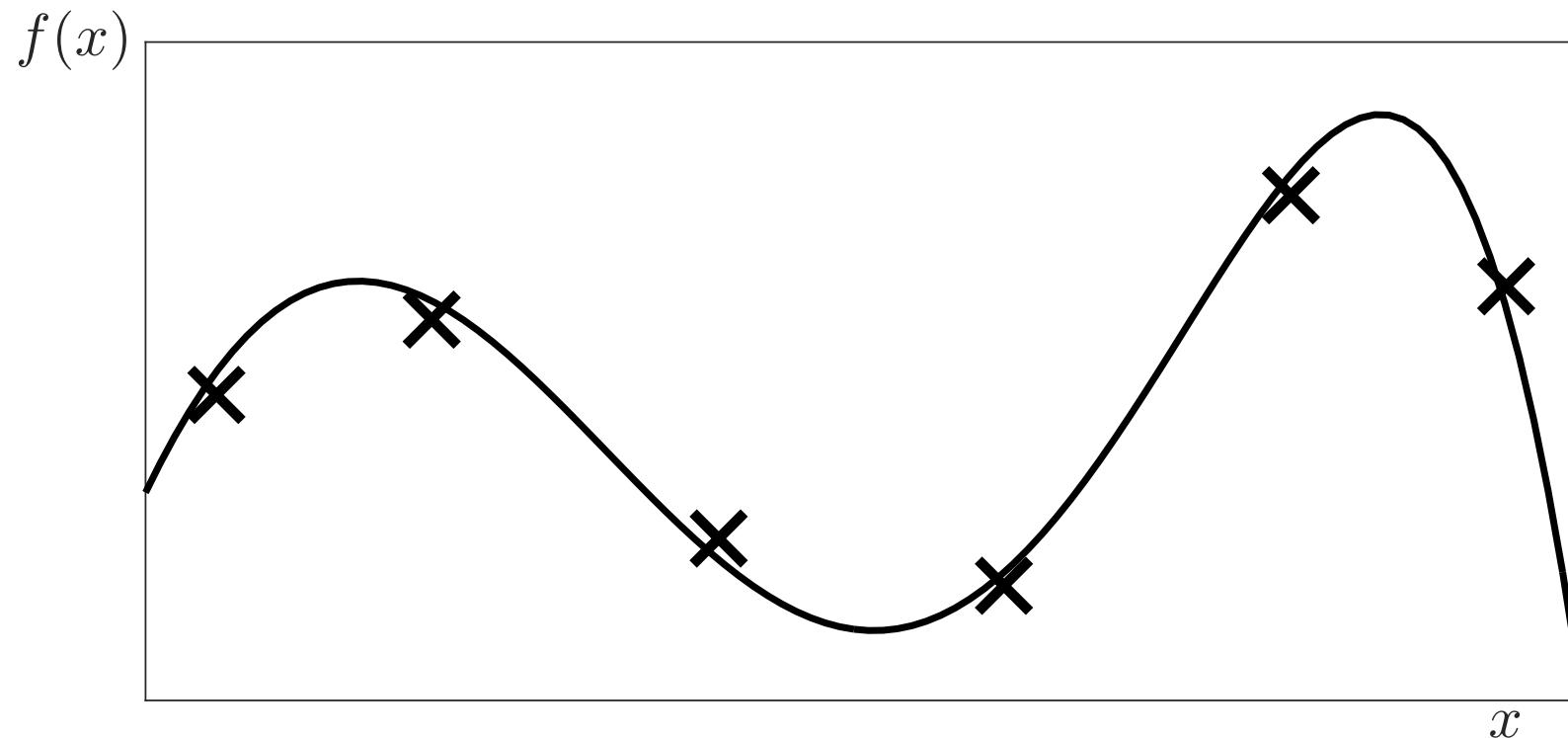
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$f : \mathcal{X} \rightarrow \mathbb{R}$  is an expensive, black-box function, accessible only via noisy evaluations.



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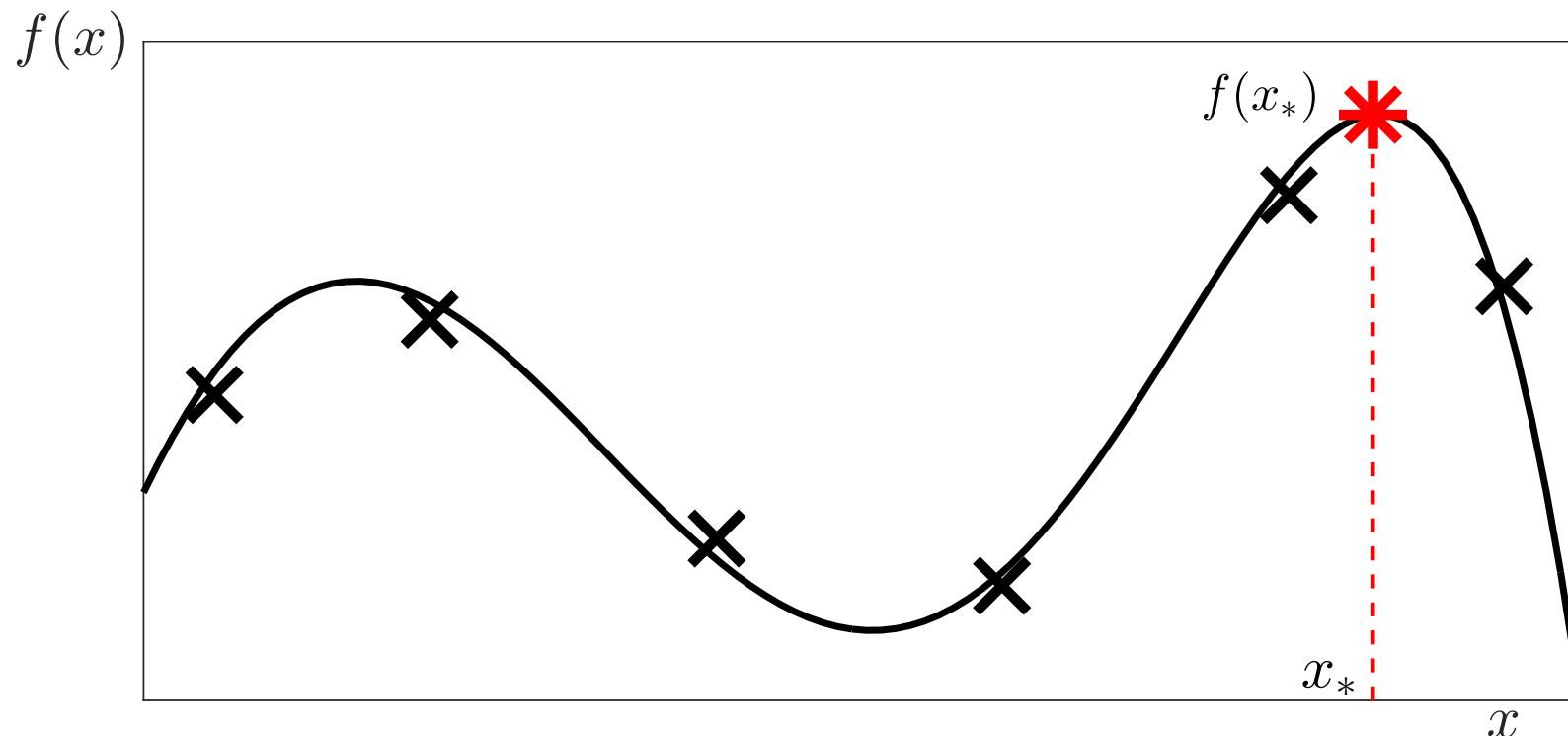
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Let  $x_* = \operatorname{argmax}_x f(x)$ .



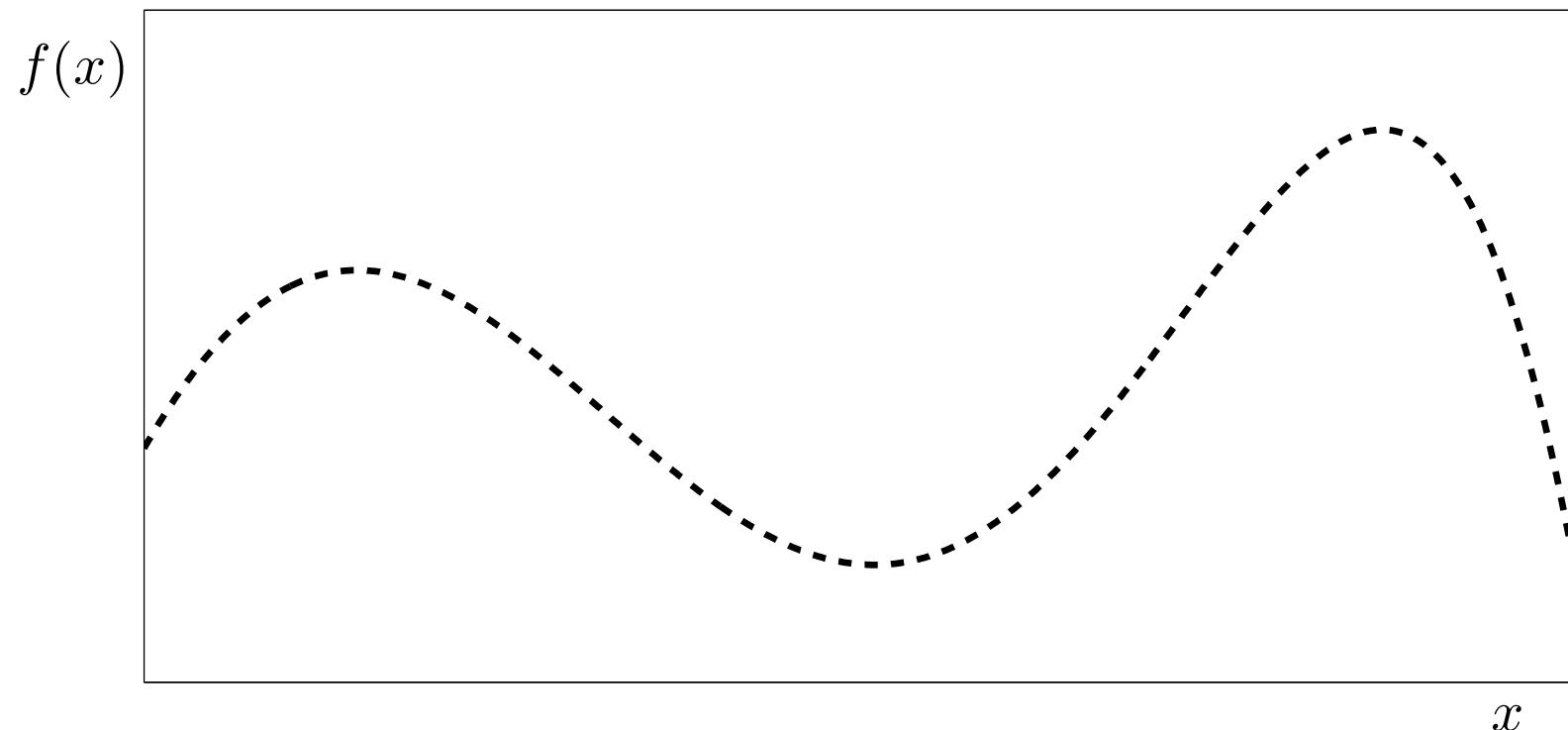
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Functions with no observations

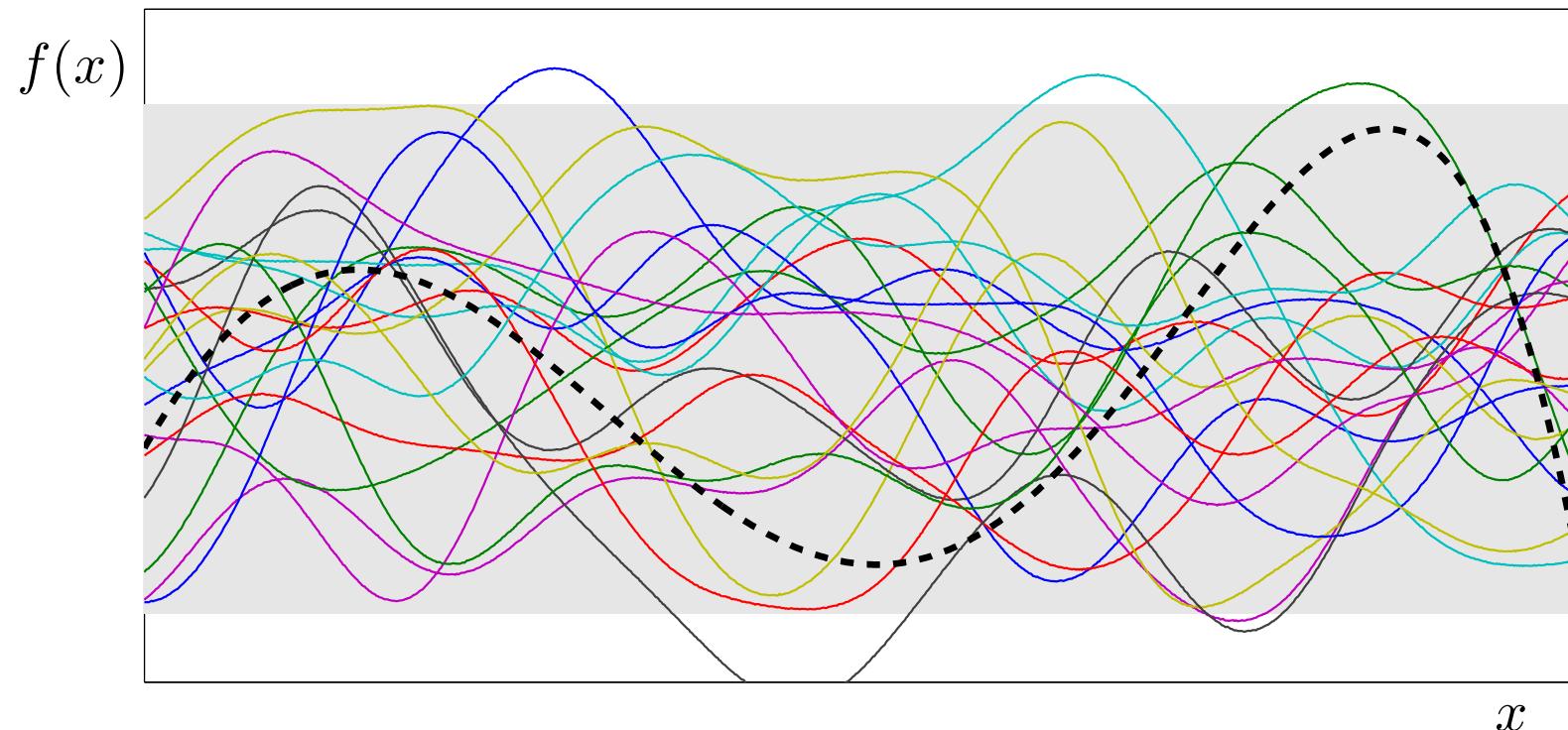


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Prior  $\mathcal{GP}$

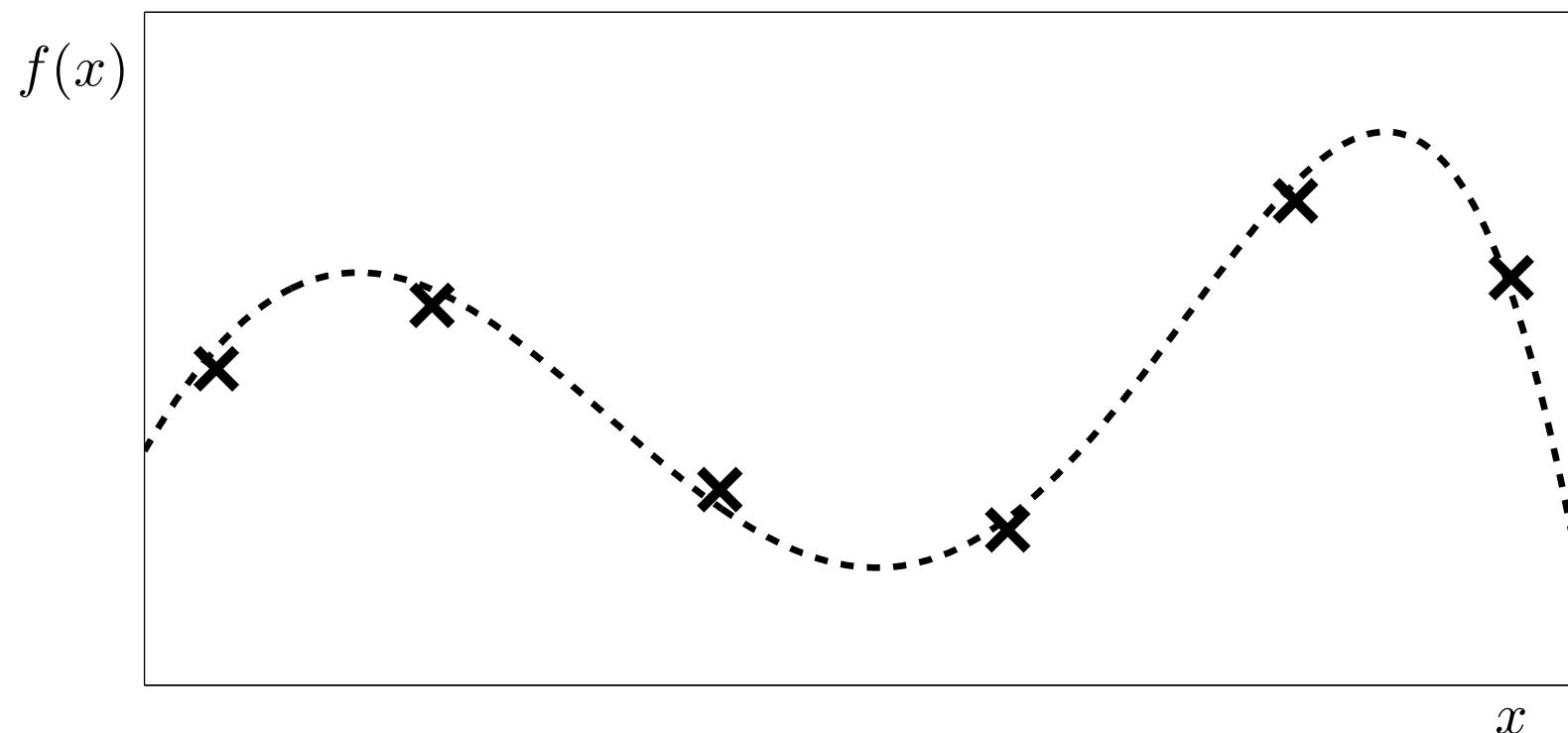


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Observations

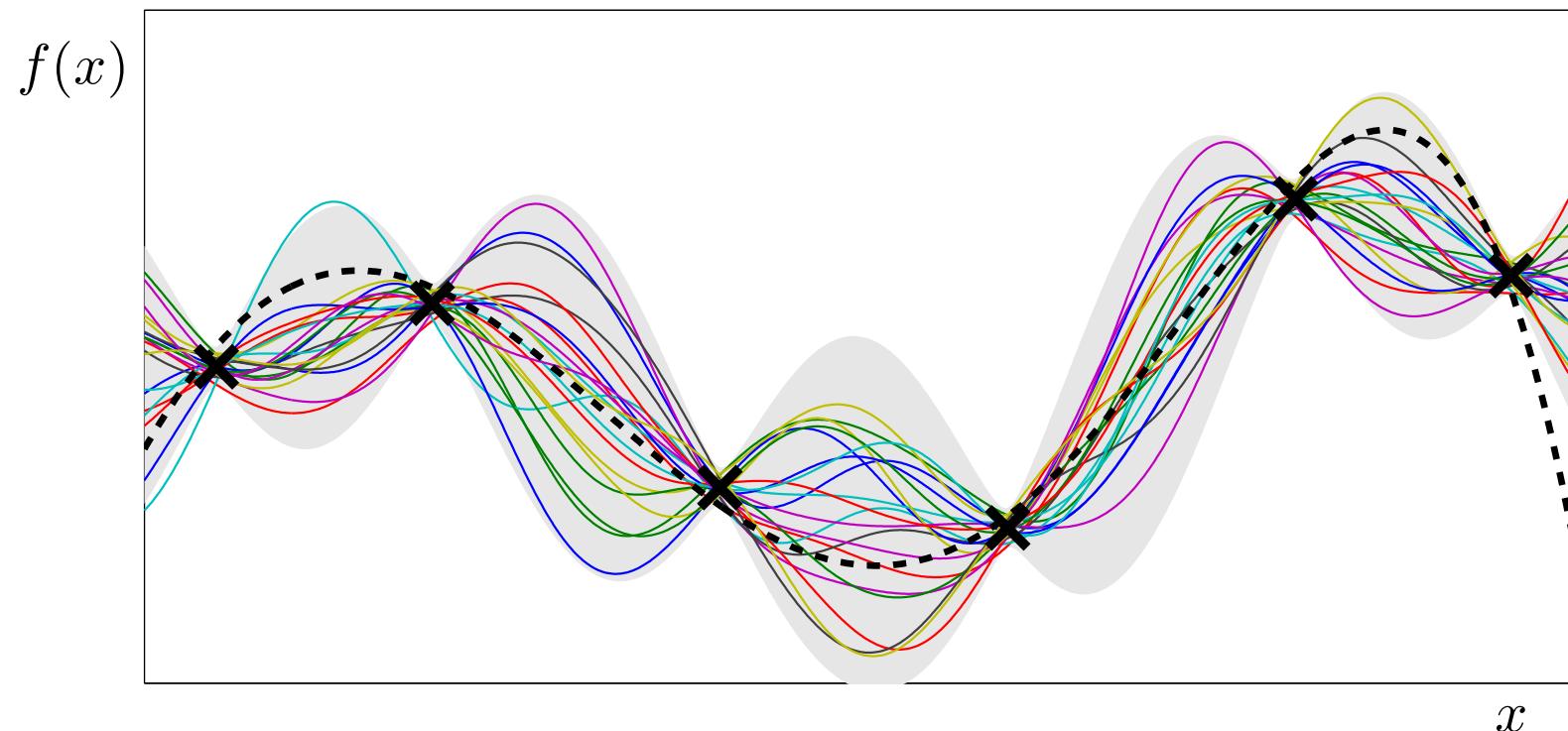


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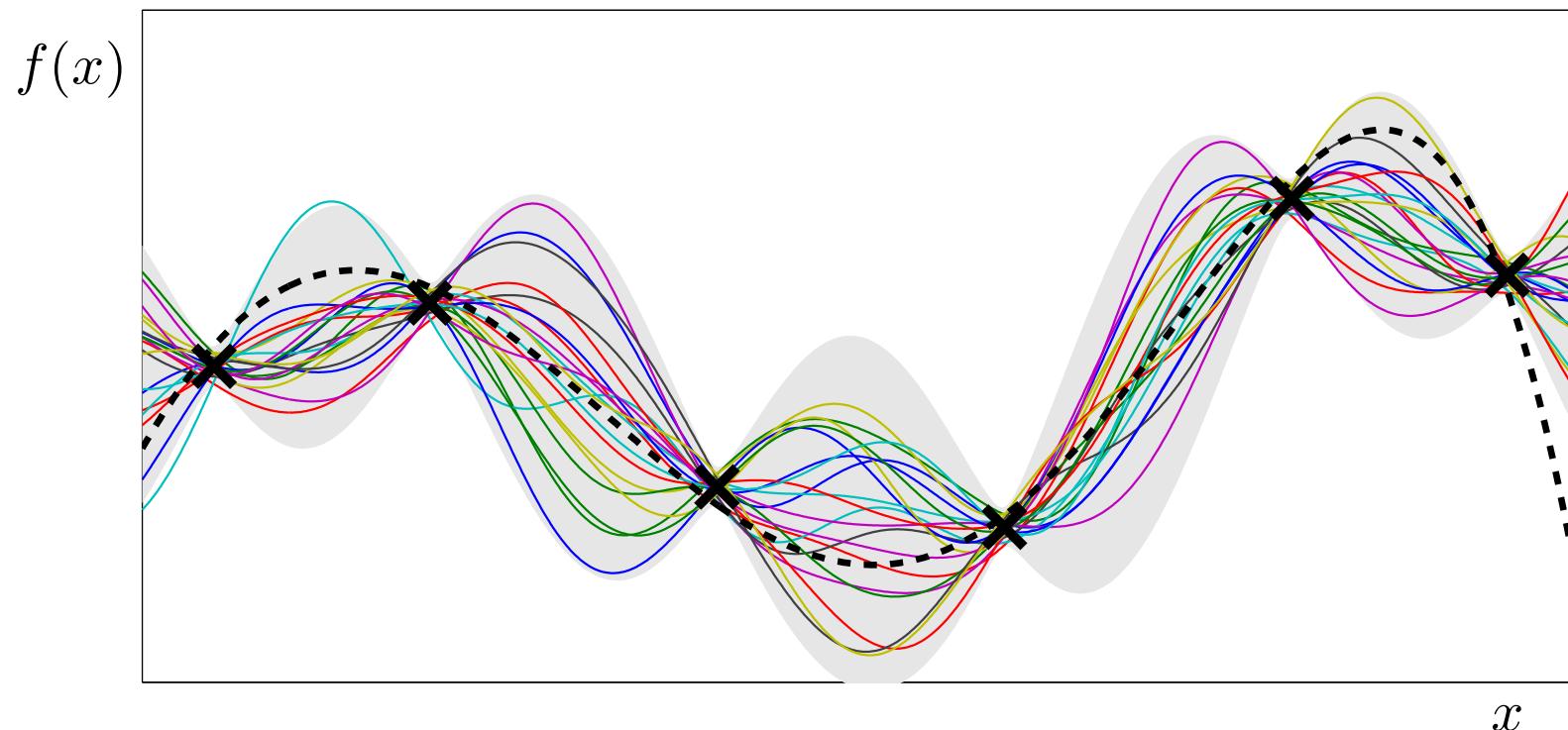


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After  $t$  observations,  $f(x) \sim \mathcal{N}(\mu_t(x), \sigma_t^2(x))$ .

# Mathematical Foundations: Definition

Gaussian process = generalization of multivariate Gaussian distribution to infinitely many variables.

**Definition:** a Gaussian process is a collection of random variables, any finite number of which have (consistent) Gaussian distributions.

A Gaussian distribution is fully specified by a mean vector,  $\mu$ , and covariance matrix  $\Sigma$ :

$$\mathbf{f} = (f_1, \dots, f_n) \sim \mathcal{N}(\mu, \Sigma), \text{ indices } i = 1, \dots, n$$

A Gaussian process is fully specified by a mean function  $m(\mathbf{x})$  and covariance function  $K(\mathbf{x}, \mathbf{x}')$ :

$$f(\mathbf{x}) \sim \mathcal{GP}(m(\mathbf{x}), K(\mathbf{x}, \mathbf{x}')), \text{ indices } \mathbf{x}$$

# Gaussian Processes

## – Noise free observations

- Model
  - $(x, f)$  are the observed locations and values (training data)
  - $(x^*, f^*)$  are the test or prediction data locations and values.

$$\begin{bmatrix} \mathbf{f} \\ \mathbf{f}_* \end{bmatrix} \sim \mathcal{N}\left(\mathbf{0}, \begin{bmatrix} K(X, X) & K(X, X_*) \\ K(X_*, X) & K(X_*, X_*) \end{bmatrix}\right)$$

- After observing some noise free data  $(x, f)$ ,

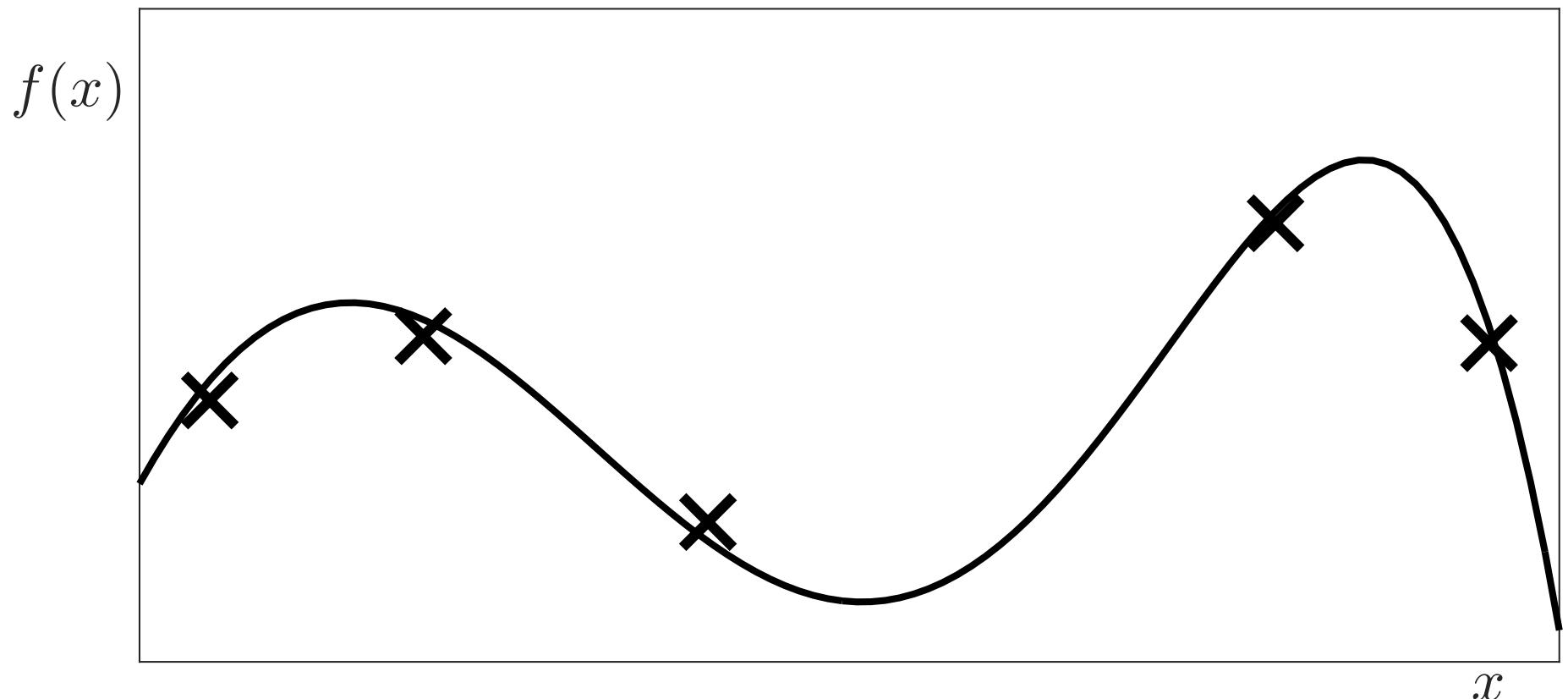
$$\begin{aligned} \mathbf{f}_* | X_*, X, \mathbf{f} &\sim \mathcal{N}\left(K(X_*, X)K(X, X)^{-1}\mathbf{f},\right. \\ &\quad \left.K(X_*, X_*) - K(X_*, X)K(X, X)^{-1}K(X, X_*)\right) \end{aligned}$$

# Bayesian Optimisation with Upper Confidence Bounds

Model  $f \sim \mathcal{GP}$ .

Gaussian Process Upper Confidence Bound (GP-UCB)

(Srinivas et al. 2010)

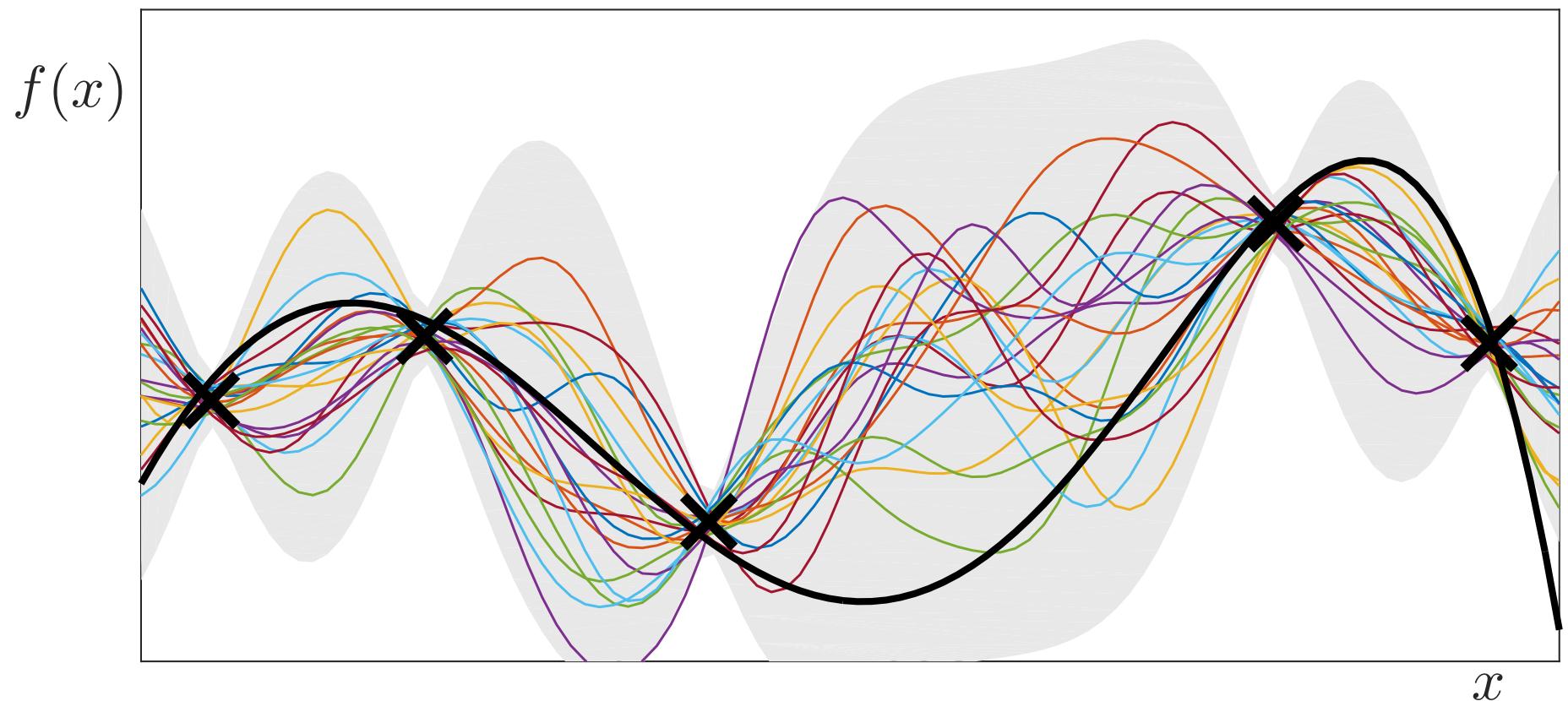


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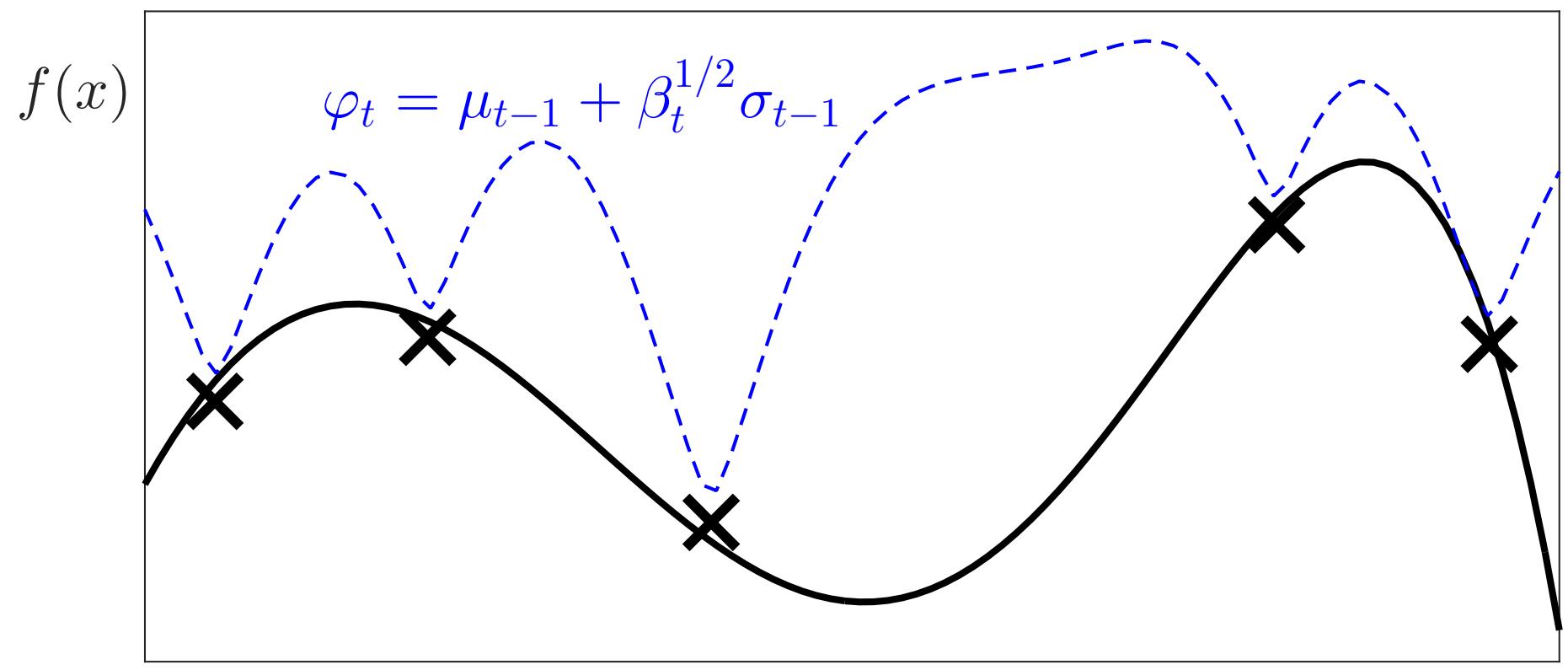
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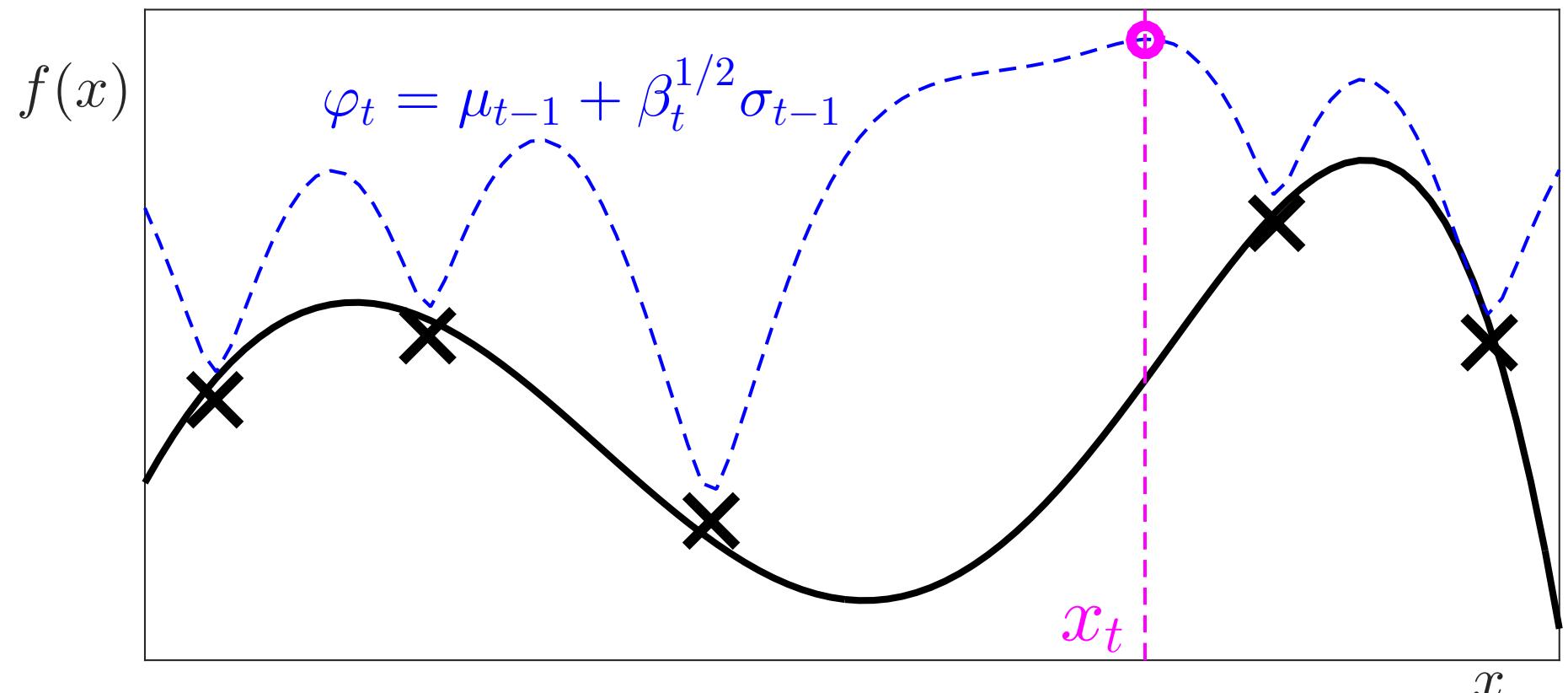
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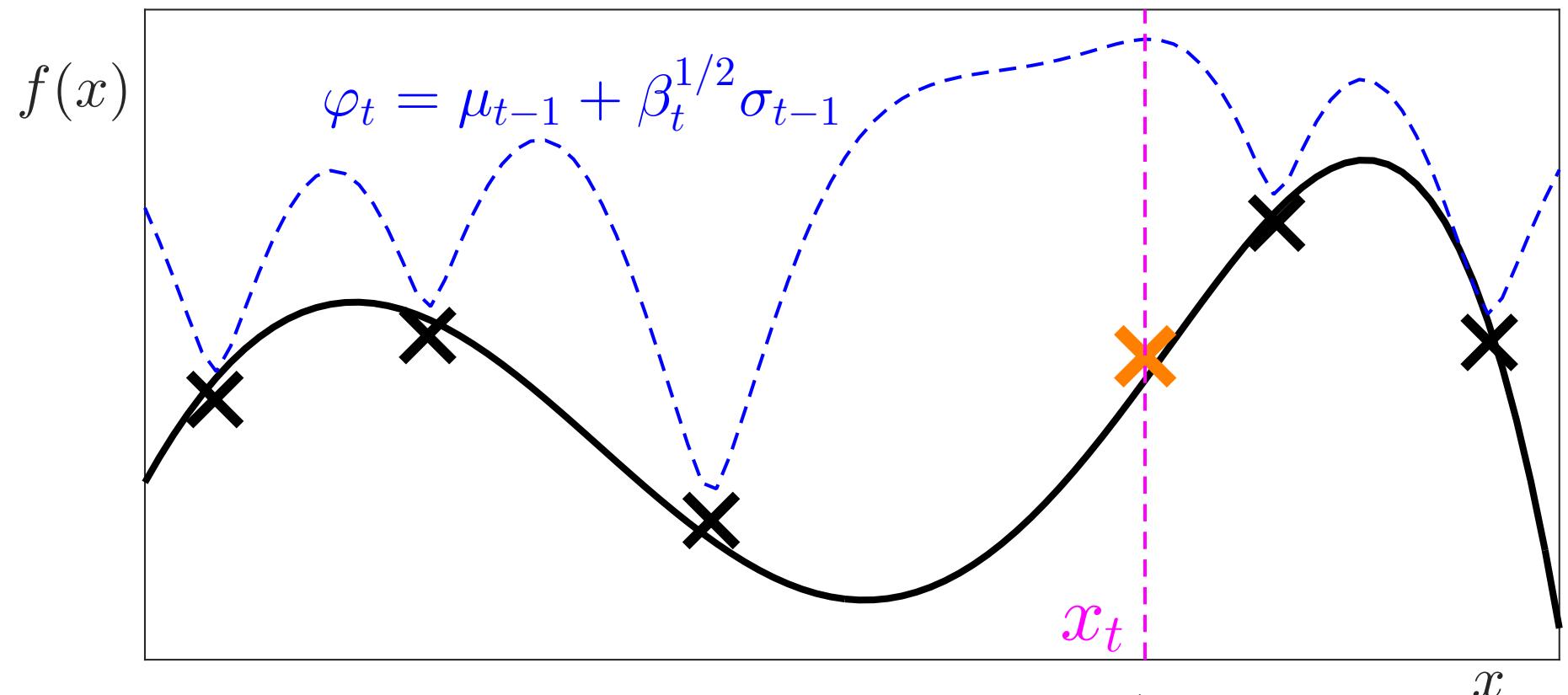
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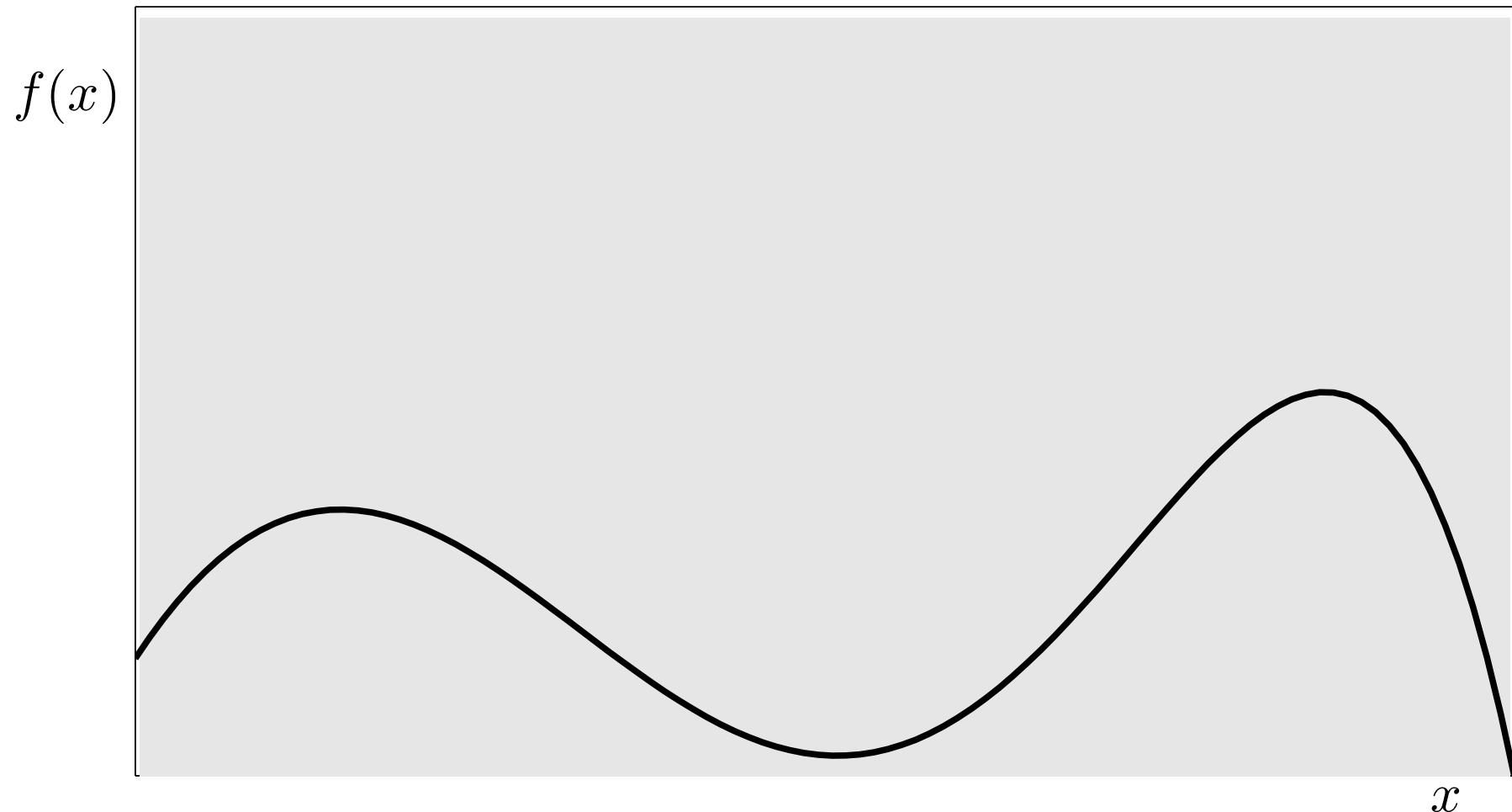
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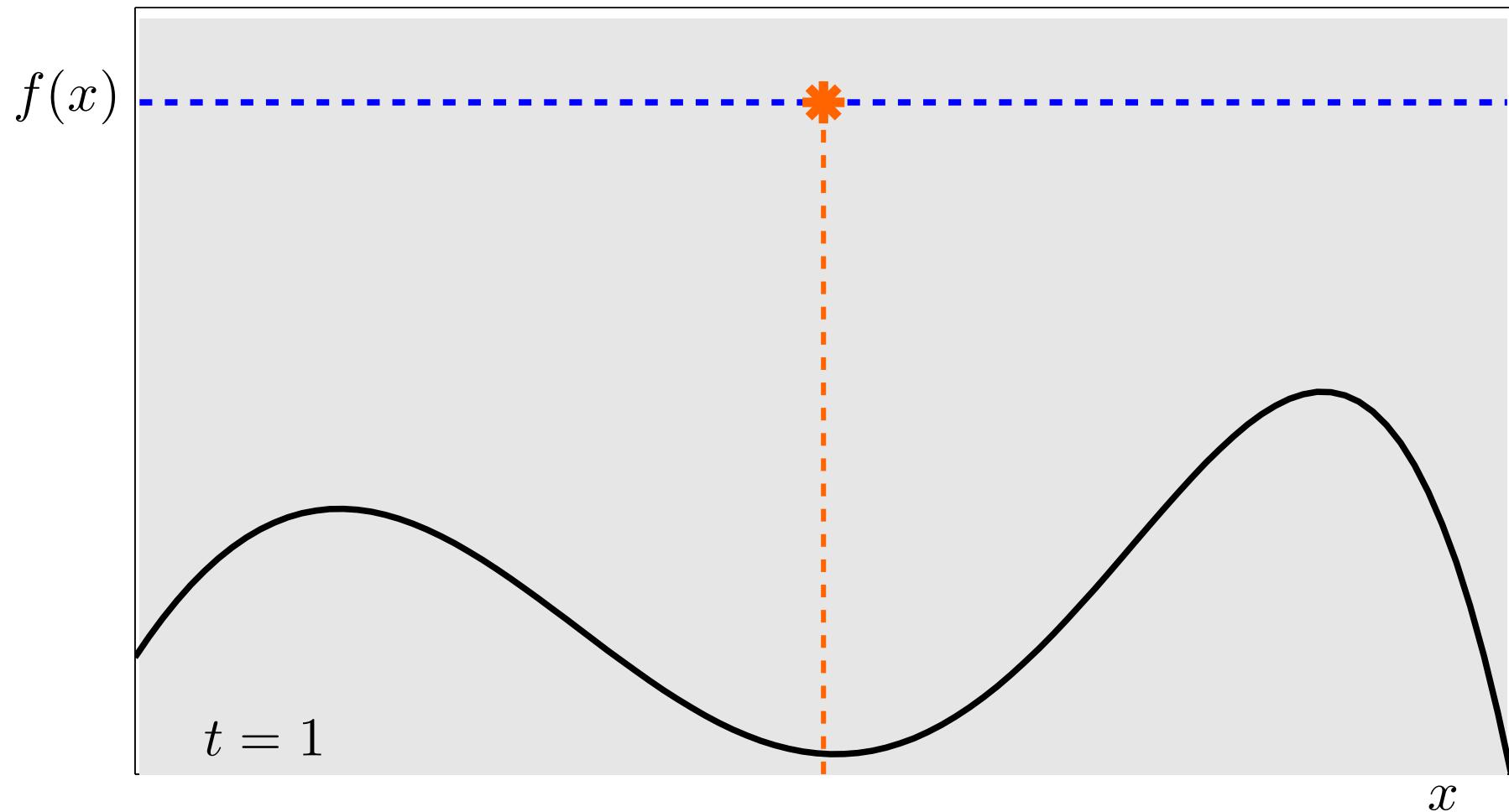
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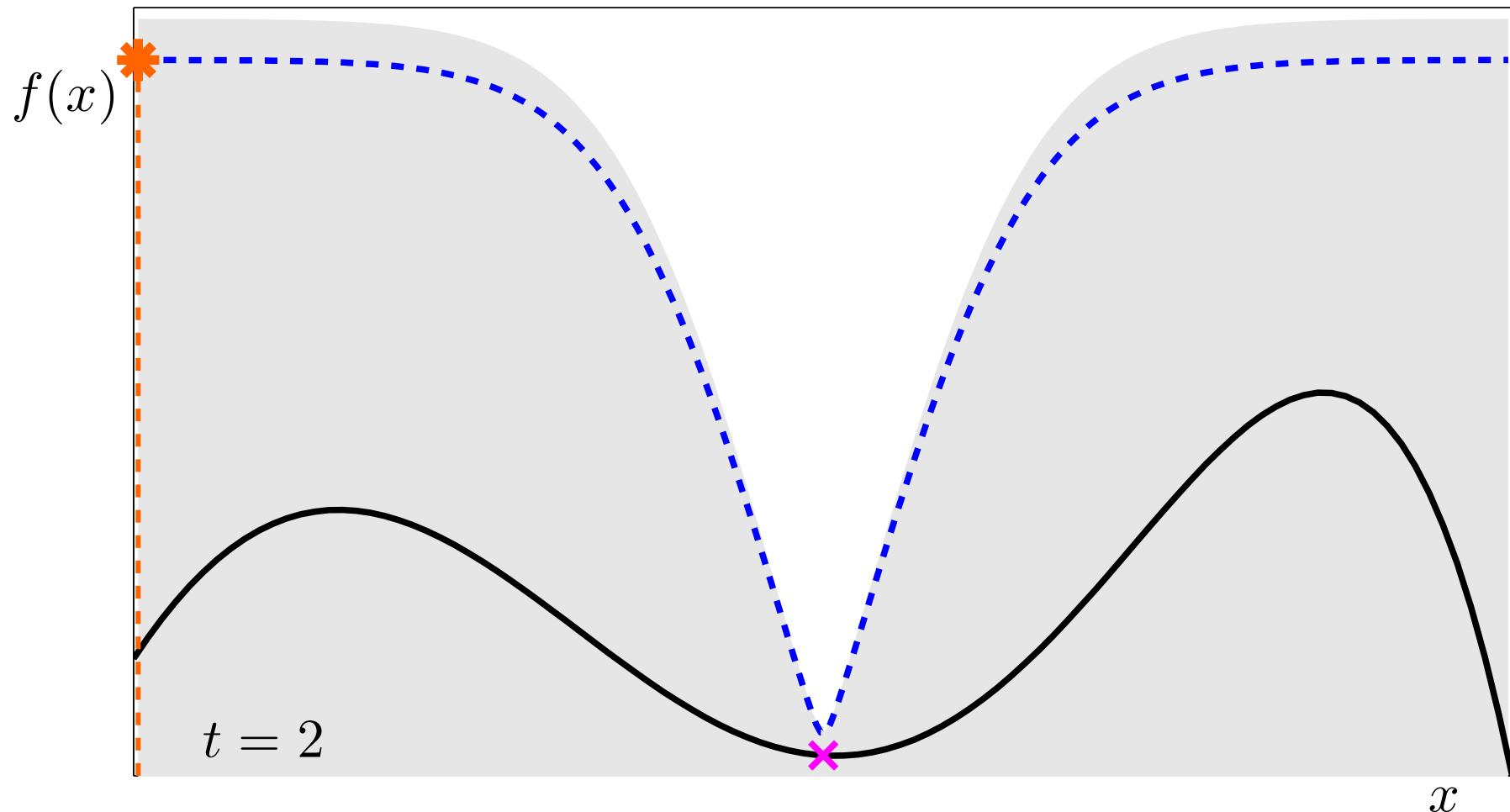
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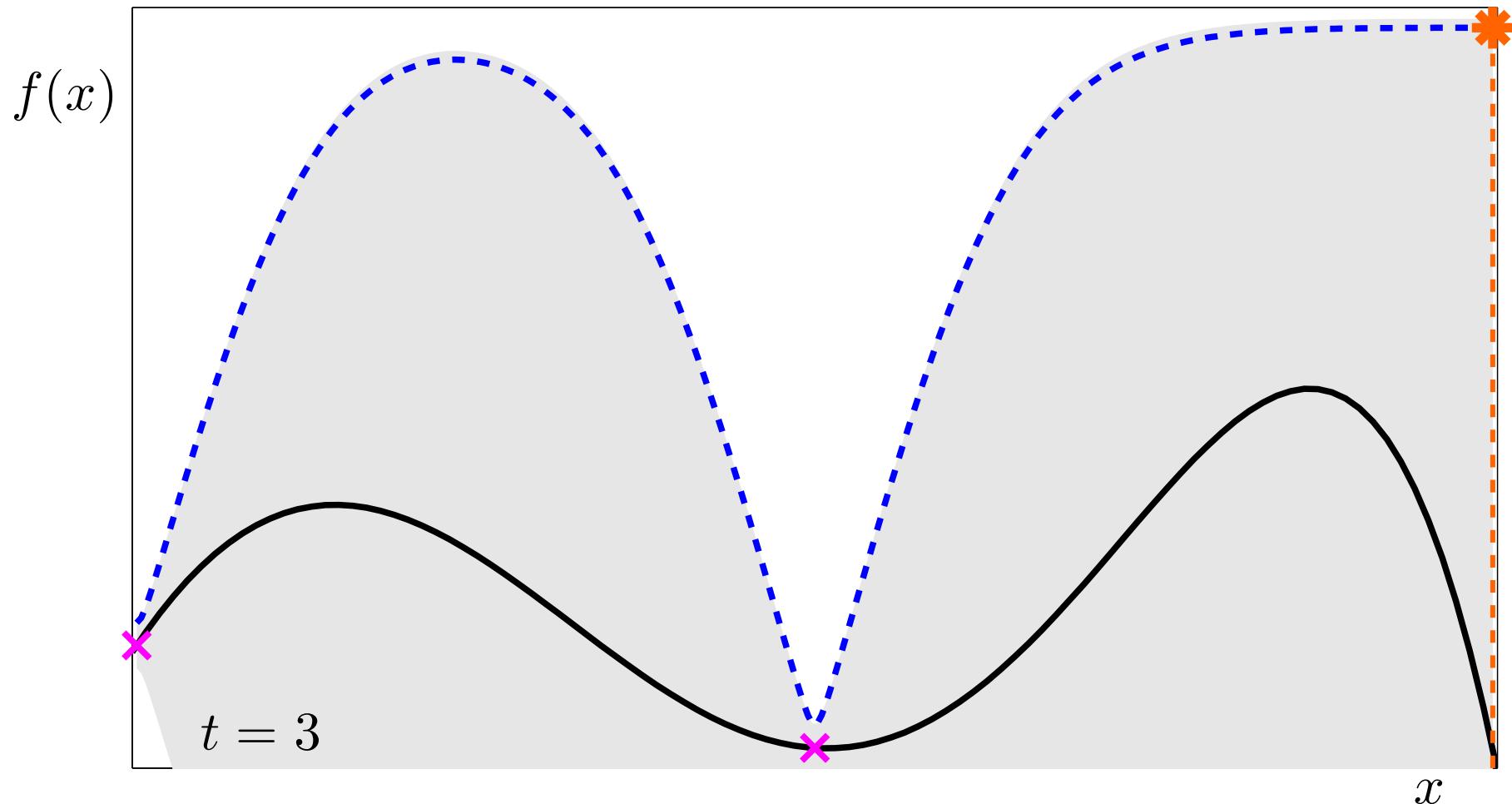
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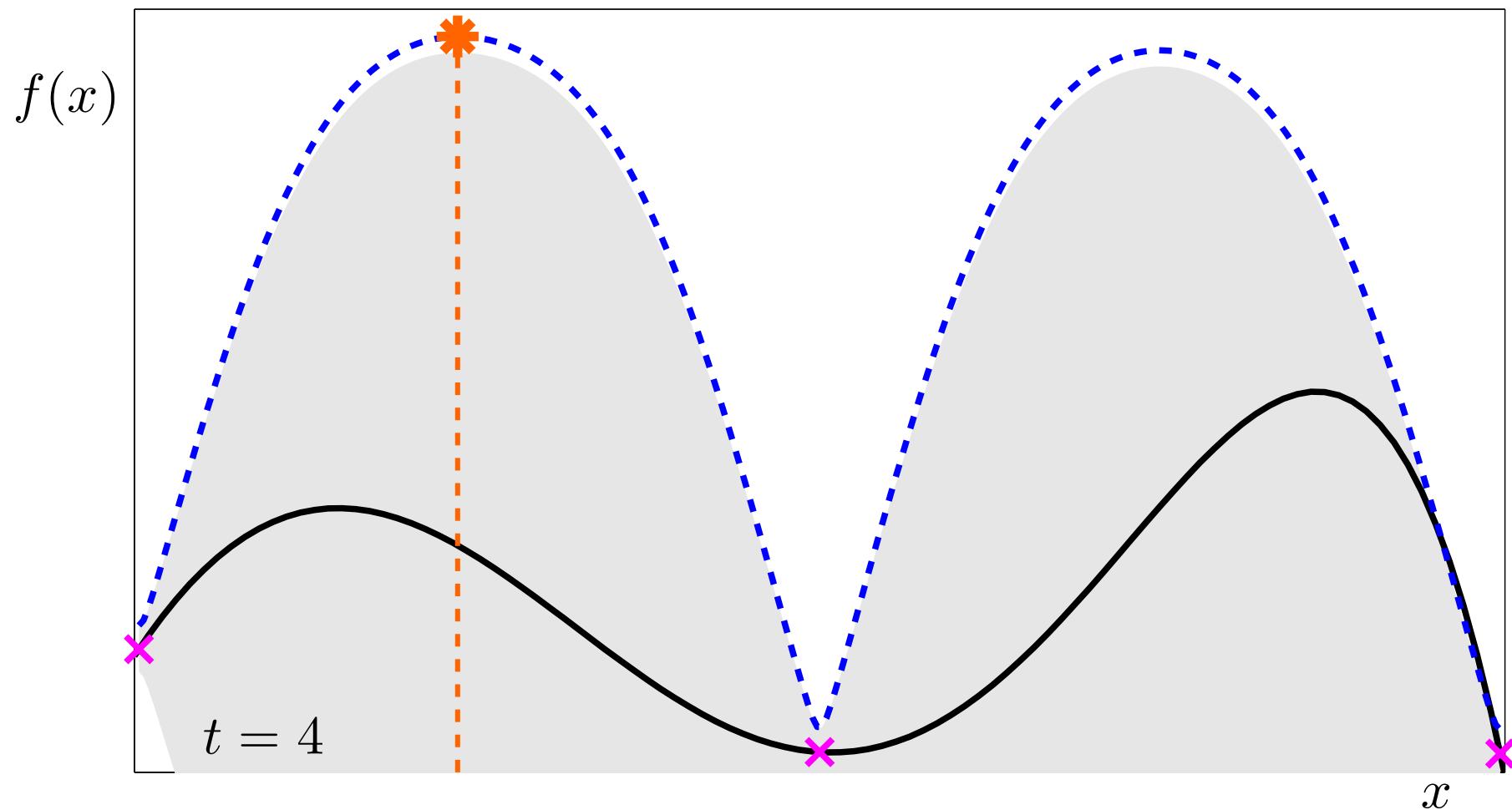
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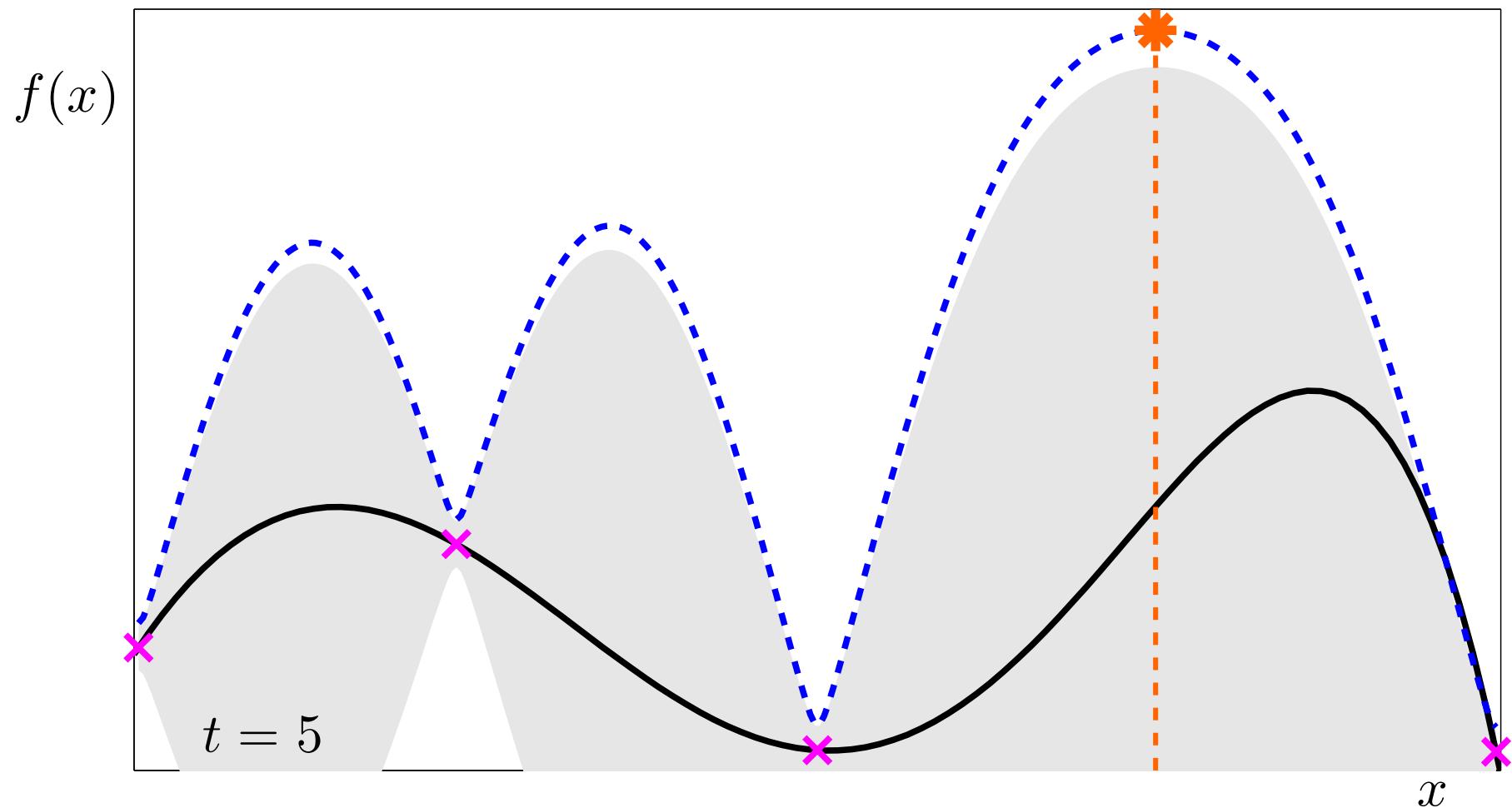
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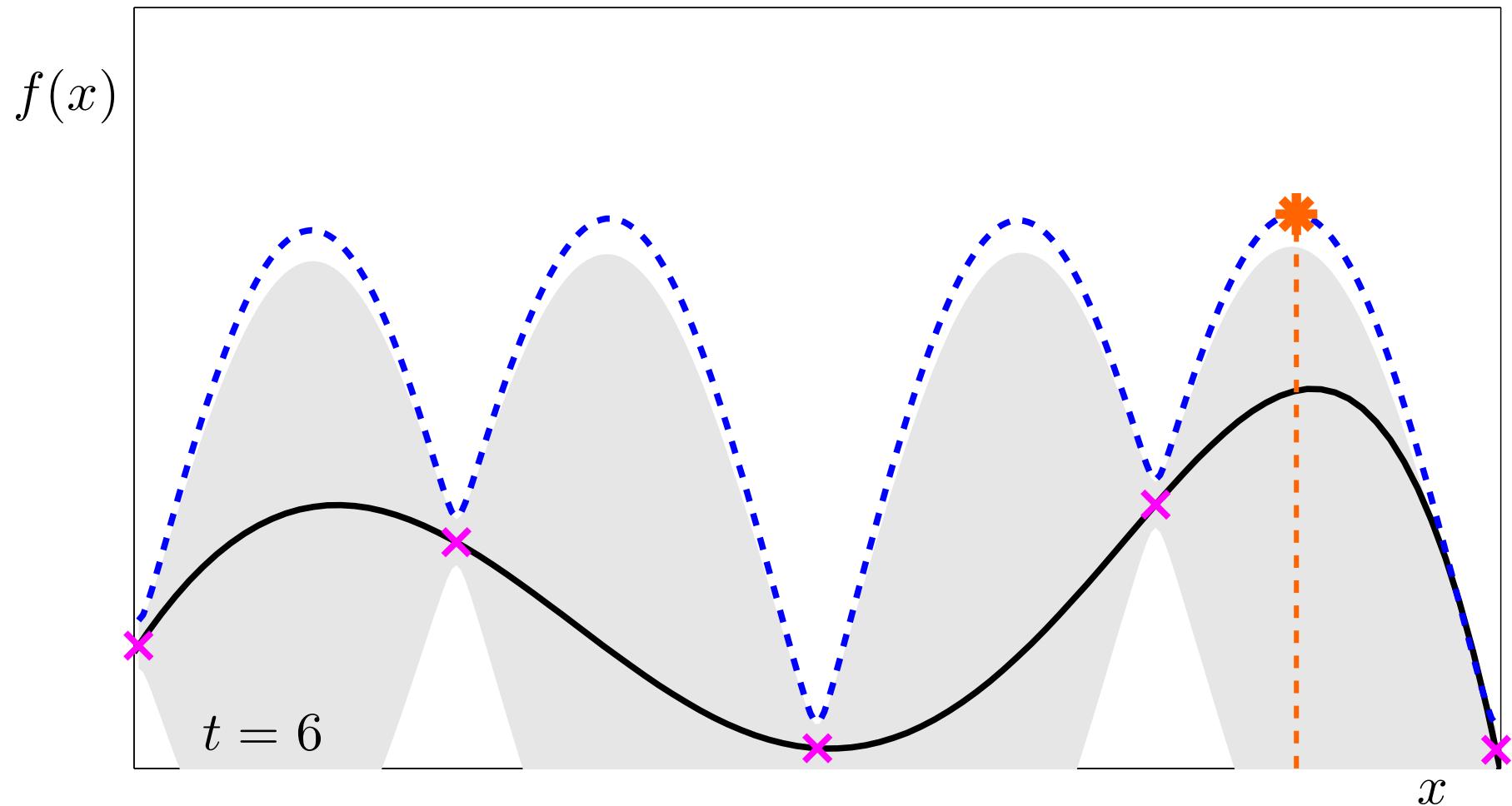
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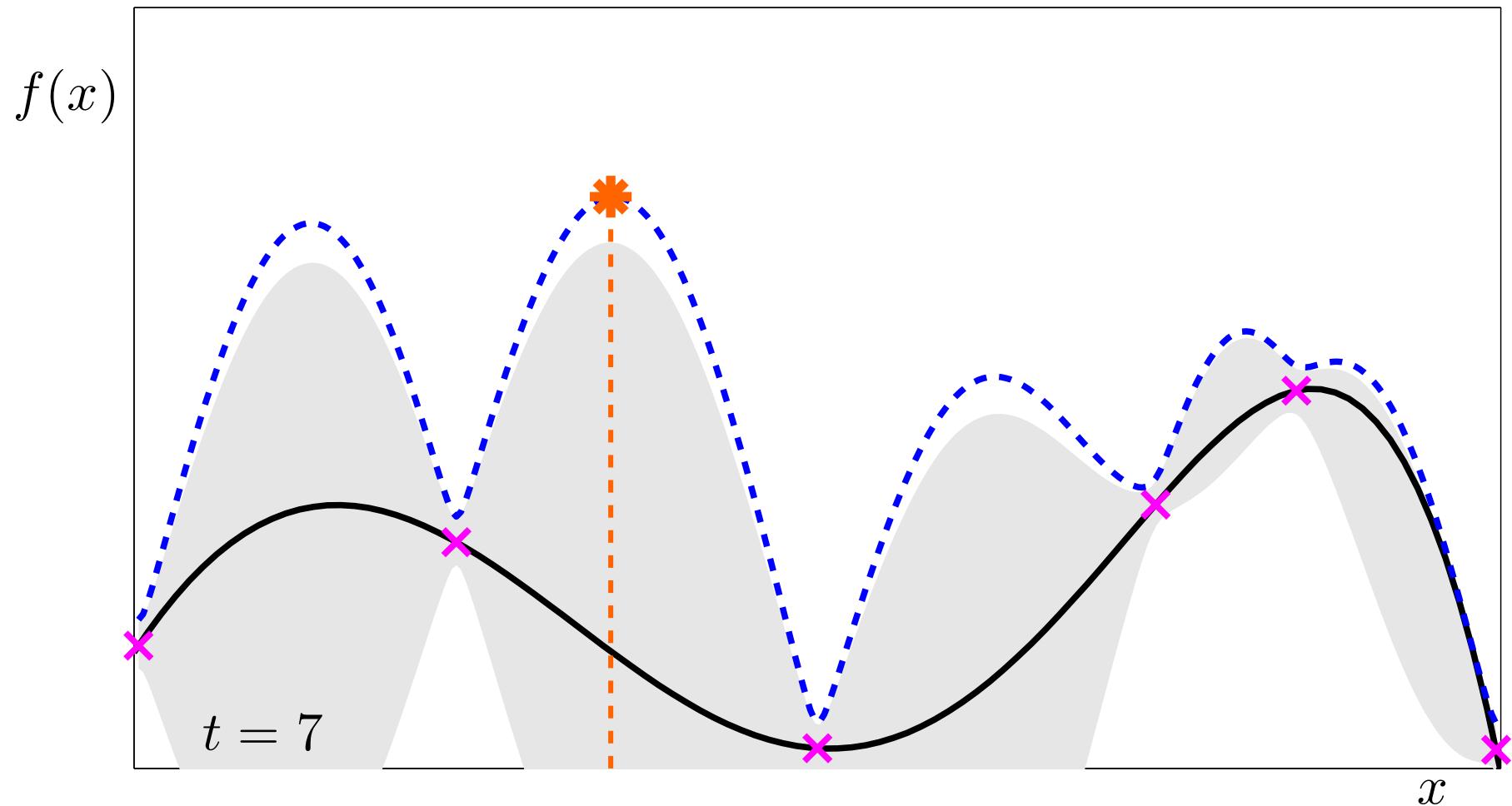
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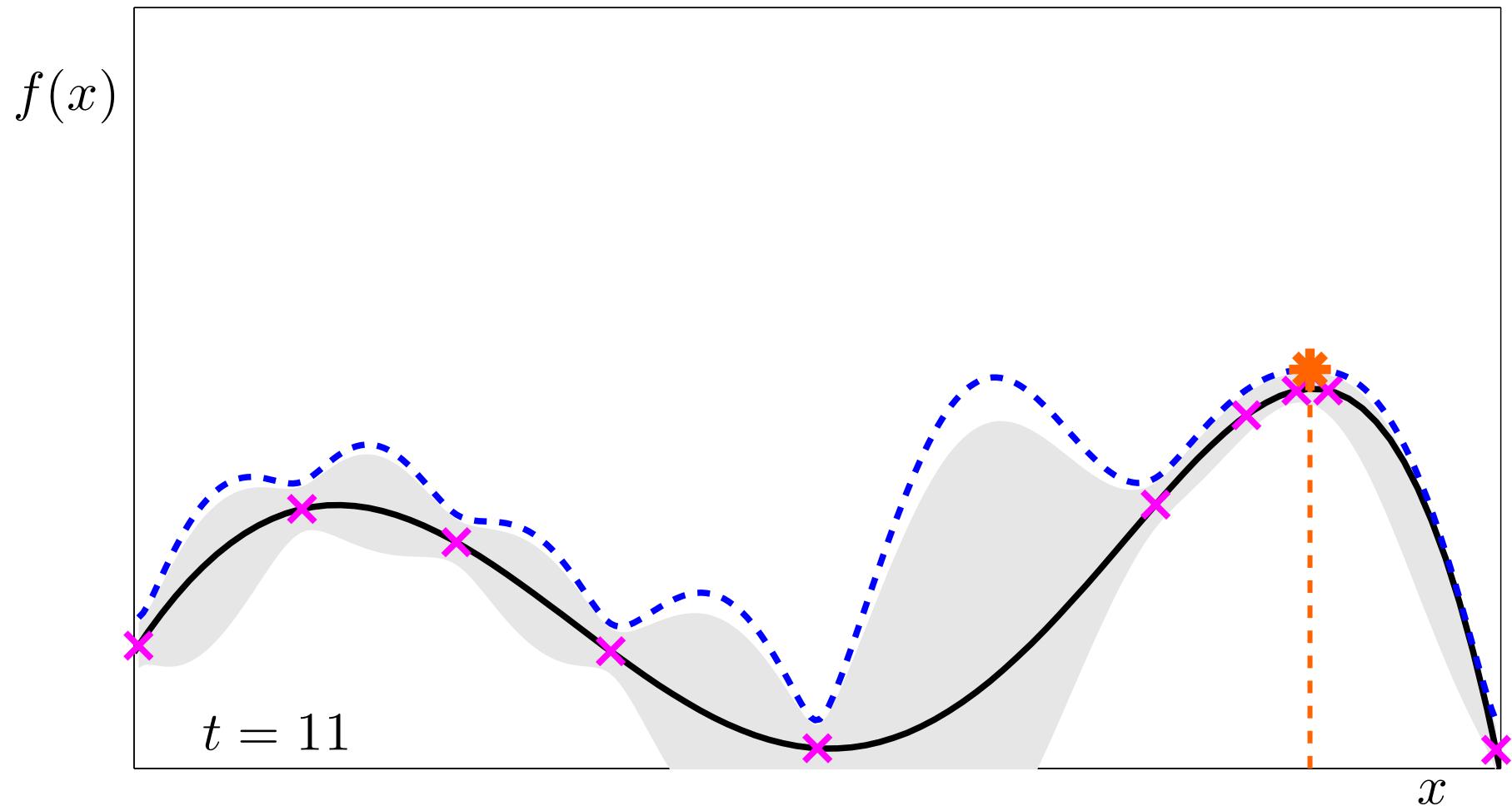


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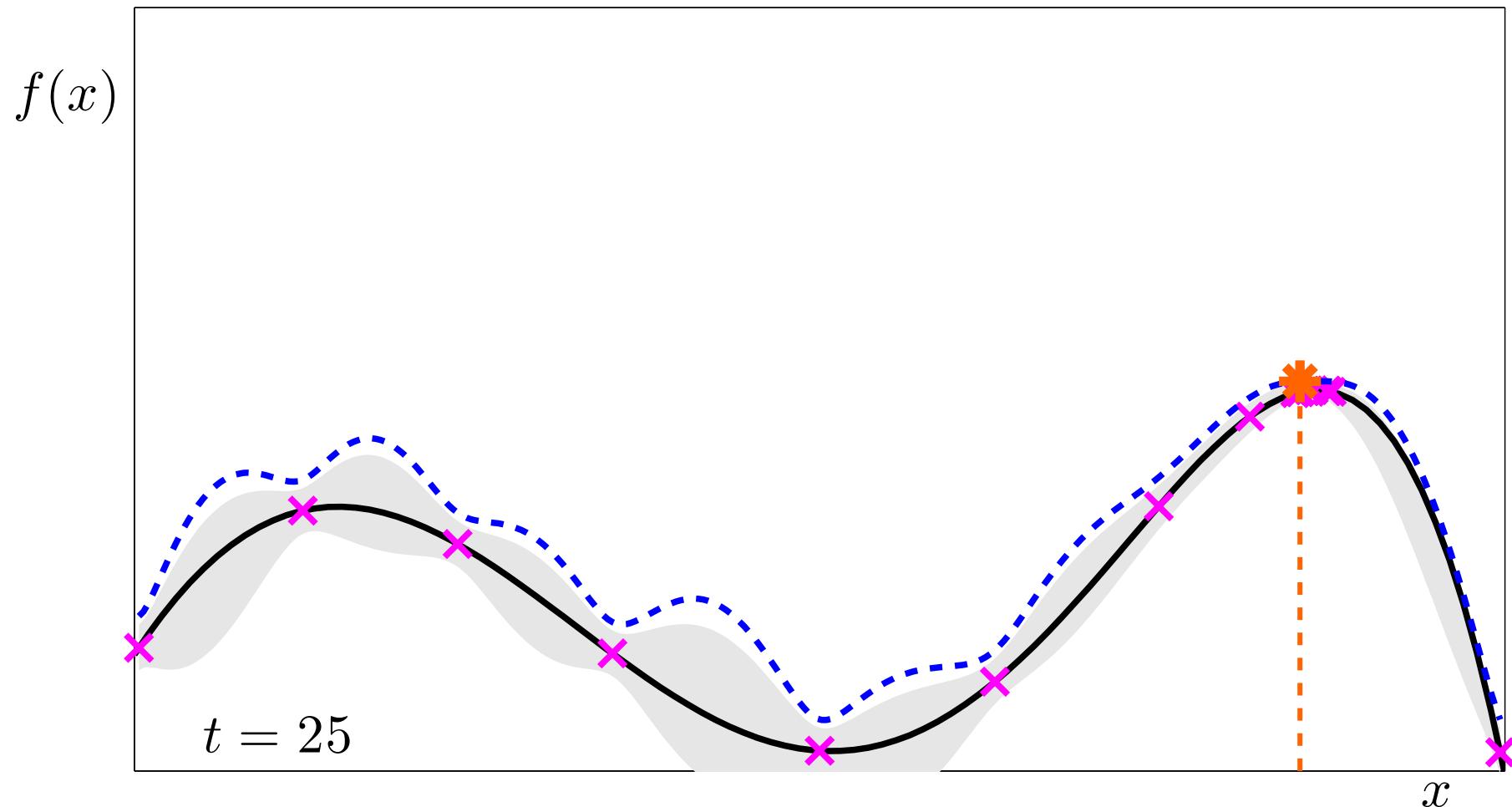


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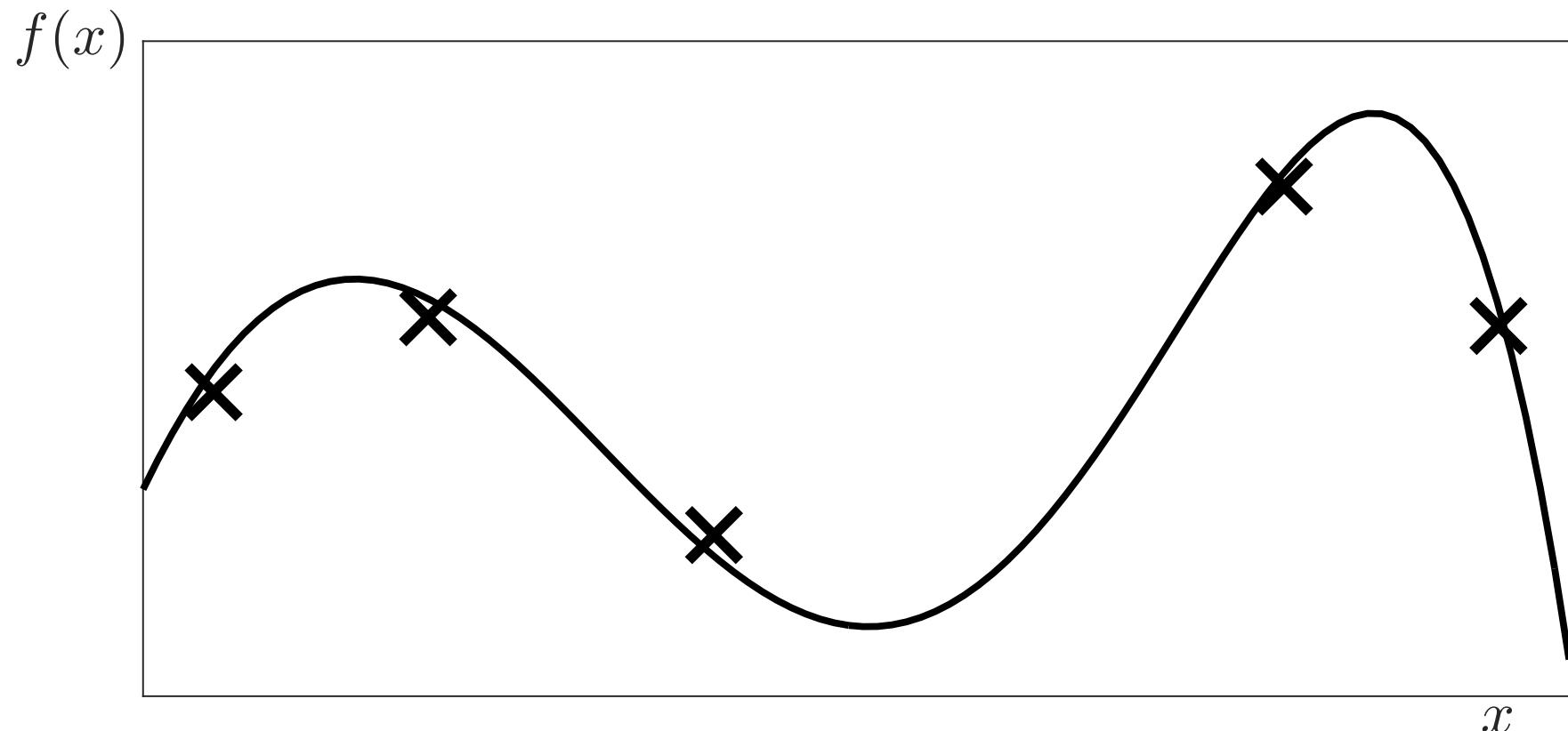


# Bayesian Optimisation with Thompson Sampling

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Thompson Sampling (TS)

(Thompson, 1933).

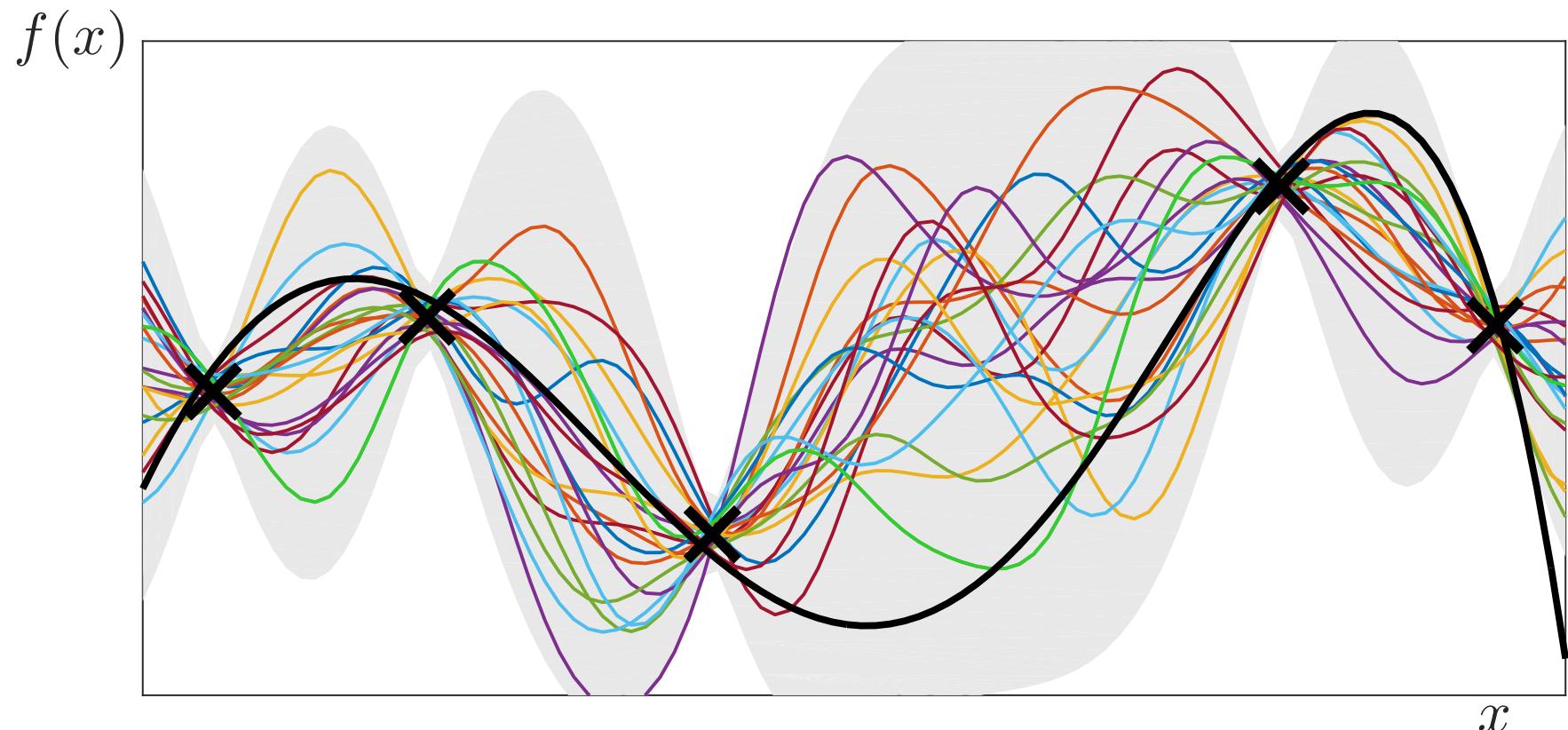


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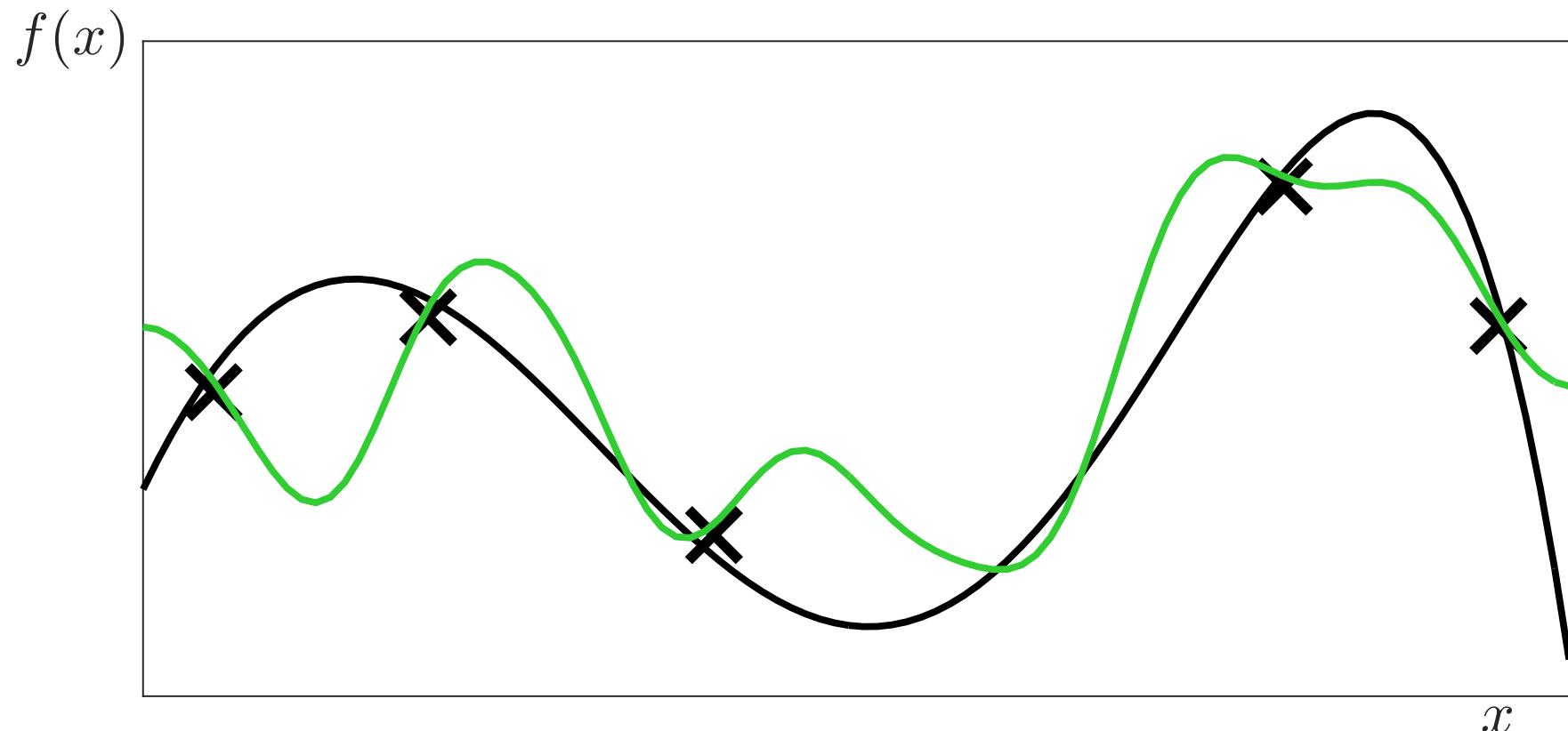
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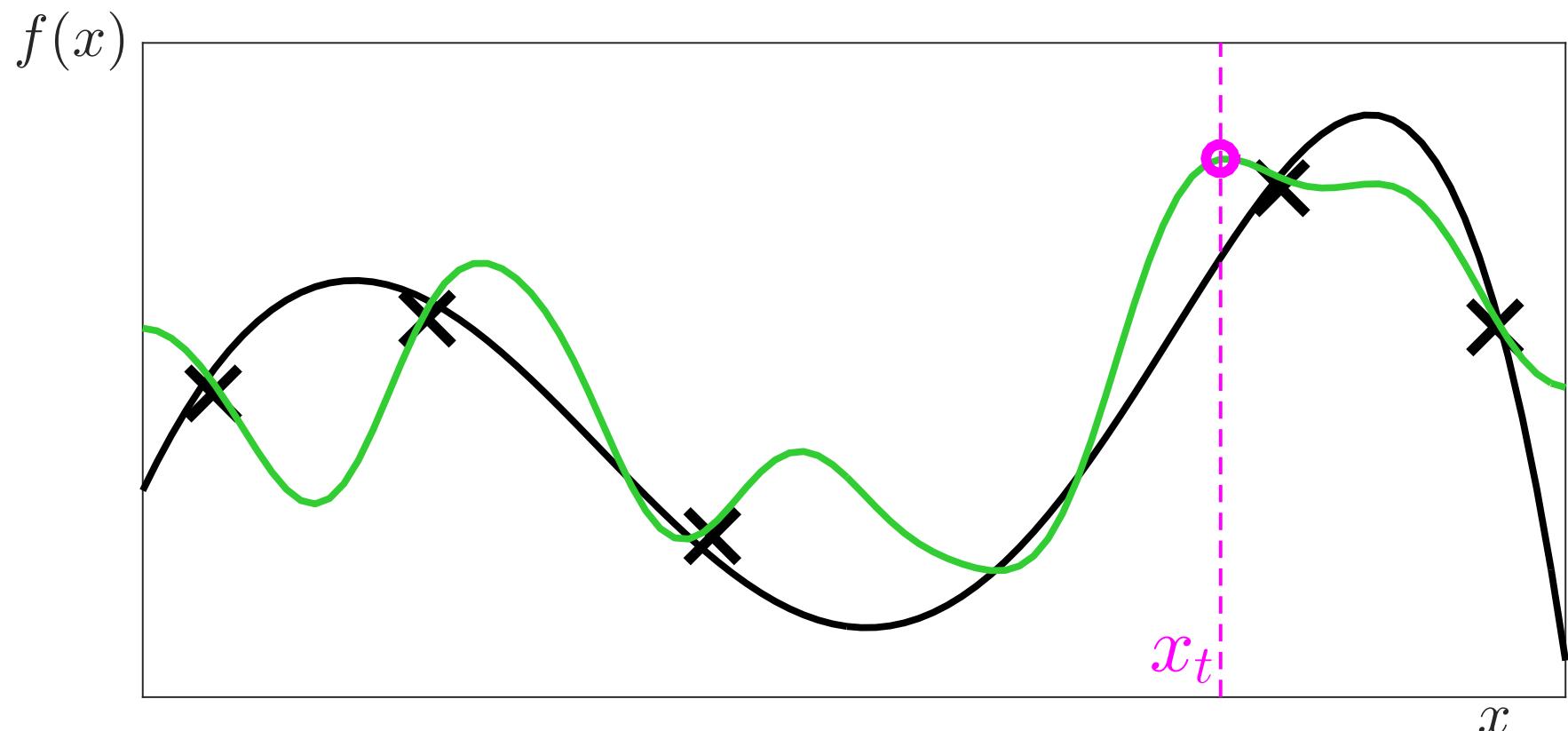
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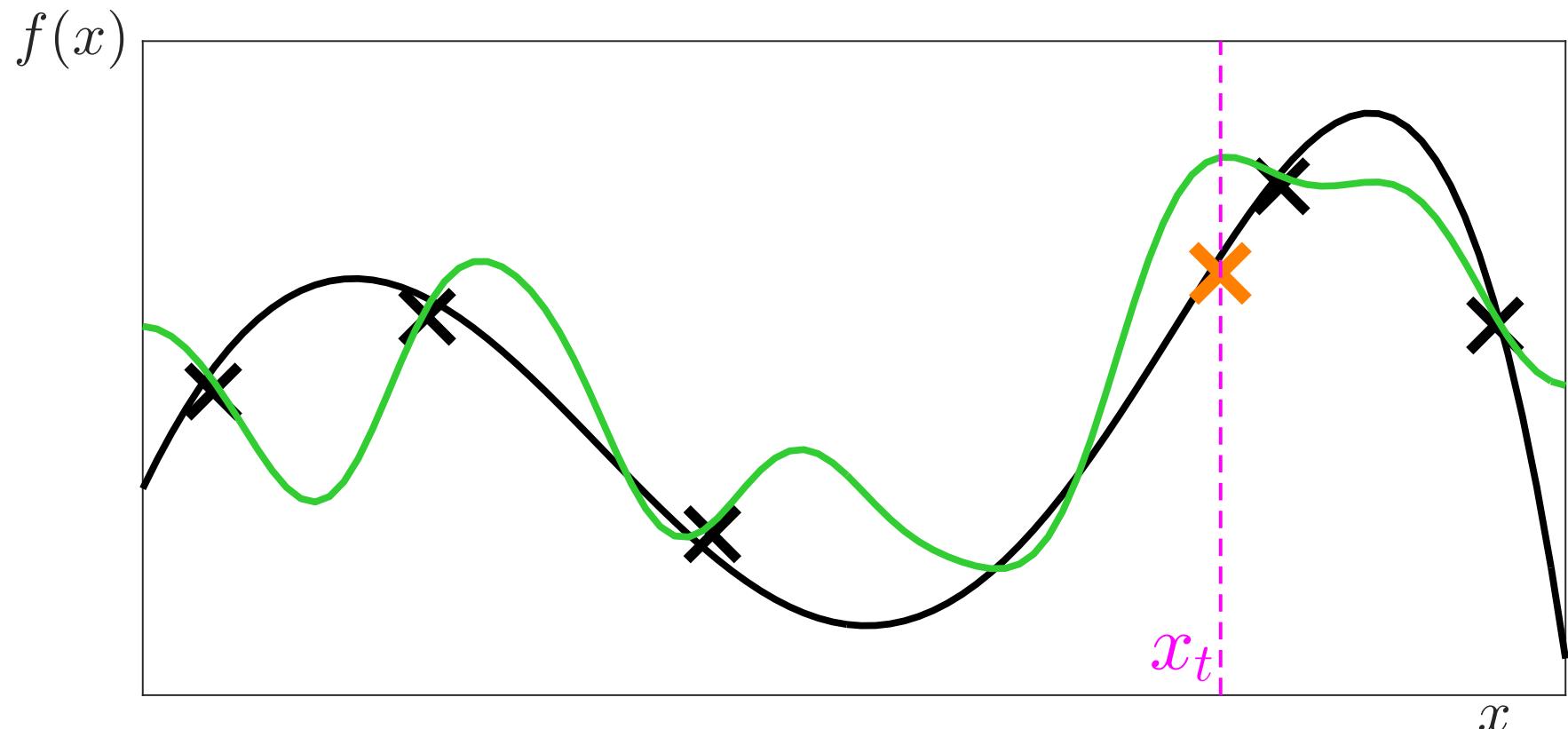
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## Reference for more detailed tutorial

- “A Tutorial on Bayesian Optimization of Expensive Cost Functions, with Application to Active User Modeling and Hierarchical Reinforcement Learning”  
(<https://arxiv.org/pdf/1012.2599.pdf>)

## Slides from

- Kirthevasan Kandasamy's talk on "An Introduction to Bayesian Optimisation and (Potential) Applications in Materials Science"  
(<https://people.eecs.berkeley.edu/~kandasamy/talks/electrochem-bo-slides.pdf>)
- University of Washington course stat527 recitation Slides 2  
(<https://sites.stat.washington.edu/courses/stat527/s14/recitation/Slides2.pptx>)
- CMU S19 10-403 slides on "Bayesian Optimization - Gaussian Processes"  
(<https://www.andrew.cmu.edu/course/10-403/slides/S19GaussianProcesses.pdf>)