
Quiz 5 Solution

1. Consider the vectors $\vec{v}_1 = \begin{pmatrix} 1 \\ -2 \\ -4 \end{pmatrix}$, $\vec{v}_2 = \begin{pmatrix} -3 \\ 7 \\ 6 \end{pmatrix}$, $\vec{b} = \begin{pmatrix} 3 \\ -1 \\ h \end{pmatrix}$. For which value(s) of h is \vec{b} in $\text{Span}\{\vec{v}_1, \vec{v}_2\}$? For which value(s) of h are the vectors $\vec{v}_1, \vec{v}_2, \vec{b}$ linearly independent?

Solution: We need to check when the system $[\vec{v}_1 \ \vec{v}_2]\vec{x} = \vec{b}$ has solution.

$$\begin{pmatrix} 1 & -3 & 3 \\ -2 & 7 & -1 \\ -4 & 6 & h \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -3 & 3 \\ 0 & 1 & 5 \\ 0 & -6 & h+12 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -3 & 3 \\ 0 & 1 & 5 \\ 0 & 0 & h+42 \end{pmatrix}.$$

The system $[\vec{v}_1 \ \vec{v}_2]\vec{x} = \vec{b}$ is consistent if and only if $h = -42$. Now, the vectors $\vec{v}_1, \vec{v}_2, \vec{b}$ are linearly independent if and only if, the system $[\vec{v}_1 \ \vec{v}_2 \ \vec{b}]\vec{x} = \vec{0}$ has a unique solution, and according to the reduced matrix, this happens if and only if $h \neq -42$. ■

2. Let $\vec{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\vec{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$, $\vec{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$, be the standard basis for \mathbb{R}^3 . Let T be the linear transformation that satisfies $T(\vec{e}_1) = \begin{pmatrix} 1 \\ -3 \\ 2 \end{pmatrix}$, $T(\vec{e}_2) = \begin{pmatrix} 0 \\ 1 \\ -3 \end{pmatrix}$, and $T(\vec{e}_3) = \begin{pmatrix} -2 \\ 4 \\ 3 \end{pmatrix}$. Determine if the transformation is one-to-one and if it is onto. Justify.

Solution: The standard matrix for T is

$$[T(\vec{e}_1) \ T(\vec{e}_2) \ T(\vec{e}_3)] = \begin{pmatrix} 1 & 0 & -2 \\ -3 & 1 & 4 \\ 2 & -3 & 3 \end{pmatrix}.$$

Reducing the matrix we get

$$\begin{pmatrix} 1 & 0 & -2 \\ -3 & 1 & 4 \\ 2 & -3 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -2 \\ 0 & -3 & 7 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix}$$

Since there is a pivot in every row and in every column, then the transformation is both one-to-one and onto. ■

3. Consider the matrix

$$A = \begin{pmatrix} 1 & 0 & -2 \\ -3 & 1 & 4 \\ 2 & -3 & 3 \end{pmatrix}.$$

Prove that it is invertible and compute its inverse.

Solution: The matrix is the same as in the previous example, so, since the associated transformation is one-to-one and onto, then the matrix is invertible. To compute the inverse we reduce the matrix alongside the identity matrix

$$\begin{aligned}
\left(\begin{array}{ccc|ccc} 1 & 0 & -2 & 1 & 0 & 0 \\ -3 & 1 & 4 & 0 & 1 & 0 \\ 2 & -3 & 3 & 0 & 0 & 1 \end{array}\right) &\rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 3 & 1 & 0 \\ 0 & -3 & 7 & -2 & 0 & 1 \end{array}\right) \rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 3 & 1 & 0 \\ 0 & 0 & 1 & 7 & 3 & 1 \end{array}\right) \\
&\rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 15 & 6 & 2 \\ 0 & 1 & 0 & 17 & 7 & 2 \\ 0 & 0 & 1 & 7 & 3 & 1 \end{array}\right)
\end{aligned}$$

Therefore $A^{-1} = \begin{pmatrix} 15 & 6 & 2 \\ 17 & 7 & 2 \\ 7 & 3 & 1 \end{pmatrix}.$

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