# PHYS 2211 Test 1 Spring 2011

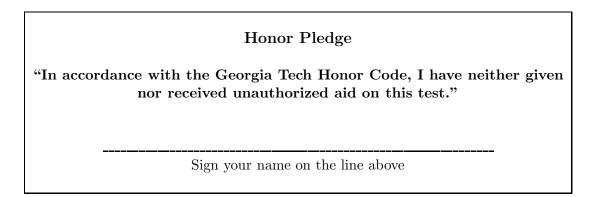
Name(print)	

#### Instructions

- Read all problems carefully before attempting to solve them.
- Your work must be legible, and the organization must be clear.
- You must show all work, including correct vector notation.
- Correct answers without adequate explanation will be counted wrong.
- Incorrect work or explanations mixed in with correct work will be counted wrong. Cross out anything you don't want us to read!
- Make explanations correct but brief. Don't write a lot of prose.
- Include diagrams!
- Show what goes into a calculation, not just the final number, e.g.:  $\frac{a \cdot b}{c \cdot d} = \frac{(8 \times 10^{-3})(5 \times 10^6)}{(2 \times 10^{-5})(4 \times 10^4)} = 5 \times 10^4$
- Give standard SI units with your results.

Unless specifically asked to derive a result, you may start from the formulas given on the formula sheet, including equations corresponding to the fundamental concepts. If a formula you need is not given, you must derive it.

If you cannot do some portion of a problem, invent a symbol for the quantity you can't calculate (explain that you are doing this), and use it to do the rest of the problem.

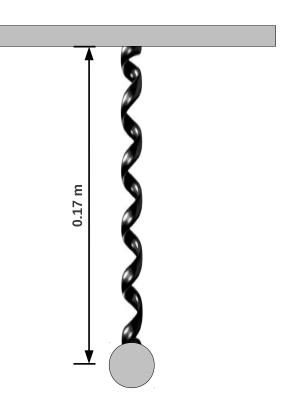


PHYS 2211

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Problem	Score	Grader
Problem 1 (25 pts)		
Problem 2 (30 pts)		
Problem 3 (25 pts)		
Problem 4 (20 pts)		

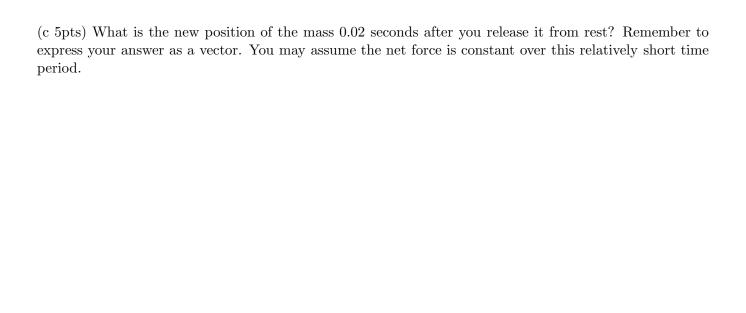
A mass of 0.03 kg is attached to a vertically-hanging spring with a spring stiffness of 12 N/m and a relaxed length of 0.15 m. You pull the mass downwards, so that the spring's length is 0.17m. Then you release it so that when it leaves your hand it has zero velocity.



# The First Time Step

(a 5pts) What is the net force on the mass the instant after you release it? Remember to express your answer as a vector.

(b 5pts) What is the new velocity of the mass 0.02 seconds after you release it from rest? Remember to express your answer as a vector. You may assume the net force is constant over this relatively short time period.

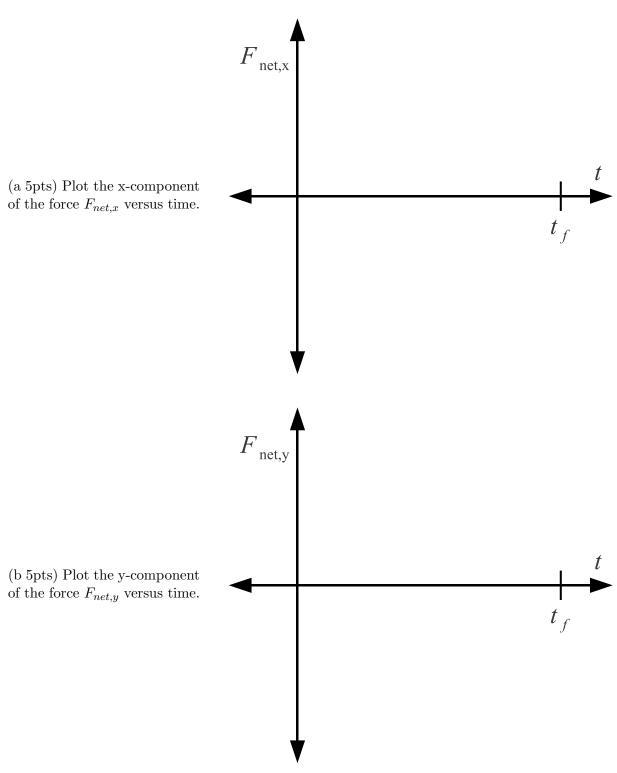


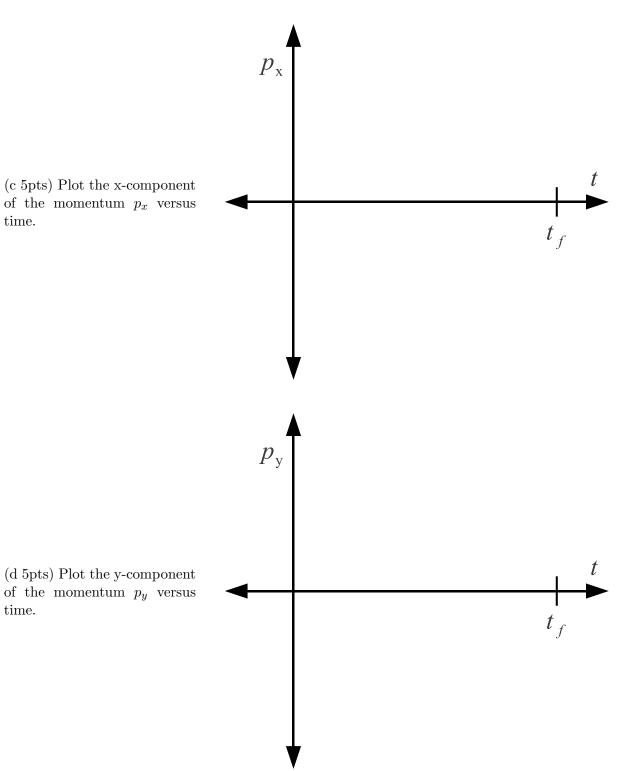
# The Second Time Step

(d 10pts) What is the new velocity of the mass, a second time step later (i.e. at 0.04 seconds) after you release it from rest? Remember to express your answer as a vector. You may assume the net force is constant over the relatively short time period 0.02 to 0.04 seconds.

#### Problem 2 (30 Points)

Consider a ball of mass m that is kicked such that it has and an initial velocity of  $\langle v_{x,i}, v_{y,i}, 0 \rangle$  m/s, where  $v_{x,i} > 0$  and  $v_{y,i} > 0$  are both positive. The initial position of the ball is  $\langle 0, 0, 0 \rangle$  m and the only force acting on the ball is gravity (the weight) In the questions below, you will be asked to plot various components of the force, velocity and position versus time. When doing this, consider a time interval from the instant just after the ball is kicked (t = 0) until the instant before the ball reaches the ground  $(t = t_f)$ .

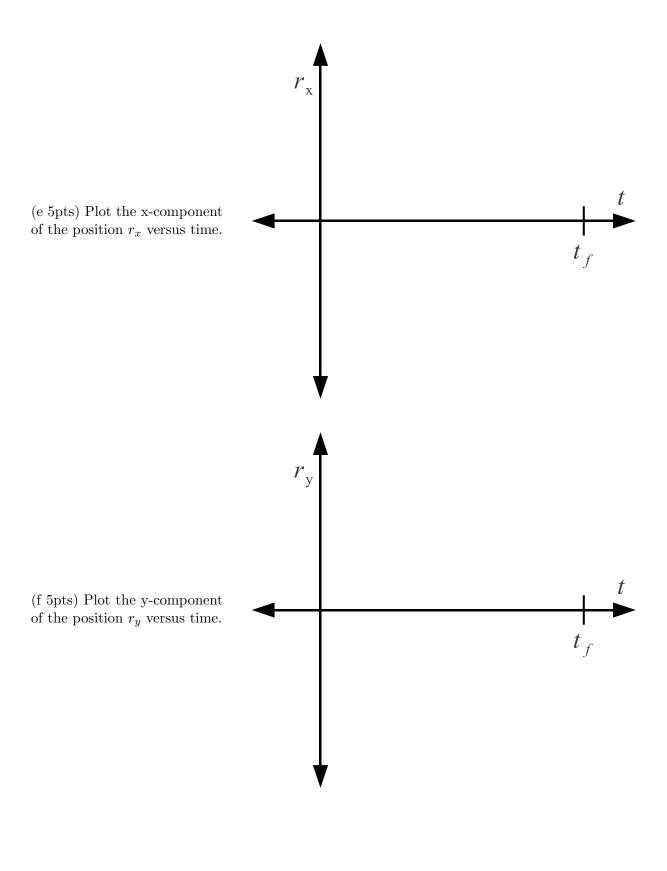




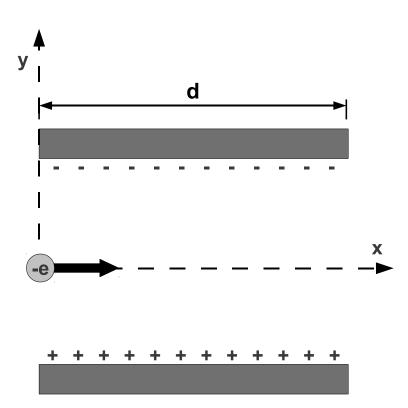
(d 5pts) Plot the y-component of the momentum  $p_y$  versus

time.

time.



An electron of mass  $m_e$  enters a set of charged parallel plates with an initial velocity  $\vec{v}_0 = \langle v_{ix}, 0, 0 \rangle$ . The electron experiences a constant force  $\vec{F} = \langle 0, -F, 0 \rangle$  in the negative y direction. The gravitational force on the electron is small compared to this force and can be neglected. The length of the plates is d. You may assume that the electron is moving, at all times, with a speed much less than c.



(a 5pts) How long does it take for the electron to reach the end of the parallel plates (i. e. at x = d)?



#### Problem 4 (20 Points)

Recall that, in last week's lab, you studied the motion of a fan cart, and you wrote a computer model (VPython script) to predict a fancart's motion. The script given below, which is nearly identical to your computer model from lab, is missing a few lines of code. In the space provided in the body of the script, add the statements necessary to complete the code.

```
#*****************************
from __future__ import division
from visual import *
track = box(pos = vector(0, -.05, 0), size = (2.0, 0.05, .10), color = color.white)
cart = box(pos=vector(0.081,0,0), size=(.1,.04,.06), color=color.green)
mcart = .2395
vcart = vector(.375, .368, 0)
pcart = mcart*vcart
print 'cart momentum =', pcart
deltat = 0.01
t = 0
Fair = vector(-0.062, 0, 0)
while t < 5.01:
    rate(100)</pre>
```

(a 12pts) Add statements here to update the momentum and the position of the fancart.

Refer to the code above to answer the following four questions:
(b 2pts) What is the initial position of the fancart? (Answer should be a vector with units.)
(c 2pts) What is the initial momentum of the fancart? (Answer should be a vector with units.)
(d 2pts) What is the net force on the fancart? (Answer should be a vector with units.)
(e 2pts) The animation from the computer model, as written above, shows motion of a fancart that is not typically observed for fancarts in lab experiments. (Hint: at the end of last week's fancart lab, you modified your computer model so that your animation showed the same untypical behavior.) Identify the source of this untypical behavior in the code and state briefly how you would change the model so that the animation of fancart motion would look like typical fancart lab observations.

This page is for extra work, if needed.

#### Things you must know:

Definition of average velocity Definition of momentum The Momentum Principle
The Energy Principle

Definitions of particle energy, kinetic energy, and work

The Angular Momentum Principle

#### Vector Products:

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$
 
$$\vec{A} \times \vec{B} = \langle A_y B_z - A_z B_y, A_z B_x - A_x B_z, A_x B_y - A_y B_x \rangle$$

## Multiparticle systems:

$$\vec{r}_{cm} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2 + \dots}{m_1 + m_2 + \dots}$$

$$\vec{F}_{tot} \approx M_{tot} \vec{v}_{cm} \ (v << c)$$

$$K_{tot} = K_{trans} + K_{rel}$$

$$K_{rel} = K_{rot} + K_{vib}$$

$$K_{trans} \approx \frac{1}{2} M_{tot} v_{cm}^2 \ (v << c)$$

$$I = m_1 r_{1\perp}^2 + m_2 r_{2\perp}^2 + \dots$$

$$K_{rot} = \frac{L_{rot}^2}{2I} = \frac{1}{2} I \omega^2$$

$$\vec{\tau}_A = \vec{r}_A \times \vec{F}$$

$$\vec{L}_{trans,A} = \vec{r}_{cm,A} \times \vec{P}_{tot}$$

$$\vec{L}_A = \vec{L}_{trans,A} + \vec{L}_{rot}$$

### Other physical quantities:

$$\gamma \equiv \frac{1}{\sqrt{1 - \left(\frac{|\vec{v}|}{c}\right)^2}} \qquad \qquad E^2 - (pc)^2 = \left(mc^2\right)^2$$
 
$$\vec{F}_{grav} = -G\frac{m_1 m_2}{|\vec{r}|^2} \hat{r} \qquad \qquad U_{grav} = -G\frac{m_1 m_2}{|\vec{r}|}$$
 
$$\left|\vec{F}_{grav}\right| \approx mg \text{ near Earth's surface} \qquad \qquad \Delta U_{grav} \approx mg\Delta y \text{ near Earth's surface}$$
 
$$\vec{F}_{elec} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{|\vec{r}|^2} \hat{r} \qquad \qquad U_{elec} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{|\vec{r}|}$$
 
$$\left|\vec{F}_{spring}\right| = k_s s \text{ opposite to the stretch} \qquad \qquad U_{spring} = \frac{1}{2} k_s s^2 \text{ for ideal spring}$$
 
$$U_i \approx \frac{1}{2} k_{si} s^2 - E_M \text{ approx. interatomic pot. energy} \qquad \Delta E_{thermal} = mC\Delta T$$
 
$$E_N = -\frac{13.6 \text{eV}}{N^2} \text{ where } N = 1, 2, 3 \dots \text{ (Hydrogen atom energy levels)}$$

$$E_N = N\hbar\omega_0 + E_0$$
 where  $N = 0, 1, 2...$  and  $\omega_0 = \sqrt{\frac{k_{si}}{m_s}}$  (Quantized oscillator energy levels)

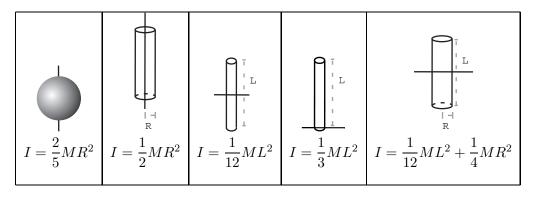
$$\frac{d\vec{p}}{dt} = \frac{d|\vec{p}|}{dt}\hat{p} + |\vec{p}|\frac{d\hat{p}}{dt} \text{ where } \vec{F}_{\parallel} = \frac{d|\vec{p}|}{dt}\hat{p} \text{ and } \vec{F}_{\perp} = |\vec{p}|\frac{d\hat{p}}{dt} = |\vec{p}|\frac{|\vec{v}|}{R}\hat{n} \text{ and } R \text{ is the radius of the kissing circle}$$

$$\omega = \frac{2\pi}{T} \qquad x = A\cos\omega t \qquad \omega = \sqrt{\frac{k_s}{m}}$$

$$Y = \frac{F/A}{\Delta L/L} \text{ (macro)} \qquad Y = \frac{k_{si}}{d} \text{ (micro)} \qquad \text{speed of sound } v = d\sqrt{\frac{k_{si}}{m_a}}$$

 $\hat{f} = \langle \cos \theta_x, \cos \theta_y, \cos \theta_z \rangle$  unit vector from angles

# Moment of intertia for rotation about indicated axis



$$\Omega = \frac{(q+N-1)!}{q! (N-1)!} \qquad S \equiv k \ln \Omega \qquad \frac{1}{T} \equiv \frac{\partial S}{\partial E}$$

$$\Delta S = \frac{Q}{T} \text{ (small } Q) \qquad \text{prob}(E) \propto \Omega (E) e^{-\frac{E}{kT}}$$

Constant	Symbol	Approximate Value
Speed of light	c	$3 \times 10^8 \text{ m/s}$
Gravitational constant	G	$6.7 \times 10^{-11} \text{ N} \cdot \text{m}^2/\text{kg}^2$
Approx. grav field near Earth's surface	g	$9.8 \mathrm{\ N/kg}$
Electron mass	$m_e$	$9 \times 10^{-31} \text{ kg}$
Proton mass	$m_p$	$1.7 \times 10^{-27} \text{ kg}$
Neutron mass	$m_n$	$1.7 \times 10^{-27} \text{ kg}$
Electric constant	$\frac{1}{4\pi\epsilon_0}$	$9\times10^9~\mathrm{N}\cdot\mathrm{m}^2/\mathrm{C}^2$
Proton charge	$e^{-e}$	$1.6 \times 10^{-19} \text{ C}$
Electron volt	1  eV	$1.6 \times 10^{-19} \text{ J}$
Avogadro's number	$N_A$	$6.02 \times 10^{23} \text{ atoms/mol}$
Plank's constant	h	$6.6 \times 10^{-34}$ joule · second
$hbar = \frac{h}{2\pi}$	$\hbar$	$1.05 \times 10^{-34}$ joule · second
specific heat capacity of water	C	$4.2 \mathrm{~J/g/K}$
Boltzmann constant	k	$1.38 \times 10^{-23} \text{ J/K}$
milli m $1 \times 10^{-3}$	kilo K	$1 \times 10^3$
micro $\mu = 1 \times 10^{-6}$	mega M	$1 \times 10^6$
nano n $1 \times 10^{-9}$	giga G	$1 \times 10^9$
pico p $1 \times 10^{-12}$	tera T	$1 \times 10^{12}$