

Print Your Name: Key-)

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1. The augmented matrix for a system of equations is given by:

$$\left[\begin{array}{ccccc|c} 1 & 0 & 0 & 0 & -7 & 5 \\ 0 & 1 & 0 & -1 & 0 & 4 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right]$$

- (a) (6 points) Is the matrix above in RREF? If not, use row operations to obtain a matrix in reduced row echelon form.

Not in RREF: x_1, x_2, x_3, x_4, x_5

$$R_1 = R_1 + 7R_3 \quad \left[\begin{array}{ccccc|c} 1 & 0 & 0 & 0 & 0 & 5 \\ 0 & 1 & 0 & -1 & 0 & 4 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right]$$

- (b) (6 points) Write out the solution to the system (you may label the variables however you wish).

$$\begin{cases} x_1 = 5 \\ x_2 = 4 + t \\ x_3 = 5 \end{cases} \quad \begin{cases} x_4 = t \\ x_5 = 0 \end{cases}$$

- (c) (6 points) Describe the solution to part (b) geometrically (i.e., is it a point, line, plane, hyperplane, etc.).

Since there are two "free" variables,
the solution is a plane in \mathbb{R}^5 .

- (d) (6 points) Which columns from the matrix form a linearly independent set? Explain how you obtained your answer.

Columns 1, 2, and 5 are pivotal, so they
form a linearly independent set.

- (e) (6 points) Describe the **span** of the columns geometrically (i.e., is the span a point, line, plane, hyperplane, etc.).

Since there are 3 pivotal columns
and the columns are vectors in \mathbb{R}^3 ,
the span is all of \mathbb{R}^3 .

2. (10 points) Compute $A^T B$ for the matrices A and B below.

$$A = \begin{bmatrix} 6 & -6 & 1 \\ 1 & -5 & -4 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 0 & -1 \\ 5 & -5 & 4 \end{bmatrix}$$

$$A^T B = \begin{bmatrix} 6 & 1 \\ -6 & -5 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 5 & -5 & 4 \end{bmatrix} = \begin{bmatrix} 11 & -5 & -2 \\ -31 & 25 & -14 \\ -19 & 20 & -17 \end{bmatrix}.$$

3. Let $\vec{v}_1 = \begin{bmatrix} 4 \\ 1 \\ -6 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} -4 \\ 1 \\ 1 \end{bmatrix}$, and $\vec{v}_3 = \begin{bmatrix} -20 \\ 1 \\ 15 \end{bmatrix}$.

(a) (10 points) Do the three vectors $\{v_1, v_2, v_3\}$ above form a linearly independent set? If so, explain why. If not, write \vec{v}_3 as a linear combination of \vec{v}_1 and \vec{v}_2 .

$$\begin{bmatrix} 4 & -4 & -20 \\ 1 & 1 & 1 \\ -6 & 1 & 15 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 1 & 1 \\ 4 & -4 & -20 \\ -6 & 1 & 15 \end{bmatrix}$$

$$\xrightarrow{\begin{subarray}{l} R_2 - 4R_1 \\ R_3 + 6R_1 \end{subarray}} \begin{bmatrix} 1 & 1 & 1 \\ 0 & -8 & -24 \\ 0 & 7 & 21 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 1 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

Since only 2 columns are pivotal, linearly dependent and $\vec{v}_3 = -2\vec{v}_1 + 3\vec{v}_2$.

(b) (10 points) Describe the span of the vectors in part (a). Write a "formula" to find any vector in the span.

The span is all linear combinations of \vec{v}_1 and \vec{v}_2 . So, if $\vec{w} \in \text{span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$,

$$\text{then } \vec{w} = a \begin{bmatrix} 4 \\ 1 \\ -6 \end{bmatrix} + b \begin{bmatrix} -4 \\ 1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 4a - 4b \\ a + b \\ -6a + b \end{bmatrix}, \quad a, b \in \mathbb{R}$$

This is a plane in \mathbb{R}^3 .

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4. (15 points) (a) Solve the following system of equations using the Gauss-Jordan elimination method. If the solution is not unique, write your answer as a **vector equation**. You should continue your row operations until you obtain a matrix in reduced row-echelon form (RREF). (b) Then describe your solution geometrically (i.e., is it a line, plane, hyperplane, etc.).

$$\begin{cases} 3x_1 + 3x_2 + 6x_3 = 12 \\ -9x_1 - 9x_2 - 18x_3 = -36 \\ -4x_2 + 8x_3 = 8 \end{cases}$$

$$\begin{bmatrix} 3 & 3 & 6 & | & 12 \\ -9 & -9 & -18 & | & -36 \\ 0 & -4 & 8 & | & 8 \end{bmatrix} \xrightarrow[\substack{-1/9 R_2 \\ -1/4 R_3}]{1/3 R_1} \begin{bmatrix} 1 & 1 & 2 & | & 4 \\ 1 & 1 & 2 & | & 4 \\ 0 & 1 & -2 & | & -2 \end{bmatrix}$$

$$\xrightarrow{R_2 - R_1} \begin{bmatrix} 1 & 1 & 2 & | & 4 \\ 0 & 0 & 0 & | & 0 \\ 0 & 1 & -2 & | & -2 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{bmatrix} 1 & 1 & 2 & | & 4 \\ 0 & 1 & -2 & | & -2 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$\xrightarrow{R_1 - R_2} \begin{bmatrix} 1 & 0 & 4 & | & 6 \\ 0 & 1 & -2 & | & -2 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 + 4x_3 = 6 \\ x_2 - 2x_3 = -2 \end{cases} \Rightarrow \begin{cases} x_1 = 6 - 4x_3 \\ x_2 = -2 + 2x_3 \\ x_3 = x_3 \end{cases}$$

So

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6 \\ -2 \\ 0 \end{bmatrix} + \begin{bmatrix} -4 \\ 2 \\ 1 \end{bmatrix} x_3$$

This is a line in \mathbb{R}^3 .

5. (5 points each) Given the points $P = (2, -1, -1)$ and $Q = (0, 2, 3)$ and the vector $\vec{v} = \begin{bmatrix} -2 \\ 0 \\ 4 \end{bmatrix}$ in \mathbb{R}^3 , calculate each of the following expressions, or explain why the expression is undefined.

(a) $P \cdot Q$ not defined - cannot dot points

(b) $\vec{PQ} \cdot \vec{v}$ $\vec{PQ} = \begin{bmatrix} -2 \\ 3 \\ 4 \end{bmatrix}$, so $\vec{PQ} \cdot \vec{v} = (-2)(-2) + (3)(0) + (4)(4) = 4 + 16 = \boxed{20}$

(c) $\|\vec{v}\| \cdot \vec{v}$ not defined - cannot dot a scalar with a vector

(d) $\text{proj}_{\vec{v}} \vec{PQ} = \frac{\vec{PQ} \cdot \vec{v}}{\|\vec{v}\|^2} \vec{v} = \frac{20}{4+16} \vec{v} = \vec{v} = \begin{bmatrix} -2 \\ 0 \\ 4 \end{bmatrix}$

(e) $\frac{\vec{v}}{\|\vec{v}\|} = \frac{1}{\sqrt{20}} \vec{v} = \begin{bmatrix} -2/\sqrt{20} \\ 0 \\ 4/\sqrt{20} \end{bmatrix}$

BONUS: (5 points) Prove the following vector property. Let \vec{a}, \vec{b} be vectors in \mathbb{R}^n and let k be any real number. Then $(k\vec{a}) \cdot \vec{b} = k(\vec{a} \cdot \vec{b})$.

Let $\vec{a} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$. Then:

$$(k\vec{a}) \cdot \vec{b} = \begin{bmatrix} ka_1 \\ \vdots \\ ka_n \end{bmatrix} \cdot \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} = (ka_1)(b_1) + (ka_2)(b_2) + \dots + (ka_n)(b_n)$$

$$= ka_1b_1 + ka_2b_2 + \dots + ka_nb_n$$

$$= k(a_1b_1 + a_2b_2 + \dots + a_nb_n)$$

$$= k(\vec{a} \cdot \vec{b}). \quad \text{qed}$$

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1. (15 points) (a) Solve the following system of equations using the Gauss-Jordan elimination method. If the solution is not unique, write your answer as a **vector equation**. You should continue your row operations until you obtain a matrix in reduced row-echelon form (RREF). (b) Then describe your solution geometrically (i.e., is it a line, plane, hyperplane, etc.).

$$\begin{cases} 2x_1 + 2x_2 + 4x_3 = 8 \\ -6x_1 - 6x_2 - 12x_3 = -24 \\ -5x_2 - 15x_3 = 15 \end{cases}$$

$$\left[\begin{array}{ccc|c} 2 & 2 & 4 & 8 \\ -6 & -6 & -12 & -24 \\ 0 & -5 & -15 & 15 \end{array} \right] \xrightarrow[\substack{-1/6 R_2 \\ -1/5 R_3}]{1/2 R_1} \left[\begin{array}{ccc|c} 1 & 1 & 2 & 4 \\ 1 & 1 & 2 & 4 \\ 0 & 1 & 3 & -3 \end{array} \right]$$

$$\xrightarrow{R_2 - R_1} \left[\begin{array}{ccc|c} 1 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 3 & -3 \end{array} \right] \xrightarrow{R_2 \leftrightarrow R_3} \left[\begin{array}{ccc|c} 1 & 1 & 2 & 4 \\ 0 & 1 & 3 & -3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\xrightarrow{R_1 - R_2} \left[\begin{array}{ccc|c} 1 & 0 & -1 & 7 \\ 0 & 1 & 3 & -3 \\ 0 & 0 & 0 & 0 \end{array} \right] \Rightarrow \begin{cases} x_1 - x_3 = 7 \\ x_2 + 3x_3 = -3 \end{cases} \Rightarrow$$

$$\begin{aligned} x_1 &= 7 + x_3 \\ x_2 &= -3 - 3x_3 \\ x_3 &= x_3 \end{aligned}$$

So

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 7 \\ -3 \\ 0 \end{bmatrix} + \begin{bmatrix} 1 \\ -3 \\ 1 \end{bmatrix} x_3$$

This is a line in \mathbb{R}^3 .

2. Let $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ -3 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} -2 \\ 4 \\ 5 \end{bmatrix}$, and $\vec{v}_3 = \begin{bmatrix} 2 \\ -16 \\ -3 \end{bmatrix}$.

(a) (10 points) Do the three vectors $\{v_1, v_2, v_3\}$ above form a linearly independent set? If so, explain why. If not, write \vec{v}_3 as a linear combination of \vec{v}_1 and \vec{v}_2 .

$$\begin{bmatrix} 1 & -2 & 2 \\ 1 & 4 & -16 \\ -3 & 5 & -3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 2 \\ 0 & 6 & -18 \\ 0 & -1 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 2 \\ 0 & 1 & -3 \\ 0 & -1 & 3 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & -4 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{only 2 pivotal columns} \Rightarrow \text{the set is linearly dependent and}$$

$$\boxed{\vec{v}_3 = -4\vec{v}_1 - 3\vec{v}_2}$$

(b) (10 points) Describe the span of the vectors in part (a). Write a "formula" to find any vector in the span.

There are 2 pivotal columns \Rightarrow span is a plane in \mathbb{R}^3 .

If $\vec{w} \in \text{span}(\{\vec{v}_1, \vec{v}_2, \vec{v}_3\})$, then

$$\vec{w} = a \begin{bmatrix} 1 \\ 1 \\ -3 \end{bmatrix} + b \begin{bmatrix} -2 \\ 4 \\ 5 \end{bmatrix} = \begin{bmatrix} a - 2b \\ a + 4b \\ -3a + 5b \end{bmatrix}, \quad a, b \in \mathbb{R}$$

3. (10 points) Compute $A^T B$ for the matrices A and B below.

$$A = \begin{bmatrix} 2 & 1 & 4 \\ 0 & 6 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 6 & -1 & 0 \\ -8 & 0 & 3 \end{bmatrix}$$

$$A^T B = \begin{bmatrix} 2 & 0 \\ 1 & 6 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 6 & -1 & 0 \\ -8 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 12 & -2 & 0 \\ -42 & -1 & 18 \\ 16 & -4 & 3 \end{bmatrix}$$

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4. The augmented matrix for a system of equations is given by:

$$\left[\begin{array}{ccccc|c} 1 & 0 & 0 & 0 & -4 & 3 \\ 0 & 1 & 0 & -1 & 0 & 6 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right]$$

(a) (6 points) Is the matrix above in RREF? If not, use row operations to obtain a matrix in reduced row echelon form.

Not yet in RREF:

$$R_1 = R_1 + 4R_3 \quad \left[\begin{array}{ccccc|c} x_1 & x_2 & x_3 & x_4 & x_5 & \\ 1 & 0 & 0 & 0 & 0 & 3 \\ 0 & 1 & 0 & -1 & 0 & 6 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right]$$

(b) (6 points) Write out the solution to the system (you may label the variables however you wish).

$$\begin{cases} x_1 = 3 \\ x_2 = 6 + t \\ x_3 = 5 \end{cases} \quad \begin{cases} x_4 = t \\ x_5 = 0 \end{cases}$$

(c) (6 points) Describe the solution to part (b) geometrically (i.e., is it a point, line, plane, hyperplane, etc.).

Since there ~~are two~~ "free" variables
this is a plane in \mathbb{R}^5 .

(d) (6 points) Which columns from the matrix form a linearly independent set? Explain how you obtained your answer.

Columns 1, 2, and 5 are linearly independent
because they are the pivotal columns.

(e) (6 points) Describe the **span** of the columns geometrically (i.e., is the span a point, line, plane, hyperplane, etc.).

There are 3 pivotal columns and each column is a vector in \mathbb{R}^3 , so the span of the columns is all of \mathbb{R}^3 .

5. (5 points each) Given the points $P = (1, -2, -4)$ and $Q = (4, 3, -1)$ and the vector $\vec{v} = \begin{bmatrix} 3 \\ 5 \\ 0 \end{bmatrix}$ in \mathbb{R}^3 , calculate each of the following expressions, or explain why the expression is undefined.

(a) $P \cdot Q$ undefined (you cannot dot points)

(b) $\vec{PQ} \cdot \vec{v}$ $\vec{PQ} = \langle 3, 5, 3 \rangle$, so
 $\vec{PQ} \cdot \vec{v} = (3)(3) + (5)(5) + (3)(0) = 9 + 25 = \boxed{34}$

(c) $\|\vec{v}\| \cdot \vec{v}$ undefined (scalar \cdot vector cannot occur)

(d) $\text{proj}_{\vec{v}} \vec{PQ} = \frac{\vec{PQ} \cdot \vec{v}}{\|\vec{v}\|^2} \vec{v} = \frac{34}{9+25} \vec{v} = \vec{v} = \boxed{\begin{bmatrix} 3 \\ 5 \\ 0 \end{bmatrix}}$

(e) $\frac{\vec{v}}{\|\vec{v}\|} = \frac{1}{\sqrt{34}} \vec{v} = \frac{1}{\sqrt{34}} \begin{bmatrix} 3 \\ 5 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{3}{\sqrt{34}} \\ \frac{5}{\sqrt{34}} \\ 0 \end{bmatrix}$

BONUS: (5 points) Prove the following vector property. Let \vec{a}, \vec{b} be vectors in \mathbb{R}^n and let k be any real number. Then $(k\vec{a}) \cdot \vec{b} = k(\vec{a} \cdot \vec{b})$.

See Form 1.