MNISTBasicNN

March 28, 2018

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import pandas as pd
from sklearn import metrics
import matplotlib.pyplot as plt
import seaborn as sns

from IPython.display import SVG
from keras.utils.vis_utils import model_to_dot

%matplotlib inline
/usr/local/lib/python3.6/site-packages/h5py/__init__.py:36: FutureWarning: Conversion of the same statement of the same sta
```

from ._conv import register_converters as _register_converters

1 One layer NN

Using TensorFlow backend.

In [1]: import numpy as np

import keras

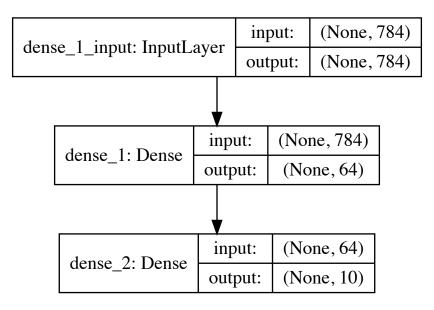
from keras.datasets import mnist

A neural network is an extension of logistic regression that can capture more complexity in the input data. The idea is that a linear function is too weak to capture the complexities of the data, so we should use some sort of nonlinear function. This can be done by taking $u = W_2g(W_1x)$, for example, which would be a neural network with a single hidden layer. u would then be passed through a softmax function in our case. If g is a nonlinear function, then u can be a nonlinear function of x. In addition, if g is differentiable most places, then we can use the chain rule to find $\frac{du}{dW_1}$ and $\frac{du}{dW_2}$. We can also compute $\frac{dL}{du}$ by the chain rule, so then we have $\frac{dL}{dW_1} = \frac{dL}{du} \frac{du}{dW_1}$ by the chain rule (up to a transpose maybe), so we can perform gradient descent here. Although this is a nonconvex function, in practice, gradient descent with a momentum term tends to be fairly effective, and g is often taken to be something like $g(x) = \max(0, x)$, which is a.e. differentiable.

If we have those parameters, when we compute our errors, by taking the derivative with respect to \hat{y} , we get a vector $\frac{dL}{d\hat{y}}$, which is 10 dimensional (say a column vector). Then, we can take $\frac{dL}{du} = \left(\frac{dL}{d\hat{y}}\right)^T \frac{d\hat{y}}{du}$. $\frac{dL}{dW_2} = \frac{dL}{du} \frac{du}{dW_2}$, and $\frac{du}{dW_2} = g(W_1x)$, so this gradient can be computed easily. If we let $v = g(W_1x)$, $\frac{dL}{dW_1} = \frac{dL}{dv} \frac{dv}{dW_1}$. $\frac{dL}{dv} = \frac{dL}{du} \frac{du}{dv} = W_2^T \frac{dL}{du}$. $\frac{dv}{dW_1} = g'(W_1x)x$, so we can plug these two in to compute $\frac{dL}{dW_1}$. With these two gradients, we can take a step of gradient descent.

Note that above I didn't specify the shapes of everything, but there is only one way where the shapes match for everything, in particular if we consider a set of many values of *x*. Then the input is a 2d matrix, so everything only works one way.

In [2]: (x_train, y_train_orig), (x_test, y_test_orig) = mnist.load_data()



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Epoch 1/3
60000/60000 [=============== ] - 3s 54us/step - loss: 0.0473 - acc: 0.9857
Epoch 2/3
Epoch 3/3
Out[10]: <keras.callbacks.History at 0x120c97780>
In [14]: model.load_weights('./super_simple_nn.h5')
In [15]: print('Test loss: %.4f, Test accuracy: %.4f'%tuple(model.evaluate(x_test, y_test, ver
Test loss: 0.0901, Test accuracy: 0.9741
In [16]: pred_y = model.predict(x_test)
In [17]: conf_mat = metrics.confusion_matrix(y_test_orig, pred_y.argmax(1))
       class_names = list(range(10))
       cm = conf_mat.astype('float') / conf_mat.sum(axis=1)[:, np.newaxis]
       df_cm = pd.DataFrame(
           cm, index=class_names, columns=class_names,
       fig = plt.figure(figsize=(7, 6))
       heatmap = sns.heatmap(df_cm, annot=conf_mat, fmt="d")
       heatmap.yaxis.set_ticklabels(heatmap.yaxis.get_ticklabels(), rotation=0, ha='right')
       heatmap.xaxis.set_ticklabels(heatmap.xaxis.get_ticklabels(), rotation=45, ha='right')
       plt.ylabel('True label')
       plt.xlabel('Predicted label')
       plt.title('Confusion Matrix')
Out[17]: Text(0.5,1,'Confusion Matrix')
```

