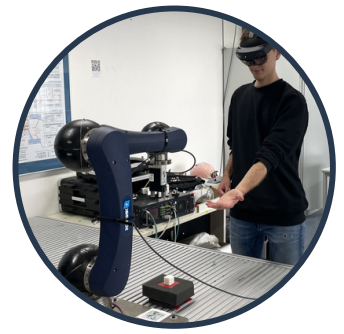


CHRISTIAN NATHAUS

AI & Robotics Engineer



About Me

I am passionate about enhancing human-robot interactions and leveraging AI methods to develop robots that are useful in real-world applications. Through my studies, internships, and projects, I have gained expertise in the diverse tasks required to develop and deploy such systems. I particularly enjoy working at the intersection of different domains. I look forward to starting my career in a dynamic, interdisciplinary, and diverse team.





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Education

	Yonsei University, South Korea Semester Abroad	2023
	Technical University of Munich, Germany M.Sc. Robotics, Cognition, Intelligence <ul style="list-style-type: none">graduated with distinction (grade: 1.5)	2020 - 2023
	NUS - National University of Singapore, Singapore Semester Abroad	2019
	RWTH Aachen University, Germany B.Sc. Mechanical Engineering <ul style="list-style-type: none">graduated among top 5% of class	2016 - 2020

Work Experience & Projects

	Master's Thesis @ TUM CPS Group <ul style="list-style-type: none">"Augmented Reality-Enhanced Active Preference Learning for Human-Robot Collaboration (grade: 1.0)received Google DeepMind grant to present work at ICRA 2023 in London	2023
	Working Student @ WZL RWTH Aachen <ul style="list-style-type: none">worked on AI part identification in additive manufacturingreceived 10k€ in funding for further research	2022 - 2023
	Internship @ BMW Israel <ul style="list-style-type: none">developed LLM prototype application for in-vehicle entertainmentworked on computer-vision based navigation in parking garages	2021-2022
	Practical Course @ RobCo <ul style="list-style-type: none">integrated welding machine onto modular robot	2021
	Bachelor's Thesis @ IGMR RWTH Aachen <ul style="list-style-type: none">worked on AI task planning for service robotics (grade: 1.0)	2020

Skills

Python, PyTorch,
Typescript, React,
Next.js
C#, Unity
ROS, C++
Matlab, Simulink

Languages

German, native
English, TOEFL C2
Korean, basic

Interests

Beachvolleyball,
Climbing, Road
biking, Chess

