

## 3.7

### 1 (a)

三电荷的电势为

$$\Phi = \frac{q}{4\pi\epsilon_0} \left[ -\frac{2}{r} + \frac{1}{|\vec{r} - a\hat{z}|} + \frac{1}{|\vec{r} + a\hat{z}|} \right] \quad (1)$$

利用勒让德多项式，

$$\frac{1}{|\vec{r} - \vec{r}'|} = \sum_{l=0}^{\infty} \frac{r_{<}^l}{r_{>}^{l+1}} P_l(\cos \gamma) \quad (1)$$

有

$$\begin{aligned} \Phi &= \frac{q}{4\pi\epsilon_0} \left[ -\frac{2}{r} + \sum_{l=0}^{\infty} \frac{r_{<}^l}{r_{>}^{l+1}} [P_l(\cos \theta) + P_l(-\cos \theta)] \right] \\ &= \frac{q}{4\pi\epsilon_0} \left[ -\frac{2}{r} + \sum_{l=0}^{\infty} \frac{r_{<}^l}{r_{>}^{l+1}} [1 + (-1)^l] P_l(\cos \theta) \right] \\ &= \frac{q}{2\pi\epsilon_0} \left[ -\frac{1}{r} + \sum_{l \text{ even}} \frac{r_{<}^l}{r_{>}^{l+1}} P_l(\cos \theta) \right] \end{aligned} \quad (2)$$

其中，

$$r_{<} = \min(r, a), \quad r_{>} = \max(r, a) \quad (3)$$

为取极限  $a \rightarrow 0$ ，设， $r_{<} = a$   $r_{>} = r$ ，有

$$\Phi(r > a) = \frac{q}{2\pi\epsilon_0} \left[ -\frac{1}{r} + \sum_{l \text{ even}} \frac{a^l}{r^{l+1}} P_l(\cos \theta) \right] = \frac{q}{2\pi\epsilon_0} \sum_{l=2,4,\dots} \frac{a^l}{r^{l+1}} P_l(\cos \theta) \quad (4)$$

随  $a \rightarrow 0$ ， $l = 2$ 项占主导地位，定义  $qa^2 = Q$ ，有

$$\Phi \rightarrow \frac{Q}{2\pi\epsilon_0 r^3} P_2(\cos \theta) = \frac{Q}{4\pi\epsilon_0 r^3} (3 \cos^2 \theta - 1) \quad (5)$$

### 2 (b)

将(1)改写有

$$\Phi = \frac{q}{4\pi\epsilon_0} \left[ -\frac{2}{r} + \frac{1}{|\vec{r} - a\hat{z}|} + \frac{1}{|\vec{r} + a\hat{z}|} + \frac{2}{b} - \frac{b/a}{|\vec{r} - (b^2/a)\hat{z}|} - \frac{b/a}{|\vec{r} + (b^2/a)\hat{z}|} \right] \quad (6)$$

勒让德多项式展开有

$$\begin{aligned} \Phi &= \frac{q}{4\pi\epsilon_0} \left[ \frac{2}{b} - \frac{2}{r} + \sum_{l=0}^{\infty} \left( \frac{r_{<}^l}{r_{>}^{l+1}} - \frac{b}{a} \frac{r^l}{(b^2/a)^{l+1}} \right) [P_l(\cos \theta) + P_l(-\cos \theta)] \right] \\ &= \frac{q}{2\pi\epsilon_0} \left[ \frac{1}{b} - \frac{1}{r} + \sum_{l \text{ even}} \left( \frac{r_{<}^l}{r_{>}^{l+1}} - \frac{1}{b} \left( \frac{ar}{b^2} \right)^l \right) P_l(\cos \theta) \right] \end{aligned} \quad (7)$$

对于  $r > 0$ ，有

$$\begin{aligned} \Phi(r > a) &= \frac{q}{2\pi\epsilon_0} \sum_{l=2,4,\dots} \left( \frac{a^l}{r^{l+1}} - \frac{1}{b} \left( \frac{ar}{b^2} \right)^l \right) P_l(\cos \theta) \\ &= \frac{q}{2\pi\epsilon_0} \sum_{l=2,4,\dots} \frac{a^l}{r^{l+1}} \left( 1 - \left( \frac{r}{b} \right)^{2l+1} \right) P_l(\cos \theta) \end{aligned} \quad (8)$$

取极限 $a \rightarrow 0$ 时, 仅 $l=2$ 项存在, 有

$$\Phi \rightarrow \frac{Q}{2\pi\epsilon_0 r^3} \left(1 - \left(\frac{r}{b}\right)^5\right) P_2(\cos\theta) = \frac{Q}{4\pi\epsilon_0 r^3} \left(1 - \left(\frac{r}{b}\right)^5\right) (3\cos^2\theta - 1) \quad (9)$$

## 5.30

### 1 (a)

有矢势

$$\mathbf{A}(\mathbf{x}) = \mathbf{e}_z \frac{\mu_0}{4\pi} \int_0^{2\pi} R d\phi' \int_{-\infty}^{\infty} dz' \frac{K(\phi')}{|\mathbf{x} - \mathbf{x}'|} \quad (10)$$

根据(3.149)有

$$\frac{1}{|\mathbf{x} - \mathbf{x}'|} = \frac{4}{\pi} \int_0^{\infty} dk \cos[k(z - z')] \left\{ \frac{1}{2} I_0(k\rho_{<}) K_0(k\rho_{>}) + \sum_{m=1}^{\infty} \cos[m(\phi - \phi')] I_m(k\rho_{<}) K_m(k\rho_{>}) \right\} \quad (11)$$

代回有

$$\mathbf{A}(\mathbf{x}) = \mathbf{e}_z \frac{\mu_0 I}{2\pi} \int_{-\infty}^{\infty} dz' \int_0^{\infty} dk' \cos[k(z - z')] \cos\phi I_1(k\rho_{<}) K_1(k\rho_{>}) \quad (12)$$

利用

$$\int_{-\infty}^{\infty} \cos[k(z - z')] dz' = \text{Re} \left[ e^{ikz} \int_{-\infty}^{\infty} e^{-ikz'} dz' \right] = \text{Re} [2\pi i \delta(k) e^{ikz}] = 2\pi \delta(k) \cos(kz) \quad (13)$$

有

$$\mathbf{A}(\mathbf{x}) = \mathbf{e}_z \mu_0 I \cos\phi \frac{1}{2} \lim_{k \rightarrow 0} \cos(kz) I_1(k\rho_{<}) K_1(k\rho_{>}) \quad (14)$$

又因为

$$I_1(k\rho_{<}) K_1(k\rho_{>}) \xrightarrow{k \rightarrow 0} \frac{1}{2} \frac{\rho_{<}}{\rho_{>}} \frac{\Gamma(2)}{\Gamma(1)} = \frac{1}{2} \frac{\rho_{<}}{\rho_{>}} \quad (15)$$

所以

$$\mathbf{A}(\mathbf{x}) = \mathbf{e}_z \frac{\mu_0 I}{4} \frac{\rho_{<}}{\rho_{>}} \cos\phi \quad (16)$$

因此有

$$\begin{aligned} \mathbf{B}(\mathbf{x}) &= \nabla \times \mathbf{A} = \frac{\partial A_z}{\partial y} \mathbf{e}_x - \frac{\partial A_z}{\partial x} \mathbf{e}_y \\ &= -\frac{\mu_0 I}{4} \left\{ \frac{1}{R} \mathbf{e}_y \right. \\ &\quad \left. R \left( \frac{2xy}{(x^2+y^2)^2} \mathbf{e}_x - \frac{x^2-y^2}{(x^2+y^2)^2} \mathbf{e}_y \right) \right. \\ &= -\frac{\mu_0 I}{4} \left\{ \frac{1}{R} \mathbf{e}_y \right. \\ &\quad \left. \frac{R}{\rho^2} (\sin(2\phi) \mathbf{e}_x - \cos(2\phi) \mathbf{e}_y) \right\} \end{aligned} \quad (17)$$

符合偶极子形式

## 2 (b)

根据半径划分内外场，各自有能量密度

$$\begin{aligned} W_{\text{inside}} &= \frac{1}{2\mu_0} \int_0^R \rho d\rho \int_0^{2\pi} d\phi \frac{\mu_0^2 I^2}{16R^2} = \frac{\mu_0 \pi I^2}{32} \\ W_{\text{outside}} &= \frac{1}{2\mu_0} \int_R^\infty \rho d\rho \int_0^{2\pi} d\phi \frac{\mu_0^2 I^2 R^2}{16} \frac{1}{\rho^2} [\sin^2 2\phi + \cos^2 2\phi] = \frac{\mu_0 \pi I^2}{32} \end{aligned} \quad (18)$$

所以

$$W = W_{\text{inside}} + W_{\text{outside}} = \frac{\mu_0 \pi I^2}{16} \quad (19)$$

## 3 (c)

$$\begin{aligned} J &= \int_{-\pi/2}^{\pi/2} K(\phi) R d\phi = I \\ L &= \frac{W}{I^2} = \frac{\mu_0 \pi}{8} \end{aligned} \quad (20)$$

可以看成回路

# 6.4

## 1 (a)

设球心位于坐标原点，转动轴跟 $z$ 轴重合， $\vec{m} = m\hat{z}$ ，有

$$\mathbf{m} = \int \mathbf{M}(\mathbf{x}) d\mathbf{x} = \mathbf{M}V = \mathbf{M} \frac{4}{3} \pi R^3 \quad (21)$$

根据5.105有

$$\begin{aligned} \vec{B} &= \frac{2\mu_0}{3} \vec{M} \\ &= \frac{2\mu_0}{3} \left( \frac{3m\hat{z}}{4\pi R^3} \right) \\ &= \frac{\mu_0 m}{2\pi R^3} \hat{z} \end{aligned} \quad (22)$$

考虑旋转坐标系内无电流，且，根据5.142有

$$\begin{aligned} \vec{E}' &= \vec{E} + \vec{v} \times \vec{B} = 0 \\ &\Downarrow \\ \mathbf{E} &= -\mathbf{v} \times \mathbf{B} \\ \mathbf{E} &= -(\boldsymbol{\omega} \times \mathbf{r}) \times \mathbf{B} \\ \mathbf{E} &= -\omega(\hat{\mathbf{z}} \times \mathbf{r}) \times \mathbf{B} \\ \mathbf{E} &= \frac{-\mu_0 m \omega}{2\pi R^3} (\hat{\mathbf{z}} \times \mathbf{r}) \times \hat{\mathbf{z}} \\ \mathbf{E} &= \frac{-\mu_0 m \omega}{2\pi R^3} \rho \hat{\boldsymbol{\rho}} \end{aligned} \quad (23)$$

利用高斯定律，有

$$\begin{aligned} \rho &= \epsilon_0 \nabla \cdot \mathbf{E} \\ \rho &= \epsilon_0 \frac{\partial E_\rho}{\partial \rho} \\ \rho &= -\frac{\epsilon_0 \mu_0 m \omega}{2\pi R^3} \\ \rho &= -\frac{m \omega}{2\pi c^2 R^3} \end{aligned} \quad (24)$$

## 2 (b)

由于球体电中性，单极矩为0，且外场为基函数， $l$ 的奇数次项为0，

所以 $l = 2$ 为最小非0项，

有电势

$$\begin{aligned}\Phi(\vec{x}) &= - \int \vec{E} \cdot d\vec{l} \\ &= - \left( - \frac{\mu_0 m \omega r^2}{2\pi R^3} \right) \\ &= \frac{\mu_0 m \omega r^2 \sin^2 \theta}{2\pi R^3}\end{aligned}\quad (25)$$

利用， $\sin^2 \theta = \frac{1}{3}[P_0(\cos \theta) - P_2(\cos \theta)]$ 有

$$\Phi(\vec{x}) = \frac{\mu_0 m \omega r^2}{2\pi R^3} \frac{1}{3} [P_0(\cos \theta) - P_2(\cos \theta)] \quad (26)$$

对于 $l = 2$ 项，

$$\Phi_{\ell=2}(r = R) = - \frac{\mu_0 m \omega}{6\pi R} P_2(\cos \theta) \quad (27)$$

由4.1，4.6有

$$\begin{aligned}q_{2,0} &= \frac{\varepsilon_0 5 R^3}{Y_{1,0}(\theta, \varphi)} \left( - \frac{\mu_0 m \omega}{6\pi R} P_2(\cos \theta) \right) \\ &= - \frac{5 m \omega R^2}{6\pi c^2} \frac{P_2(\cos \theta)}{Y_{1,0}(\theta, \varphi)} \\ &= - \frac{5 m \omega r^3}{6\pi c^2 R^3} \frac{\frac{1}{2}(3 \cos^2 \theta - 1)}{\frac{1}{4} \sqrt{\frac{5}{\pi}} (3 \cos^2 \theta - 1)} \\ &= - \frac{5 m \omega R^2}{3 c^2 \pi} \sqrt{\frac{\pi}{5}}\end{aligned}\quad (28)$$

$$\begin{aligned}Q_{3,3} &= 2 \sqrt{\frac{4\pi}{5}} q_{2,0} \\ Q_{3,3} &= 2 \sqrt{\frac{4\pi}{5}} \left( - \frac{5 m \omega R^2}{3 c^2 \pi} \sqrt{\frac{\pi}{5}} \right) \\ Q_{3,3} &= - \frac{4 m \omega R^2}{3 c^2}\end{aligned}\quad (29)$$

由于四极矩无迹， $Q_{1,1} + Q_{2,2} + Q_{3,3} = 0$ ，且 $x - y$ 对称， $Q_{1,1} = Q_{2,2}$

有， $Q_{1,1} = Q_{2,2} = -\frac{1}{2} Q_{3,3}$

## 3 (c)

球体内的静电势如上一问所示：

$$\begin{aligned}\Phi_{\text{in}}(\vec{x}) &= \frac{\mu_0 m \omega r^2}{2\pi R^3} \frac{1}{3} [P_0(\cos \theta) - P_2(\cos \theta)] \\ \therefore \vec{E}_{\text{in}}^r &= - \frac{\mu_0 m \omega r}{\pi R^3} \frac{1}{3} [P_0(\cos \theta) - P_2(\cos \theta)]\end{aligned}\quad (30)$$

因为低于 $l = 2$ 的项在球外不存在，所以静电势球外为

$$\begin{aligned}\Phi_{\text{out}}(\vec{x}) &= - \frac{\mu_0 m \omega R^2}{2\pi r^3} \frac{1}{3} P_2(\cos \theta) \\ \therefore \vec{E}_{\text{out}}^r &= - \frac{\mu_0 m \omega R^2}{2\pi r^4} P_2(\cos \theta)\end{aligned}\quad (31)$$

$$\begin{aligned}
\sigma(\theta) &= \varepsilon_0 [E_{\text{out}}^r - E_{\text{in}}^r]_{r=R} \\
&= \varepsilon_0 \left[ -\frac{\mu_0 m \omega R^2}{2\pi r^4} P_2(\cos \theta) - \left( -\frac{\mu_0 m \omega r}{\pi R^3} \frac{1}{3} [1 - P_2(\cos \theta)] \right) \right]_{r=R} \\
&= \frac{m \omega}{\pi c^2 R^2} \left( -\frac{1}{2} P_2(\cos \theta) + \frac{1}{3} [1 - P_2(\cos \theta)] \right) \\
\sigma(\theta) &= \frac{m \omega}{3\pi c^2 R^2} \left( 1 - \frac{5}{2} P_2(\cos \theta) \right)
\end{aligned} \tag{32}$$

4 (d)

$$\begin{aligned}
\mathcal{E} &= \int_{\theta=\pi/2}^0 \vec{E} \cdot d\vec{\ell} = [-\Phi_{\text{out}}]_{\theta=\pi/2}^0 \Big|_{r=R} \\
&= \frac{\mu_0 m \omega}{6\pi R} + \frac{\mu_0 m \omega}{12\pi R} \\
\mathcal{E} &= \frac{\mu_0 m \omega}{4\pi R}
\end{aligned} \tag{33}$$

## 7.16

1 (a)

在无源区，有

$$i\vec{k} \times \vec{H} = -i\omega \vec{D}, \quad i\vec{k} \times \vec{E} - i\omega \vec{B} = 0 \tag{34}$$

利用法拉第定律和 $\vec{B} = \mu_0 \vec{H}$ ，有

$$i\vec{k} \times (i\vec{k} \times \vec{E}) - i\mu_0 \omega (i\vec{k} \times \vec{H}) = 0 \tag{35}$$

对第二项利用安培定律有

$$\vec{k} \times (\vec{k} \times \vec{E}) + \mu_0 \omega^2 \vec{D} = 0 \tag{36}$$

2 (b)

设 $\vec{k} = k\hat{n}$ ，有

$$\hat{n}(\hat{n} \cdot \vec{E}) - \vec{E} + \mu_0 v^2 \vec{D} = 0 \tag{37}$$

可以写作矩阵形式

$$\begin{aligned}
A_{ij} &= n_i n_j - \delta_{ij}, \quad W_{ij} = \delta_{ij} \mu_0 \epsilon_j = \delta_{ij} / v_j^2 \\
\mathbf{A} \vec{E} &= -v^2 \mathbf{W} \vec{E}
\end{aligned} \tag{38}$$

其本征值即为传播速度，解其久期方程

$$0 = \det(\mathbf{A} + v^2 \mathbf{W}) \tag{38}$$

有

$$\begin{aligned}
v &= 0 \\
&\text{or} \\
\sum_i \frac{n_i^2}{v^2 - v_i^2} &= 0
\end{aligned} \tag{39}$$

### 3 (c)

对(38)考虑不同的特征值，有方程

$$(\mathbf{A} + v_a^2 \mathbf{W}) \vec{E}_a = 0, \quad (\mathbf{A} + v_b^2 \mathbf{W}) \vec{E}_b = 0 \quad (40)$$

分别左乘  $\vec{E}_b, \vec{E}_a$  有

$$\vec{E}_b \mathbf{A} \vec{E}_a + v_a^2 \vec{E}_b \mathbf{W} \vec{E}_a = 0, \quad \vec{E}_a \mathbf{A} \vec{E}_b + v_b^2 \vec{E}_a \mathbf{W} \vec{E}_b = 0 \quad (41)$$

由于  $A, W$  厄米，用第二个方程减去第一个方程的共轭有

$$(v_b^2 - v_a^2) \vec{E}_a \mathbf{W} \vec{E}_b = 0 \quad (42)$$

由于  $v_a \neq v_b$ ，则有  $\vec{E}_a \mathbf{W} \vec{E}_b = 0$

由于  $W_{ij} = \delta_{ij} \mu_0 \epsilon_j$ ，则有

$$\vec{E}_a \cdot \vec{D}_b = \vec{E}_b \cdot \vec{D}_a = 0 \quad (43)$$

且  $\mathbf{A}^2 = -\mathbf{A}$ ，有

$$\vec{D}_a \cdot \vec{D}_b = \vec{E}_a \mathbf{A} \vec{E}_b = \frac{1}{\mu_0^2} \vec{E}_a \mathbf{W}^2 \vec{E}_b = \frac{1}{\mu_0^2 v_a^2 v_b^2} \vec{E}_a \mathbf{A}^2 \vec{E}_b = -\frac{1}{\mu_0^2 v_a^2 v_b^2} \vec{E}_a \mathbf{A} \vec{E}_b \quad (44)$$

但因为  $\mathbf{A} \vec{E}_b = -v_b^2 \mathbf{W} \vec{E}_b$ ，得到

$$\vec{D}_a \cdot \vec{D}_b = \frac{1}{\mu_0^2 v_a^2} \vec{E}_a \mathbf{W} \vec{E}_b = \frac{1}{\mu_0 v_a^2} \vec{E}_a \cdot \vec{D}_b = 0 \quad (45)$$

## 9.11

有电荷和电流密度

$$\begin{aligned} \rho &= q[2\delta(z) - \delta(z - a \cos \omega t) - \delta(z + a \cos \omega t)]\delta(x)\delta(y) \\ \vec{J} &= \hat{z} q a \omega \sin \omega t [\delta(z - a \cos \omega t) - \delta(z + a \cos \omega t)]\delta(x)\delta(y) \end{aligned} \quad (46)$$

因为  $ka \ll 1$ ，可以计算

$$\begin{aligned} \vec{p}(t) &= \int \vec{x} \rho d^3x = -q(a \cos \omega t - a \cos \omega t) = 0 \\ \vec{m}(t) &= \frac{1}{2} \int \vec{x} \times \vec{J} d^3x = 0 \end{aligned} \quad (47)$$

$$\begin{aligned} Q_{ij}(t) &= \int (3x_i x_j - r^2 \delta_{ij}) \rho(t) d^3x = -q a^2 \cos^2 \omega t (3\delta_{i3} \delta_{j3} - \delta_{ij}) \\ Q_{33}(t) &= -2Q_{11}(t) = -2Q_{22}(t) = -4q a^2 \cos^2 \omega t \end{aligned} \quad (48)$$

因为电荷直线运动，所以所有磁多极矩都不存在，电极矩中，电四极矩存在

电四极矩可变形为

$$Q_{33}(t) = -2q a^2 [1 + \cos(2\omega t)] = \text{Re} [-2q a^2 (1 + e^{-2i\omega t})] \quad (49)$$

由于零频项不辐射，因此可以假设一个四极矩谐波

$$Q_{33} = -2Q_{11} = -2Q_{22} = -2q a^2 \quad (50)$$

以角频率  $2\omega$  振荡，

其辐射角分布为

$$\frac{dP}{d\Omega} = \frac{c^2 Z_0 k^6}{\epsilon_0 \mu_0^2} |Q_{33}|^2 \sin^2 \theta \cos^2 \theta = \frac{Z_0 q^2}{\epsilon_0 \mu_0^2} (ck)^2 (ka)^4 \sin^2 \theta \cos^2 \theta \quad (51)$$

利用,  $ck = 2\omega$ , 有

$$\frac{dP}{d\Omega} = \frac{Z_0 q^2 \omega^2}{32\pi^2} (ka)^4 \sin^2 \theta \cos^2 \theta \quad (52)$$

立体角积分得总功率

$$P = \frac{Z_0 q^2 \omega^2}{60\pi} (ka)^4 \quad (53)$$

## 11.5

根据11.31, 有

$$\begin{aligned} a_{\parallel}(t) &= \frac{du_{\parallel}}{dt} = \frac{d}{dt} \left( \frac{u'_{\parallel} + v}{1 + \frac{u'_{\parallel} v}{c^2}} \right) \\ &= \frac{1}{\left(1 + \frac{u'_{\parallel} v}{c^2}\right)^2} \left[ \left(1 + \frac{u'_{\parallel} v}{c^2}\right) \frac{du'_{\parallel}}{dt} - (u'_{\parallel} + v) \frac{v}{c^2} \frac{du'_{\parallel}}{dt} \right] \\ &= \frac{1}{\left(1 + \frac{u'_{\parallel} v}{c^2}\right)^2} \left[ 1 + \frac{u'_{\parallel} v}{c^2} - \frac{u'_{\parallel} v}{c^2} - \frac{v^2}{c^2} \right] \left[ \frac{dt'}{dt} \right] \frac{du'_{\parallel}}{dt'} \\ &= \frac{1}{\left(1 + \frac{u'_{\parallel} v}{c^2}\right)^2} \frac{1}{\gamma^2} \left[ \frac{dt'}{dt} \right] a'_{\parallel} \\ &= \frac{a'_{\parallel}}{\gamma^2 \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^2} \left[ \frac{d}{dt} \left( \gamma t - \frac{\beta \gamma x_{\parallel}(t)}{c} \right) \right] \\ &= \frac{a'_{\parallel}}{\gamma \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^2} \left[ 1 - \frac{v}{c^2} \frac{dx_{\parallel}}{dt} \right] \\ &= \frac{a'_{\parallel}}{\gamma \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^2} \left[ 1 - \frac{v}{c^2} u_{\parallel} \right] \\ &= \frac{a'_{\parallel}}{\gamma \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^2} \left[ 1 - \frac{v}{c^2} \left( \frac{u'_{\parallel} + v}{1 + \frac{u'_{\parallel} v}{c^2}} \right) \right] \\ &= \frac{a'_{\parallel}}{\gamma \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^3} \left[ 1 + \frac{u'_{\parallel} v}{c^2} - \frac{v(u'_{\parallel} + v)}{c^2} \right] \\ &= \frac{a'_{\parallel}}{\gamma^3 \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^3} \end{aligned} \quad (54)$$

化为矢量式为

$$\mathbf{a}_{\parallel}(t) = \frac{\mathbf{a}'_{\parallel}}{\gamma^3 \left(1 + \frac{\mathbf{u} \cdot \mathbf{v}}{c^2}\right)^3} \quad (55)$$

对于法向

$$\mathbf{a}_{\perp}(t) = \frac{1}{\gamma} \frac{d}{dt} \left( \frac{\mathbf{u}'_{\perp}}{1 + \frac{u'_{\parallel} v}{c^2}} \right)$$

, \quad \left[ \left( \frac{u'\_{\parallel} v}{c^2} \right) \frac{d}{dt} \left( \frac{u'\_{\parallel} v}{c^2} \right) \right]

$$\begin{aligned}
&= \frac{1}{\gamma \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^2} \left[ \left(1 + \frac{u'_{\parallel} v}{c^2}\right) \frac{a}{dt} \mathbf{u}'_{\perp} - \mathbf{u}'_{\perp} \frac{a}{dt} \left(1 + \frac{u'_{\parallel} v}{c^2}\right) \right] \\
&= \frac{1}{\gamma \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^2} \left[ \frac{dt'}{dt} \right] \left[ \left(1 + \frac{u'_{\parallel} v}{c^2}\right) \frac{d}{dt'} \mathbf{u}'_{\perp} - \mathbf{u}'_{\perp} \frac{v}{c^2} \frac{d}{dt'} u'_{\parallel} \right] \\
&= \frac{1}{\gamma^2 \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^3} \left[ \left(1 + \frac{u'_{\parallel} v}{c^2}\right) \frac{d}{dt'} \mathbf{u}'_{\perp} - \mathbf{u}'_{\perp} \frac{v}{c^2} \frac{d}{dt'} u'_{\parallel} \right] \\
&= \frac{1}{\gamma^2 \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^3} \left[ \left(1 + \frac{u'_{\parallel} v}{c^2}\right) \mathbf{a}'_{\perp} - \mathbf{u}'_{\perp} \frac{v}{c^2} a'_{\parallel} \right] \\
&= \frac{1}{\gamma^2 \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^3} \left[ \mathbf{a}'_{\perp} + \mathbf{a}'_{\perp} \frac{u'_{\parallel} v}{c^2} - \mathbf{u}'_{\perp} \frac{v}{c^2} a'_{\parallel} \right] \\
&= \frac{1}{\gamma^2 \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^3} \left[ \mathbf{a}'_{\perp} + \left(\mathbf{a}' - a'_{\parallel} \hat{\mathbf{v}}\right) \frac{u'_{\parallel} v}{c^2} - \mathbf{u}'_{\perp} \frac{v}{c^2} a'_{\parallel} \right] \\
&= \frac{1}{\gamma^2 \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^3} \left[ \mathbf{a}'_{\perp} + \mathbf{a}' \frac{u'_{\parallel} v}{c^2} + \frac{va'_{\parallel}}{c^2} \left(-\mathbf{u}'_{\perp} - \hat{\mathbf{v}} u'_{\parallel}\right) \right] \\
&= \frac{1}{\gamma^2 \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^3} \left[ \mathbf{a}'_{\perp} + \frac{1}{c^2} \left(\mathbf{a}' u'_{\parallel} v - va'_{\parallel} \mathbf{u}'\right) \right] \\
&= \frac{1}{\gamma^2 \left(1 + \frac{u'_{\parallel} v}{c^2}\right)^3} \left[ \mathbf{a}'_{\perp} + \frac{1}{c^2} (\mathbf{a}' (\mathbf{u}' \cdot \mathbf{v}) - (\mathbf{a}' \cdot \mathbf{v}) \mathbf{u}') \right] \\
&= \frac{1}{\gamma^2 \left(1 + \frac{\mathbf{u}' \cdot \mathbf{v}}{c^2}\right)^3} \left[ \mathbf{a}'_{\perp} + \frac{1}{c^2} \mathbf{v} \times (\mathbf{a}' \times \mathbf{u}') \right] \quad \text{q.e.d}
\end{aligned} \tag{56}$$

## 11.23

### 1 (a)

设 $\mathcal{P}\mathcal{P}'$ 分别为 $lab, cm$ 坐标系内四矢量，有

$$\begin{aligned}
\mathcal{P}_1 &= (E_1, \vec{p}_{\text{LAB}}), \quad \mathcal{P}_2 = (m_2, \vec{0}) \\
\mathcal{P}'_1 &= (E'_1, \vec{p}'), \quad \mathcal{P}'_2 = (E'_2, -\vec{p}')
\end{aligned} \tag{57}$$

lab系内，利用动量守恒、能量守恒有

$$\begin{aligned}
\mathcal{P}_1 + \mathcal{P}_2 &= \mathcal{P}_3 + \mathcal{P}_4 \\
W^2 &= (E'_1 + E'_2)^2 = (E'_1 + E'_2)^2 - \left(\vec{p}'_1 + \vec{p}'_2\right)^2 = (\mathcal{P}'_1 + \mathcal{P}'_2)^2
\end{aligned} \tag{58}$$

其中， $(\mathcal{P}'_1 + \mathcal{P}'_2)^2$ 为洛伦兹不变量

进一步有

$$W^2 = (\mathcal{P}'_1 + \mathcal{P}'_2)^2 = (\mathcal{P}_1 + \mathcal{P}_2)^2 = \mathcal{P}_1^2 + \mathcal{P}_2^2 + 2\mathcal{P}_1 \cdot \mathcal{P}_2 = m_1^2 + m_2^2 + 2m_2 E_1 \tag{59}$$

考虑

$$(\mathcal{P}_1 \cdot \mathcal{P}_2)^2 = (m_2 E_1)^2 = m_2^2 (p_1^2 + m_1^2) = m_2^2 p_1^2 + m_1^2 m_2^2 \tag{60}$$

$$\begin{aligned}
(\mathcal{P}'_1 \cdot \mathcal{P}'_2)^2 &= (E'_1 E'_2 + p'^2)^2 = E_1'^2 E_2'^2 + 2E'_1 E'_2 p'^2 + p'^4 \\
&= (p'^2 + m_1^2) (p'^2 + m_2^2) + 2E'_1 E'_2 p'^2 + p'^4 \\
&= p'^4 + (m_1^2 + m_2^2) p'^2 + m_1^2 m_2^2
\end{aligned}$$



$$\begin{aligned}
&= 2p'^2 + (m_1^2 + m_2^2)p'^2 + 2E_1'E_2'p'^2 + m_1^2m_2^2 \\
&= p'^2 (2p'^2 + m_1^2 + m_2^2 + 2E_1'E_2') + m_1^2m_2^2 \\
&= p'^2 (E_1'^2 + 2E_1'E_2' + E_2'^2) + m_1^2m_2^2 \\
&= p'^2 W^2 + m_1^2m_2^2
\end{aligned} \tag{61}$$

由于洛伦兹不变性，有

$$(\mathcal{P}_1 \cdot \mathcal{P}_2)^2 = (\mathcal{P}'_1 \cdot \mathcal{P}'_2)^2 \Rightarrow m_2^2 p_1^2 = p'^2 W^2 \Rightarrow p' = \frac{m_2}{W} p_1 \tag{62}$$

由于 $\vec{p}_1, \vec{p}'$ 同向，有

$$\vec{p}' = \frac{m_2}{W} \vec{p}_1 \tag{63}$$

## 2 (b)

从 $\vec{p}'$ 洛伦兹变换有

$$p' = \gamma_{\text{cm}} (p_1 - \beta_{\text{cm}} E_1); \quad (-p') = \gamma_{\text{cm}} (-\beta_{\text{cm}} m_2) \tag{64}$$

因此有

$$\begin{aligned}
\beta_{\text{cm}} &= \frac{p_1}{m_2 + E_1}, \quad \Rightarrow \quad \vec{\beta}_{\text{cm}} = \frac{\vec{p}_1}{m_2 + E_1} \\
\gamma_{\text{cm}} &= \frac{1}{\sqrt{1 - \beta_{\text{cm}}^2}} = \frac{m_2 + E_1}{\sqrt{(m_2 + E_1)^2 - p_1^2}} = \frac{m_2 + E_1}{\sqrt{m_2^2 + 2m_2 E_1 + E_1^2 - p_1^2}} = \frac{m_2 + E_1}{W}
\end{aligned} \tag{65}$$

## 3 (c)

非相对论极限下有

$$E_1 \approx m_1 + \frac{p_1^2}{2m_1} \tag{66}$$

因此有

$$\begin{aligned}
W^2 &\approx m_1^2 + m_2^2 + 2m_2 \left( m_1 + \frac{p_1^2}{2m_1} \right) \\
&= (m_1 + m_2)^2 + \frac{m_2}{m_1} p_1^2 \\
&= (m_1 + m_2)^2 \left\{ 1 + \frac{m_2}{(m_1 + m_2)^2} \frac{p_1^2}{m_1} \right\}
\end{aligned} \tag{67}$$

$$\begin{aligned}
W &= (m_1 + m_2) \sqrt{1 + \frac{m_2}{(m_1 + m_2)^2} \frac{p_1^2}{m_1}} \\
&\approx (m_1 + m_2) \left\{ 1 + \frac{m_2}{(m_1 + m_2)^2} \frac{p_1^2}{2m_1} \right\} \\
&= m_1 + m_2 + \frac{m_2}{m_1 + m_2} \frac{p_1^2}{2m_1}
\end{aligned} \tag{68}$$

同样有

$$\begin{aligned}
\vec{p}' &= \frac{m_2}{W} \vec{p}_1 \approx \frac{m_2}{m_1 + m_2} \vec{p}_1 \\
\vec{\beta}_{\text{cm}} &= \frac{\vec{p}_1}{m_2 + E_1} \approx \frac{\vec{p}_1}{m_1 + m_2}
\end{aligned} \tag{69}$$

即伽利略变换下的结果