Training [rad/s] error 2.5 e_vx [m/s] 1 pred 0.0 0 e_wx_ error -2.5 pred **-**2 -5.0 error e_wy [rad/s] e_vy [m/s] 1 pred 0 0 error pred **-**5 [rad/s] 0.50 0.25 $[s/w]_{0.00}^{0.25}$ $[-0.25]_{0.025}^{0.25}$ error error pred pred e_wz [0.25 0.00 1000 3000 1000 2000 3000 2000 0 0