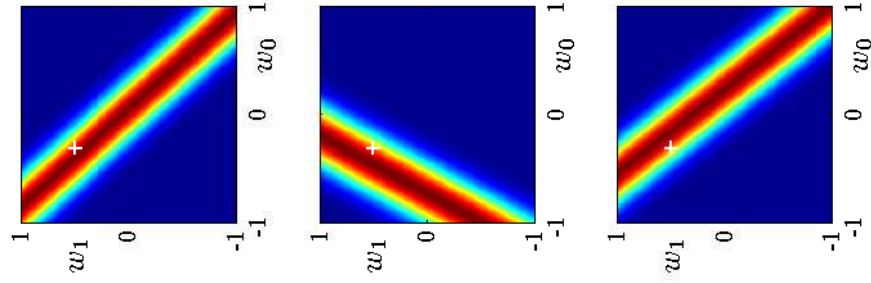
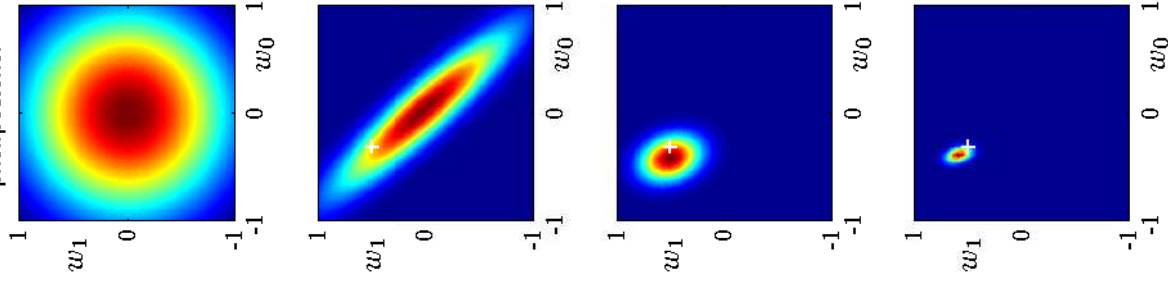


Likelihood



prior/posterior



data space

