Machine Learning I Lecture VII: Logistic Regression

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Plan for today

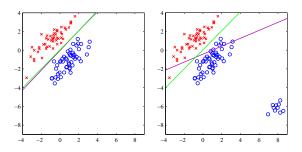
Logistic Regression

Maximum likelihood estimation of Logistic Regression

Bayesian Logistic Regression: Approximating the posterior distribution

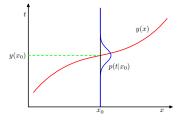
For the linear classification model, we assumed the class-conditional distributions to be Gaussian

- ▶ We assumed $x|(t=1) \sim \mathcal{N}(\mu_+, \Sigma_+)$ and $x|(t=-1) \sim \mathcal{N}(\mu_-, \Sigma_-)$, and two class-probabilities P(t=1) and P(t=-1).
- ► This is called an generative model, as we have written down a full joint model over the data.
- We saw that violations of the model assumption can lead to 'bad' decision boundaries.



For regression, we assumed Gaussian outputs, but did not need assumptions about the distribution of inputs.

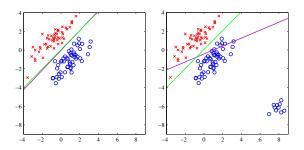
- For linear regression, we conditioned on x, and assumed a Gaussian distribution over t: $t|x \sim \mathcal{N}(y(x), \gamma^2)$
- We maximized the conditional log-likelihood $L(\omega) = \sum_{n} \log p(t_n|x_n, \omega)$, i.e we assumed that the x were given.
- ► Therefore, this approach to linear regression works for any distribution over *x*.
- \triangleright x is typically high-dimensional, so it is difficult to make appropriate distributional assumptions for it.



We can define a discriminative model for classification by modelling the conditional class probabilities.

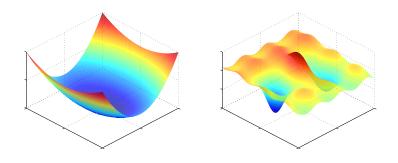
- From the homework-exercise, we know that $P(t = 1|z(x)) = \sigma(z(x))$ where $\sigma(z) = 1/(1 + \exp(-z))$ and $z(x) = \omega^{\top} x + \omega_o$.
- Notation is simpler if we use 0 and 1 as class labels, so we define $s_n = 1$ as the label for the positive class, and $s_n = 0$ als label for the negative class.
- ▶ In other words, $s|x \sim \text{Bernoulli}(\sigma(y(x)))$.
- ▶ Also, we set $y_n = \sigma(z(x))$.
- ► The parameters of $z(x) = \omega^{\top} x + \omega_o$ can be learned by maximizing the conditional log-likelihood $L(\omega) = \sum_n \log p(t_n | x_n, \omega)$ [on board]
- ▶ This is an discriminative approach to classification, as we only model the labels, and not the inputs.
- ▶ Decision rule and function shape of p(t|x) will be the same for the generative ('Linear Discriminant Analysis') and the discriminative model, but the parameters were obtained differently.

Maximum likelihood estimation of Logistic Regression



- ▶ This algorithm is called logistic regression, and is a *much* better algorithm than the algorithms we discussed last week.
- ▶ Need to optimize log-likelihood numerically.
- ▶ People typically minimize the negative log-likelihood \mathcal{L} rather than maximize the log-likelihood...
- ▶ To numerically minimize the negative log-likelihood, we need its gradient (and maybe its hessian) [on board]

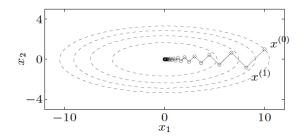
The cost-function for logistic regression is convex.

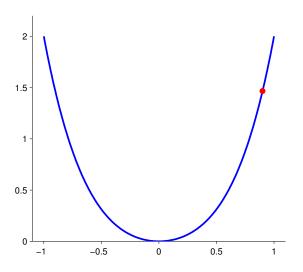


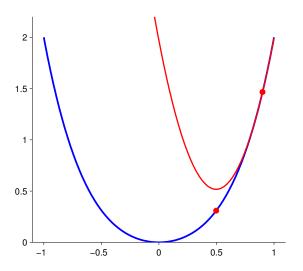
- ► Fact: The negative log-likelihood is *convex* this makes life much more easier.
- ▶ There are no local minima to get stuck in, and there is good optimization techniques for convex problems.

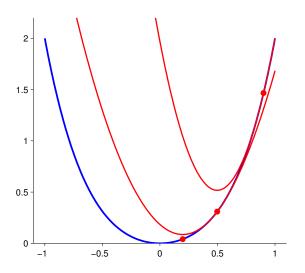
Gradient descent is a simple method for numerically minimizing a function.

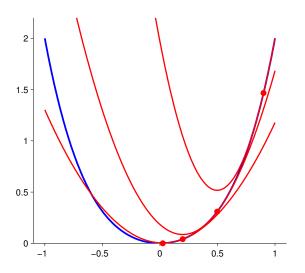
- ▶ The gradient $\nabla \mathcal{L}$ of a function points into the direction of steepest descent.
- ▶ Gradient descent: 'run down the gradient' $\omega_{new} = \omega_{old} \alpha \nabla \mathcal{L}_{\omega}$, with learning rate α .
- ▶ Slightly more sophisticated version: numerically optimize α for each step by doing a *line search*.
- ► Convergence can be very slow if cost-function has 'valleys'.

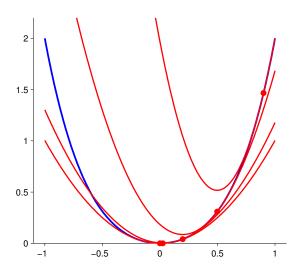


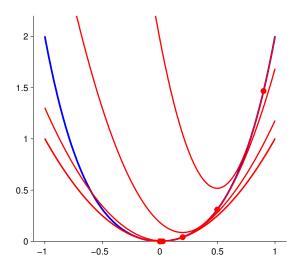


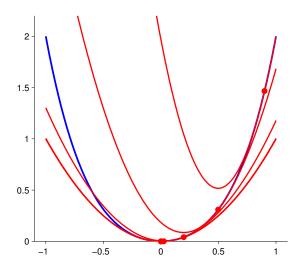












Iterative Least Squares is a more efficient method for minimizing the cost-function

- ▶ Newton-Raphson: $\omega_{new} = \omega_{old} \alpha (\nabla \nabla \mathcal{L})^{-1} \nabla L_{\omega}$
- ▶ Pre-multiplying the gradient by the inverse-hessian speeds up convergence 'along valleys' (analogy with LDA)
- ▶ Motivation: For quadratic functions $F(x) = a + b^{\top}x + x^{\top}Bx$, Newton-Raphson finds the minimum in one iteration.
- ▶ In this contex, Newton-Raphson (with $\alpha = 1$) is often called iterative least squares.
- ▶ Note: Newtwn's method can be bad if problem is not convex, and can be slow if it is difficult to calculate/invert the Hessian. A large number of optimization algorithms exist which do not require the (complete) Hessian (quasi Newton/BFGS, etc..).



[on board]

Bayesian inference for this model does not have a closed form solution

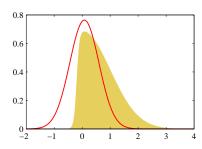
- ▶ Typically use Gaussian prior on ω .
- ▶ For linear regression, posterior distribution was Gaussian, with closed-form solutions for the mean and covariance.
- ▶ For logistic regression, the posterior distribution is non-Gaussian.
- ▶ Popular approximation: Approximate posterior by a Gaussian

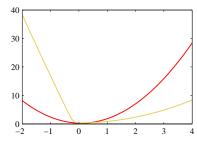
$$p(\omega|D) \approx \mathcal{N}(\mu_{post}, \Sigma_{post})$$
 (1)

▶ Different methods exist for finding 'good' μ_{post} and Σ_{post} : Expectation Propagation (EP), Laplace Approximation, Variational Inference

The Laplace-Approximation is a simple Gaussian approximation to the posterior

- ▶ Laplace approximation: $\mu_{post} = \omega_{MAP}$, $\Sigma_{post} = (\nabla \nabla_{\omega} L)^{-1}$.
- ▶ Take MAP as mean, and inverse hessian at MAP as covariance.
- ▶ Motivation: Curvature matching, Taylor-expansion [on board]
- ▶ Q: When will the Laplace approximation fail?





The poster	rior distribu	tion can	ı be used	to calcul	late the
predictive	distribution	and to	optimze	hyper-pa	rameters

 $[{\rm on\ board}]$

One last bit of business: The exam

- ▶ Next Friday, 2pm sharp.
- ▶ You will have 90 minutes.
- ➤ You are allowed to use a pen or other writing utensils and your brain, no other tools/materials/books/notes will be allowed.
- ▶ All mobiles phones need to be switched off.
- ▶ Master-Students: Graded
- ▶ Everyone else: Pass/Fail. If you want a grade for whatever reason, let me know (but it might not have any official meaning).

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Have fun in the second half of the course!

If you did like (some bits) from these lectures ...

... and want to do a lab-rotation on using machine-learning methods to analyse neural data and to model neural population dynamics

... write an email to jakobtuebingen.mpg.de.