# Image Processing and Computer Graphics Rendering Pipeline

**Matthias Teschner** 

Computer Science Department University of Freiburg



## **Outline**

- introduction
- rendering pipeline
- vertex processing
- primitive processing
- fragment processing
- summary

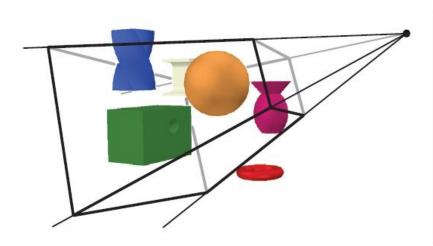
## Rendering

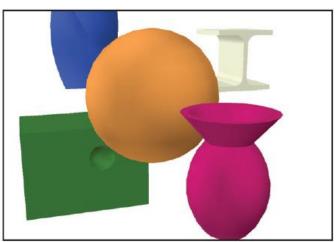
- the process of generating an image given
  - a virtual camera
  - objects
  - light sources
- various techniques, e. g.
  - rasterization (topic of this course)
  - raytracing (topic of the course "Advanced Computer Graphics")
- one of the major research topics in computer graphics
  - rendering
  - animation
  - geometry processing



### Rasterization

- rendering algorithm for generating 2D images from 3D scenes
- transforming geometric primitives such as lines and polygons into raster image representations, i. e. pixels

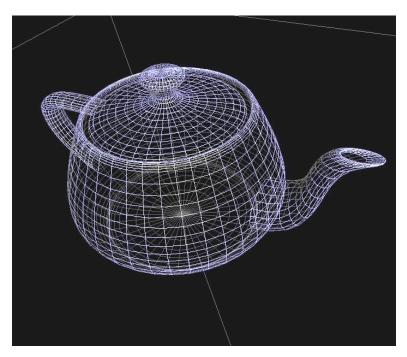


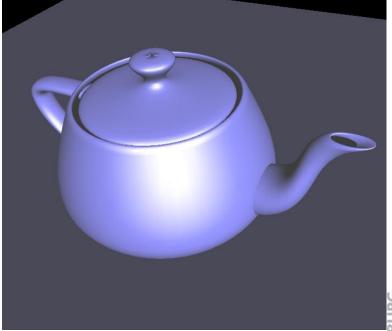


[Akenine-Moeller et al.: Real-time Rendering]

### Rasterization

- 3D objects are approximately represented by vertices (points), lines, polygons
- these primitives are processed to obtain an 2D image





[Akenine-Moeller]

## Rendering Pipeline

- processing stages comprise the rendering pipeline (graphics pipeline)
- supported by commodity graphics hardware
  - GPU graphics processing unit
  - computes stages of the rasterization-based rendering pipeline
- OpenGL and DirectX are software interfaces to graphics hardware
  - this course focuses on concepts of the rendering pipeline
  - this course assumes OpenGL in implementation-specific details

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## Rendering Pipeline - Task

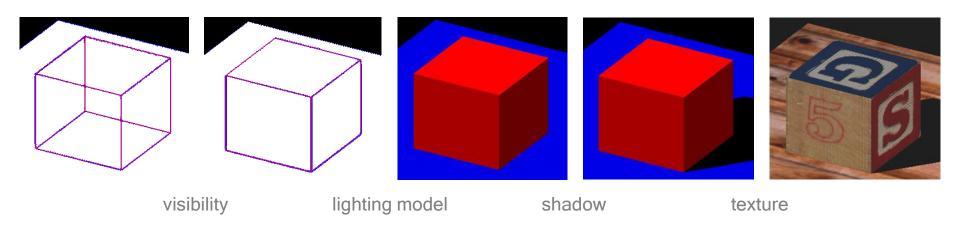
#### 3D input

- a virtual camera
  - position, orientation, focal length
- objects
  - points (vertex / vertices), lines, polygons
  - geometry and material properties (position, normal, color, texture coordinates)
- light sources
  - direction, position, color, intensity
- textures (images)
- 2D output
  - per-pixel color values in the framebuffer



# Rendering Pipeline / Some Functionality

- resolving visibility
- evaluating a lighting model
- computing shadows (not core functionality)
- applying textures

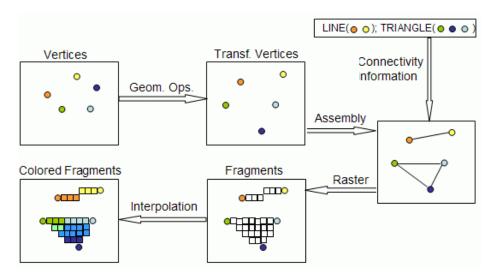


# Rendering Pipeline Main Stages

- vertex processing / geometry stage / vertex shader
  - processes all vertices independently in the same way
  - performs transformations per vertex, computes lighting per vertex
- geometry shader
  - generates, modifies, discards primitives
- primitive assembly and rasterization / rasterization stage
  - assembles primitives such as points, lines, triangles
  - converts primitives into a raster image
  - generates fragments / pixel candidates
  - fragment attributes are interpolated from vertices of a primitive
- fragment processing / fragment shader
  - processes all fragments independently in the same way
  - fragments are processed, discarded or stored in the framebuffer

# Rendering Pipeline Main Stages

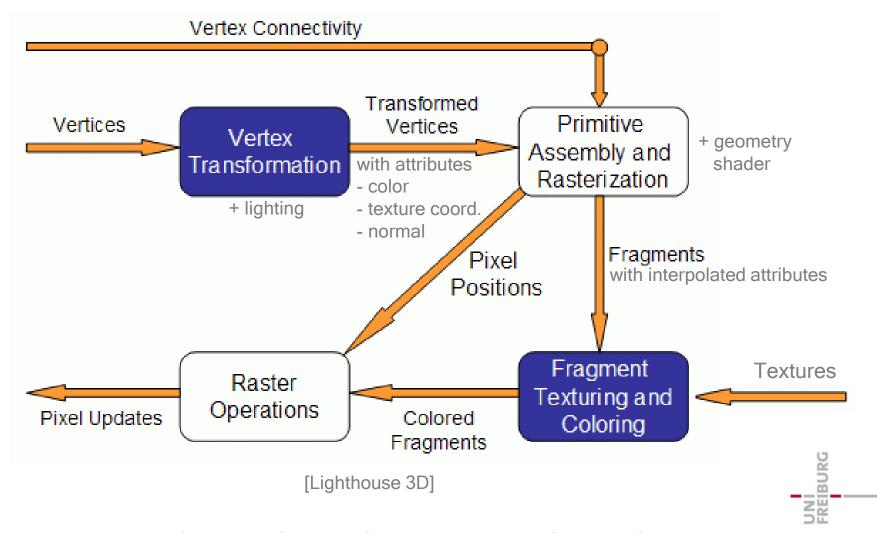
- vertex position transform
- lighting per vertex
- primitive assembly, combine vertices to lines, polygons
- rasterization, computes pixel positions affected by a primitive
- fragment generation with interpolated attributes, e. g. color
- fragment processing (not illustrated),
   fragment is discarded or used to update
   the pixel information in the framebuffer,
   more than one fragment can be processed
   per pixel position



[Lighthouse 3D]



# Rendering Pipeline Main Stages



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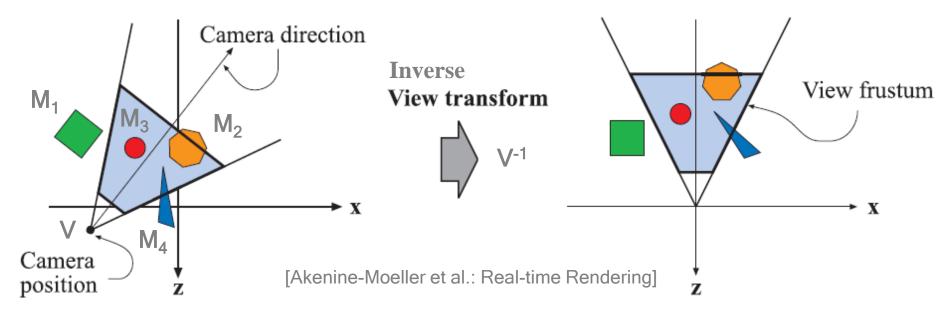
# Vertex Processing (Geometry Stage)

- model transform
- view transform
- lighting
- projection transform
- clipping
- viewport transform

# Model Transform View Transform

- each object and the respective vertices are positioned, oriented, scaled in the scene with a model transform
- camera is positioned and oriented, represented by the view transform
- i. e., the inverse view transform is the transform that places the camera at the origin of the coordinate system, facing in the negative z-direction
- entire scene is transformed with the inverse view transform

## Model Transform View Transform



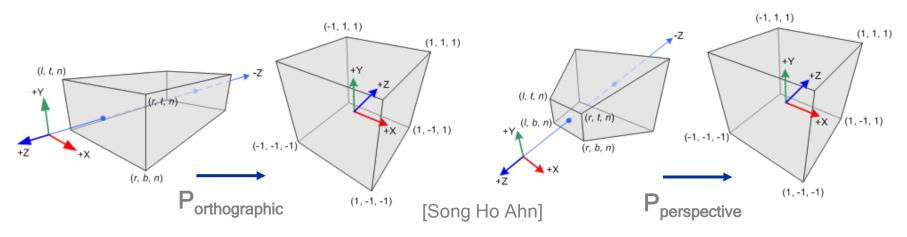
- M<sub>1</sub>, M<sub>2</sub>, M<sub>3</sub>, M<sub>4</sub>, V are matrices representing transformations
- M<sub>1</sub>, M<sub>2</sub>, M<sub>3</sub>, M<sub>4</sub> are model transforms to place the objects in the scene
- V places and orientates the camera in space
  - V<sup>-1</sup> transforms the camera to the origin looking along the negative z-axis
- model and view transforms are combined in the modelview transform
- the modelview transform V<sup>-1</sup>M<sub>1..4</sub> is applied to the objects

# Lighting

- interaction of light sources and surfaces
   is represented with a lighting / illumination model
- lighting computes color for each vertex
  - based on light source positions and properties
  - based on transformed position, transformed normal, and material properties of a vertex

## Projection Transform

- P transforms the view volume to the canonical view volume
- the view volume depends on the camera properties
  - orthographic projection → cuboid
  - perspective projection → pyramidal frustum



- canonical view volume is a cube from (-1,-1,-1) to (1,1,1)
- view volume is specified by near, far, left, right, bottom, top

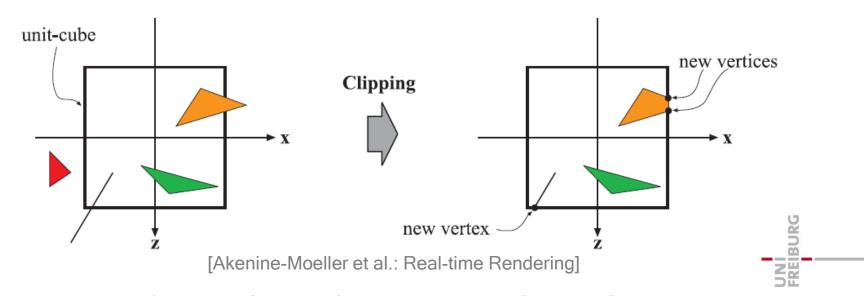
## Projection Transform

- view volume (cuboid or frustum) is transformed into a cube (canonical view volume)
- objects inside (and outside) the view volume are transformed accordingly
- orthographic
  - combination of translation and scaling
  - all objects are translated and scaled in the same way
- perspective
  - complex transformation
  - scaling factor depends on the distance of an object to the viewer
  - objects farther away from the camera appear smaller



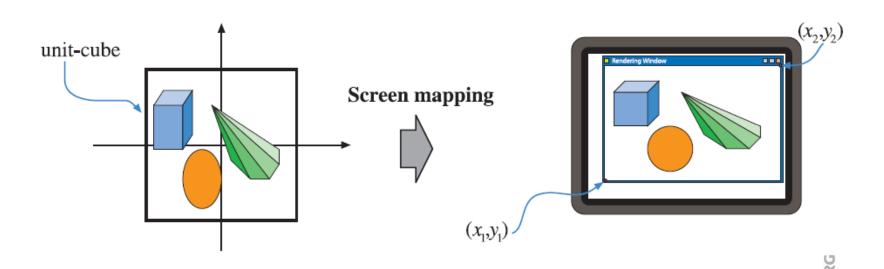
# Clipping

- primitives, that intersect the boundary of the view volume, are clipped
  - primitives, that are inside, are passed to the next processing stage
  - primitives, that are outside, are discarded
- clipping deletes and generates vertices and primitives



# Viewport Transform / Screen Mapping

- projected primitive coordinates (x<sub>p</sub>, y<sub>p</sub>, z<sub>p</sub>) are transformed to screen coordinates (x<sub>s</sub>, y<sub>s</sub>)
- screen coordinates together with depth value are window coordinates (x<sub>s</sub>, y<sub>s</sub>, z<sub>w</sub>)



[Akenine-Moeller et al.: Real-time Rendering]

# Viewport Transform / Screen Mapping

- $(x_p, y_p)$  are translated and scaled from the range of (-1, 1) to actual pixel positions  $(x_s, y_s)$  on the display
- z<sub>p</sub> is generally translated and scaled from the range of (-1, 1) to (0,1) for z<sub>w</sub>
- screen coordinates (x<sub>s</sub>, y<sub>s</sub>) represent the pixel position of a fragment that is generated in a subsequent step
- z<sub>w</sub>, the depth value, is an attribute of this fragment used for further processing

# Vertex Processing - Summary

object space



modelview transform

eye space / camera space



lighting, projection

clip space / normalized device coordinates



clipping, viewport transform

window space



## Vertex Processing - Summary

#### input

- vertices in object / model space
- 3D positions
- attributes such as normal, material properties, texture coordinates

#### output

- vertices in window space
- 2D pixel positions
- attributes such as normal, material properties, texture coordinates
- additional or updated attributes such as
  - normalized depth (distance to the viewer)
  - color (result of the evaluation of the lighting model)



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# Primitive Assembly / Rasterization

#### primitive assembly

- vertex information and connectivity information are combined for further processing of points, lines and triangles
- geometry shader
  - change, delete, generate primitives
- rasterization
  - converts primitives into fragments
  - computes positions of screen pixels that are affected by a primitive
  - generates a fragment for each affected pixel position
  - interpolates attributes from vertices to fragments



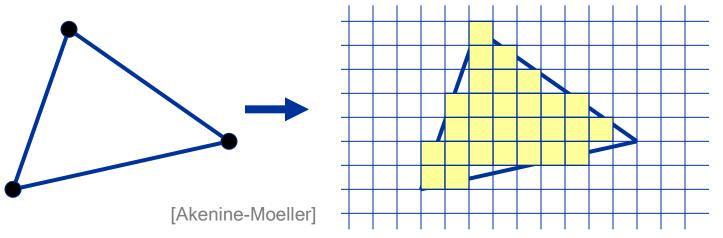
### Rasterization

#### input

- vertices with attributes and connectivity information
- attributes: color, depth, texture coordinates

#### output

- fragments with attributes
  - pixel position
  - interpolated color, depth, texture coordinates



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## Fragment Processing

- fragment attributes are processed and tests are performed
  - fragment attributes are processed
  - fragments are discarded or
  - fragments pass a test and finally update the framebuffer
- processing and testing make use of
  - fragment attributes
  - textures
  - additional data that is available for each pixel position
    - depth buffer
    - color buffer
    - stencil buffer
    - accumulation buffer



## Attribute Processing

#### texture lookup

use texture coordinates to look up a texel (pixel of an texture image)

#### texturing

combination of color and texel

#### fog

adaptation of color based on fog color and depth value

#### antialiasing

- adaptation of alpha value (and color)
- color has three components: red, green, blue
- color is represented as a 4D vector (red, green, blue, alpha)



### **Tests**

#### scissor test

- check if fragment is inside a specified rectangle
- used for, e. g., masked rendering

#### alpha test

- check if the alpha value fulfills a certain requirement
- comparison with a specified value
- used for, e. g., transparency and billboarding

#### stencil test

- check if the stencil value in the framebuffer at the position of the fragment fulfills a certain requirement
- comparison with a specified value
- used for various rendering effects, e. g. masking, shadows



## Depth Test

#### depth test

- compare depth value of the fragment and depth value of the framebuffer at the position of the fragment
- used for resolving the visibility
- if the depth value of the fragment is larger than the framebuffer depth value, the fragment is discarded
- if the depth value of the fragment is smaller than the framebuffer depth value, the fragment passes and (potentially) overwrites the current color and depth values in the framebuffer

## Blending / Merging

#### blending

- combines the fragment color with the framebuffer color at the position of the fragment
- usually determined by the alpha values
- resulting color (including alpha value) is used to update the framebuffer

#### dithering

- finite number of colors
- map color value to one of the nearest renderable colors
- logical operations / masking



# Fragment Processing - Summary

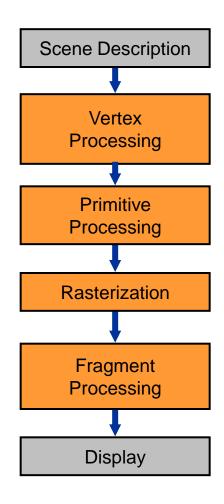
- texture lookup
- texturing
- fog
- antialiasing
- scissor test
- alpha test
- stencil test
- depth test
- blending
- dithering
- logical operations



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# Rendering Pipeline - Summary



## Rendering Pipeline - Summary

- primitives consist of vertices
- vertices have attributes (color, depth, texture coordinates)
- vertices are transformed and lit
- primitives are rasterized into fragments / pixel candidates with interpolated attributes
- fragments are processed using
  - their attributes such as color, depth, texture coordinates
  - texture data / image data
  - framebuffer data / data per pixel position (color, depth, stencil, acc.)
- if a fragment passes all tests, it replaces the pixel data in the framebuffer