## 线性代数第一、二章测验(A卷)

1. 设
$$D(x) = \begin{vmatrix} 1 & x & x^2 & x^3 \\ 1 & 2 & 4 & 8 \\ 1 & 3 & 9 & 27 \\ 1 & 4 & 16 & 64 \end{vmatrix}$$
, 求出 $D(x) = 0$ 的全部根

拔性代数测验I (A卷)解释。

:由D(X)=0=> X=2, X=3, X=4 为所或部品根

$$2. \left(\frac{1}{2}A\right)^{-1} = \begin{pmatrix} 0 & -1 & 3\\ 0 & 1 & -1\\ -2 & 0 & 0 \end{pmatrix}, \quad \Re A;$$

2. 
$$\mathbb{Z}^{N}$$
,  $\mathbb{E}\left[\left(\frac{1}{2}A\right)^{+}\right]^{-1}$   $(:(A^{+})^{+}=A)$ 

$$\begin{pmatrix}
0 & + & 3 & 1 & 0 & 0 \\
0 & 1 & + & 0 & 1 & 0 \\
-2 & 0 & 0 & 0 & 1
\end{pmatrix}
\rightarrow
\begin{pmatrix}
1 & 0 & 0 & 0 & -\frac{1}{2} \\
0 & 1 & 0 & \frac{1}{2} & \frac{3}{2} & 0 \\
0 & 0 & 1 & \frac{1}{2} & \frac{3}{2} & 0
\end{pmatrix}
\Rightarrow
\frac{1}{2}A = \begin{pmatrix}
0 & 0 & -\frac{1}{2} \\
\frac{1}{2} & \frac{3}{2} & 0 \\
\frac{1}{2} & \frac{1}{2} & 0
\end{pmatrix}
\Rightarrow A = \begin{pmatrix}
0 & 0 & + \\
1 & 3 & 0 \\
1 & 1 & 0
\end{pmatrix}$$

### 这里一定要看懂这种解法,并能灵活应用

3. 若方阵 A 满足 $A^2 = A$ 且  $A \neq E$ ,E 是单位矩阵,

3. 压确公牧法是柳氏沼坛,若称A、A=A且A=E,例A不可逐 注晰: 若A可遂,则由A=A;B A+A2=A+A=E 即A=E(赤首) 国此A不可遂

指法-、::A2=A → A2-A=0 ⇒ A(A-E)=0 (AB=0+)A=0成B=0 ·: A+E ⇒ A-E+0 、所以A=0

原は A= (° ° ) A=A, 且A+E 、1日A+O(製Aを引き)

(イン) \*\* (1) \*

- 4. 已知A,B为 4 阶方阵,且|A|=-2,|B|=3,求
  - (1) |5AB|;

试证明 A 不可逆.

- (2)  $\left| -AB^T \right|$ ;
- $(3) \left| (AB)^{-1} \right|;$
- (4)  $|A^{-1}B^{-1}|$ ;

$$(5) \left| ((AB)^T)^{-1} \right|$$

(3) 
$$|(AB)^{-1}| = |B^{-1}A^{-1}| = |B^{-1}||A^{-1}| = \frac{1}{|B|} \cdot \frac{1}{|A|}$$
  
=  $\frac{1}{3} \cdot \frac{1}{-2} = -\frac{1}{6}$ 

(4) 
$$|A_{+}B_{+}| = |A_{+}||B_{+}| = \frac{|A_{1}|}{1} \cdot \frac{|B_{1}|}{1} = -\frac{Q}{1}$$

$$|(AB)^{T}|^{4} = |(AB)^{4}|^{T} = |(AB)^{4}|^{T} = \frac{1}{6}$$

- 5. (1) 设 A 是方阵且 $A^2 + A 8I = 0$ , E 是单位矩阵, 证明: A 2I 可逆;
  - (2) 对满足(1) 中条件的 A, 设矩阵 X 与之具有关系:

I. (1) A清洁且 A2+A-8E=O , j3M A-2E可通

「記明: :: 
$$A^2+A-6E=2E \Rightarrow (A+3E)(A-2E)=2E$$

$$\Rightarrow \left(\frac{1}{2}(A+3E)\right)(A-2E)=E \longrightarrow (A+3E)^{-1}=\frac{1}{2}(A-2E)$$
::  $A-2E$  可達, 且  $(A-2E)^{-1}=\frac{1}{2}(A+3E)$ 

$$Z = \frac{1}{2}(A+3E)(2E) - (A+3E)(A+3E)^{T}A$$

$$D = \begin{vmatrix} -a_1 & a_1 & 0 & \cdots & 0 & 0 \\ 0 & -a_2 & a_2 & \cdots & 0 & 0 \\ 0 & 0 & -a_3 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -a_n & a_n \\ 1 & 1 & 1 & \cdots & 1 & 1 \end{vmatrix}$$

$$D = \begin{vmatrix} -a_1 & 0 & 0 & \cdots & 0 & 0 \\ 0 & -a_2 & 0 & \cdots & 0 & 0 \\ 0 & -a_2 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -a_n & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -a_n & 0 \\ 1 & 2 & 3 & \cdots & n & n+1 \end{vmatrix}$$

# 线性代数第一、二章测验(B卷)

1. 已知A是可逆的三阶矩阵,且|A|=3,求 $|A^*|$ .

# (B卷)科释

1. A可逐三阶段时,且1A1=3,只 |A\*|=1A1<sup>54</sup>=1A1<sup>54</sup>=1A1<sup>5</sup>=9

2. 设
$$A = \begin{vmatrix} 1 & 2 & 3 & 4 \\ 4 & 3 & 2 & 1 \\ 1 & 0 & -1 & 2 \\ 5 & 1 & -1 & 6 \end{vmatrix}$$
, 求 $4A_{41} + 3A_{42} + 2A_{43} + A_{44}$   
其中 $A_{ij}$ 是 $A$ 的代数余子式  
 $i = 1, 2, 3, 4; \quad j = 1, 2, 3, 4$ 

2. 4A4+3A4+2A63+A64=第二行《注言第四行《代教 (居)Po. 性度7 全状化兼积之和=0

3. 设方阵  ${\bf A}$  满足方程  ${\bf A^2-A-7I=0}$ , ${\bf E}$  是单位矩阵, 试证明:  $({\bf A-3I})$ 可逆, 并求出其逆.

3. 由A²-A-71=0 ⇒ A²-A-61=I ⇒ (A-31)(A+≥I)=I ⇒ A-31 も A+≥I均可逆 且之行至为逆矩阵,所以 (A-31)1= A+2I

4. 求方程
$$\begin{vmatrix} a_1 & a_2 & a_3 & a_4 + x \\ a_1 & a_2 & a_3 + x & a_4 \\ a_1 & a_2 + x & a_3 & a_4 \\ a_1 + x & a_2 & a_3 & a_4 \end{vmatrix} = 0$$
的全部解.

4. ボ方(2) 
$$a_1, a_2, a_3, a_4+x$$
 $a_1, a_2, a_3+x, a_4$ 
 $a_1, a_2+x, a_3, a_4$ 
 $a_1+x, a_2, a_3, a_4$ 
 $a_1+x, a_2, a_3, a_4$ 
 $a_1, a_2+x, a_3, a_4$ 
 $a_1, a_2+x, a_3, a_4$ 
 $a_1, a_2, a_3+x, a_4$ 
 $a_1, a_2, a_3, a_4+x$ 
 $a_1, a_2,$ 

5. 设
$$A = \begin{pmatrix} 1 & 2 & -2 \\ 4 & t & 3 \\ 3 & -1 & 1 \end{pmatrix}$$
, B 是非零的  $3 \times 5$  的矩阵,且  $AB = 0$ ,求  $t$  的值.

6. 已知
$$A = \begin{pmatrix} -4 & -3 & 1 \\ -5 & -3 & 1 \\ 6 & 4 & -1 \end{pmatrix}$$
, 且 $A^2 - AB = I$ , E 是单位矩阵, 求 B.

7. 设 $\pmb{A}$ , $\pmb{B}$ , $\pmb{C}$  为三阶可逆方阵,化简: $(\pmb{B}\pmb{C}^T - \pmb{I})^T(\pmb{A}\pmb{B}^{-1})^T + [(\pmb{B}\pmb{A}^{-1})^T]^{-1}$ 

# 线性代数测验 II (A卷)

1. 设 4 元非齐次线性方程组 Ax = b 有三个线性无关的特解  $\eta_1, \eta_2, \eta_3$ ,且 R(A) = 2,则方程组的通解  $x = C_1(\eta_1 - \eta_2) + C_2(\eta_2 - \eta_3) + \eta_3$ , $C_1, C_2$ 为任意常数

证明:  $:: \eta_1, \eta_2, \eta_3,$ 线性无关, :: 它各互不相同 且 $\eta_1 - \eta_2, \eta_2 - \eta_3$ 是Ax = 0的非零解. 又设 $k_1(\eta_1 - \eta_2) + k_2(\eta_2 - \eta_3) = 0, \Rightarrow k_1\eta_1 + k_2\eta_2 - (k_1 + k_2)\eta_3 = 0$  $:: \eta_1, \eta_2, \eta_3,$ 线性无关,  $:: k_1 = k_2 = 0$ ,故 $\eta_1 - \eta_2, \eta_2 - \eta_3$ 线性无关 又 $:: R(A) = 2, n = 4, \Rightarrow n - R(A) = 2,$ 

2. 设
$$A = \begin{pmatrix} a & 1 & 1 & 2 \\ 2 & a+1 & 2a & 3a+1 \\ 1 & 1 & 1 & 2 \end{pmatrix}$$
 , 且存在 3 阶非零方阵 **B** 使 **BA**=0,求 a

 $\Rightarrow$  Ax = 0的基础解系中含有2个解向量

 $A^{T}B^{T} = A^{T}(\beta_{1}, \beta_{2}, \beta_{3}) = (A^{T}\beta_{1}, A^{T}\beta_{2}, A^{T}\beta_{3}) = (0, 0, 0)$   $\Rightarrow A^{T}\beta_{1} = 0, A^{T}\beta_{2} = 0, A^{T}\beta_{3} = 0, \ \ X : B \neq 0, \ \ \text{故存在某} \land \beta_{j} \neq 0 (j = 1, 2, 3)$   $\oplus A^{T}\beta_{j} = 0, \ \ \text{也即次性方程} A^{T}x = 0$   $\Rightarrow a = 1, \ R(A^{T}) = R(A) = 1 < 3$   $\Rightarrow a = 1, \ R(A^{T}) = R(A) = 1 < 3$ 

3. 讨论 
$$\lambda$$
 取什么值时线性方程组 
$$\begin{cases} \lambda x_1 + x_2 + x_3 = 1 \\ x_1 + \lambda x_2 + x_3 = 1 \end{cases}$$
  $x_1 + x_2 + x_3 = 1$ 

解: 方程组的增广矩阵为  $\begin{pmatrix} \lambda & 1 & 1 & 1 \\ 1 & \lambda & 1 & 1 \\ 1 & 1 & \lambda & 1 \end{pmatrix}$ ,系数行列式为  $\begin{vmatrix} \lambda & 1 & 1 \\ 1 & \lambda & 1 \\ 1 & 1 & \lambda \end{vmatrix} = (\lambda + 2)(\lambda - 1)^2$ 

(1) 当  $\lambda \neq 1$  且  $\lambda \neq -2$  时,方程有唯一解,此时

$$\begin{pmatrix} \lambda & 1 & 1 & 1 \\ 1 & \lambda & 1 & 1 \\ 1 & 1 & \lambda & 1 \end{pmatrix} \rightarrow \begin{pmatrix} \lambda + 2 & \lambda + 2 & \lambda + 2 & 3 \\ 1 & \lambda & 1 & 1 \\ 1 & 1 & \lambda & 1 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 1 & 1 & \frac{3}{\lambda+2} \\ 1 & \lambda & 1 & 1 \\ 1 & 1 & \lambda & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & \frac{3}{\lambda+2} \\ 0 & \lambda-1 & 0 & \frac{\lambda-1}{\lambda+2} \\ 0 & 0 & \lambda-1 & \frac{\lambda-1}{\lambda+2} \end{pmatrix}$$

故得解为 
$$x_1 = x_2 = x_3 = \frac{1}{\lambda + 2}$$
;

(2) 当
$$\lambda = -2$$
时,增广矩阵 $\begin{pmatrix} -2 & 1 & 1 & 1 \\ 1 & -2 & 1 & 1 \\ 1 & 1 & -2 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} -2 & 1 & 1 & 1 \\ 1 & -2 & 1 & 1 \\ 0 & 0 & 0 & 3 \end{pmatrix}$ ,无解;

解, 同解方程为  $x_1 = 1 - x_2 - x_3$  ( $x_2, x_3$ ) 自由未知量), 原方程的同解是:

$$\xi = (1,0,0) + c_1(-1,1,0) + c_2(-1,0,1)$$
,  $c_1,c_2$ 是任意常数

4. 若 $\alpha_1$ , $\alpha_2$ , $\alpha$  线性无关,证明: $\beta_1 = \alpha_1 + \alpha_2 + 2\alpha_3$ , $\beta_2 = \alpha_1 - \alpha_2$ , $\beta_3 = \alpha_1 + \alpha_3$ 线性相关.

 $R(B) = R(AC), \Rightarrow R(B) \le R(A), \exists R(B) \le R(C)$ 

 $:: \alpha_1, \alpha_2, \alpha_3$ 线性无关,  $\Rightarrow R(A) = 3$ 

$$\mathbb{X} \cdot C = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & 0 \\ 2 & 0 & 1 \end{pmatrix} \dot \begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & -1 \\ 0 & -2 & -1 \end{bmatrix} \dot \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \Rightarrow R(C) = 2$$

 $\Rightarrow R(B) \le 2$ , [:  $R(AB) \le \min\{R(A), R(B)\}\] \Rightarrow \beta_1, \beta_2, \beta_3$ 线性相关

- 5. 已知向量空间 $R^3$ 中的四个向量:  $\alpha_1 = (1,1,0), \alpha_2 = (1,1,1), \alpha_3 = (2,2,1), \alpha_4 = (-1,-1,1)$ ,
- ①求向量组 $\alpha_1,\alpha_2,\alpha_3,\alpha_4$ 的秩与一个最大线性无关组;
- ②把①中的最大线性无关组扩充为 R³的一组基

$$\Re: (1) \ A = \left(\alpha_1^T, \alpha_2^T, \alpha_3^T, \alpha_4^T\right) = \begin{pmatrix} 1 & 1 & 2 & -1 \\ 1 & 1 & 2 & -1 \\ 0 & 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{pmatrix}$$

$$\Rightarrow R(A) = 2 \Rightarrow r\{\alpha_1, \alpha_2, \alpha_3, \alpha_4\} = 2$$

显然 $\alpha_1,\alpha_2$ 线性无关,故 $\alpha_1,\alpha_2$ 就是一个最大线性无关组

(2) 一般的方法:

制作
$$(A,E) = (\alpha_1^T, \alpha_2^T, \alpha_3^T, \alpha_4^T, e_1, e_2, e_3)$$
,  $\Rightarrow R(A,E) = 3$ 

$$(A,E) = \begin{pmatrix} 1 & 1 & 2 & -1 & 1 & 0 & 0 \\ 1 & 1 & 2 & -1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 & 1 \end{pmatrix} \begin{bmatrix} \begin{pmatrix} 1 & 1 & 2 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{pmatrix}
 1 & 0 & 1 & -2 & 0 & 1 & -1 \\
 0 & 1 & 1 & 1 & 0 & 0 & 1 \\
 0 & 0 & 0 & 0 & 1 & -1 & 0
 \end{pmatrix}, \Rightarrow e_1, \alpha_1^T, \alpha_2^T \angle R^3$$
的一组基

特别地,对这道题可以有一个更简单的方法:

制作: 
$$(e_1, \alpha_1^T, \alpha_2^T) = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \Rightarrow R(e_1, \alpha_1^T, \alpha_2^T) = 3 \Rightarrow e_1, \alpha_1^T, \alpha_2^T \neq R^3$$
的一组基

以下进行正交化: 取 $\boldsymbol{\beta}_1 = (1,0,0), \boldsymbol{\beta}_2 = \boldsymbol{\alpha}_1 - \frac{(\boldsymbol{\alpha}_1, \boldsymbol{\beta}_1)}{(\boldsymbol{\beta}_1, \boldsymbol{\beta}_1)} \boldsymbol{\beta}_1 = (0,1,0)$ 

$$\boldsymbol{\beta}_3 = \boldsymbol{\alpha}_2 - \frac{(\boldsymbol{\alpha}_2, \boldsymbol{\beta}_2)}{(\boldsymbol{\beta}_2, \boldsymbol{\beta}_2)} \boldsymbol{\beta}_2 - \frac{(\boldsymbol{\alpha}_2, \boldsymbol{\beta}_1)}{(\boldsymbol{\beta}_1, \boldsymbol{\beta}_1)} \boldsymbol{\beta}_1 = (\boldsymbol{0}, \boldsymbol{0}, \boldsymbol{1}) \Rightarrow \|\boldsymbol{\beta}_3\| = 1$$

 $: \beta_1, \beta_2, \beta_3$ 都是单位向量,无需单位化,所以 $\beta_1, \beta_2, \beta_3$ 是一组规范正交基

6. 设 V 是 3 维向量空间,
$$\eta_1, \eta_2, \eta_3$$
 是 V 的一个基, 令 
$$\begin{cases} \alpha_1 = \eta_1 + \eta_2 + \eta_3, \\ \alpha_2 = \eta_1 + 2\eta_2 + 2\eta_3, \\ \alpha_3 = \eta_1 + 2\eta_2 + 3\eta_3, \end{cases}$$
  $\begin{cases} \beta_1 = \eta_2 + \eta_3 \\ \beta_2 = \eta_1 + \eta_3 \\ \beta_3 = \eta_1 + \eta_2 \end{cases}$ 

- ①证明 $\alpha_1, \alpha_2, \alpha_3$ 与 $\beta_1, \beta_2, \beta_3$ 都是V的基;
- ②求 $\alpha_1,\alpha_2,\alpha_3$ 到 $\beta_1,\beta_2,\beta_3$ 的过渡矩阵;
- ③求 $\gamma = 2\eta_1 2\eta_2 3\eta_3$ 在基 $\alpha_1, \alpha_2, \alpha_3$ 的坐标。

解: ①令
$$k_1\alpha_1 + k_2\alpha_2 + k_3\alpha_3 = 0$$
, 则有 
$$k_1(\eta_1 + \eta_2 + \eta_3) + k_2(\eta_1 + 2\eta_2 + 2\eta_3) + k_3(\eta_1 + 2\eta_2 + 3\eta_3) = 0$$
 
$$(k_1 + k_2 + k_3)\eta_1 + (k_1 + 2k_2 + 2k_3)\eta_2 + (k_1 + 2k_2 + 3k_3)\eta_3 = 0$$

因为
$$\eta_1$$
,  $\eta_2$ ,  $\eta_3$ 线性无关,  $\Rightarrow$  
$$\begin{cases} k_1 + k_2 + k_3 = 0 \\ k_1 + 2k_2 + 2k_3 = 0 \\ k_1 + 2k_2 + 3k_3 = 0 \end{cases}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix} \stackrel{\vdash}{\Box} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 2 \end{pmatrix} \stackrel{\vdash}{\Box} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \Rightarrow k_1 = k_2 = k_3 = 0$$

 $\Rightarrow \alpha_1, \alpha_2, \alpha_3$ 是V的一组基,

同理可证 $\beta_1,\beta_2,\beta_3$ 也是V的一组基.

### ② 把上述向量组之间的关系式表示为

$$\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right) = \left(\eta_{1}, \quad \eta_{2}, \quad \eta_{3}\right) \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix}$$
 [1]

$$(\beta_1, \beta_2, \beta_3) = (\eta_1, \eta_2, \eta_3) \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$$
 [2]

曲【1】得,
$$(\eta_1, \eta_2, \eta_3) = (\alpha_1, \alpha_2, \alpha_3) \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix}^{-1}$$

曲【2】得,
$$(\beta_1,\beta_2,\beta_3)$$
= $(\alpha_1,\alpha_2,\alpha_3)$  $\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix}^{-1}$  $\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$ 

所以从 $\alpha_1,\alpha_2,\alpha_3$ 到 $\beta_1,\beta_2,\beta_3$ 的过渡矩矩阵

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 2 & 1 \\ 1 & -2 & 1 \\ 0 & 1 & -1 \end{pmatrix}$$

③
$$\gamma = 2\eta_1 - 2\eta_2 - 3\eta_3 \Rightarrow \gamma$$
在基 $\eta_1$ ,  $\eta_2$ ,  $\eta_3$ 的坐示 $(2, -2, -3)^T$ 

又因为从
$$\eta_1$$
,  $\eta_2$ ,  $\eta_3$ 到 $\alpha_1$ , $\alpha_2$ , $\alpha_3$ 的过渡矩阵是 $\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix}$   $\Rightarrow$ 

令 $\gamma$ 在 $\alpha_1,\alpha_2,\alpha_3$ 的坐标是 $(x_1,x_2,x_3)^{T}$ 故有

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 2 \\ -2 \\ -3 \end{pmatrix} = \begin{pmatrix} 6 \\ -3 \\ -1 \end{pmatrix}$$