Learning Sparse Networks Using Targeted Dropout

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What we'll see



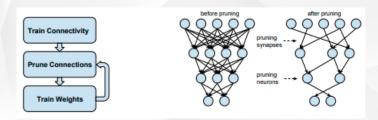
- 1 Neural Network Pruning
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Neural Network Pruning

Procedure of removing neurons or sub-networks with the goal of reducing the computational resources such as:

- memory complexity size of the final network
- time complexity inference time



Identifying Important Subnetworks



The result of targeted dropout is a reduction in the important subnetwork's dependency on the unimportant subnetwork, i.e Better performance after pruning.

Evaluation:

Observe the Taylor expansion of error after removing subnetwork d:

$$\Delta \epsilon = |\epsilon(\theta - d) - \epsilon(\theta)|$$

$$\Delta \epsilon = |-\nabla_{\theta} \epsilon^{T} d + \frac{1}{2} d^{T} H d + \Theta(||d||^{3})|$$

- Θ Parameters of the network
- d Deleted sub-network
- H Hessian matrix

Identifying Important Subnetworks



$$\Delta \epsilon = |-\nabla_{\theta} \epsilon^{\mathsf{T}} d + \frac{1}{2} d^{\mathsf{T}} H d + \Theta(||d||^{3})|$$

Focus only on the middle term $\frac{1}{2}d^THd$ since first term vanishes Still a problem, H is intractable.

Solutions:

- Weight independence
 Sparse H with diagonal approximation known as Optimal Brain Damage
- First order approx.

 Not really vanishes:

 Expectation yes, Variance informative $E[|\nabla_{\theta}\epsilon * d^{T}|]$
- Zero order approx.
 In practice works pretty well.

Magnitude-based pruning



Treat the top-k largest magnitude weights as important.

Notation:

$$heta\in\Theta$$
 — Vector of NN parameters
$$| heta|- ext{Number of parameters}$$
 $W\in\Omega_{ heta}$ — Weights connect one layer to another $w_0\equiv W_{ heta}$

Unit Pruning:

$$W(\theta) = \left\{ \underset{W_0}{\operatorname{argmax-k}} \|W_0\|_2 \, \middle| \, 1 \leq o \leq N_{\operatorname{col}}(W), \, W \in \Omega_\theta \right\}$$

Weight Pruning:

$$W(\theta) = \left\{ \underset{W_{io}}{\mathsf{argmax-k}} \, \|W_{io}\|_2 \, \middle| \quad 1 \leq o \leq N_{col}(W), \, 1 \leq i \leq N_{row}(W), \, W \in \Omega_\theta \right\}$$



We will consider two Bernoulli Dropout techniques:

• Dropout - Unit Dropout

$$Y = (X \odot M)W$$
, $M \sim Bernoulli(1 - \alpha)$

• DropConnect - Weight Dropout

$$Y = X(W \odot M), \quad M \sim Bernoulli(1 - \alpha)$$

Targeted Dropout



We hope to find optimal parameters Θ such that our loss $E(W(\Theta))$ is low, and at the same time $|W(\Theta)| <= k$.

A deterministic pruning selects the bottom $|\Theta|k$ elements and drop them out.

Add stochasticity into the process:

- Targeting proportion γ
- Drop probability α

Algorithm 1 Targeted Dropout - Training

- 1: repeat
- 2: Train for X epochs
- 3: Pick the γ $|\Theta|$ units/weights with lowest magnitude
- 4: Apply Dropout with probability α on them.
- 5: until Convergence

$$E(Units\ To\ Keep) = (1 - \gamma\alpha)|\Theta|$$

Known Pruning Techniques



We will cover the following techniques:

- L¹ Regularization
- L⁰ Regularization
- Smallify
- Variational Dropout

These will be later used and compared to the suggested Targeted Dropout

L¹ Regularization



Using L¹ Regularization term in order to achieve sparsity in the weights.

 L^1 Regularization drives and force more weights to be close to zero in magnitude. Usually important against overfitting and being robust. Here, used as a **sparsity and pruning** mechanism.

$$R(\theta) = \frac{1}{N} \left(\sum_{i=1}^{N} L(h(x_i; \theta), y_i) \right) + \beta ||\theta||_1$$

In the Experminent the notation is L^1_β with β being the cost-balancing coefficient.

L⁰ Regularization



 L^0 Regularization encourage weights to become exactly zero. Use it as a regularization term in the objective function.

$$R(\theta) = \frac{1}{N} \left(\sum_{i=1}^{N} L(h(x_i; \theta), y_i) \right) + \lambda ||\theta||_0, \quad ||\theta||_0 = \sum_{j=1}^{|\theta|} \mathbb{1}[\theta_j \neq 0]$$

Important to observe that it's non-differential. In practice:

- Stochastic Gating Mechanism reparameterization trick
- Approximate the expected L⁰ regularized objective with smooth differential distribution

Smallify



Combining the training and pruning in the same step, in order for the neuron to learn and adjust to the new architecture such that there is no need for post-training step.

The paper present a SwitchLayer which turns on/off neuron of the fly:

$$S_{\beta}(L(x))_{i,...} = \beta_i L(x)_{i,...} \forall i \in [1...c]$$

Algorithm 2 Smallify - Training

- 1: **for** i = 1 to N **do**
- Train with SwitchLayer
- 3: Remove off neurons by some criteria
- 4: end for

Loss:

$$L_{SN}(x, y; \theta, \beta) = L(x, y; \beta) + \lambda ||\beta||_1 + \lambda_2 ||\theta||_p^p$$

Variational Dropout



Apply Gaussian dropout with trainable drop rates to the weights of the network and interprets the model as a variational posterior with a particular prior.

The authors note that the variational lower bound used in training favors higher drop probabilities and experimentally confirm that networks trained in this way do indeed sparsify.

Experiments and Results

Experiments



The following architectures covered in order to check the effect of Targeted Dropout method:

- · ResNet with CIFAR-10 and ImageNet
- · Wide ResNet -With CIFAR-10 and ImageNet
- Transformer with WMT English-German Translation

Analysing the Important Subnetwork



Toy example - single dense hidden layer with ten units and ReLUs, on CIFAR-10.

- · Left Unregularised
- Right Targeted dropout, with $\gamma = 75\%$ and $\alpha = 50\%$.

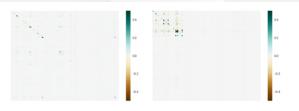


Figure 1: A comparison between a network without dropout (left) and with targeted dropout (right) of the matrix formed by $\theta^{\top} \odot \mathbf{H} \odot \theta$. The weights are ordered such that the last 75% are the weights with the lowest magnitude (those we intend to prune). The sum of the elements of the lower right hand corner approximates the change in error after pruning (Eqn. (3)). Note the stark difference between the two networks, with targeted dropout concentrating its dependence on the top left corner, leading to a much smaller error change after pruning (given in Table 1).

REGULARISATION	$ \Delta \mathcal{E} $	UNPRUNED ACCURACY	PRUNED ACCURACY
None	0.120698	38.11%	26.13%
TARGETED DROPOUT	0.0145907	40.09%	40.14%

Table 1: Comparison of the change in loss ($|\Delta \mathcal{E}|$ of Equation (3)) for dense networks.

ResNet



ResNet-32 on CIFAR-10

Weight Dropout/Pruning

		none	dropout α =0.25	targeted $\alpha=0.5, \gamma=0.5$	targeted α =0.33, γ =0.75	targeted α =0.66, γ =0.75	targeted α =0.75, γ =0.90
e	0 %	93.71	93.62	93.03	89.88	92.64	92.53
percentag	10%	93.72	93.63	93.04	89.80	92.62	92.55
Ħ	20%	93.77	93.66	93.02	89.93	92.63	92.48
3	30%	93.59	93.58	92.98	89.89	92.66	92.53
e.	40%	93.09	93.45	93.03	89.75	92.70	92.63
	50%	92.20	93.07	92.99	89.72	92.65	92.54
prune	60%	90.46	90.81	92.66	89.84	92.70	92.55
ь	70%	81.88	72.29	92.22	89.80	92.66	92.56
	80%	32.02	19.84	84.03	85.80	91.86	92.54
	90%	14.63	10.05	28.27	27.04	67.58	92.48

variational	$L^1_{0.1}$	$L^0_{0.1}$
92.09	92.80	88.83
92.00	92.72	90.66
92.02	92.84	88.64
92.07	92.63	87.16
92.12	92.80	85.31
91.84	92.29	80.94
91.48	91.20	69.48
90.23	86.30	46.19
83.44	63.00	23.71
15.16	21.08	12.55

Unit Dropout/Pruning

		none	dropout $\alpha=0.25$	targeted $\alpha=0.5, \gamma=0.5$	targeted α =0.33, γ =0.75	targeted α =0.66, γ =0.75	targeted α =0.90, γ =0.75
e	0 %	93.69	92.43	92.21	90.46	89.38	89.78
å	10%	90.05	67.52	91.96	88.44	89.48	90.18
Ħ	20%	80.34	25.05	91.63	83.55	88.89	89.79
3	30%	59.94	13.47	91.30	69.82	88.84	89.88
percentage	40%	35.40	10.02	89.89		87.54	89.98
e	50%	12.63	9.97	88.41	28.88	84.86	90.05
prune	60%	10.65	9.99	26.55	18.55	81.98	90.08
Ed	70%	11.70	10.01	17.41	17.84	75.47	90.03
_	80%	9.99	9.95	10.63	10.87	28.99	34.18
	90%	9.85	9.98	9.30	10.29	9.97	10.04

variational	$L^1_{0.01}$	$L_{0.01}^{0}$
93.14	93.31	93.35
92.91	91.03	83.01
90.38	85.63	54.59
86.38	72.19	21.34
83.59		10.82
65.79	26.72	15.04
	12.11	9.46
19.36	11.81	10.02
9.56	14.73	14.88
10.41	10.22	9.98



Unit Dropout/Pruning

		none	targeted α =0.33, γ =0.75	$L^0_{10^{-6}}$
	0 %	92.21	92.24	94.15
ge	10%	89.76	92.09	88.05
ıţa	20%	82.37	91.55	
Sel	30%	52.20	90.09	13.34
prune percentage	40%	18.48	87.47	10.01
	50%	10.53	82.09	10.00
	60%	10.04	69.58	10.00
	70%	10.00		10.00
	80%	10.00	16.94	10.00
	90%	10.00	10.43	10.00

Table 4: Wide ResNet [43] model classification accuracy on CIFAR-10 test set at differing prune percentages.

Transformer



Robustness of **Targeted Dropout** to various of architectures, for example - Transformer.

Weight Dropout/Pruning

		none	targeted α =0.66, γ =0.75	targeted α =0.66, γ =0.90
	0 %	26.01	26.52	25.32
prune percentage	10%	26.05	26.44	25.32
nta	20%	25.90	26.48	25.19
S	30%	25.91	26.30	25.27
er.	40%	25.81	26.20	24.97
e 1	50%	25.08	26.03	24.93
3	60%	23.31	25.62	24.27
Id	70%	8.89	24.07	22.41
	80%	0.24	12.39	10.57
	90%	0.01	0.07	0.64

⁽a) Transformer model uncased BLEU score.

Weight Dropout/Pruning

		_	-	_
		none	targeted α =0.66, γ =0.75	targeted α =0.66, γ =0.90
	0 %	62.29	58.31	
g	10%	62.54		58.10
	20%	62.21	59.39	58.52
percentag	30%	62.33	58.66	57.86
5	40%	61.81	59.39	58.67
	50%			
orune	60%	58.13	58.42	
ā	70%		55.39	54.85
	80%	25.80		
	90%	6.90	21.64	27.02

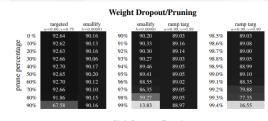
⁽b) Transformer model per-token accuracy.

Table 5: Evaluation of the Transformer Network under varying sparsity rates on the WMT new-stest2014 EN-DE test set.

Scheduling the Targeting Proportion



Ramping targeted dropout - Anneals the targeting rate γ from zero to specific γ through the course of training.



Unit Dropout/Pruning

		targeted α =0.66, γ =0.75	smallify $\lambda = 0.0001$	ramp targ α =0.99, γ =0.90
	0 %	90.55	90.20	85.98
g	10%	90.83	90.33	86.12
ğ	20%	89.88	90.30	86.01
ë	30%	87.35	90.27	86.10
ĕ	40%	85.39	89.46	85.98
prune percentage	50%	80.84	89.41	86.13
	60%		88.55	86.02
ď	70%		86.35	86.08
	80%	10.02		85.95
	90%	10.07	13.83	85.99

Table 6: Comparing Smallify to targeted dropout and ramping targeted dropout. Experiments on CIFAR10 using ResNet32.

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