

Assignment 1b

Alex Cochrane

February 21, 2014

1 ABSTRACT

The problem for this project was to create a Genetic Algorithm(GA) for a set of benchmark optimization problems. My GA works as it is expected to but my populations rarely start with a good enough individual to ever get to a global minimum using hill-climbing. Introducing crossover had little affect at increasing the effectiveness of the GA. The results of the runs through the GA however show that conformation to the best solution is done in each case. In other words, the population might not move towards a global minimum but it does move towards the best individual and their local minimum. While the global minimum may not have always been found. The last generation is always conformed to the local minimum that the best solution has gotten stuck in.

2 ALGORITHM DESCRIPTION

The algorithms used to create the GA revolve around tournament selection for a generational type. Below is some pseudo code for what will be explained next. To begin the GA that I built uses generational tournament selection. The pseudo code demonstrates that generations were built that then were used to replace the current population after crossover/mutation/etc. The fitness was measured during and after each generation was selected. The speed decrease was worth the assurance that the fitness values were always correct. After a new generation was created, crossover and mutation were preformed and the new generation replaced the population currently being stored.

For crossover, there was a 50% chance that I would swap a value in the vector of two side by side individuals in the new generation. Because elitism was not used and the new generation was not sorted yet, good and bad values could be swapped and better or worse solutions are almost guaranteed unless the same vector is being swapped.

For mutation, there was a 25% chance that I would subtract 0.01 from the value in the vector and a 25% chance that I would add 0.01 to the value in the vector. There were also no restrictions on only accepting better solutions. If it wanted to accept worse values for the vectors it was more than capable of doing so.

The fitness of each function is calculated on the benchmark functions provided for each one. It can be done solely for each individual for testing purposes if updated vector values have changed fitness and the value is needed now. The more common calculations for fitness were done for the whole population at once. After which, the population was then sorted by their fitness from minimum to maximum. This made print outs nicer and allowed me to "seed" my tournament selection to some degree, using some simple math to get values closer to 0 then 100.

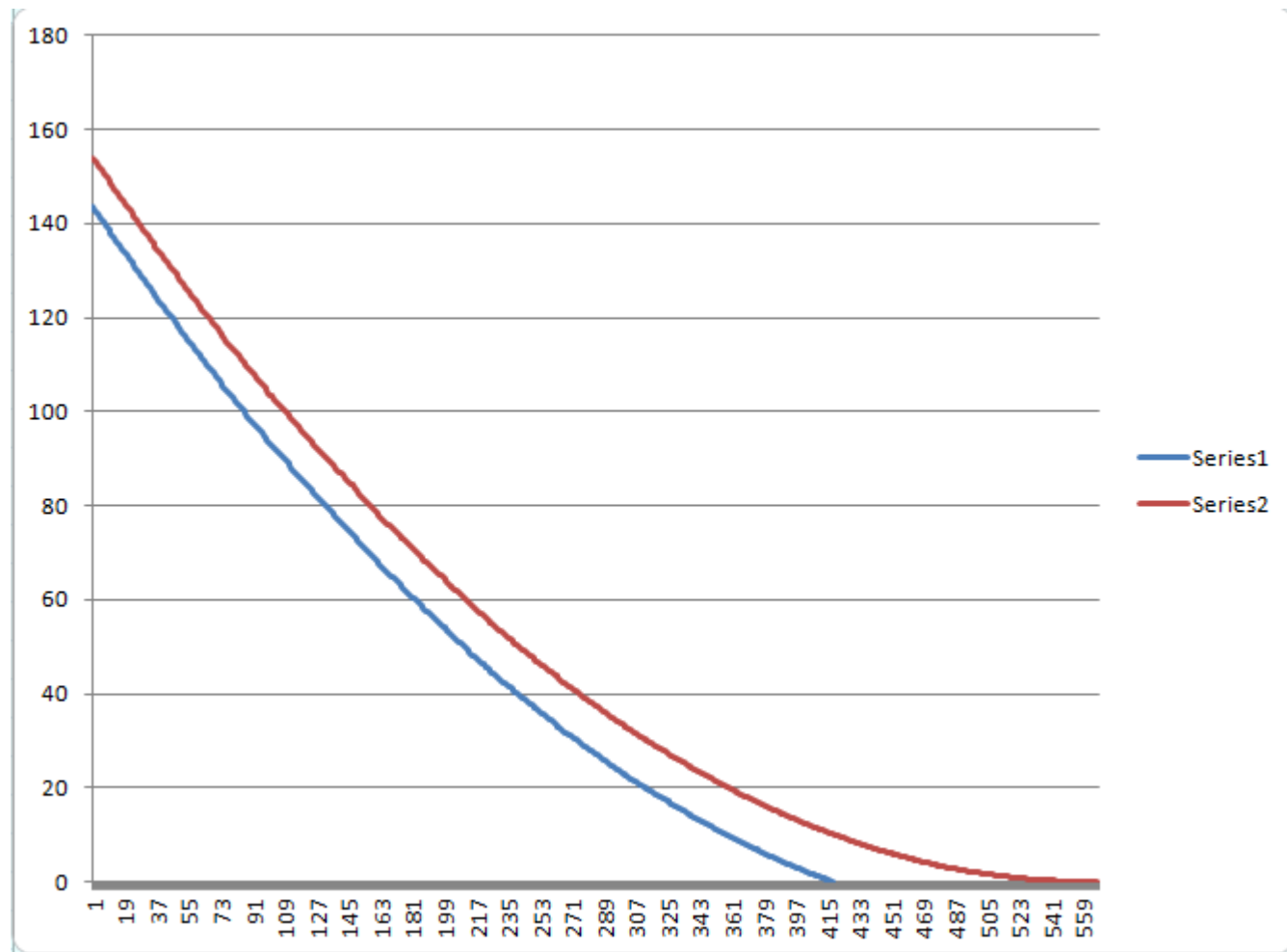
Some other information that is useful in recreating this GA is that populations consisted of 1000 individuals. They were filled with random values for their vectors. Runs consisted of 1000 generations or enough generations to get within a thousandth of 0.

PSEUDO CODE

```
while ( Individual[]->fitness > 0.01 ) //larger then the smallest value measured
    if( repeated fitness 100 times || 1000 generations have been created)
        break
    while( next Population is not filled )
        create a new individual to put in the population
        randomly select an individual from the current population N = 5 times
        select the one with the best fitness and make the new individual it
    crossover
    mutate
    calculate the new fitness / sort
```

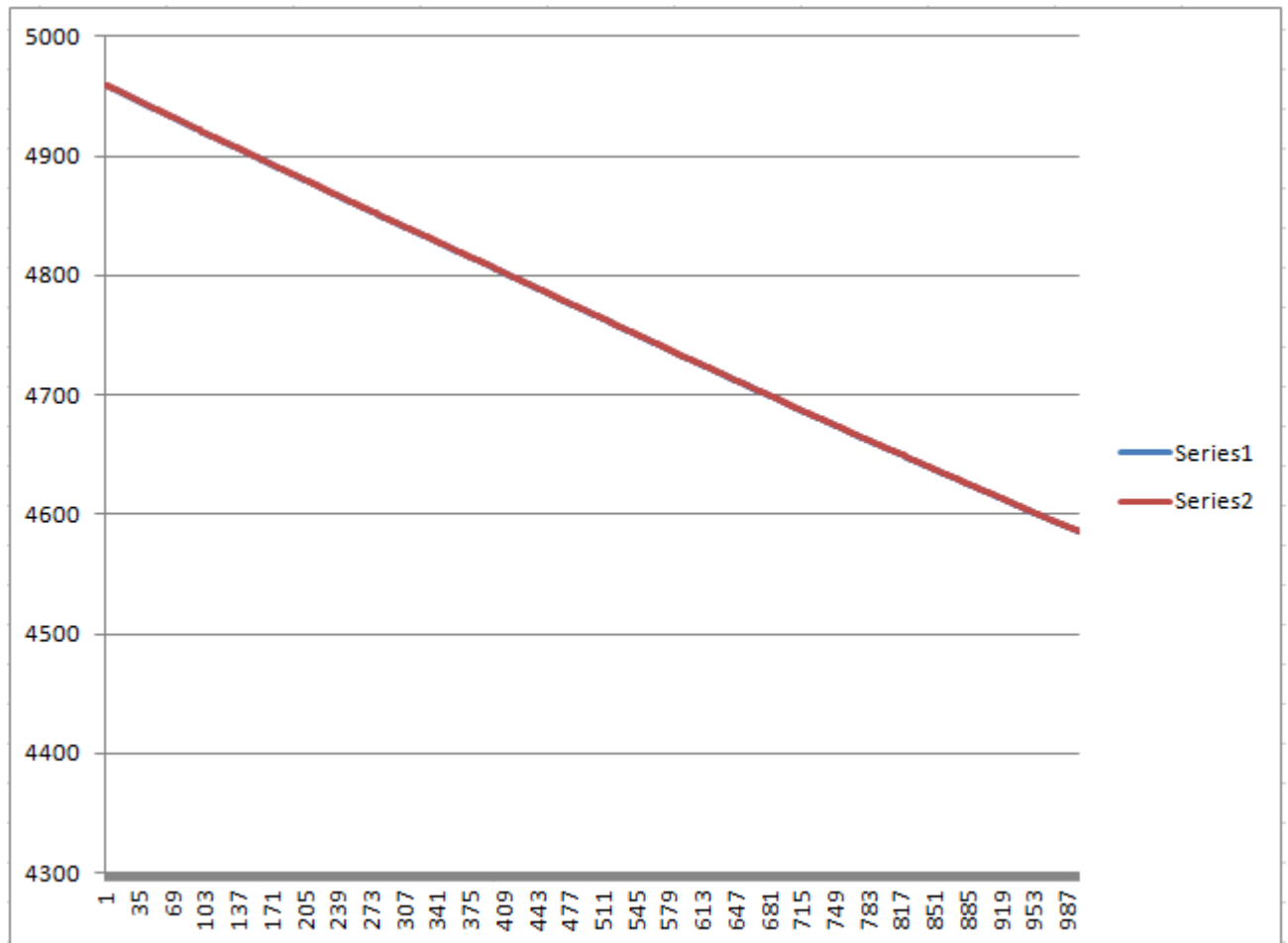
When the process is over it prints the best solutions fitness which should be below 0.01 unless it got stuck with a bad population that could not get to zero. It also prints how many times it iterated just to get a feel of how changes made the process more efficient or not. For most well situated solutions $\tilde{0}$ is found much sooner then the max 1000 generations.

3 RESULTS



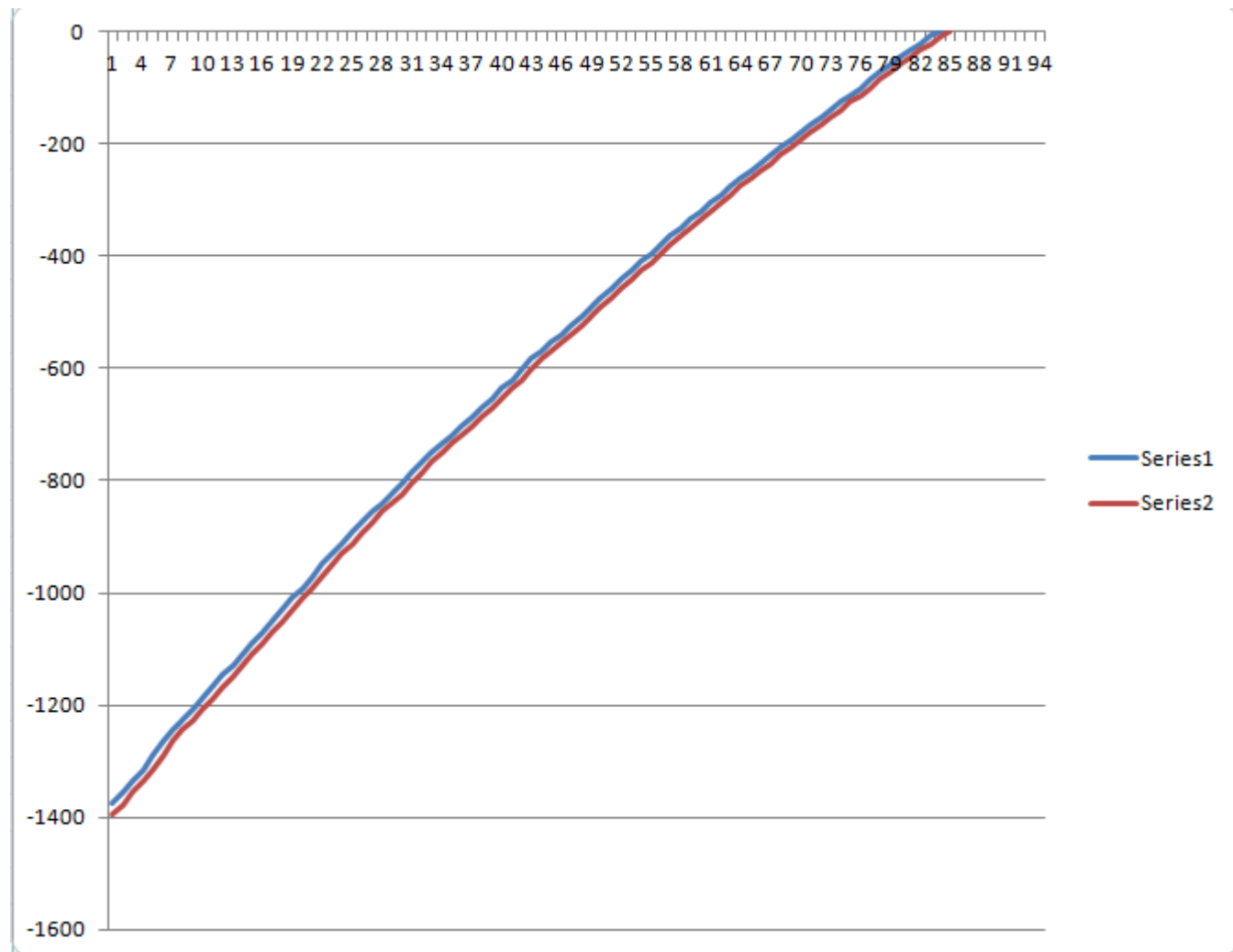
Sphere Graph

The following set of graphs will feature two lines, one showing best individual fitness and then an average individual fitness over the total duration of the run. The first graph is of the sphere function. The red line here represents the average fitness for the population. The blue line is representing that of the best individual. In this instance, a very good solution was in the initial population but during tournament selection, it was not chosen with great bias and therefore the population was slow to converge on it.



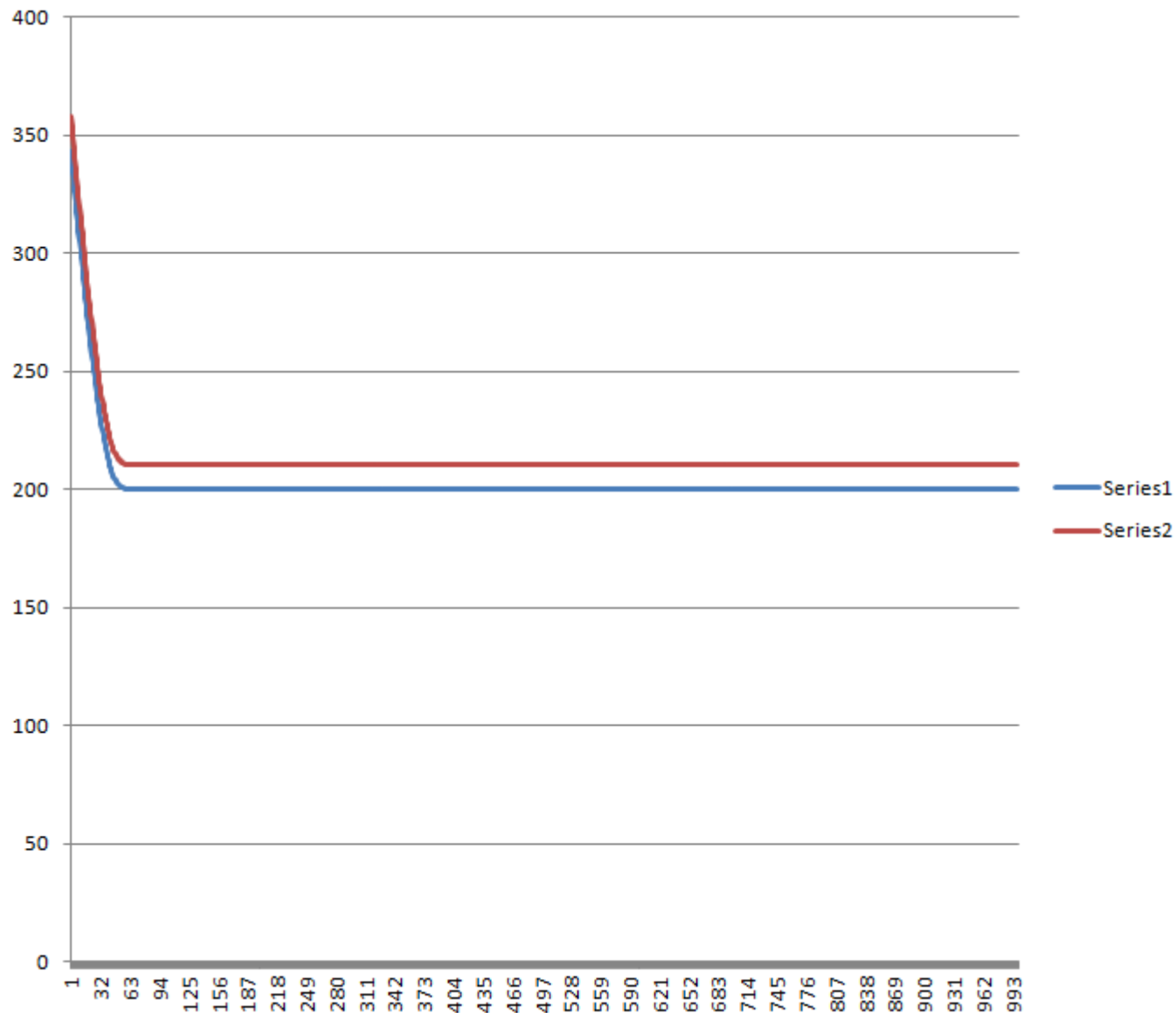
Schwefel Graph

This graph is for the Schwefel function. The red line represents the average, the blue line would represent the best case but because this graph is standardized the line is really hard to see. The graph itself has the correct slope that you would expect with a steep initial reading and then steadying off into a gradual decent. The initial slope however is small and as this graph shows very well, the population becomes more and more centralized to the best individual as it hill climbs down into a valley.



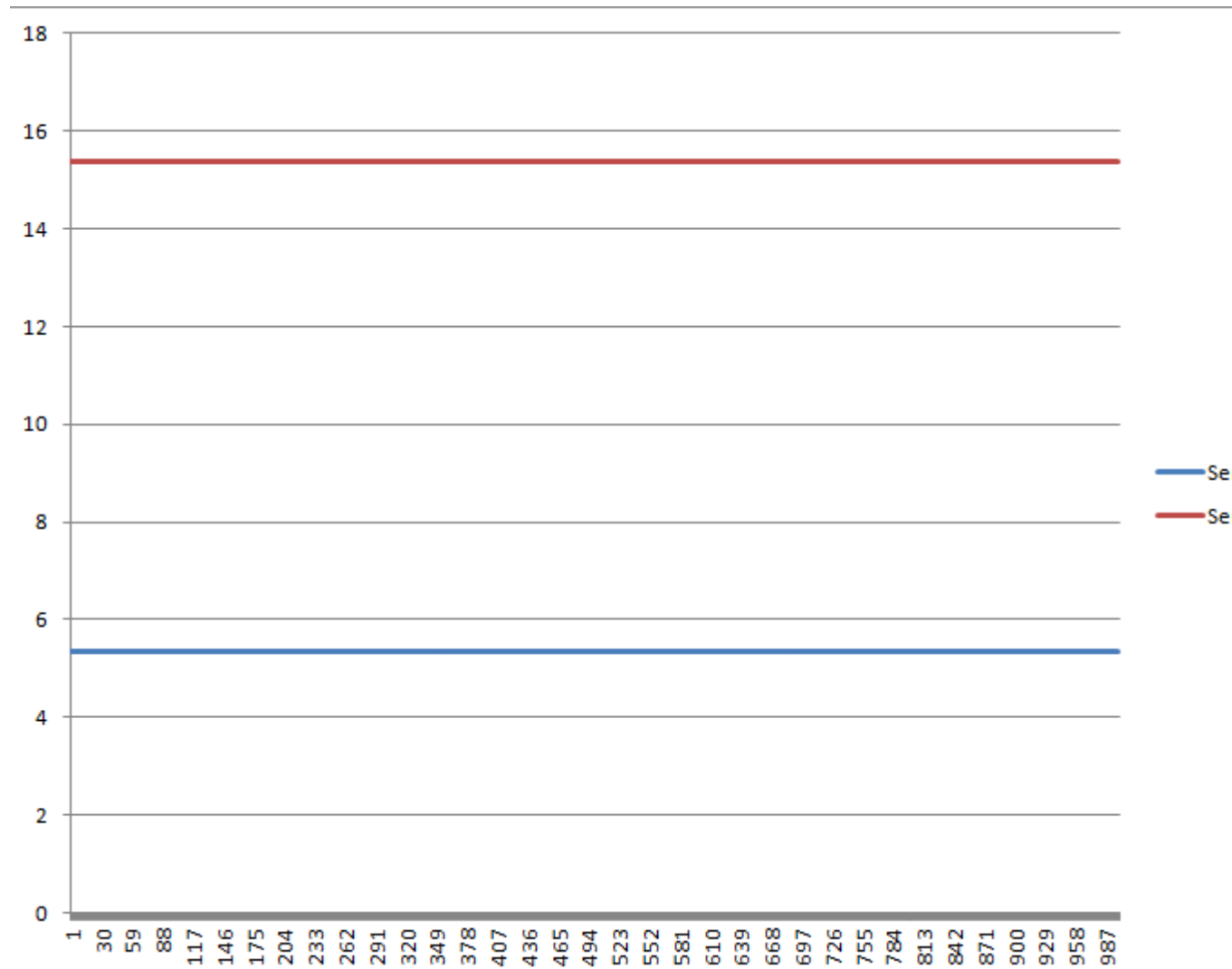
Rosenbrock Graph

With the Rosenbrock graph, the blue line shows the best individual while the red line shows the average. Rosenbrock has the fitness function that produces negative values. This was handled in code by taking the absolute value but I thought the real graph would look unique. For this graph a lot of movement can be seen by the slope of the lines. While it is not clear in the graph, the values themselves make a drastic jump from bad values to conform quickly to the best individual.



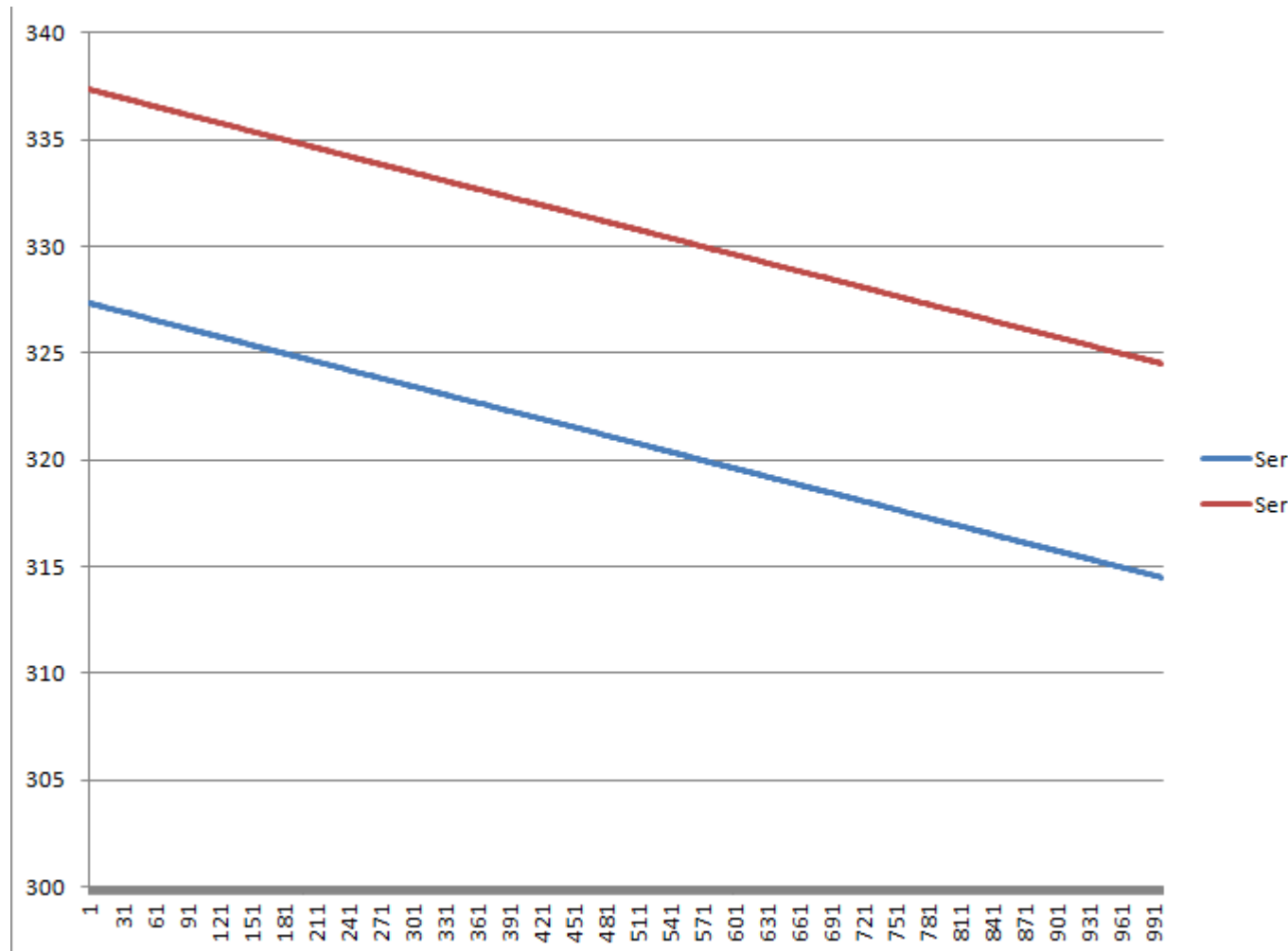
Rastrigin Graph

Finally with the Rastrigin graph the drastic curve can be seen. The blue line representing the best individual moves quickly into a hole that it cannot leave while at almost the same speed the entire population, represented by the red line, moves towards a stagnant state as well. This steep initial movement is present in all the graphs but it is masked by the linear nature of the graphs and their axes morphing.



Ackley Graph

The Ackley graph is interesting in the since that the individuals fitness values are not changing. This is because drastic changes in vector values are needed to get to the function to produce different values for fitness. Therefore the fitness gets stuck in the hole that it falls into at the start. The exponential nature of the fitness function creates this uniqueness.



Griewangk Graph

For this graph it is easy to see that the fitness is slowly moving towards the minimum. The average fitness stays at an almost constant distance away from the best fitness. The population has varying fitnesses but the average seems to stay very linear. With more time or a larger interval the same hole is found.

Some things to note are that the Ackley graph and the Griewangk graph are labelled in a misleading way. The labels for fitness should be in thousandths but for some reason the leading zeros and decimal were neglected when presenting in \LaTeX . Hopefully this will not hinder the usage of the graphs as it occurred to me too late for a quick fix. The desired look would be that similar to Rosenbrock or Schwefel.

4 CONCLUSION

The Genetic Algorithm seems to be working well in the since that it is taking good individuals and mutating them along with crossover to get a better next generation. The problem with this solution however is that a great individual is not present in the population at the start. Without this individual that is almost at the minimum at the start, it is very unlikely to actually find the global minimum.

Some improvements that could have been done were to add an individual to the population that was not random but was in fact very close to the actual minimums vector/fitness. This would guarantee that I had an individual that would be able to move to the minimum. This does take away from the whole purpose of the GA but as stated before, it guarantees a solution is found.

While it would be interesting to get these problems to all work correctly, the run time for them with 1000 individuals in the population takes quite some time. Each fix could take up to 5 minutes to run that fix to see if an improvement was made. Therefore I would like to rewrite the way I do sorting a bit but as just an exercise I have learned quite a bit about GA's and how they operate. The most interesting bit was the affect or the mutation ratio as well as the likely hood for crossover to occur. Changing these values had the greatest affect on the shape as the graph as well. The lower the mutation value was the more linear the graph looked which is why most of these graphs are linear. The values took a steep initial two or three steps and then hill climbed as a group to a minima.

Crossover had this same affect. The more likely two individuals were to crossover, the slower it took to hill climb. This is because good individuals are not always taken. Especially without elitism in the GA, it was difficult to assume that the best individual always stayed. Nonetheless it worked out to were the algorithms were working well together to at least find minima and with more tweaking of values and intervals it is plausible to think that the global minimum would eventually be found.
