

#### COMPUTER ORGANIZATION AND DE

The Hardware/Software Interface



# **Chapter 2**

**Part 5: Synchronization** 

# Multiple Programs on Single CPU

- ☐ Problem: resource sharing
- □ Examples
  - Updating 64-bit global variable in 32-bit machine
  - Updating global data structure
    - Linked list of free buffers and associated count
  - Printer sharing
  - Reserving airline tickets
- □ Problem: operations not atomic ("all or nothing")
- ☐ Issue of data corruption
- □ Solution: exclusive access until operation is complete
  - Mutual exclusion, MUTEX

## Mutual Exclusion (Mutex)

- Mutex
  - Simple form of synchronization
- □ Same synchronization problem can occur on (shared memory) multiprocessor systems

#### Mutual Exclusion (Mutex)

- ☐ Only one program running on CPU
  - Problem can occur with interrupts
- □ Disable interrupt for MUTEX

```
Disable interrupt;
Access shared resource (critical section);
```

- Disabling interrupt is a general solution for Mutex
  - Process switch on timer interrupts

Enable interrupt;

 Not a good solution because all unrelated programs are also affected

## Implementing Mutex

☐ Minimize the impact of Interrupt Disable

```
Disable interrupt;
if('Access Variable' is 0) {
      Set variable to 1;
      Re-enable interrupts;
      Access the resource (critical section);
      Disable interrupts;
      Set the 'Access Variable' back to 0;
      Re-enable interrupts;
} else {
      Re-enable interrupts;
      /* Try back later; */
```

## Implementing Mutex

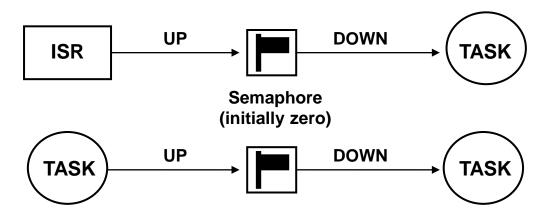
- □ Better: provide an CPU instruction for synchronization
  - Why is a machine instruction atomic?
- ☐ Mutual exclusion with test-and-set

# (Binary) Semaphore: Higher Level

- □ Dijkstra: what if TAS return failure, how to busy-wait?
  - Associate semaphore for shared resource
- □ INIT: sem\_printer = 1 (i.e., printer is free)
- □ DOWN (or wait)
  - If available, sem\_printer=0 and give exclusive access
    - Entire operation must be atomic (cf. test-and-set)
  - If unavailable, put task in waiting list
- ☐ UP (or signal)
  - If no waiting, sem\_printer = 1
  - · If no, waiting, give exclusive access to waiting task

#### Inter-Task Communications

- □ Semaphore (binary and counting)
  - Mutex plus additional data structures and service
- Barrier synchronization
- Producer and consumer: synchronization with semaphore



- Synchronization plus information exchange
  - Place to hold a pointer

# Data Exchange Models (IPC)

- □ Signal
  - Asynchronous interrupt via OS
- ☐ Pipe
  - Byte stream, via a file
- ☐ Message queue
  - Notion of message
- ☐ Shared memory
  - Just share physical memory block



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#### **Section 2.10**

# Parallelism and Instructions: Synchronization

## **Synchronization**

- Two processors sharing an area of memory
  - P1 writes, then P2 reads
  - Data race if P1 and P2 don't synchronize
    - Result depends of order of accesses
- Hardware support required
  - Atomic read/write memory operation
  - No other access to the location allowed between the read and write

# **Synchronization**

- System programmers build user-level library routines (synchronization library, lock and unlock)
  - Architect supply synchronization instructions
    - A number of alternative formulations
    - Atomically read and modify a memory location
- Hardware primitive can be a single instruction
  - Challenge to put both memory read and write in a single uninterruptable instruction
- An alternative is to use a pair of instructions

## Synchronization in MIPS

- Load linked: 11 rt, offset(rs)
- Store conditional: sc rt, offset(rs)
  - Succeeds if location not changed since the 11
    - Returns 1 in rt
  - Fails if location is changed
    - Returns 0 in rt
- Example: atomic swap (to test/set lock variable)

```
try: addi $t0,$zero,1 ;copy locked value
ll $t1,0($s1) ;load linked
sc $t0,0($s1) ;store conditional
beq $t0,$zero,try ;branch store fails
add $s4,$zero,$t1 ;put load value in $s4
```

#### **Concurrent Programming Example**

