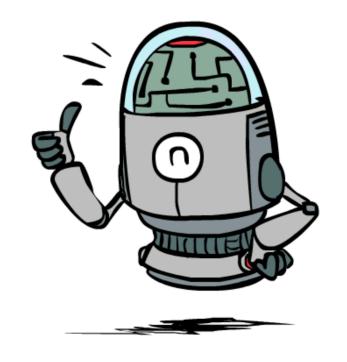
CS 5522: Artificial Intelligence II

Final Review



Instructor: Wei Xu

Ohio State University

[Cartoons were adapted from CS188 Intro to AI at UC Berkeley.]

Final Exam

The final exam will be closed notes, books, laptops, and people.
 (You will be given an instructor-provided "cheat sheet")

■ 105 minutes. 12/12 Wednesday 12:00-1:45pm. This room.

• Preparation:

- Lecture Slides
- Written Homework
- Example Exam
- Project 3: Ghostbusters

Final Exam

 Make sure you understand the fundamentals in addition to being able to procedurally execute algorithms.

The exam will not test your knowledge of Python, however questions may assume familiarity with the projects and test ability of writing pseudocode.

See written homework and example exam for examples

Possible Final Exam Topics

Markov Models and HMMs:

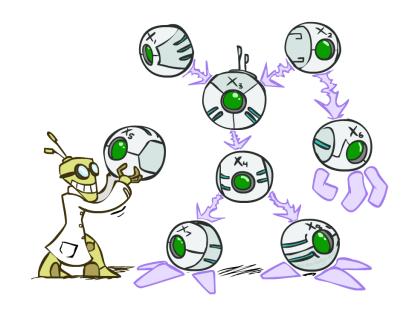
- Markov Model and HMM definition
- Observation and Time Elapse
- Exact Inference
- Approximate Inference
- Particle Filtering
- Most Likely Explanation

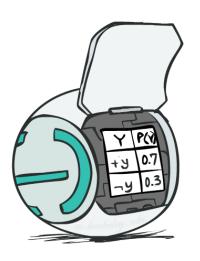
Bayes Nets:

- Probabilistic Representations
- D-Seperation
- Inference
- Variable Elimination

Naive Bayes:

- Classification
- Parameter Estimation
- Prediction





Possible Final Exam Topics

Will not cover the follows:

- Search
- Reinforcement Learning
- Neural Networks
- Speech Recognition
- Computer Vision
- Natural Language Processing

Office Hours

- Office Hour Wednesday, 12/5 4-5pm (DL 495)
- Office Hour Friday, 12/7 4-5pm (DL 495)

Will also answer questions on Piazza

Instructor provided "cheat sheet"

Inference: Base Cases













$$P(x_1|e_1) = P(x_1, e_1)/P(e_1)$$

$$\propto_{X_1} P(x_1, e_1)$$

$$= P(x_1)P(e_1|x_1)$$



$$P(X_2)$$

$$P(x_2) = \sum_{x_1} P(x_1, x_2)$$

= $\sum_{x_1} P(x_1) P(x_2|x_1)$

Passage of Time

Assume we have current belief P(X | evidence to date)

$$B(X_t) = P(X_t | e_{1:t})$$

• Then, after one time step passes:

$$\begin{split} P(X_{t+1}|e_{1:t}) &= \sum_{x_t} P(X_{t+1}, x_t|e_{1:t}) \\ &= \sum_{x_t} P(X_{t+1}|x_t, e_{1:t}) P(x_t|e_{1:t}) \\ &= \sum_{x_t} P(X_{t+1}|x_t) P(x_t|e_{1:t}) \end{split}$$

$$B'(X_{t+1}) = \sum_{x_t} P(X'|x_t) B(x_t)$$

- Basic idea: beliefs get "pushed" through the transitions
- With the "B" notation, we have to be careful about what time step t the belief is about, and

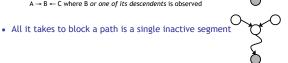
The Forward Algorithm

Active / Inactive Paths

- Question: Are X and Y conditionally independent given Active Triples evidence variables {Z}?
 - Yes, if X and Y "d-separated" by Z
- · Consider all (undirected) paths from X to Y



- Causal chain A → B → C where B is unobserved (either direction)
- Common cause A ← B → C where B is unobserved
- Common effect (aka v-structure)
 - A → B ← C where B or one of its descendents is observed





Inactive Triples



Observation

Assume we have current belief P(X | previous evidence):

$$B'(X_{t+1}) = P(X_{t+1}|e_{1:t})$$

Then, after evidence comes in:

$$\begin{split} P(X_{t+1}|e_{1:t+1}) &= P(X_{t+1},e_{t+1}|e_{1:t})/P(e_{t+1}|e_{1:t}) \\ &\propto_{X_{t+1}} P(X_{t+1},e_{t+1}|e_{1:t}) \\ &= P(e_{t+1}|e_{1:t},X_{t+1})P(X_{t+1}|e_{1:t}) \\ &= P(e_{t+1}|X_{t+1})P(X_{t+1}|e_{1:t}) & \text{Basic idea: beliefs} \end{split}$$

Or, compactly:

 $B(X_{t+1}) \propto_{X_{t+1}} P(e_{t+1}|X_{t+1})B'(X_{t+1})$



"reweighted" by likelihood of

Unlike passage of time, we

have to renormalize

- We are given evidence at each time and want to know
 - $B_t(X) = P(X_t|e_{1:t})$

We can normalize as we go if we want to have
$$P(x_t|e_{1:t}) \propto_X P(x_t,e_{1:t})$$

$$= \sum_{x_{t-1}} P(x_{t-1},x_t,e_{1:t})$$

$$= \sum_{x_{t-1}} P(x_{t-1},e_{1:t-1}) P(x_t|x_{t-1}) P(e_t|x_t)$$

$$= P(e_t|x_t) \sum_{x_{t-1}} P(x_t|x_{t-1}) P(x_{t-1},e_{1:t-1})$$

- Forward Algorithm
- D-Seperation