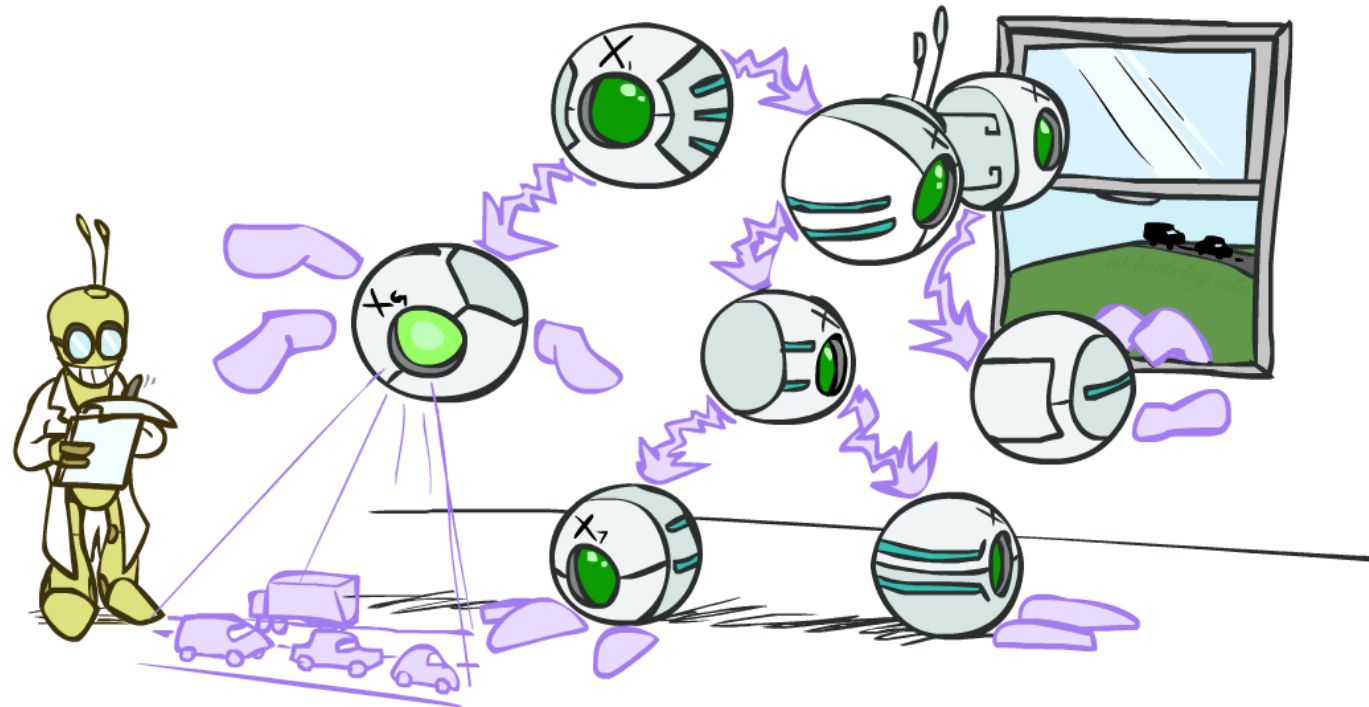


# CS 5522: Artificial Intelligence II

## Bayes' Nets: Inference



Instructor: Wei Xu

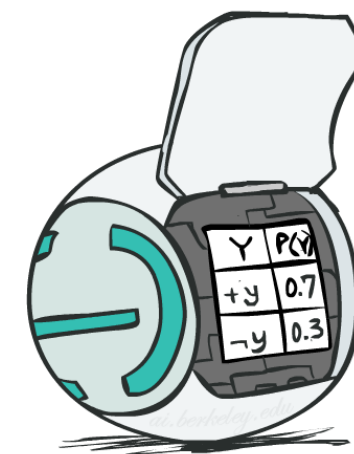
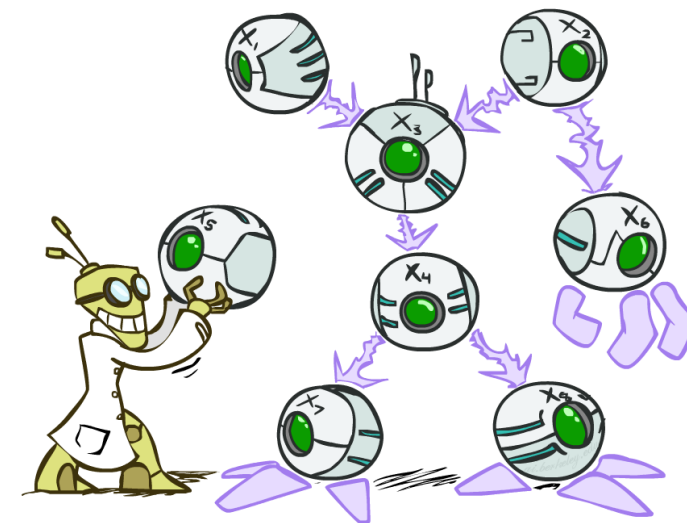
Ohio State University

[These slides were adapted from CS188 Intro to AI at UC Berkeley.]

# Bayes' Net Representation

- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node
  - A collection of distributions over  $X$ , one for each combination of parents' values  $P(X|a_1 \dots a_n)$
- Bayes' nets implicitly encode joint distributions
  - As a product of local conditional distributions
  - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$



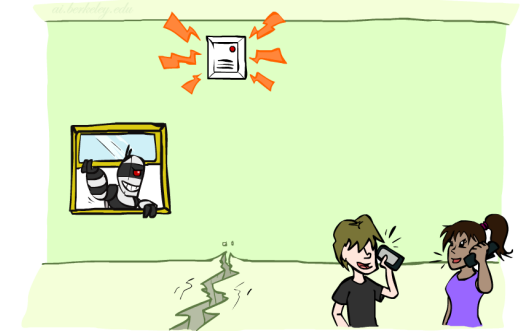
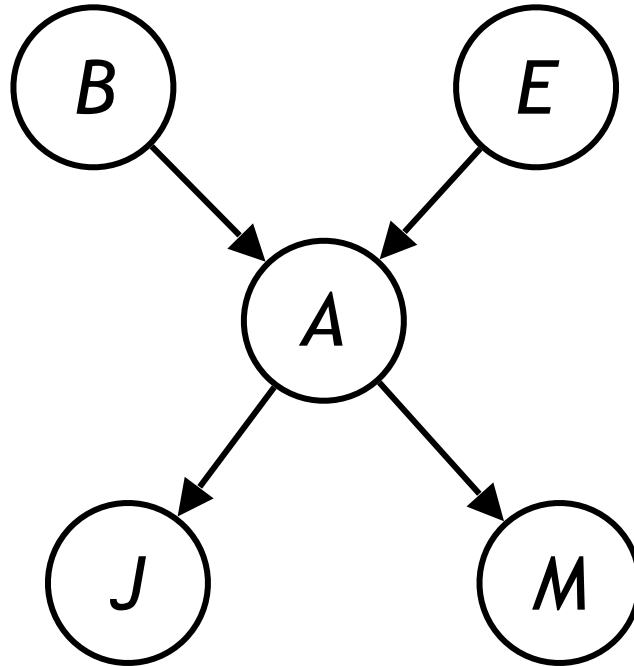
# Example: Alarm Network

B	P(B)
+b	0.001
-b	0.999

E	P(E)
+e	0.002
-e	0.998

A	J	P(J A)
+a	+j	0.9
+a	-j	0.1
-a	+j	0.05
-a	-j	0.95

A	M	P(M A)
+a	+m	0.7
+a	-m	0.3
-a	+m	0.01
-a	-m	0.99



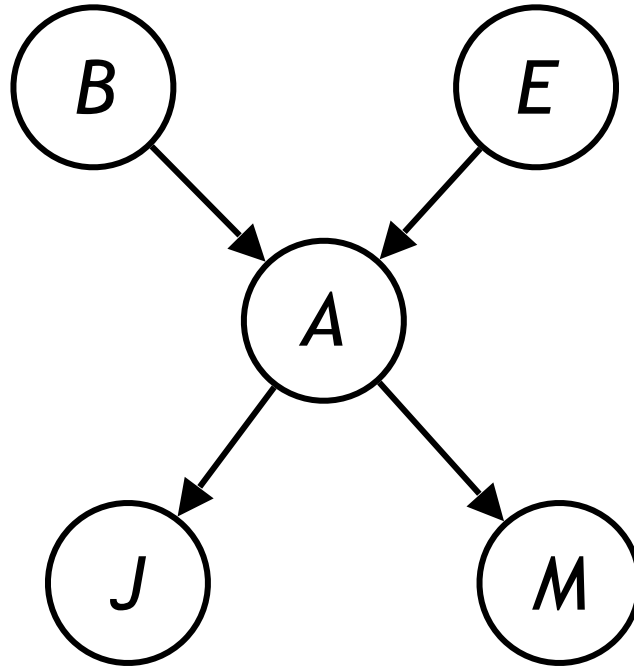
B	E	A	P(A B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-e	+a	0.94
+b	-e	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-e	+a	0.001
-b	-e	-a	0.999

$$P(+b, -e, +a, -j, +m) =$$

$$P(+b)P(-e)P(+a|+b, -e)P(-j|+a)P(+m|+a) =$$

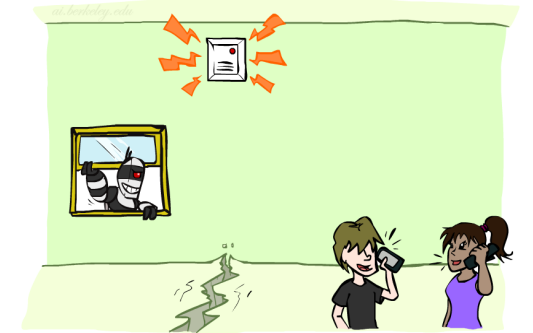
# Example: Alarm Network

B	P(B)
+b	0.001
-b	0.999



E	P(E)
+e	0.002
-e	0.998

A	M	P(M A)
+a	+m	0.7
+a	-m	0.3
-a	+m	0.01
-a	-m	0.99



A	J	P(J A)
+a	+j	0.9
+a	-j	0.1
-a	+j	0.05
-a	-j	0.95

B	E	A	P(A B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-e	+a	0.94
+b	-e	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-e	+a	0.001
-b	-e	-a	0.999

$$\begin{aligned}
 P(+b, -e, +a, -j, +m) &= \\
 P(+b)P(-e)P(+a|+b, -e)P(-j|+a)P(+m|+a) &= \\
 0.001 \times 0.998 \times 0.94 \times 0.1 \times 0.7 &=
 \end{aligned}$$

# Bayes' Nets

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✓ Representation

✓ Conditional Independences

- Probabilistic Inference

- Enumeration (exact, exponential complexity)
- Variable elimination (exact, worst-case exponential complexity, often better)
- Probabilistic inference is NP-complete
- Sampling (approximate)

- Learning Bayes' Nets from Data

# Inference

- Inference: calculating some useful quantity from a joint probability distribution

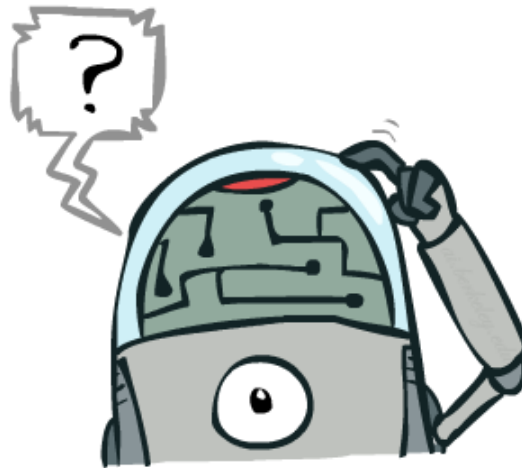
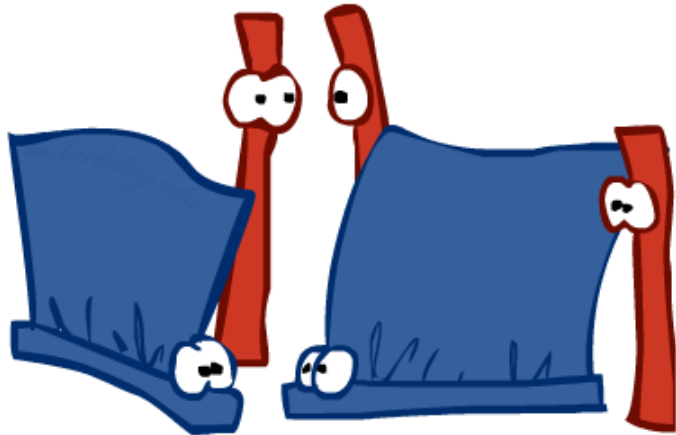
- Examples:

- Posterior probability

$$P(Q|E_1 = e_1, \dots, E_k = e_k)$$

- Most likely explanation:

$$\operatorname{argmax}_q P(Q = q|E_1 = e_1 \dots)$$



# Inference by Enumeration

- General case:


- Evidence variables:  $E_1 \dots E_k = e_1 \dots e_k$
  - Query\* variable:  $Q$
  - Hidden variables:  $H_1 \dots H_r$
- $\left. \begin{array}{l} E_1 \dots E_k = e_1 \dots e_k \\ Q \\ H_1 \dots H_r \end{array} \right\} \begin{array}{l} X_1, X_2, \dots X_n \\ \text{All variables} \end{array}$

- We want:

$$P(Q|e_1 \dots e_k)$$

\* Works fine with multiple query variables, too

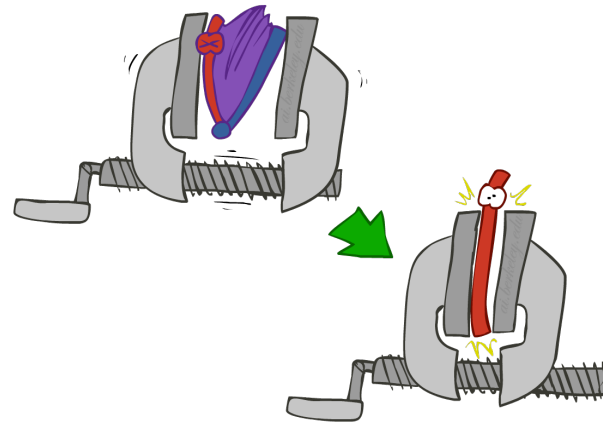
- Step 1: Select the entries consistent with the evidence



x	P(x)
-3	0.05
-1	0.25
0	0.07
1	0.2
5	0.01

2    0.15

- Step 2: Sum out H to get joint of Query and evidence



$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} \underbrace{P(Q, h_1 \dots h_r, e_1 \dots e_k)}_{X_1, X_2, \dots X_n}$$

- Step 3: Normalize

$$\times \frac{1}{Z}$$

$$Z = \sum_q P(Q, e_1 \dots e_k)$$

$$P(Q|e_1 \dots e_k) = \frac{1}{Z} P(Q, e_1 \dots e_k)$$

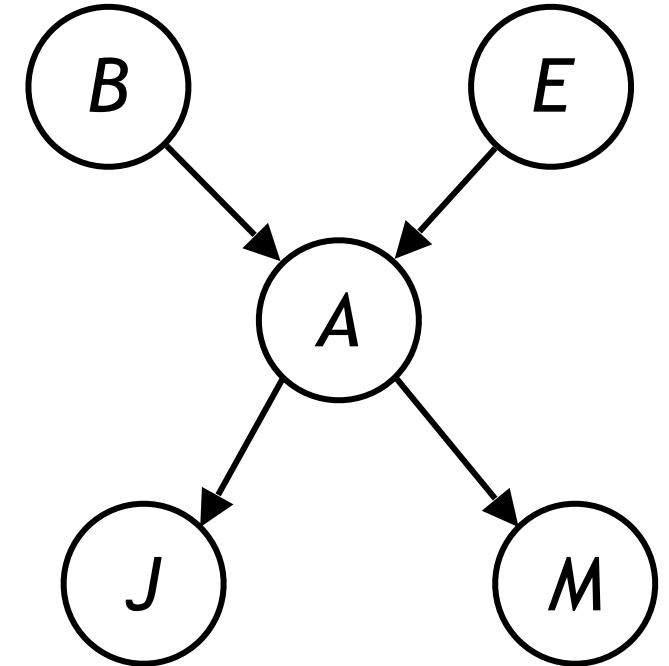
# Inference by Enumeration in Bayes' Net

- Given unlimited time, inference in BNs is easy
- Reminder of inference by enumeration by example:

$$P(B \mid +j, +m) \propto_B P(B, +j, +m)$$

$$= \sum_{e,a} P(B, e, a, +j, +m)$$

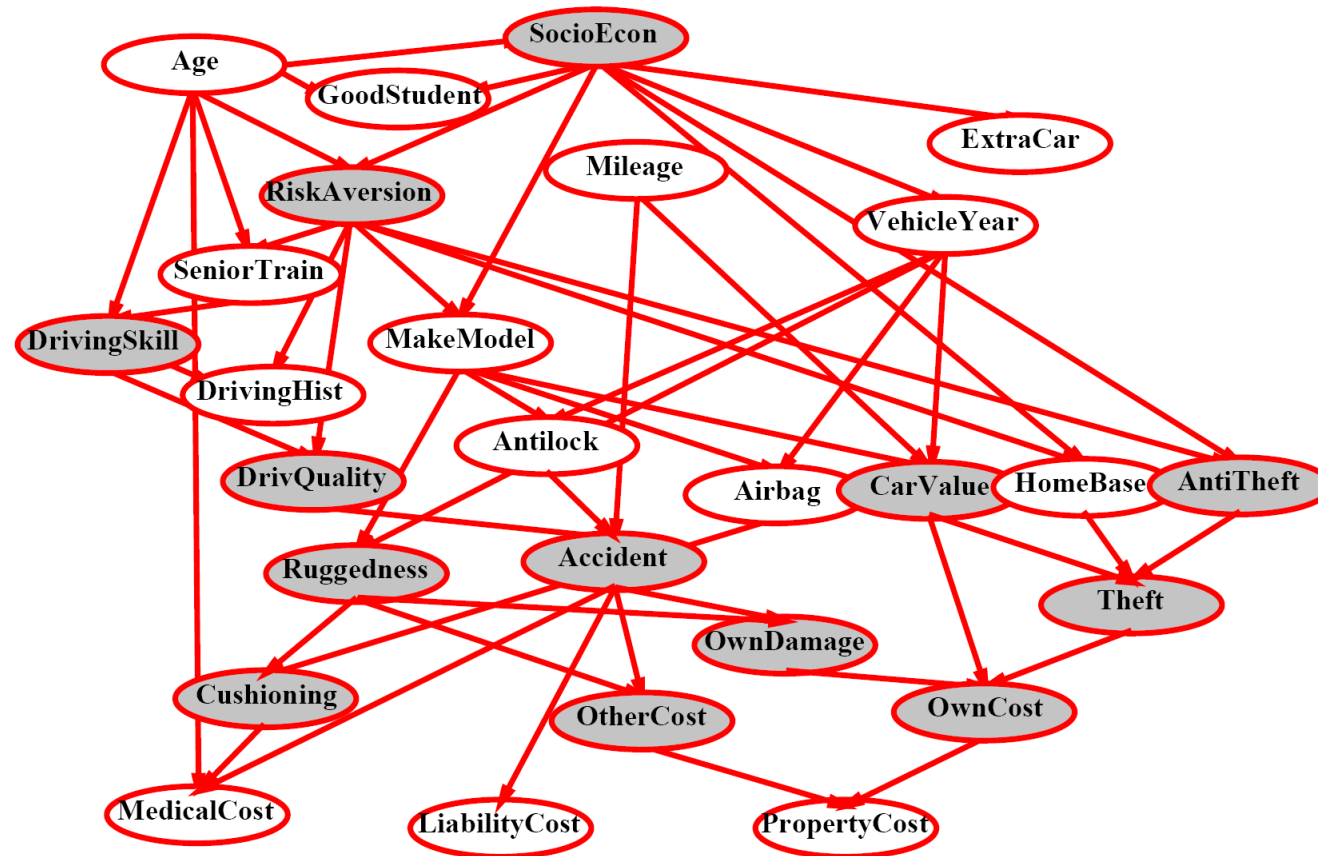
$$= \sum_{e,a} P(B)P(e)P(a|B, e)P(+j|a)P(+m|a)$$



$$= P(B)P(+e)P(+a|B, +e)P(+j|+a)P(+m|+a) + P(B)P(+e)P(-a|B, +e)P(+j|-a)P(+m|-a) \\ + P(B)P(-e)P(+a|B, -e)P(+j|+a)P(+m|+a) + P(B)P(-e)P(-a|B, -e)P(+j|-a)P(+m|-a)$$



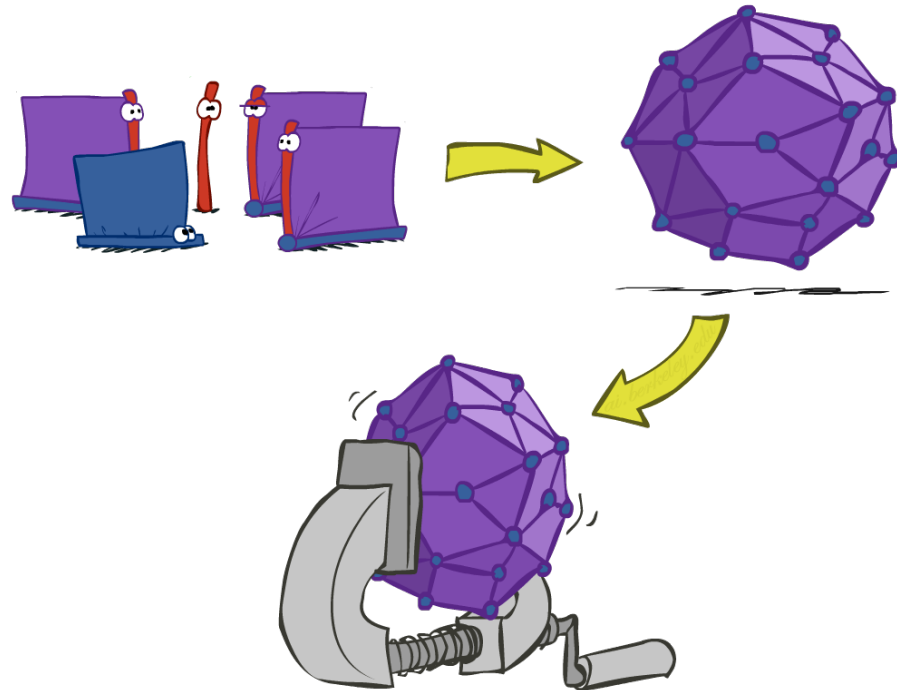
# Inference by Enumeration?



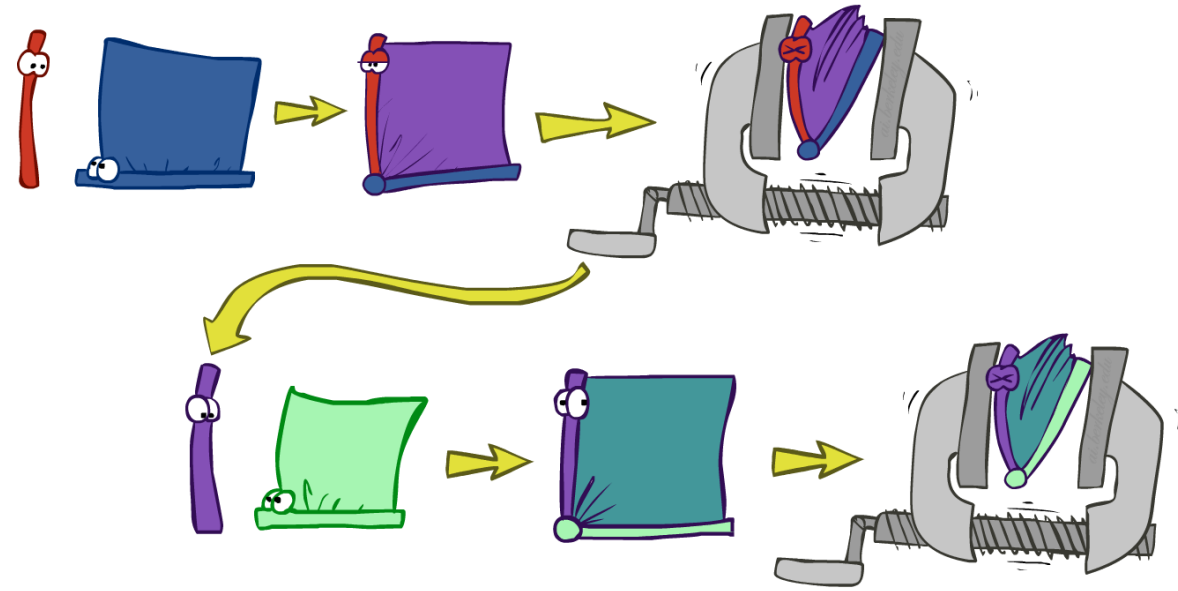
$$P(\textit{Antilock} | \textit{observed variables}) = ?$$

# Inference by Enumeration vs. Variable Elimination

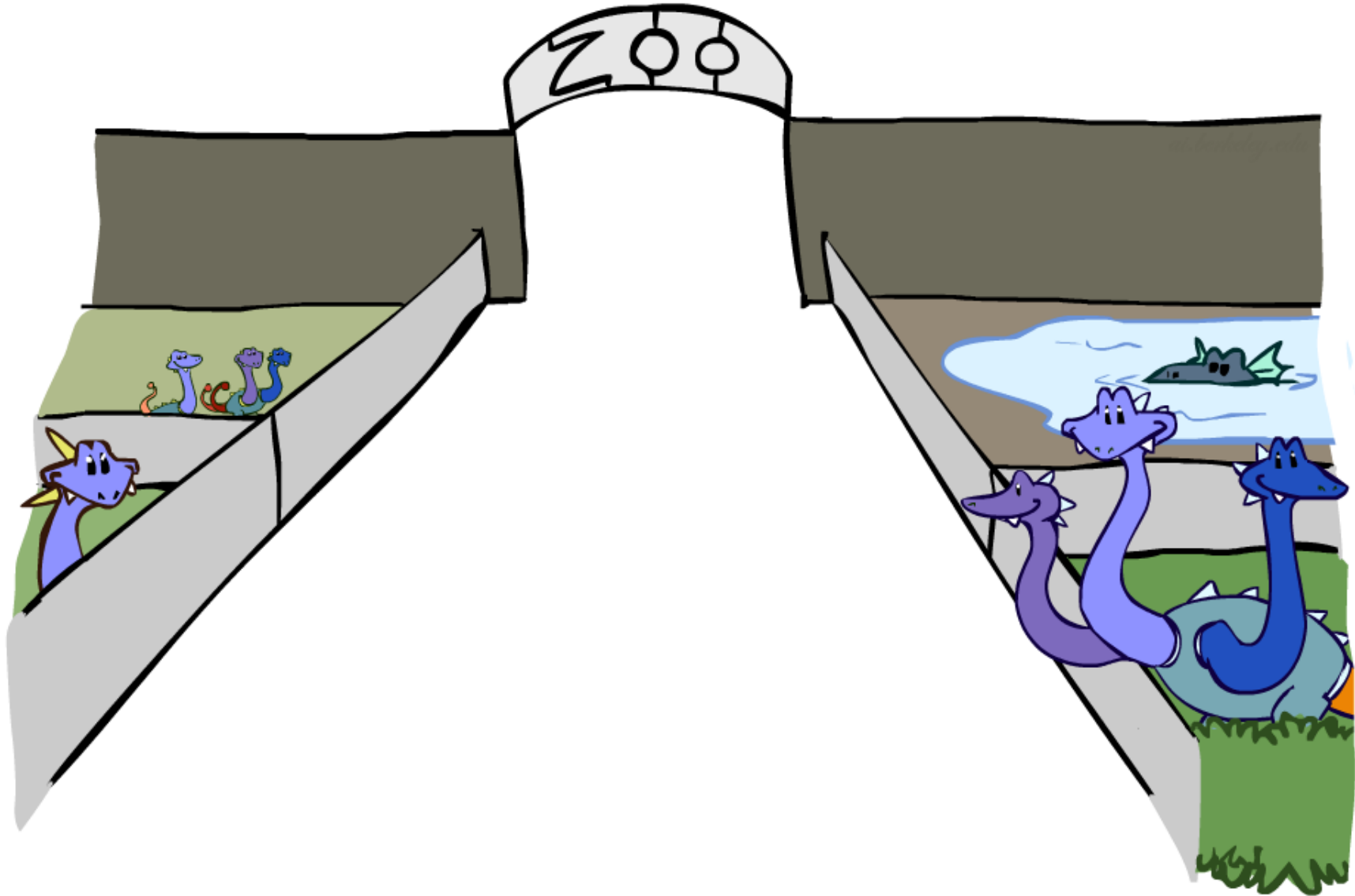
- Why is inference by enumeration so slow?
  - You join up the whole joint distribution before you sum out the hidden variables



- Idea: interleave joining and marginalizing!
  - Called “Variable Elimination”
  - Still NP-hard, but usually much faster than inference by enumeration



# Factor Zoo



# Factor Zoo I

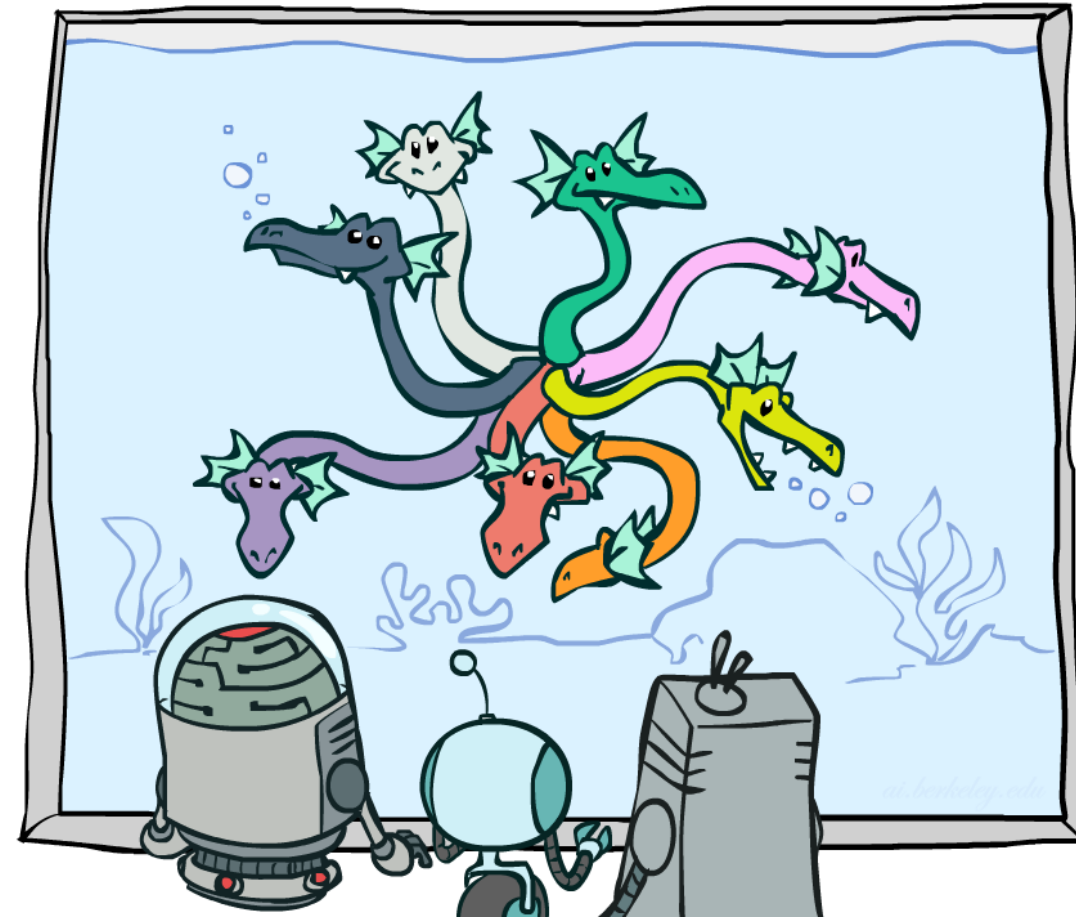
- Joint distribution:  $P(X,Y)$ 
  - Entries  $P(x,y)$  for all  $x, y$
  - Sums to 1
- Selected joint:  $P(x,Y)$ 
  - A slice of the joint distribution
  - Entries  $P(x,y)$  for fixed  $x$ , all  $y$
  - Sums to  $P(x)$
- Number of capitals = dimensionality of the table

$P(T, W)$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

$P(\text{cold}, W)$

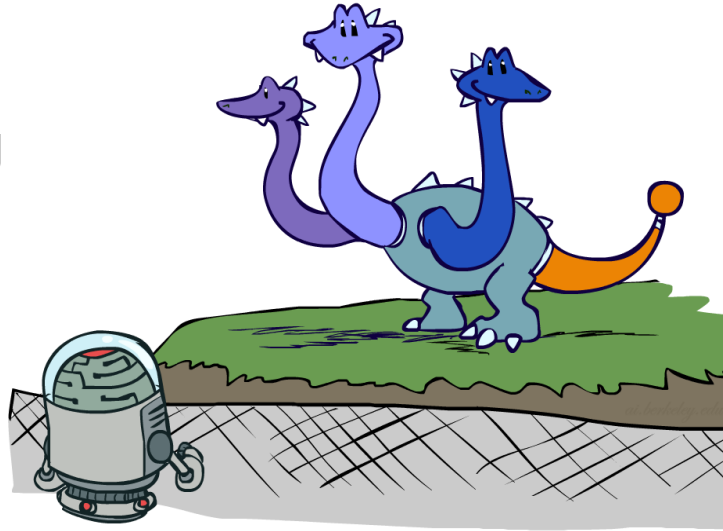
T	W	P
cold	sun	0.2
cold	rain	0.3



# Factor Zoo II

- Single conditional:  $P(Y | x)$

- Entries  $P(y | x)$  for fixed  $x$ , a
- Sums to 1



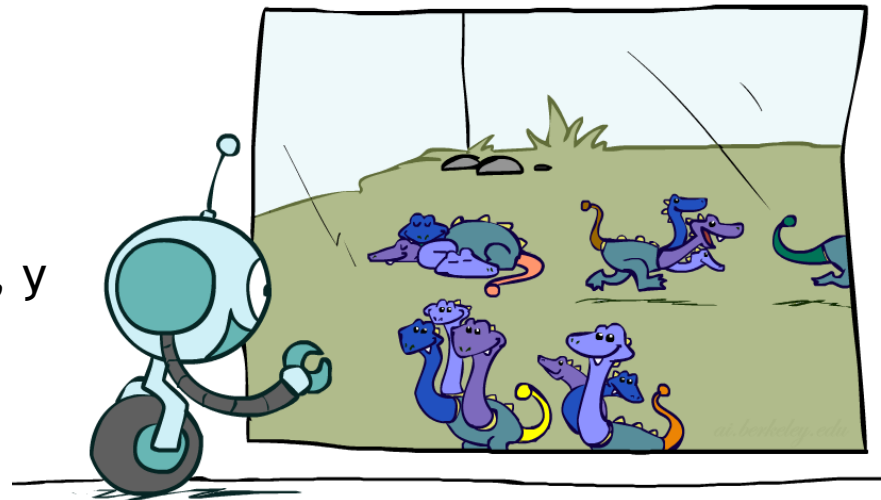
$$P(W|cold)$$

T	W	P
cold	sun	0.4
cold	rain	0.6

- Family of conditionals:

$$P(X | Y)$$

- Multiple conditionals
- Entries  $P(x | y)$  for all  $x, y$
- Sums to  $|Y|$



$$P(W|T)$$

T	W	P
hot	sun	0.8
hot	rain	0.2
cold	sun	0.4
cold	rain	0.6

$$P(W|hot)$$

$$P(W|cold)$$

# Factor Zoo III

- Specified family:  $P(y \mid X)$

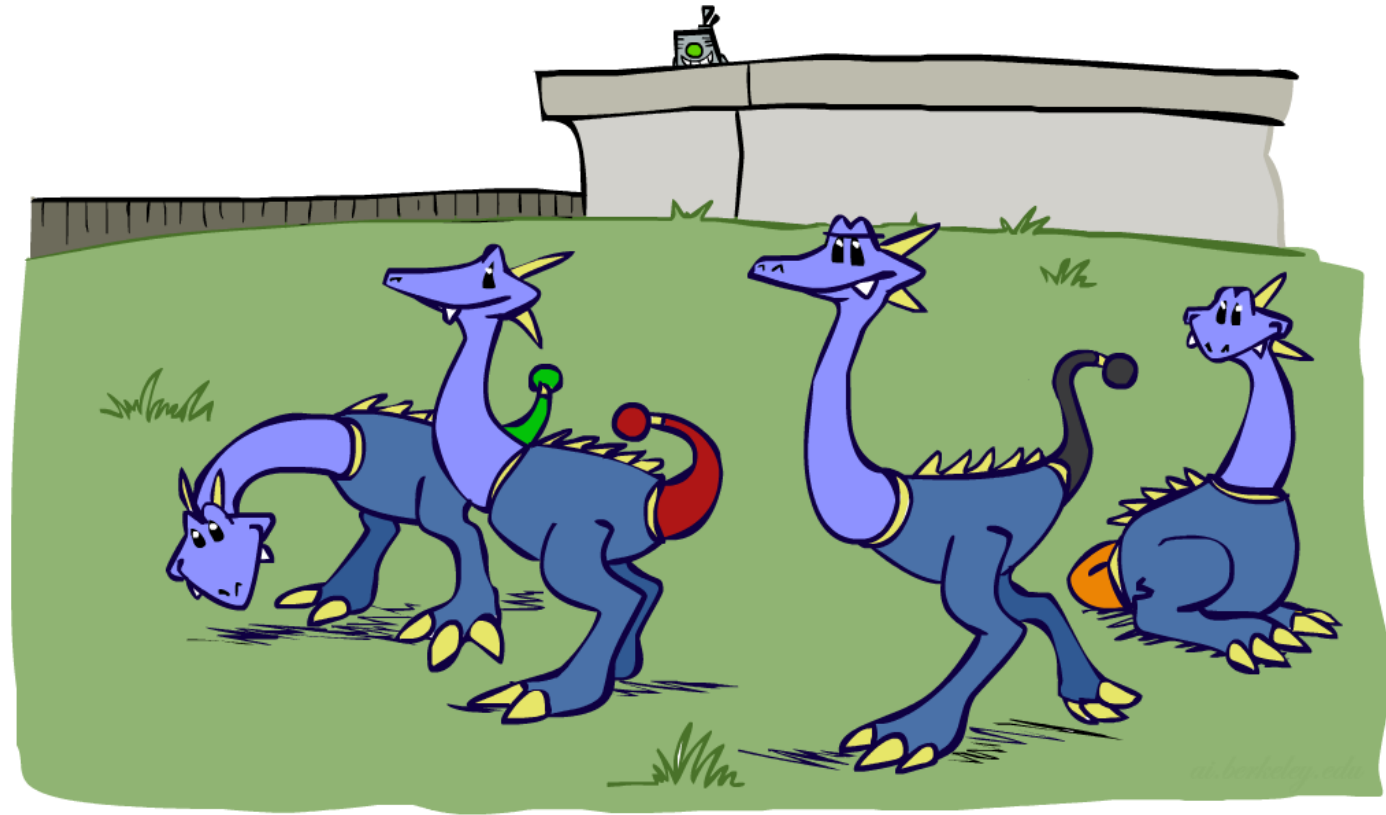
- Entries  $P(y \mid x)$  for fixed  $y$ , but for all  $x$
- Sums to ... who knows!

$$P(\text{rain} \mid T)$$

T	W	P
hot	rain	0.2
cold	rain	0.6

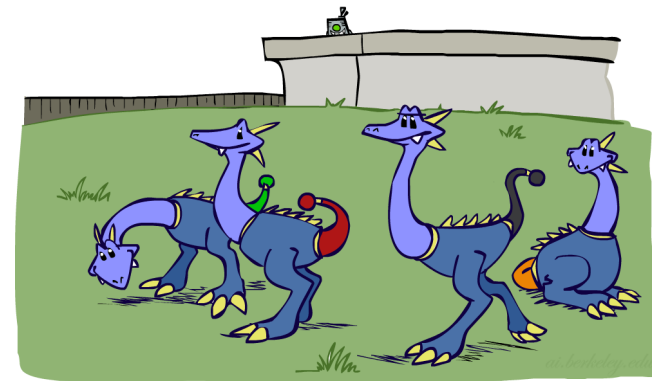
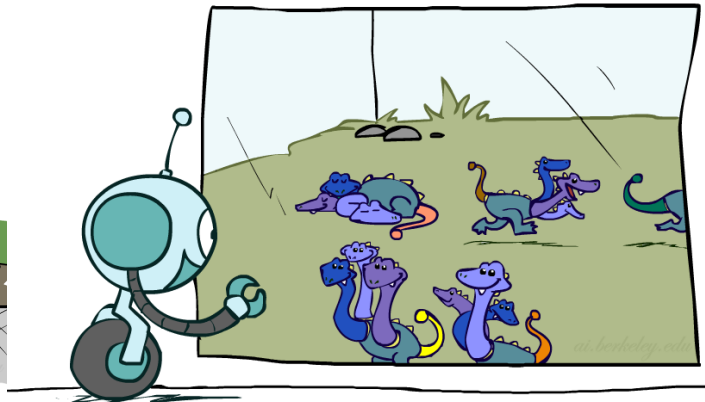
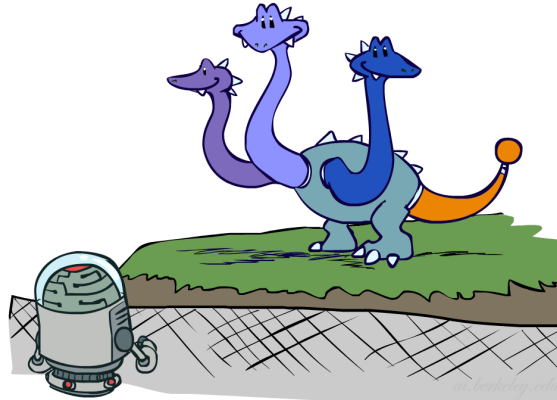
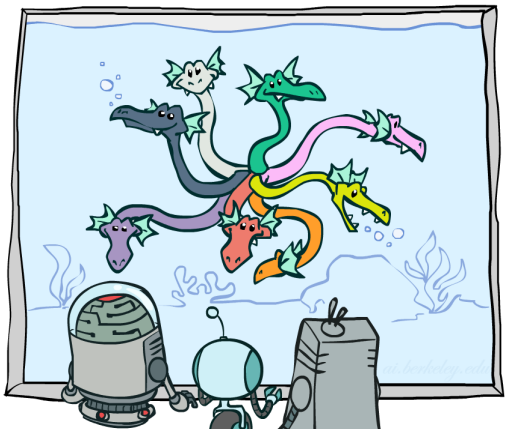
$$\left. \begin{array}{c} \\ \end{array} \right\} P(\text{rain} \mid \text{hot})$$

$$\left. \begin{array}{c} \\ \end{array} \right\} P(\text{rain} \mid \text{cold})$$



# Factor Zoo Summary

- In general, when we write  $P(Y_1 \dots Y_N \mid X_1 \dots X_M)$ 
  - It is a “factor,” a multi-dimensional array
  - Its values are  $P(y_1 \dots y_N \mid x_1 \dots x_M)$
  - Any assigned (=lower-case) X or Y is a dimension missing (selected) from the array



# Example: Traffic Domain

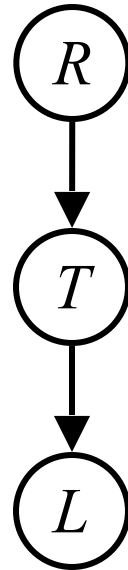
- Random Variables

- R: Raining
- T: Traffic
- L: Late for class!

$$P(L) = ?$$

$$= \sum_{r,t} P(r, t, L)$$

$$= \sum_{r,t} P(r)P(t|r)P(L|t)$$



$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9



# Inference by Enumeration: Procedural Outline

- Track objects called **factors**
- Initial factors are local CPTs (one per node)

$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- Any known values are selected
  - E.g. if we know  $L = +l$ , the initial factors are

$$P(R)$$

+r	0.1
-r	0.9

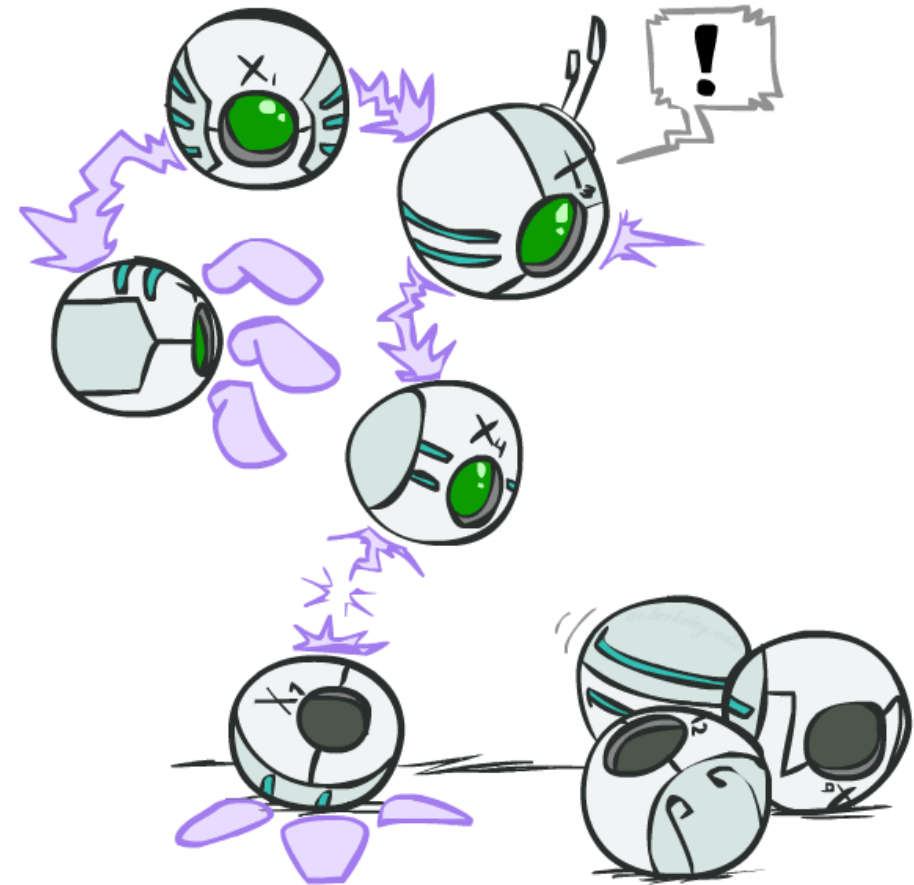
$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(+l|T)$$

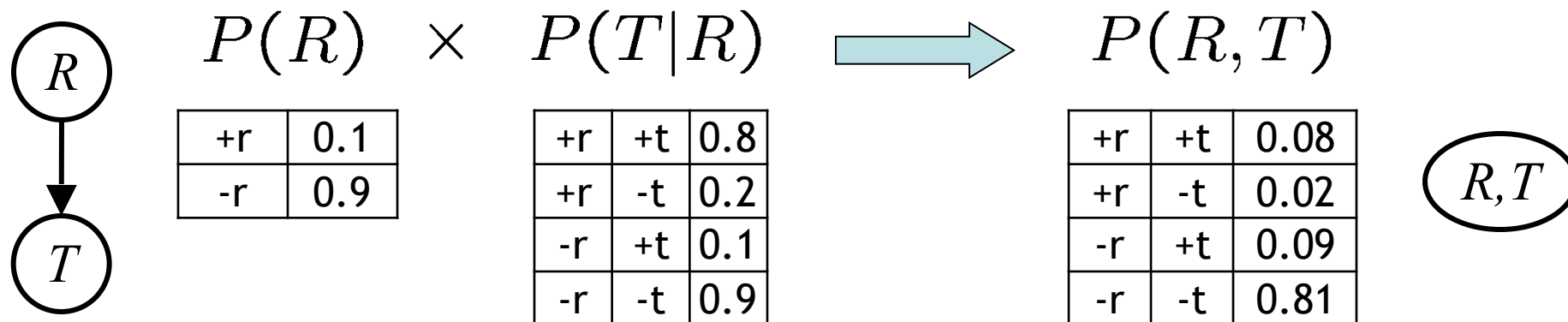
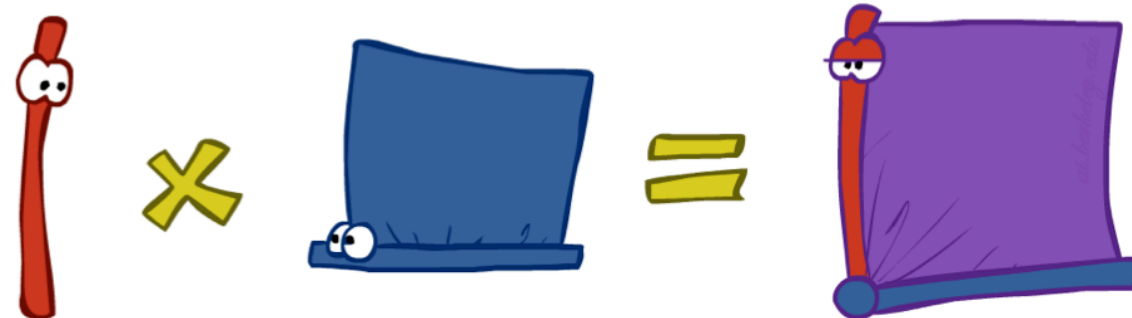
+t	+l	0.3
-t	+l	0.1

- Procedure: Join all factors, then eliminate all hidden variables



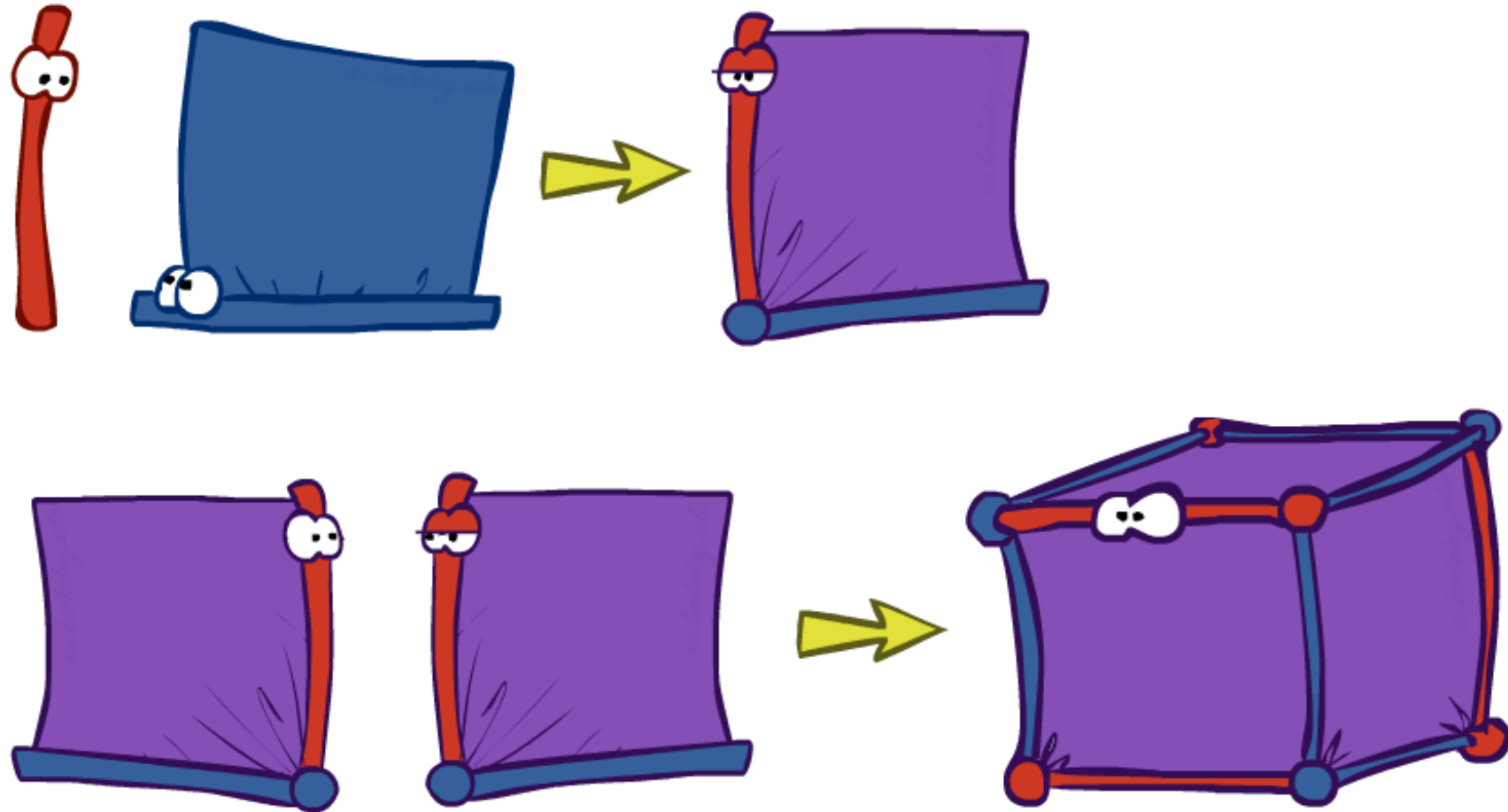
# Operation 1: Join Factors

- First basic operation: **joining factors**
- Combining factors:
  - Just like a database join**
  - Get all factors over the joining variable
  - Build a new factor over the union of the variables involved
- Example: Join on R

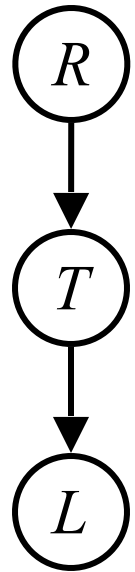


- Computation for each entry: pointwise products  $\forall r, t : P(r, t) = P(r) \cdot P(t|r)$

# Example: Multiple Joins



# Example: Multiple Joins



$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Join R

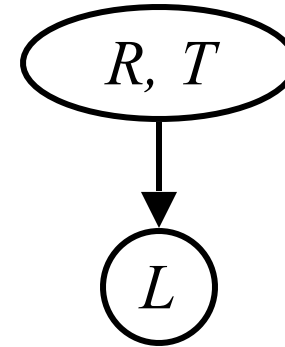


$P(R, T)$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9



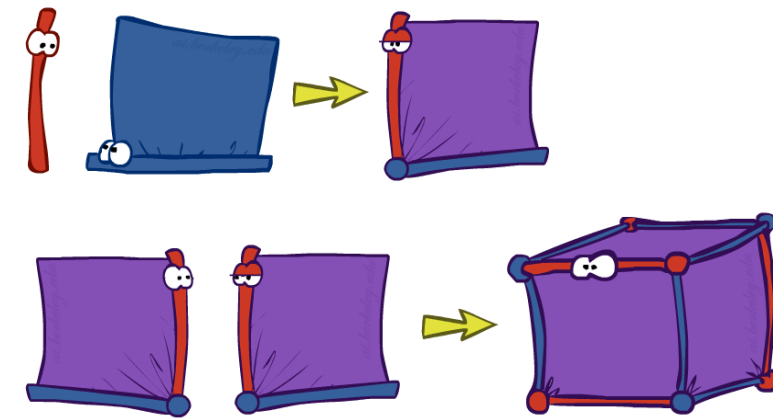
Join T



$R, T, L$

$P(R, T, L)$

+r	+t	+l	0.024
+r	+t	-l	0.056
+r	-t	+l	0.002
+r	-t	-l	0.018
-r	+t	+l	0.027
-r	+t	-l	0.063
-r	-t	+l	0.081
-r	-t	-l	0.729



# Operation 2: Eliminate

- Second basic operation: **marginalization**
- Take a factor and sum out a variable
  - Shrinks a factor to a smaller one
  - A **projection** operation
- Example:

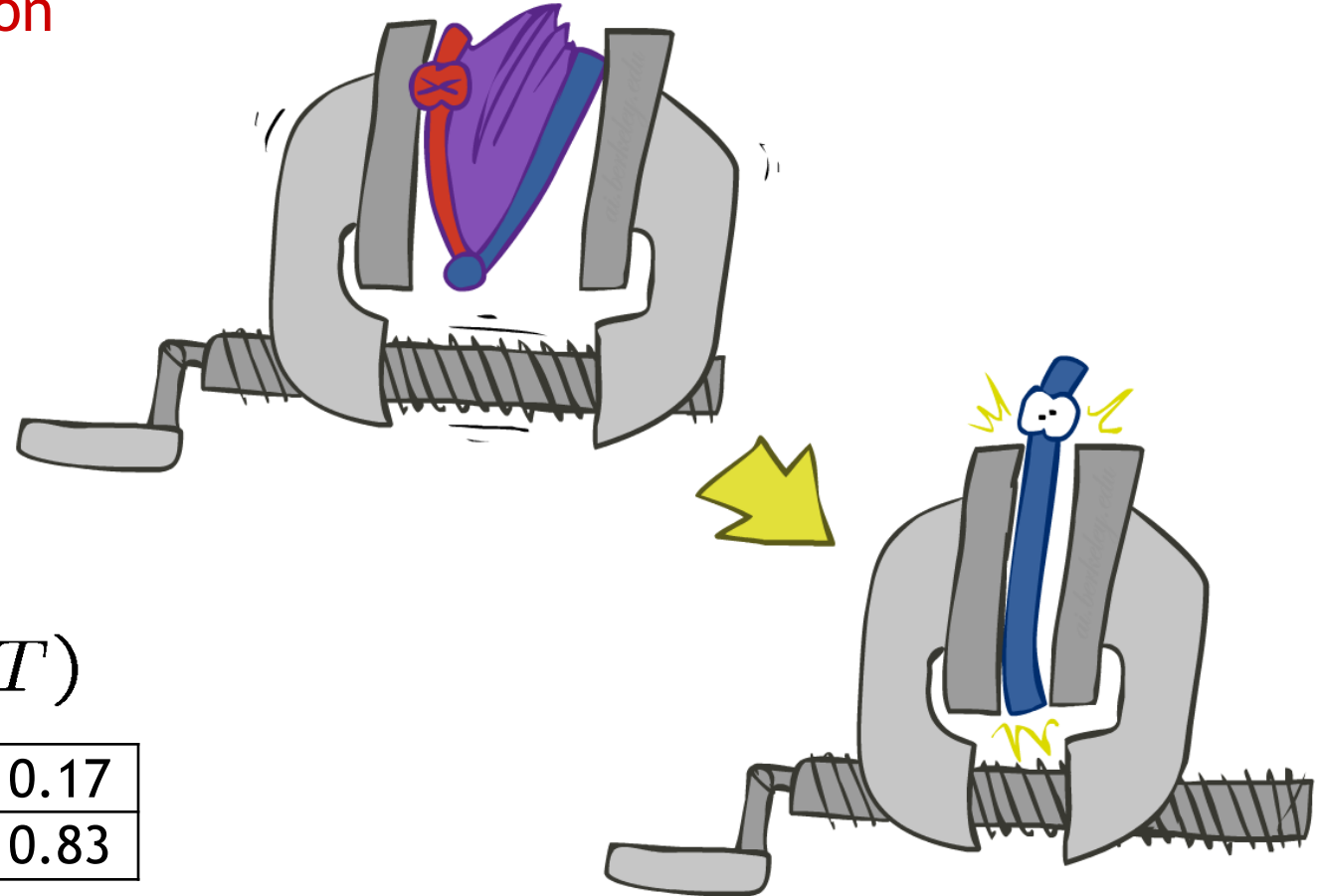
$$P(R, T)$$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

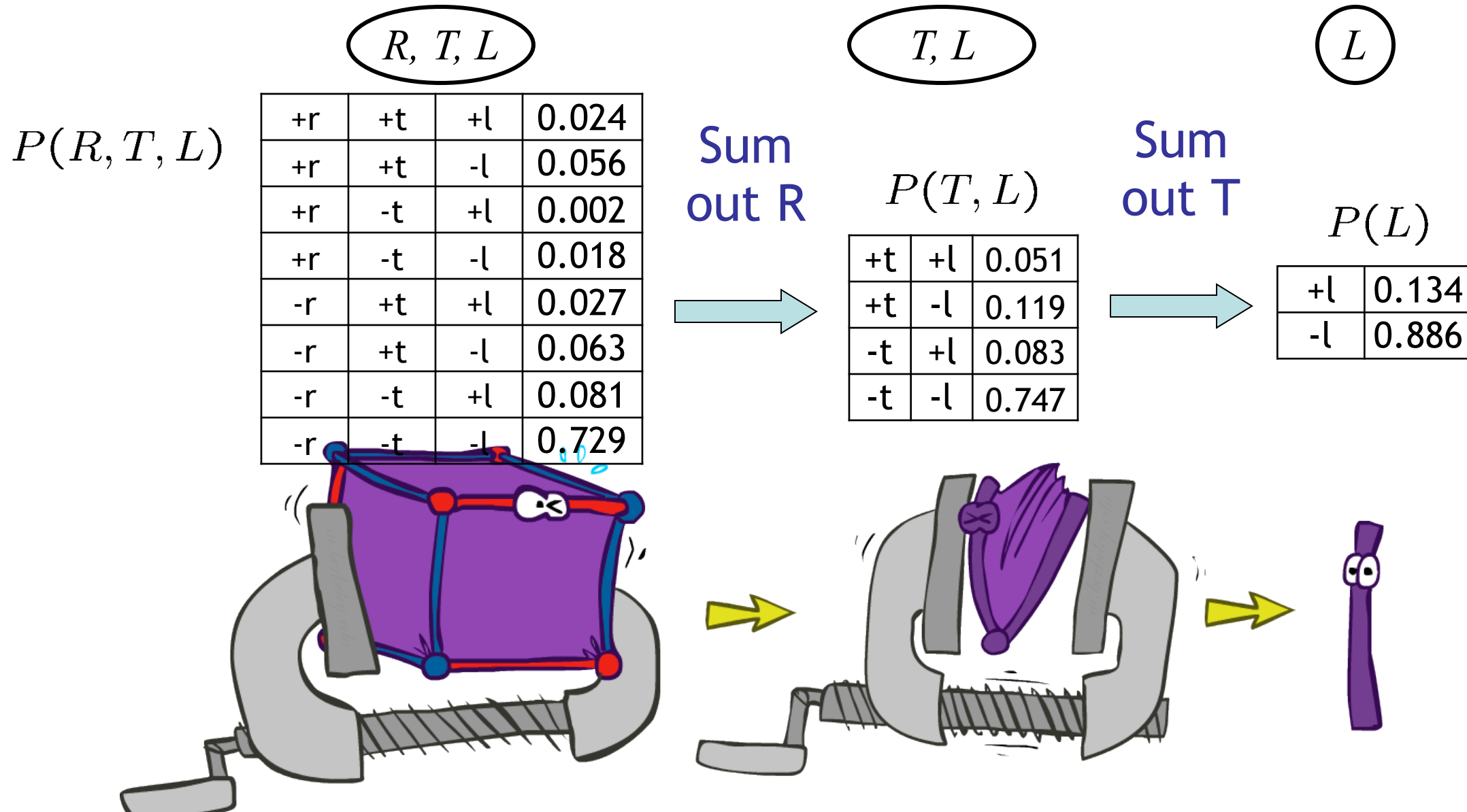
sum  $R$


$$P(T)$$

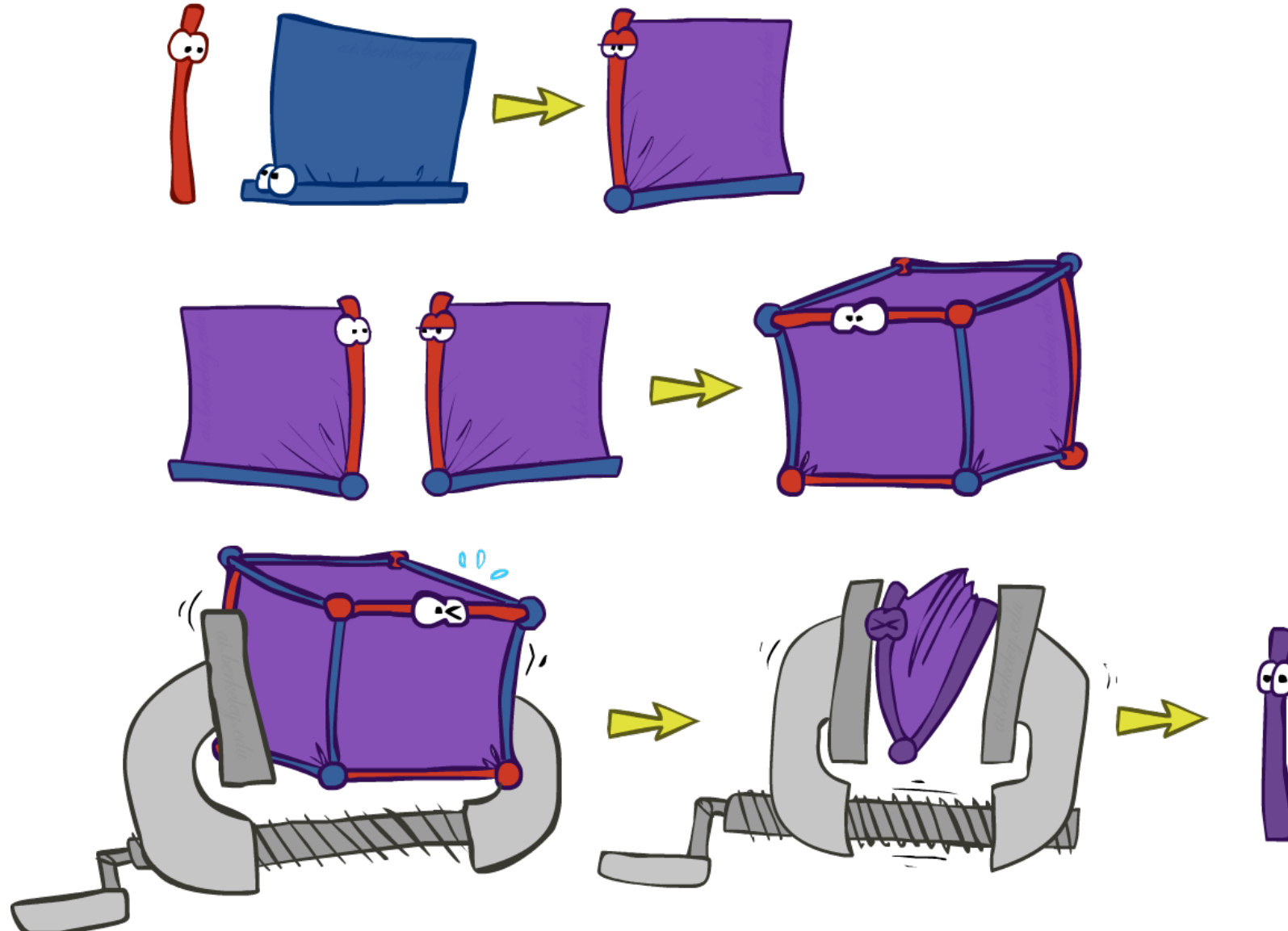
+t	0.17
-t	0.83



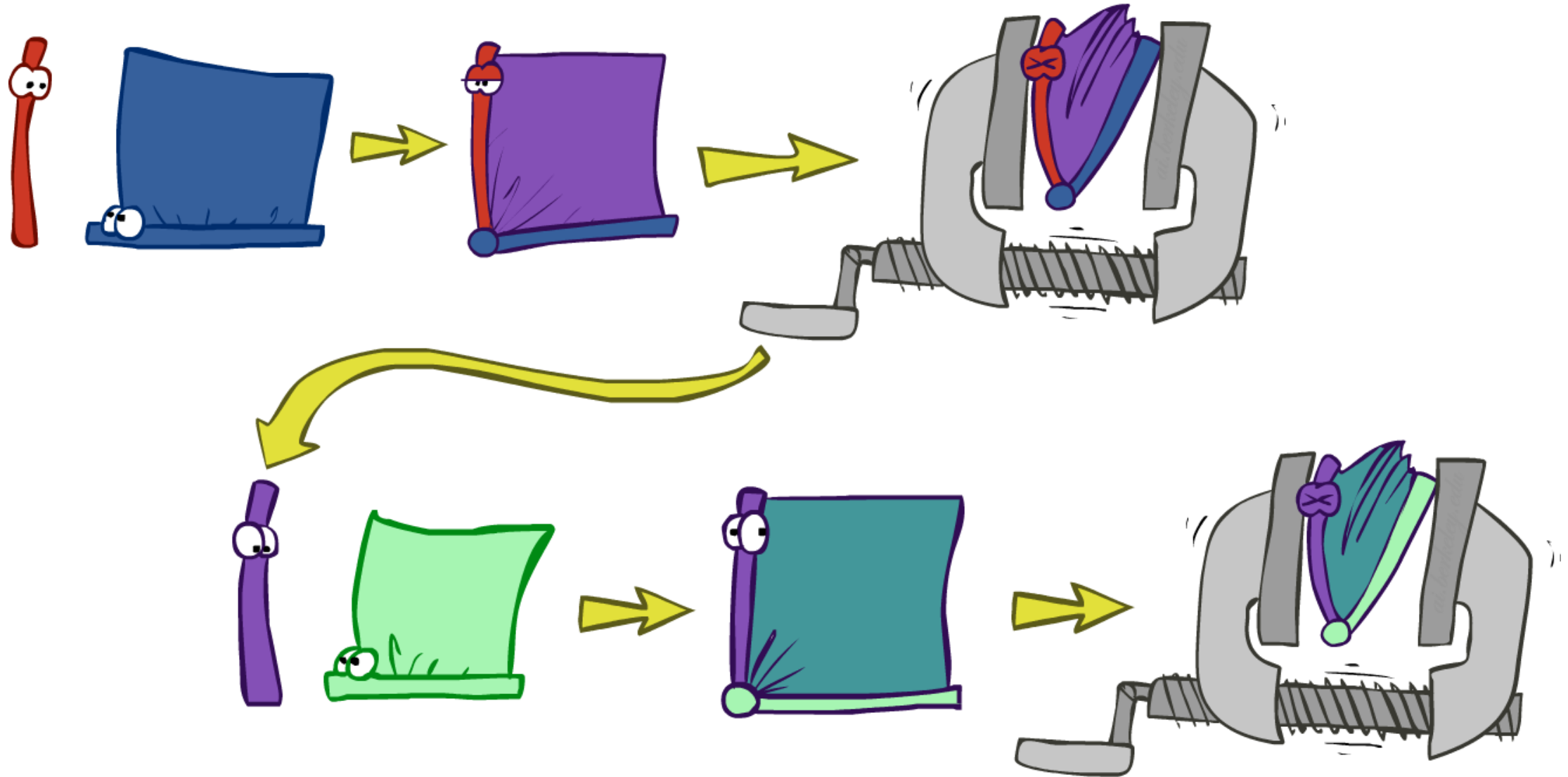
# Multiple Elimination



# Thus Far: Multiple Join, Multiple Eliminate (= Inference by Enumeration)

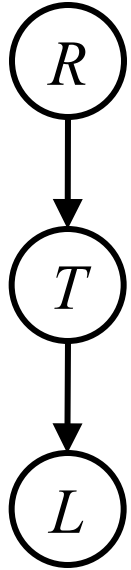


# Marginalizing Early (= Variable Elimination)





# Traffic Domain



$$P(L) = ?$$

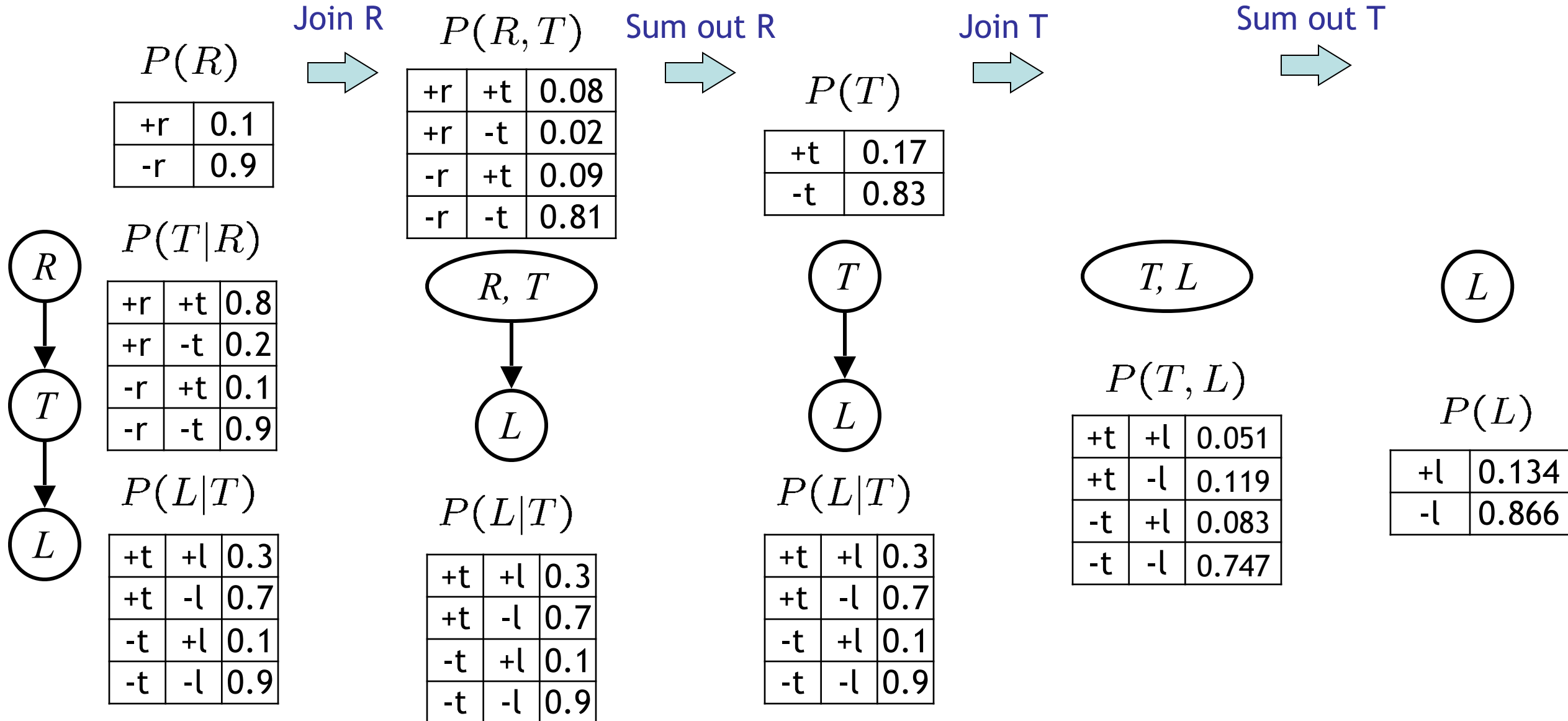
## ■ Inference by Enumeration

$$= \sum_t \sum_r \underbrace{P(L|t)P(r)P(t|r)}_{\text{Join on } r} \underbrace{\phantom{P(L|t)P(r)P(t|r)}}_{\text{Join on } t} \underbrace{\phantom{P(L|t)P(r)P(t|r)}}_{\text{Eliminate } r} \underbrace{\phantom{P(L|t)P(r)P(t|r)}}_{\text{Eliminate } t}$$

## ■ Variable Elimination

$$= \sum_t P(L|t) \underbrace{\sum_r P(r)P(t|r)}_{\text{Join on } r} \underbrace{\phantom{P(L|t)P(r)P(t|r)}}_{\text{Eliminate } r} \underbrace{\phantom{P(L|t)P(r)P(t|r)}}_{\text{Join on } t} \underbrace{\phantom{P(L|t)P(r)P(t|r)}}_{\text{Eliminate } t}$$

# Marginalizing Early! (aka VE)



# Evidence

- If evidence, start with factors that select that evidence
  - No evidence uses these initial factors:

$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- Computing  $P(L|+r)$ , the initial factors become:

$$P(+r)$$

+r	0.1
----	-----

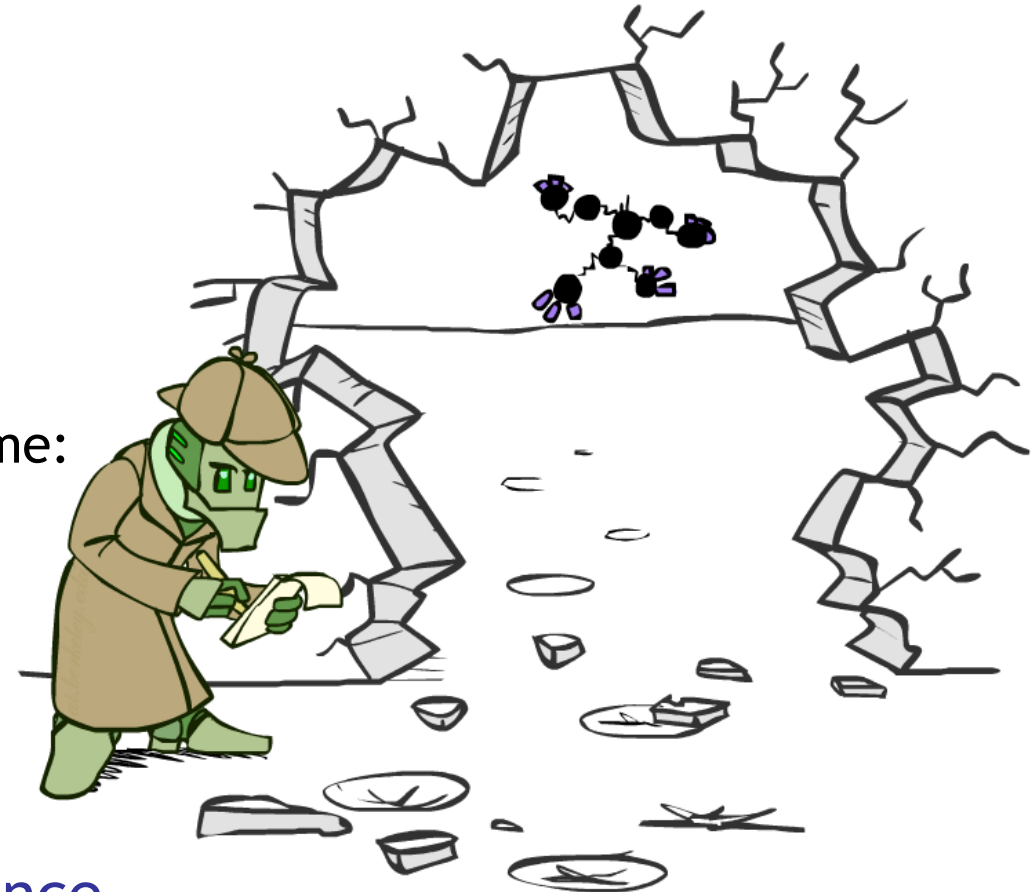
$$P(T|+r)$$

+r	+t	0.8
+r	-t	0.2

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- We eliminate all vars other than query + evidence



# Evidence II

- Result will be a selected joint of query and evidence
  - E.g. for  $P(L \mid +r)$ , we would end up with:

$$P(+r, L)$$

+r	+l	0.026
+r	-l	0.074

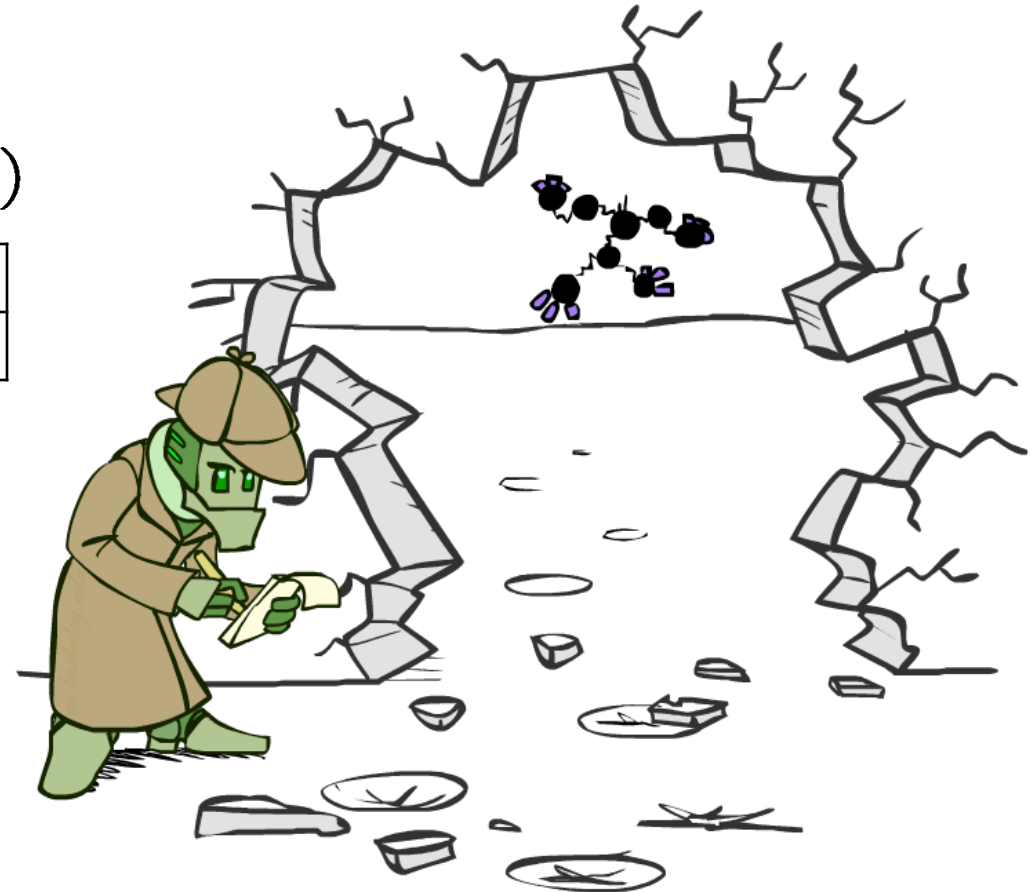
Normalize



$$P(L \mid +r)$$

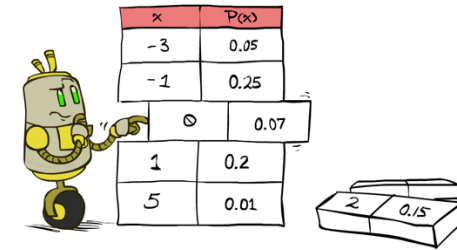
+l	0.26
-l	0.74

- To get our answer, just normalize this!
- That 's it!



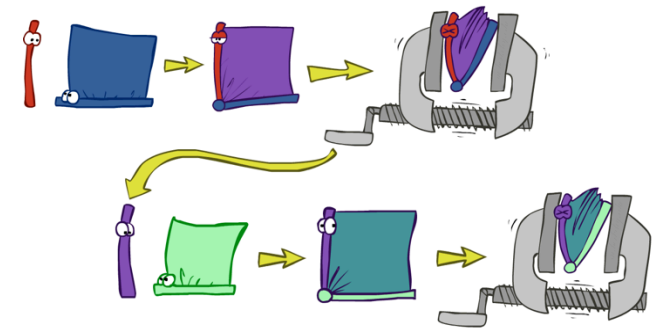
# General Variable Elimination

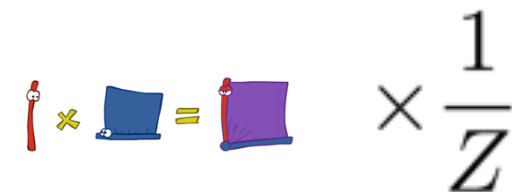
- Query:  $P(Q|E_1 = e_1, \dots, E_k = e_k)$
- Start with initial factors:
  - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
  - Pick a hidden variable H
  - Join all factors mentioning H
  - Eliminate (sum out) H
- Join all remaining factors and normalize



x	P(x)
-3	0.05
-1	0.25
0	0.07
1	0.2
5	0.01

2 0.15

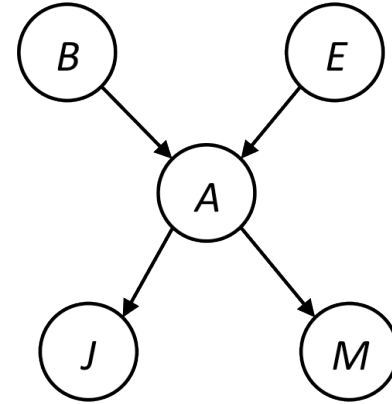



$$\text{Factor} \times \text{Constant} = \text{New Factor} \times \frac{1}{Z}$$

# Example

$$P(B|j, m) \propto P(B, j, m)$$

$P(B)$	$P(E)$	$P(A B, E)$	$P(j A)$	$P(m A)$
--------	--------	-------------	----------	----------

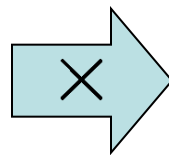


Choose A

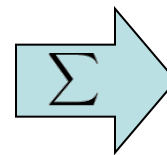
$$P(A|B, E)$$

$$P(j|A)$$

$$P(m|A)$$



$$P(j, m, A|B, E)$$



$$P(j, m|B, E)$$

$P(B)$	$P(E)$	$P(j, m B, E)$
--------	--------	----------------

# Example

$P(B)$	$P(E)$	$P(j, m B, E)$
--------	--------	----------------

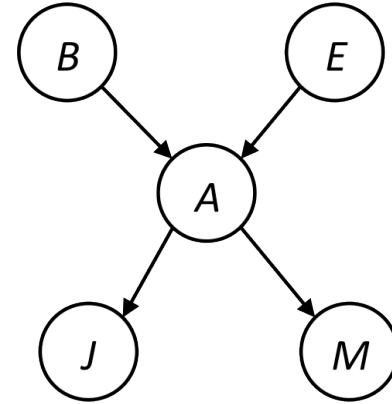
Choose E

$$\begin{array}{c} P(E) \\ P(j, m|B, E) \end{array} \xrightarrow{\times} P(j, m, E|B) \xrightarrow{\Sigma} P(j, m|B)$$

$P(B)$	$P(j, m B)$
--------	-------------

Finish with B

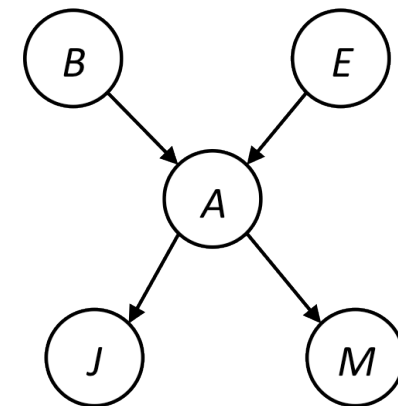
$$\begin{array}{c} P(B) \\ P(j, m|B) \end{array} \xrightarrow{\times} P(j, m, B) \xrightarrow{\text{Normalize}} P(B|j, m)$$



# Same Example in Equations

$$P(B|j, m) \propto P(B, j, m)$$

$P(B)$	$P(E)$	$P(A B, E)$	$P(j A)$	$P(m A)$
--------	--------	-------------	----------	----------



$$\begin{aligned}
 P(B|j, m) &\propto P(B, j, m) \\
 &= \sum_{e, a} P(B, j, m, e, a) \\
 &= \sum_{e, a} P(B)P(e)P(a|B, e)P(j|a)P(m|a) \\
 &= \sum_e P(B)P(e) \sum_a P(a|B, e)P(j|a)P(m|a) \\
 &= \sum_e P(B)P(e)f_1(B, e, j, m) \\
 &= P(B) \sum_e P(e)f_1(B, e, j, m) \\
 &= P(B)f_2(B, j, m)
 \end{aligned}$$

marginal can be obtained from joint by summing out

use Bayes' net joint distribution expression

use  $x^*(y+z) = xy + xz$

joining on  $a$ , and then summing out gives  $f_1$

use  $x^*(y+z) = xy + xz$

joining on  $e$ , and then summing out gives  $f_2$

All we are doing is exploiting  $uwy + uwz + uxy + uxz + vwy + vwz + vxy + vxz = (u+v)(w+x)(y+z)$  to improve computational efficiency!



# Another Variable Elimination Example

Query:  $P(X_3 | Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

$$p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$$

Eliminate  $X_1$ , this introduces the factor  $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$ , and we are left with:

$$p(Z)f_1(Z, y_1)p(X_2|Z)p(X_3|Z)p(y_2|X_2)p(y_3|X_3)$$

Eliminate  $X_2$ , this introduces the factor  $f_2(Z, y_2) = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$ , and we are left with:

$$p(Z)f_1(Z, y_1)f_2(Z, y_2)p(X_3|Z)p(y_3|X_3)$$

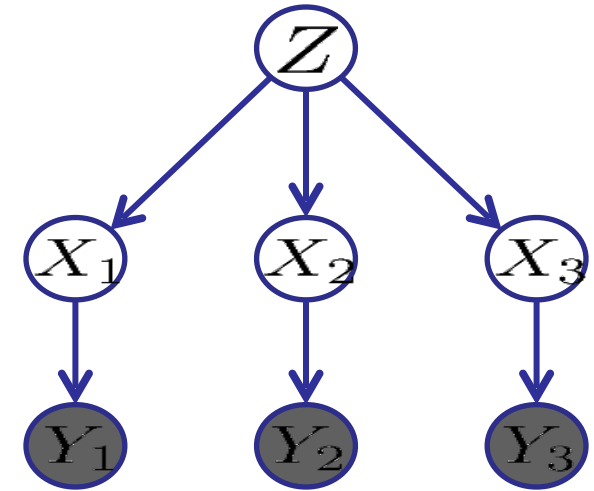
Eliminate  $Z$ , this introduces the factor  $f_3(y_1, y_2, X_3) = \sum_z p(z)f_1(z, y_1)f_2(z, y_2)p(X_3|z)$ , and we are left:

$$p(y_3|X_3), f_3(y_1, y_2, X_3)$$

No hidden variables left. Join the remaining factors to get:

$$f_4(y_1, y_2, y_3, X_3) = P(y_3|X_3)f_3(y_1, y_2, X_3).$$

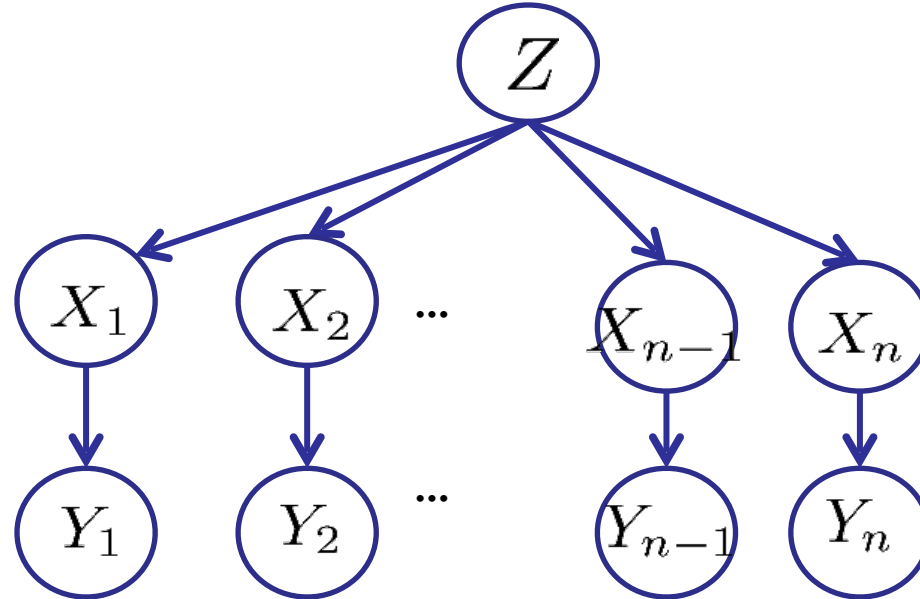
Normalizing over  $X_3$  gives  $P(X_3 | y_1, y_2, y_3)$ .



Computational complexity critically depends on the largest factor being generated in this process. Size of factor = number of entries in table. In example above (assuming binary) all factors generated are of size 2 --- as they all only have one variable ( $Z$ ,  $Z$ , and  $X_3$  respectively).

# Variable Elimination Ordering

- For the query  $P(X_n | y_1, \dots, y_n)$  work through the following two different orderings as done in previous slide:  $Z, X_1, \dots, X_{n-1}$  and  $X_1, \dots, X_{n-1}, Z$ . What is the size of the maximum factor generated for each of the orderings?



- Answer:  $2^{n+1}$  versus  $2^2$  (assuming binary)
- In general: the ordering can greatly affect efficiency.

# VE: Computational and Space Complexity

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- The computational and space complexity of variable elimination is determined by the largest factor
- The elimination ordering can greatly affect the size of the largest factor.
  - E.g., previous slide's example  $2^n$  vs. 2
- Does there always exist an ordering that only results in small factors?
  - No!

# Worst Case Complexity?

## ■ 3-SAT

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_1 \vee x_3 \vee \neg x_4) \wedge (x_2 \vee \neg x_2 \vee x_4) \wedge (\neg x_3 \vee \neg x_4 \vee \neg x_5) \wedge (x_2 \vee x_5 \vee x_7) \wedge (x_4 \vee x_5 \vee x_6) \wedge (\neg x_5 \vee x_6 \vee \neg x_7) \wedge (\neg x_5 \vee \neg x_6 \vee x_7)$$

$$P(X_i = 0) = P(X_i = 1) = 0.5$$

$$Y_1 = X_1 \vee X_2 \vee \neg X_3$$

...

$$Y_8 = \neg X_5 \vee X_6 \vee X_7$$

$$Y_{1,2} = Y_1 \wedge Y_2$$

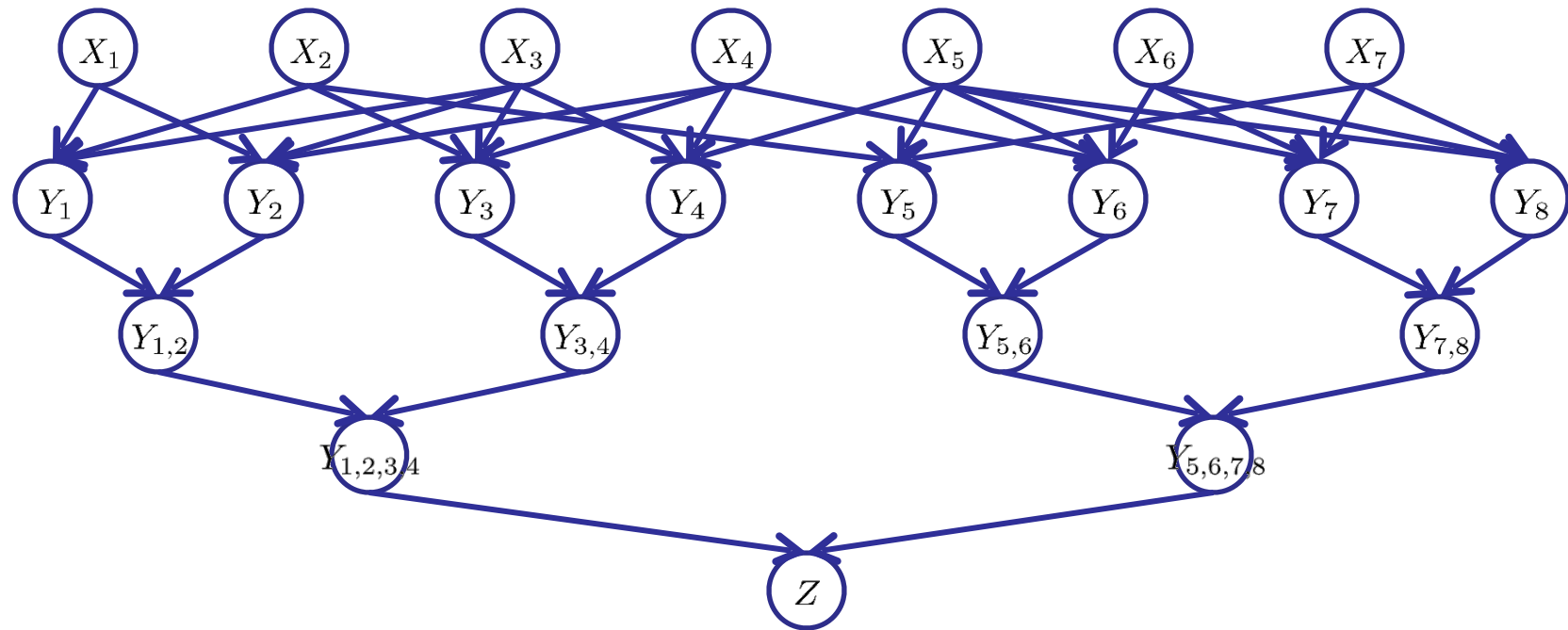
...

$$Y_{7,8} = Y_7 \wedge Y_8$$

$$Y_{1,2,3,4} = Y_{1,2} \wedge Y_{3,4}$$

$$Y_{5,6,7,8} = Y_{5,6} \wedge Y_{7,8}$$

$$Z = Y_{1,2,3,4} \wedge Y_{5,6,7,8}$$



- If we can answer  $P(z)$  equal to zero or not, we answered whether the 3-SAT problem has a solution.
- Hence inference in Bayes' nets is NP-hard. No known efficient probabilistic inference in general.

# Polytrees

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- A polytree is a directed graph with no undirected cycles
- For poly-trees you can always find an ordering that is efficient
  - Try it!!

# Bayes' Nets

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- ✓ Representation

- ✓ Conditional Independences

- Probabilistic Inference

- ✓ Enumeration (exact, exponential complexity)

- ✓ Variable elimination (exact, worst-case exponential complexity, often better)

- ✓ Inference is NP-complete

- Sampling (approximate)

- Learning Bayes' Nets from Data