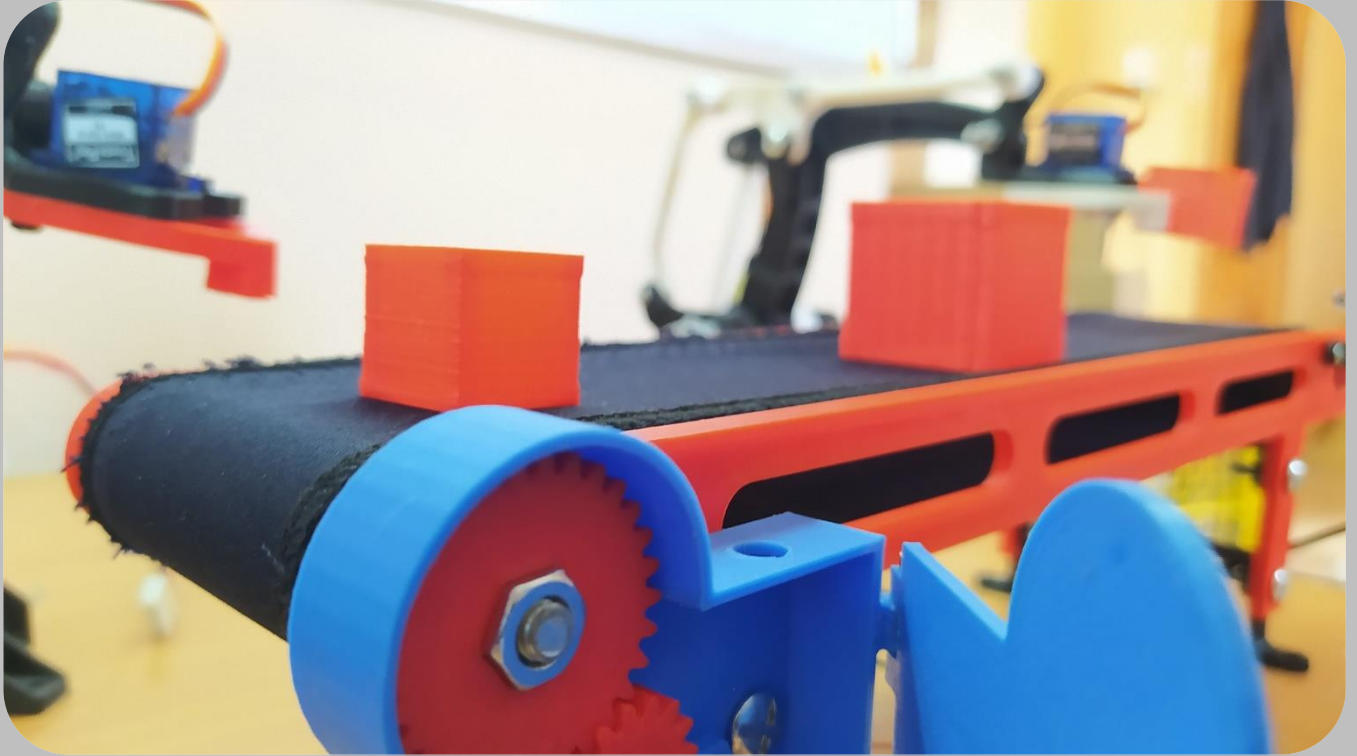


Conveyor (conveyor belt)

by

OUCHENE ABDELHAK



<https://www.facebook.com/audi.gtspyder>

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3d printing settings

I used PLA 0.4 nozzle

For the printer I used ender 3 and Anycubic Chiron

* For the layer Height 0.3mm for the most of the parts

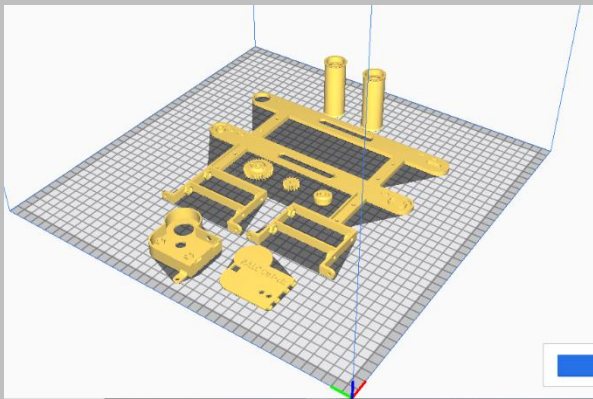
except the gear box 0.2 mm and for better result use the adaptive layer option (I use CURA)

*You need support just for coupling, the big gear and the sensor holder.

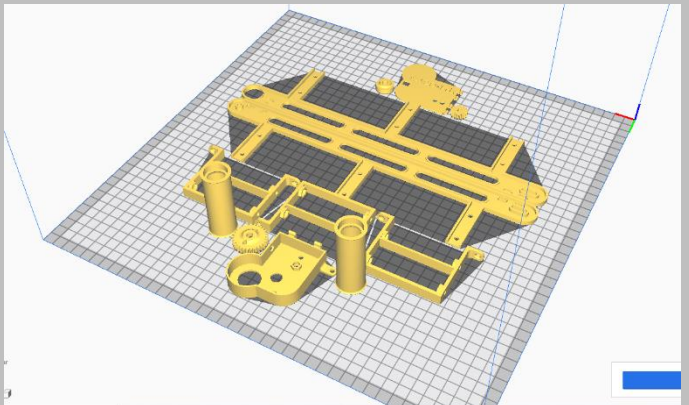
#don't forget to disable the horizontal expansion #

In the small one L you need 11 parts (without the holder of the IR sensor)

For longest one XL you need 12 (one more chassis for the middle) without the holder of the IR sensor



Small Conveyor (L)



Longest Conveyor (XL)

In this photo I put all the pieces in one base just to show you the number that you need in each version L and XL

the program of the stepper motor you will find in
YouTube

just right Stepper motor **28byj-48**

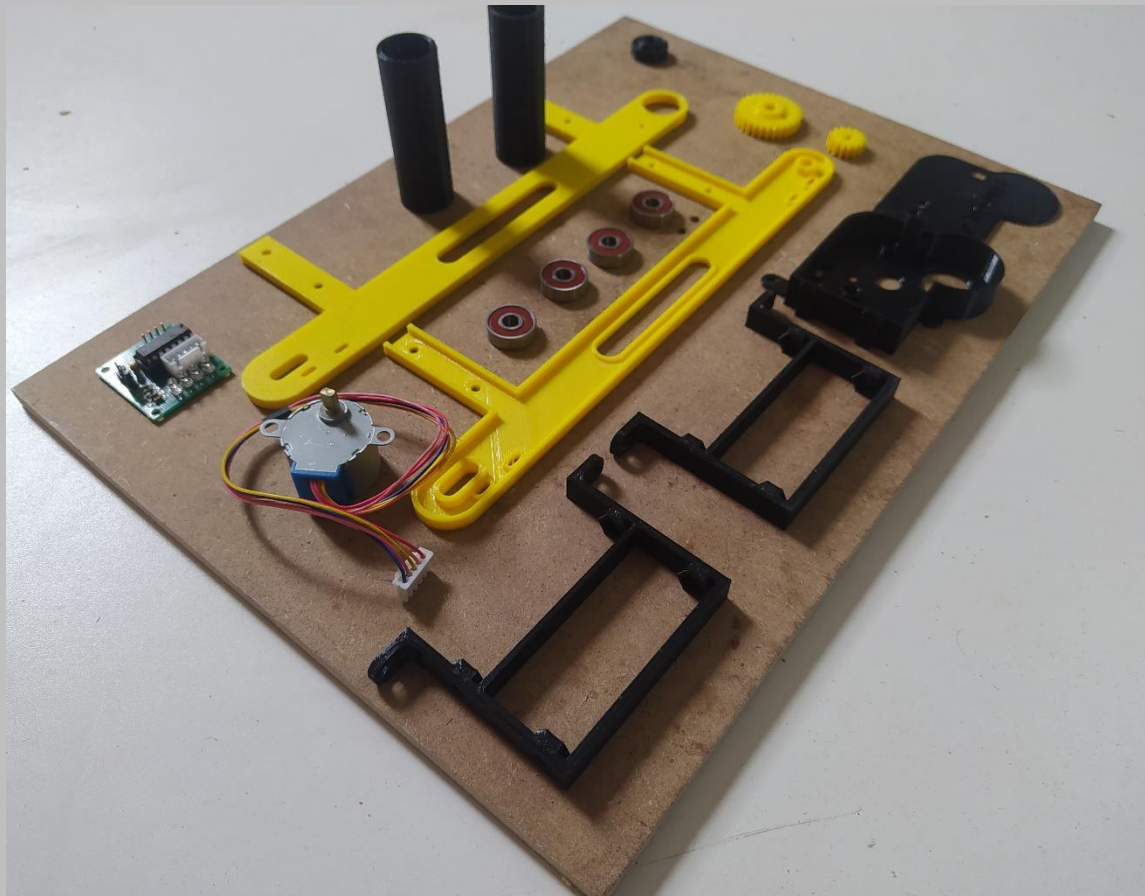
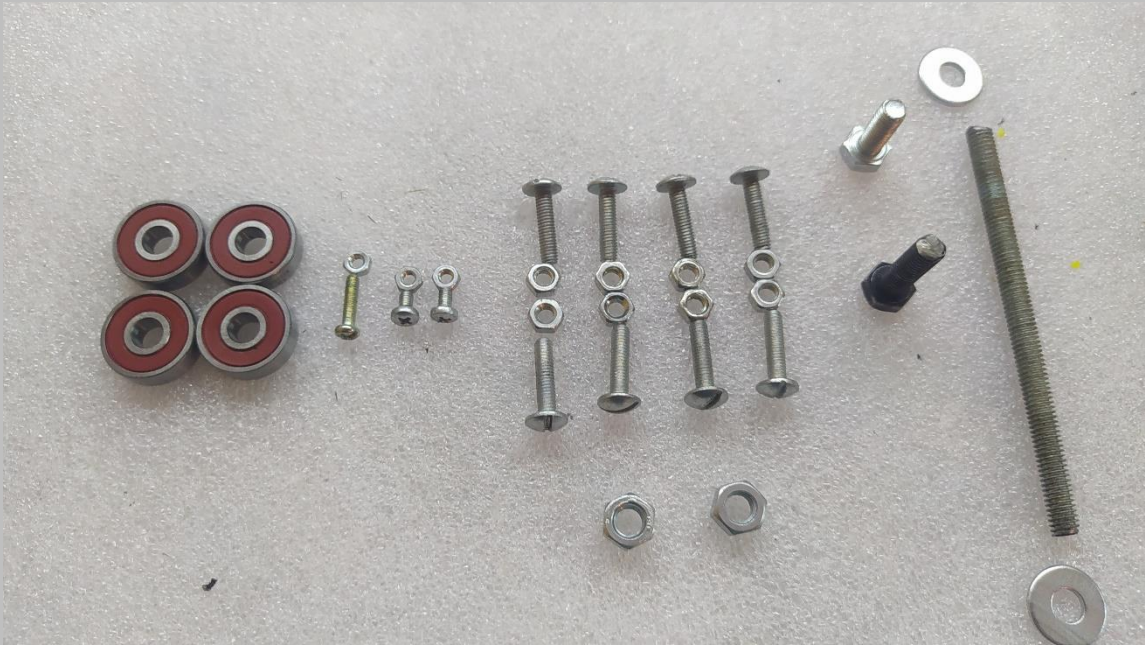
Assembly

* There is a small video for exploded animation for the conveyor you will understand the assembly and follow the steps below

- List of bolt, nuts, bearings and other stuff needed

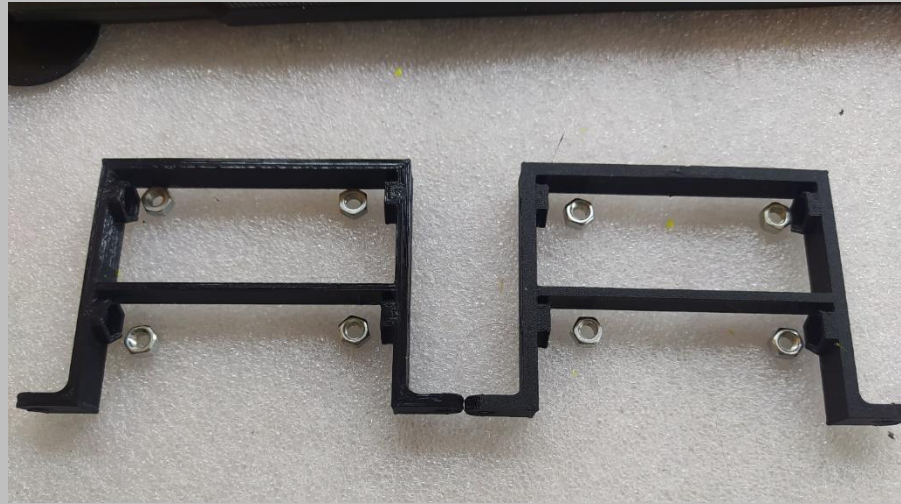
1. Stepper motor 28byj-48
2. Arduino (nano or uno ...)
3. IR sensor (additional option)
4. **x8** M4 bolt 25mm and **x8** M4 nuts to fix the chassie to the right and left side
5. **x3** M3 bolts and **x3** M3 nuts (2 of them for fixing the stepper motor the other one to fix the gear box to crop)
6. **x4** M6 nuts (one of them you press inside the big gear)
7. **x2** bolt M6 20 mm in length
8. **x1** bolt M6 85 mm in length
9. one or 2 washers for adjustment M6
10. **x4** bearings 626-2Z Bearing (single row deep groove ball Øint: 6mm Øout: 19mm W: 6mm) you will find it in amazon or Alibaba...
11. Cloth (**490mm** to **520mm**) for the small one (**L**) and for the longest version (**XL**) (**600mm** to **630mm**) depends of the quality of the cloth for bater result use the inflexible cloth, and for the width **60mm** both of them.
12. And of course, the hero of all the project mister **glue**.

- Let's start the assembly



3d printed parts for the small version (L)

squeeze it in his place



M4 nut



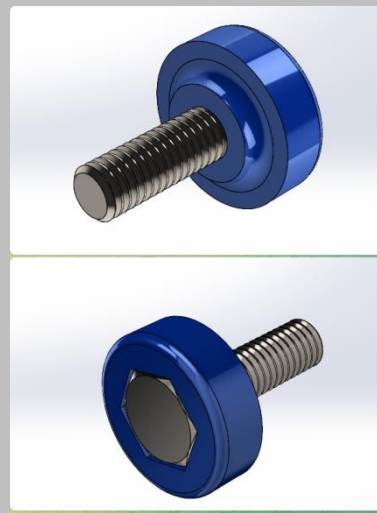
M3



M3



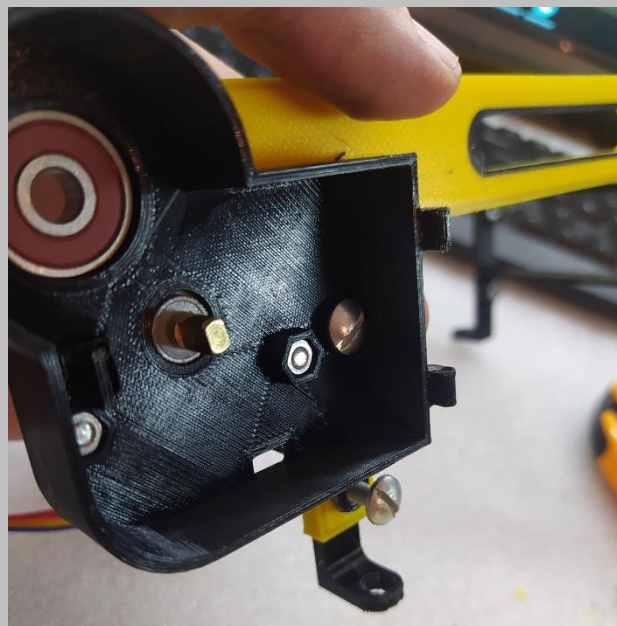
M6



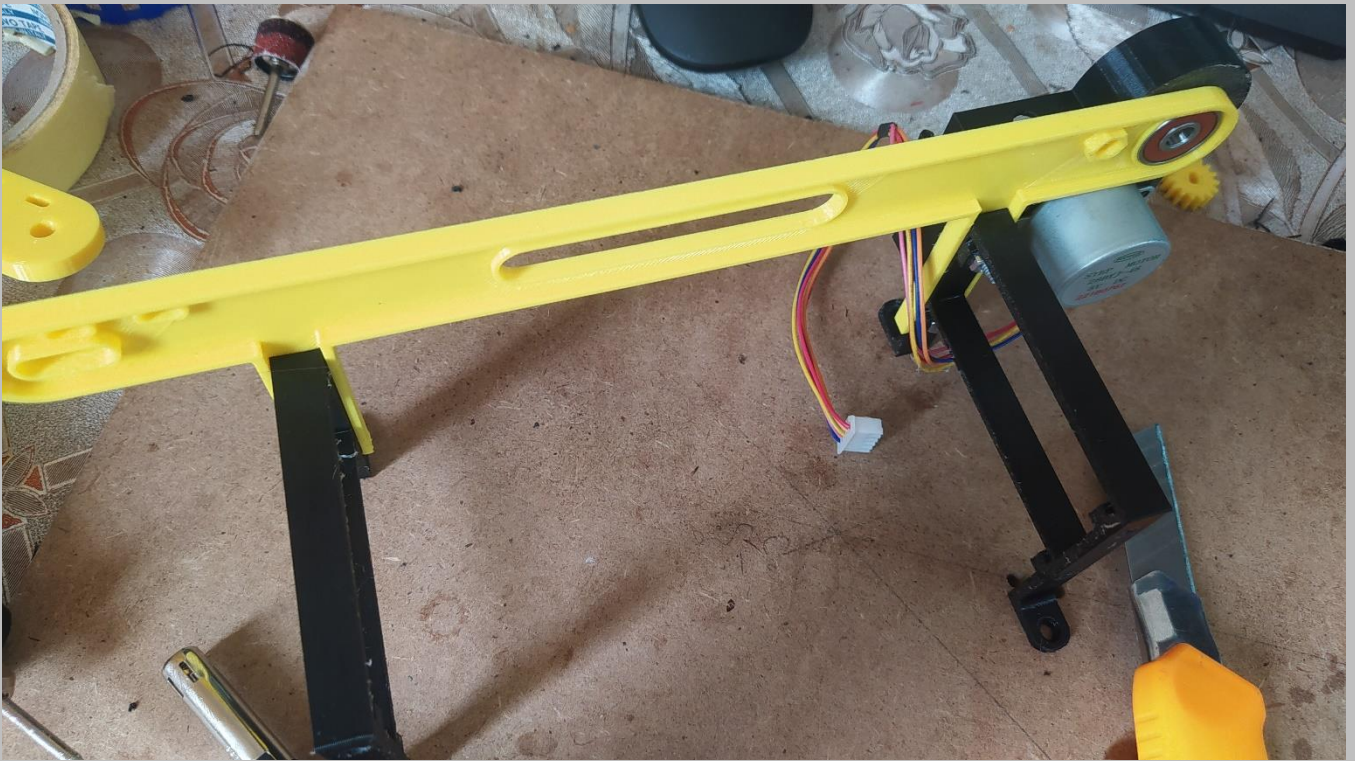
For the coupling using the M6 25mm bolt



Fix the motor use the M3 bolt



Fix the gear box use the M4 bolt

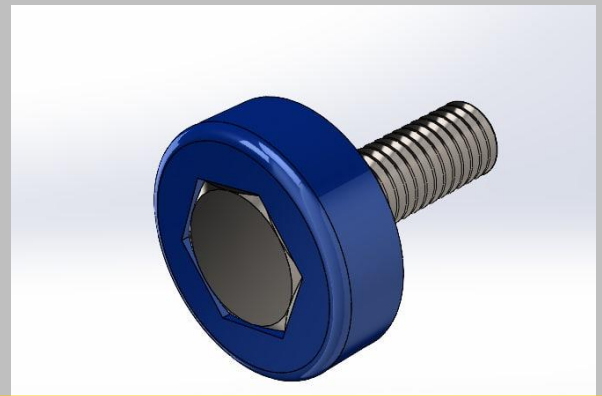
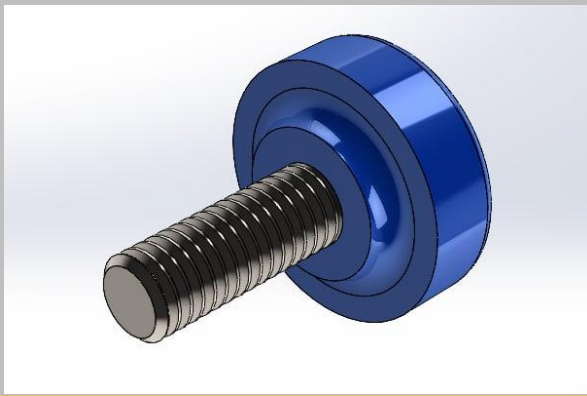


Fix the chassie and right side using the M4 bolt



Fix the bearings for the first one you don't need glue for them

For the coupling we will use the glue to fix but before that



Don't forget to put the bolt M6 20mm not a nut



Before fix the other bearing you have to put the M6 20mm or 25mm bolt inside the roulou (cylinder)





Now Fix the bearings glue not required



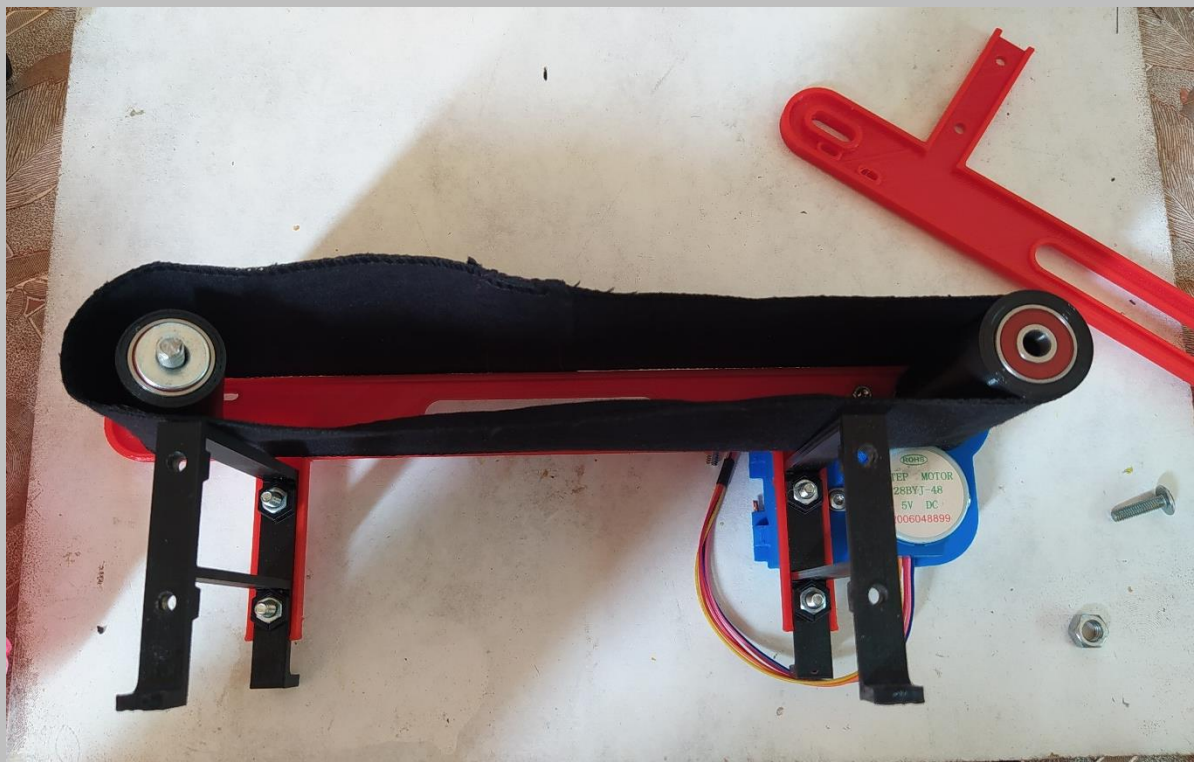
When you flip the cylinder, the bolt will appear



The belt or the cloth



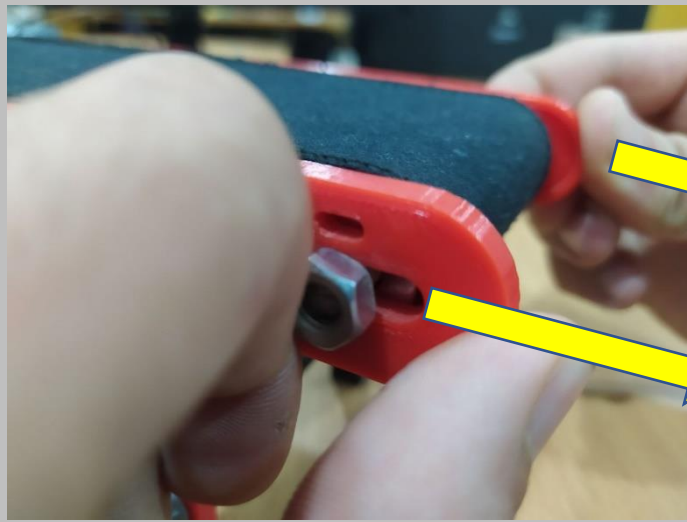
Don't forget the washers (tow washers)



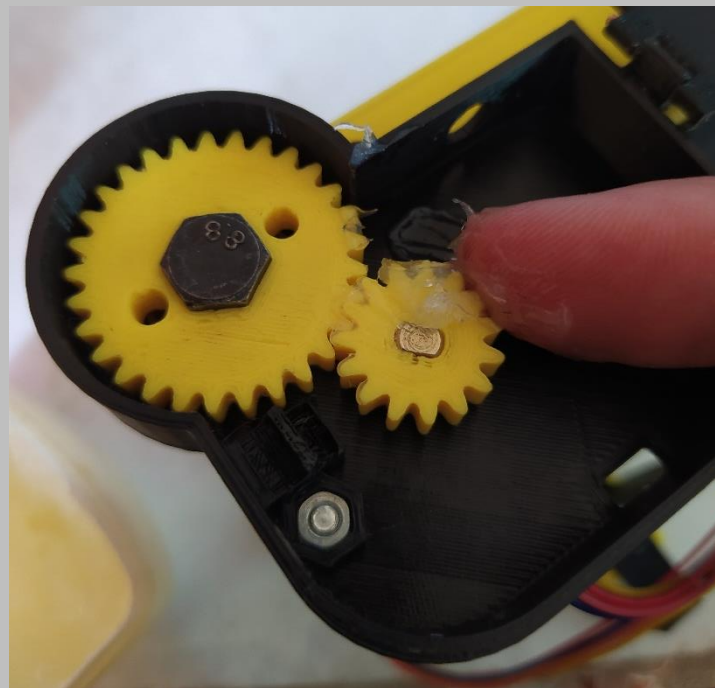
Now put on the cloth



Fix the second side with M6 nuts and M4 for the chassie bolts



Not too much

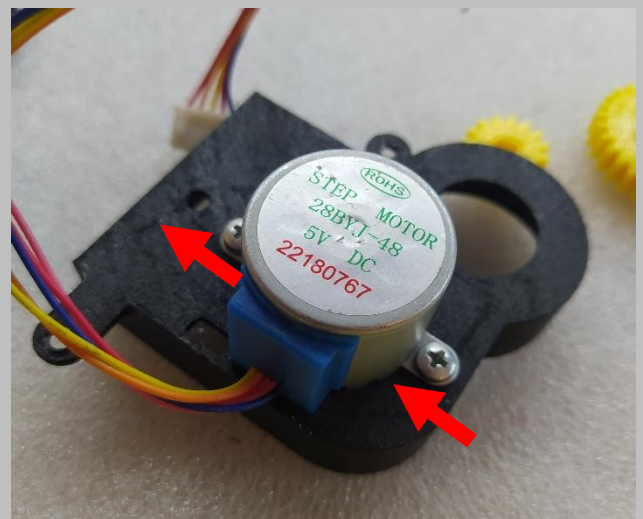


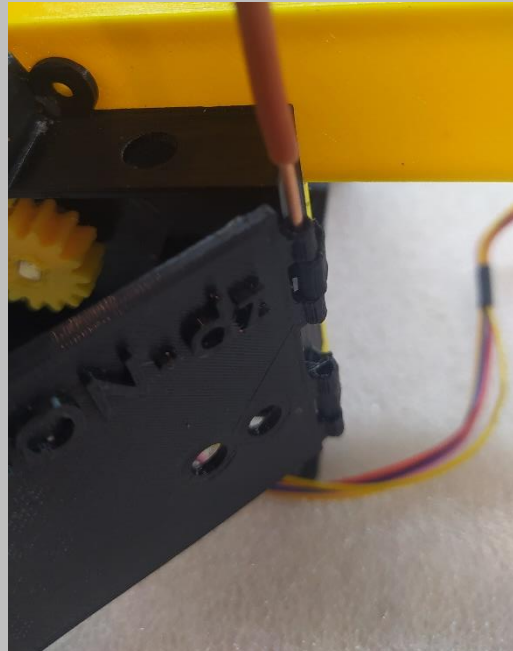
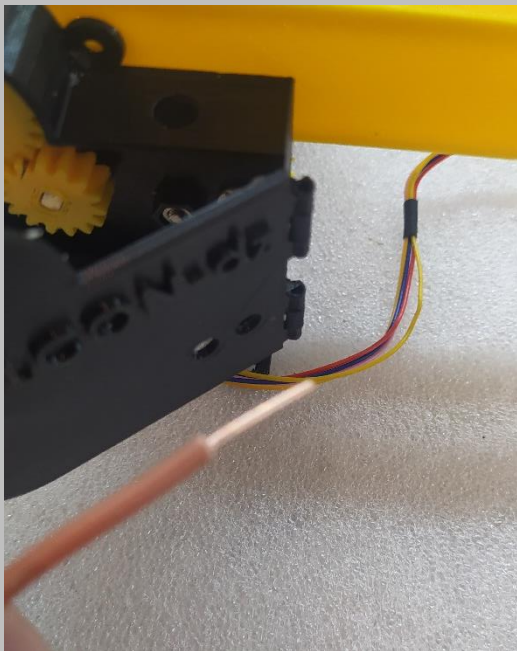
Fix the two gears starting with the big one

note well:

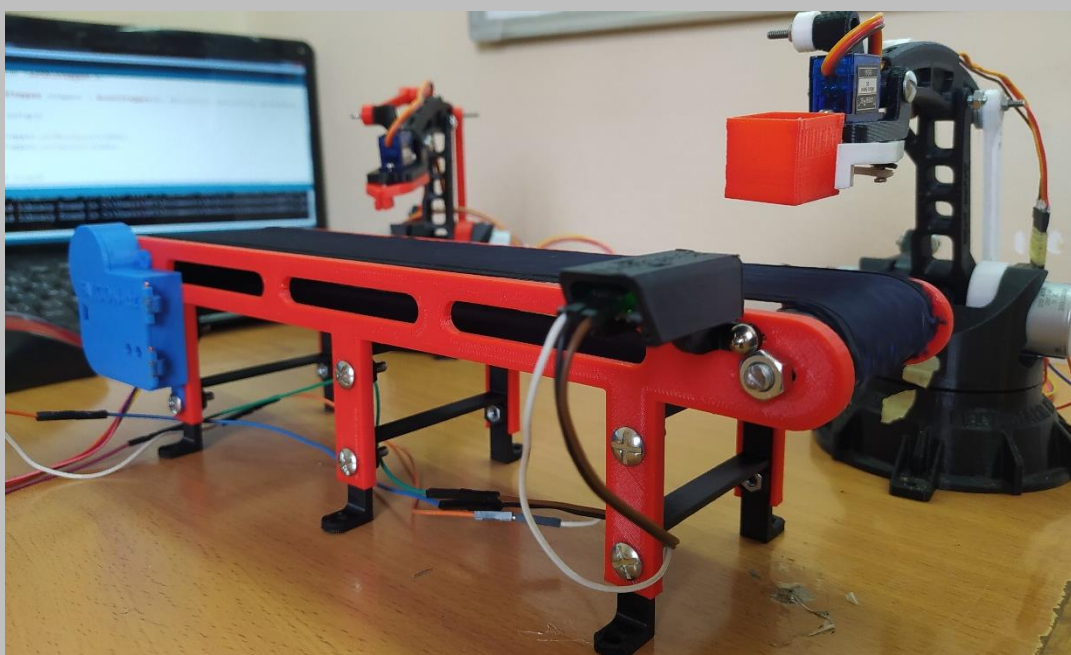
when you **finish** the assembly
and when the motor start
rotating

you have to adjust it by move it
little bit to the left, try until the
gears rotate smoothly



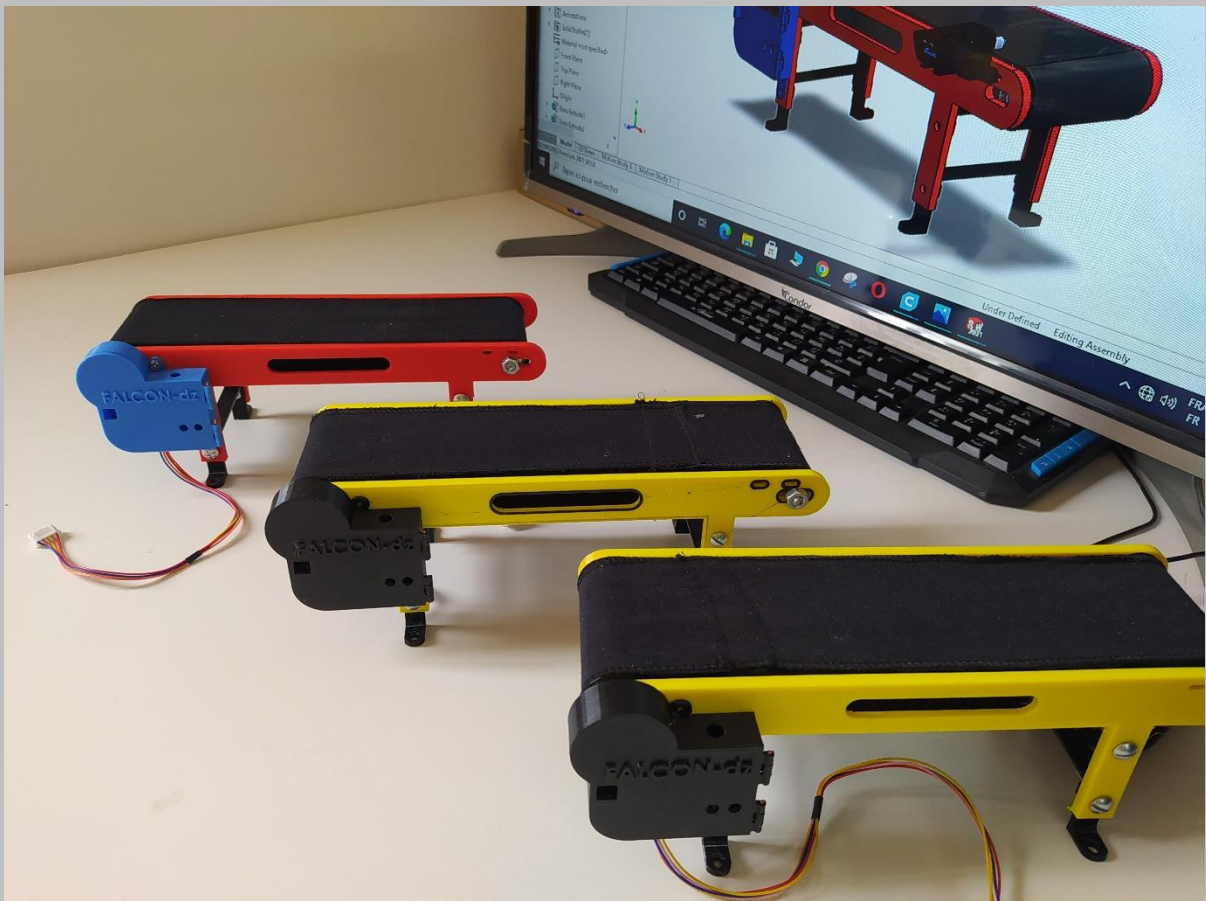
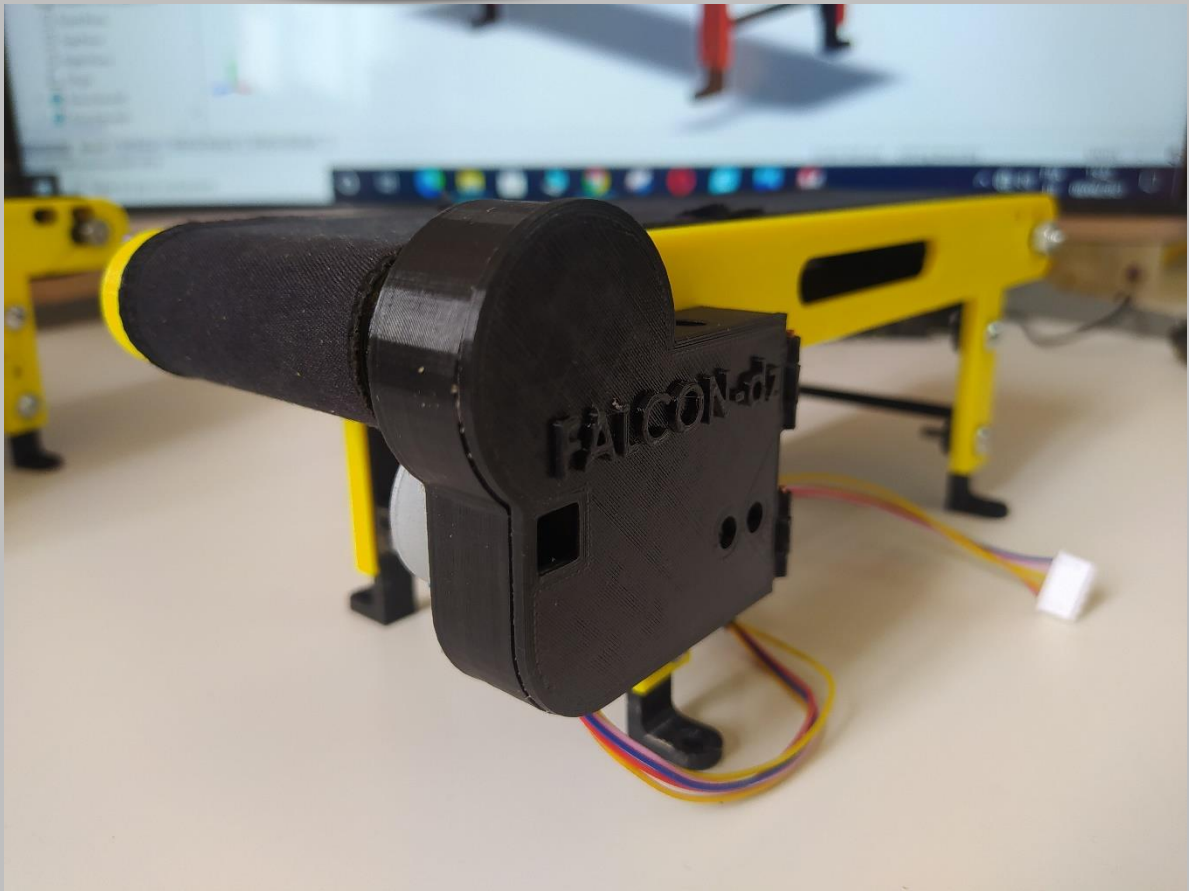


To fix the door use a wire of electricity or nail



The IR holder

congratulation



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