COMP 440 Homework 6

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1 Hidden Markov Models

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• S = \{s_{\text{enough}}, s_{\text{not}}\}
   O = \{(o_{\text{red, sleep}}, o_{\text{not red, sleep}}, o_{\text{red, not sleep}}, o_{\text{not red, not sleep}})\}
   a_{\text{not, not}} = 0.7
   a_{\text{not, enough}} = 0.3
   a_{\text{enough, not}} = 0.2
   a_{\text{enough, enough}} = 0.8
   b_{\rm not}({\rm red, sleep}) = 0.7 \times 0.3 = 0.21
   b_{\rm not}({\rm not \ red, \ sleep}) = 0.3 \times 0.3 = 0.09
   b_{\rm not}({\rm red, not sleep}) = 0.7 \times 0.7 = 0.49
   b_{\rm not}(\text{not red, not sleep}) = 0.3 \times 0.7 = 0.21
   b_{\text{enough}}(\text{red, sleep}) = 0.2 \times 0.1 = 0.02
   b_{\text{enough}}(\text{not red, sleep}) = 0.8 \times 0.1 = 0.08
   b_{\text{enough}}(\text{red, not sleep}) = 0.2 \times 0.9 = 0.18
   b_{\text{enough}}(\text{not red, not sleep}) = 0.8 \times 0.9 = 0.72
   \pi_{\rm enough} = 0.7
   \pi_{\rm not} = 0.3
   \lambda = (A, B, \Pi) specifies the HMM model.
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• \alpha_0(\text{enough}) = 0.7

\alpha_0(\text{not}) = 0.3

\alpha_1(\text{enough}) = b_{\text{enough}}(\text{not red, not sleep})(\alpha_0(\text{enough})a_{\text{enough, enough}} + \alpha_0(\text{not})a_{\text{not, enough}}) = 0.468

\alpha_1(\text{not}) = b_{\text{not}}(\text{not red, not sleep})(\alpha_0(\text{enough})a_{\text{enough, not}} + \alpha_0(\text{not})a_{\text{not, not}}) = 0.0735

So P(EnoughSleep<sub>1</sub>|e<sub>1</sub>) = \frac{0.468}{0.468+0.0735} = 0.8643.

\alpha_2(\text{enough}) = b_{\text{enough}}(\text{red, not sleep})(\alpha_1(\text{enough})a_{\text{enough, enough}} + \alpha_1(\text{not})a_{\text{not, enough}}) = 0.071361

\alpha_2(\text{not}) = b_{\text{not}}(\text{red, not sleep})(\alpha_1(\text{enough})a_{\text{enough, not}} + \alpha_1(\text{not})a_{\text{not, not}}) = 0.0710745

So P(EnoughSleep<sub>2</sub>|e<sub>1</sub>, e<sub>2</sub>) = \frac{0.071361}{0.071361+0.0710745} = 0.5010.

\alpha_3(\text{enough}) = b_{\text{enough}}(\text{red, sleep})(\alpha_2(\text{enough})a_{\text{enough, enough}} + \alpha_2(\text{not})a_{\text{not, enough}}) = 1.568 \times 10^{-3}

\alpha_3(\text{not}) = b_{\text{not}}(\text{red, sleep})(\alpha_2(\text{enough})a_{\text{enough, not}} + \alpha_2(\text{not})a_{\text{not, not}}) = 13.445 \times 10^{-3}

So P(EnoughSleep<sub>3</sub>|e<sub>1</sub>, e<sub>2</sub>, e<sub>3</sub>) = \frac{1.568 \times 10^{-3}}{1.568 \times 10^{-3} + 13.445 \times 10^{-3}} = 0.1044.
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• $\beta_3(\text{enough}) = 1$ $\beta_3(\text{not}) = 1$ So P(EnoughSleep₃|e₁, e₂, e₃) = $\frac{\beta_3(\text{enough})P(\text{EnoughSleep}_3|e_1, e_2, e_3)}{\beta_3(\text{enough})P(\text{EnoughSleep}_3|e_1, e_2, e_3) + \beta_3(\text{not})(1-P(\text{EnoughSleep}_3|e_1, e_2, e_3))}$ = 0.1044. $\beta_2(\text{enough}) = a_{\text{enough, not}}b_{\text{not}}(\text{red, sleep})\beta_3(\text{not}) + a_{\text{enough, enough}}b_{\text{enough}}(\text{red, sleep})\beta_3(\text{enough}) = 0.058$ $\beta_2(\text{not}) = a_{\text{not, not}}b_{\text{not}}(\text{red, sleep})\beta_3(\text{not}) + a_{\text{not, enough}}b_{\text{enough}}(\text{red, sleep})\beta_3(\text{enough}) = 0.153$ So P(EnoughSleep₂|e₁, e₂, e₃) = $\frac{\beta_2(\text{enough})P(\text{EnoughSleep₂|e_1,e_2})}{\beta_2(\text{enough})P(\text{EnoughSleep₂|e_1,e_2}) + \beta_2(\text{not})(1-P(\text{EnoughSleep₂|e_1,e_2}))} = 0.2757.$ $\beta_1(\text{enough}) = a_{\text{enough, not}}b_{\text{not}}(\text{red, not sleep})\beta_2(\text{not}) + a_{\text{enough, enough}}b_{\text{enough}}(\text{red, not sleep})\beta_2(\text{enough}) = 0.023346$ $\beta_1(\text{not}) = a_{\text{not, not}}b_{\text{not}}(\text{red, not sleep})\beta_2(\text{not}) + a_{\text{not, enough}}b_{\text{enough}}(\text{red, not sleep})\beta_2(\text{enough}) = 0.055611$ So P(EnoughSleep₁|e₁, e₂, e₃) = $\frac{\beta_1(\text{enough})P(\text{EnoughSleep₁|e_1})}{\beta_1(\text{enough})P(\text{EnoughSleep₁|e_1})} = 0.7278.$

• The smoothed probabilities for t = 1, 2 are lower than the filtered probability, because smoothing takes into account the future evidence that favors the occurrence of not getting enough sleep. It is as expected that the two probabilities are the same when t = 3.

2 Understanding human emotions

The hidden variable is E_t, whose domain is S = {s_{sadness}, s_{surprise}, s_{joy}, s_{disgust}, s_{anger}, s_{fear}}
The observed variable is C_t, whose domain is O = {o_{angular}, o_{glideup}, o_{descending}, o_{flat}, o_{irregular}}
The dimensions of the state transition conditional probability table A is 6.
The dimensions of the emission conditional probability table B is 5 × 6.
A reasonable probability distribution Π for E_t at t = 0 would be all six π = 1/6.

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$$P(C_1 = o_1, ..., C_n = o_n) = \sum_{s \in S^n} P(E_1 = s_1, ..., E_n = s_n, C_1 = o_1, ..., C_n = o_n)$$

$$= \sum_{s \in S^n} [\pi_{s_1} b_{s_1}(c_1) \prod_{i=2}^n a_{s_{i-1}, s_i} b_{s_i}(c_i)]$$

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$$P(R = x | C = c) = \alpha P(C = c) P(R = x) = \alpha \Theta_x \phi_x$$

3 Conditional random fields and named entity recognition

Problem 3.3: Handling long-range dependencies

Gibbs sampling for linear chain CRF

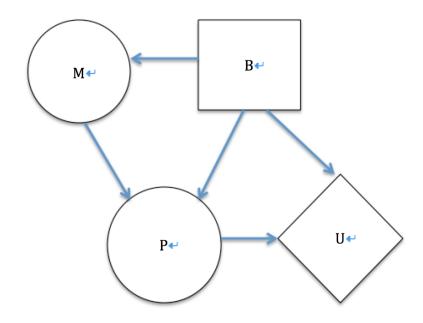
$$P(y_{t}|y_{-t}, x; \theta) = \frac{P(y|x; \theta)}{P(y_{-t}|x; \theta)}$$

$$= \frac{G_{t}(y_{t-1}, y_{t}|x; \theta)G_{t+1}(y_{t}, y_{t+1}|x; \theta)}{\sum_{y' \in Y} G_{t}(y_{t-1}, y'|x; \theta)G_{t+1}(y', y_{t+1}|x; \theta)}$$

Special case: when t = T then

$$P(y_t|y_{-t}, x; \theta) = \frac{G_t(y_{t-1}, y_t|x; \theta)}{\sum_{y' \in Y} G_t(y_{t-1}, y'|x; \theta)}$$

4 Decision networks



- $U(b) = 2000 * P(p|b) 100 = 2000 * (P(p|b,m) * P(m|b) + P(p|b,\neg m) * P(\neg m|b)) 100 = 2000 * (0.9 * 0.9 + 0.5 * 0.1) 100 = 1620$ $U(\neg b) = 2000 * P(p|\neg b) = 2000 * (P(p|\neg b,m) * P(m|\neg b) + P(p|b,\neg m) * P(\neg m|\neg b)) = 2000 * (0.8 * 0.7 + 0.3 * 0.3) = 1300$
- $U(b) > U(\neg b)$, so the optimal decision for Sam is to buy the book.