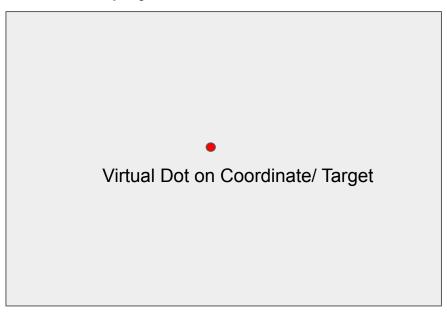
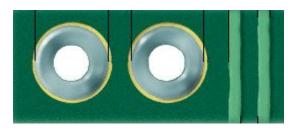


**Confidential Document** 

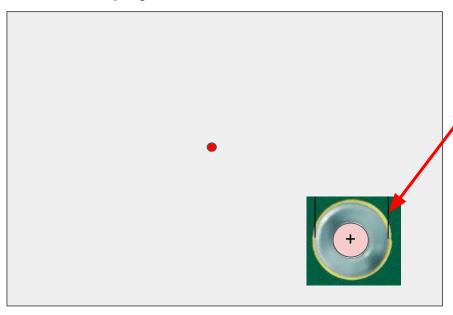
### Camera display



### **Consider Object Under Camera**

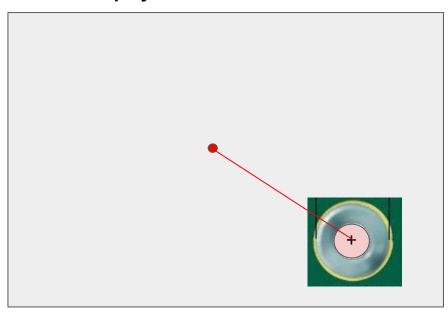


### Camera display



Whenever Object Detects on Camera Display, Algorithm should capture the median

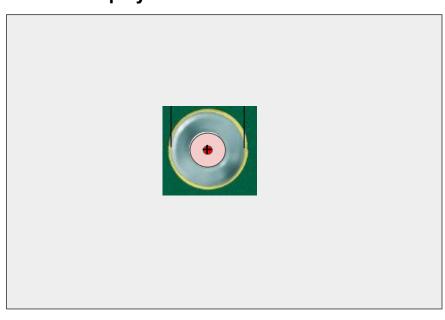
### Camera display



Algorithm should guide to reach the median to virtual dot.

When both the dots are not matching the Value of Target signal will be False

### Camera display



Once median reaches to virtual dot or Target, Algorithm should give True to the Target Signal.

# Software Requirements

Python 3.6 and above

OpenCV

Tkinter for UI

Note: Provide facility to change the Virtual Dot/Target to set.

Provide facility to train the object to calculate the median.