

Planning assumptions - vacuum world example

State₁ $\xrightarrow{\text{Action}}$ State₂

In State₂: $\neg In(B)$ holds
Assignment Project Exam Help

<https://tutorcs.com>

What can you say about Action? State₁?

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- Action is not a move into B
- Action is a move from B or the vacuum cleaner is not in B in State₁

