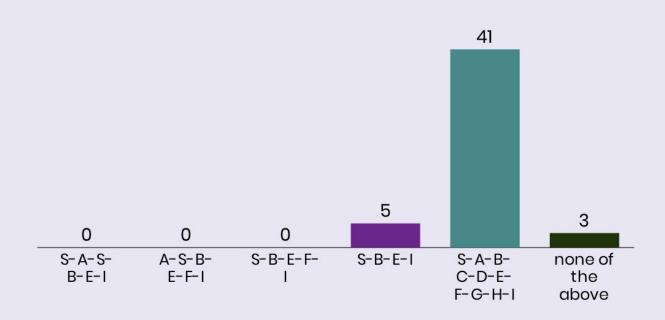
Breadth-first (shallowest)



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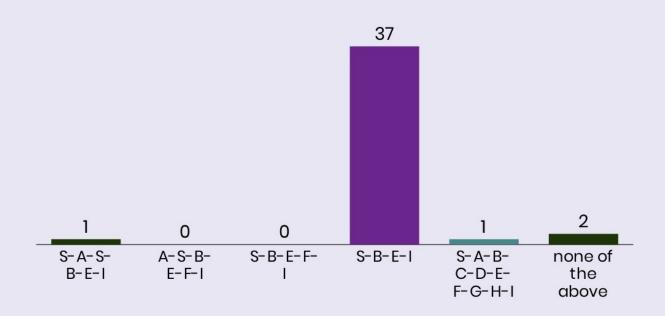
uniform-cost (lowest path cost): best path?



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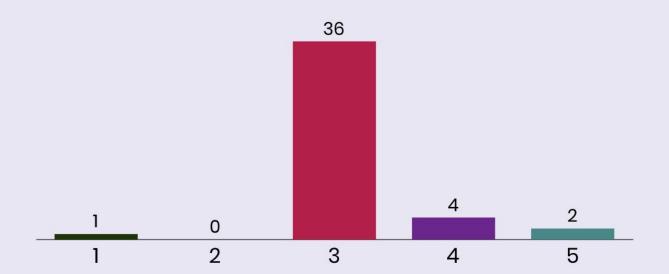
depth-first (deepest)



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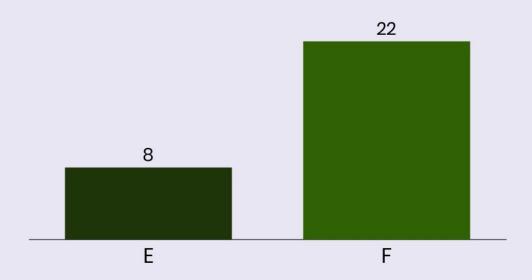
Least depth for depth-limited?



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Which node will A* search expand first?

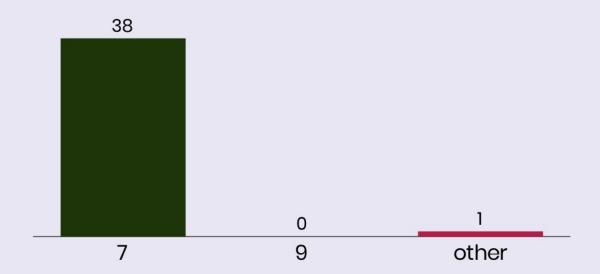


4 30

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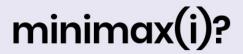
minimax(h)?



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4 39

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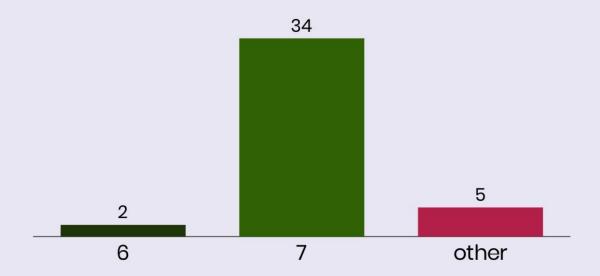




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minimax(d)?



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minimax(e)?





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minimax(b)?





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minimax(c)?



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minimax(a)?

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