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# CIS 471/571 (Fall 2020): Introduction to Artificial Intelligence

Assignment Project Exam Help

## Lecture 7: Expectimax, Utilities

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Source: <http://ai.berkeley.edu/home.html>



# Reminders

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- Project 2: Multi-agent Search

- Deadline: Oct 27th, 2020

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- Homework 2: CSPs and Games

- Deadline: Oct 24th, 2020

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# Today

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- Expectimax Search

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- Utilities

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# Uncertain Outcomes

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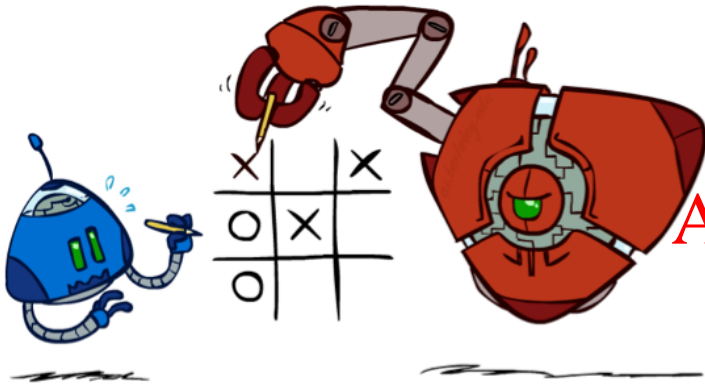
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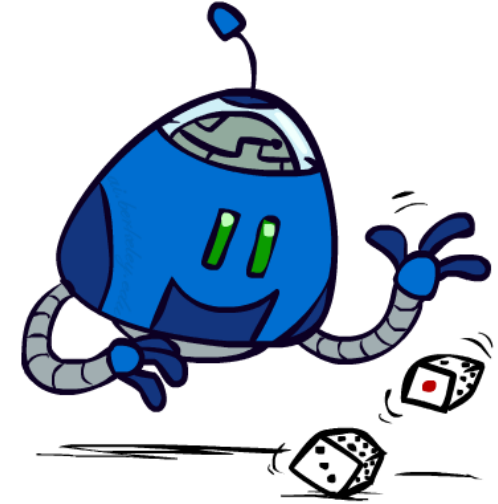
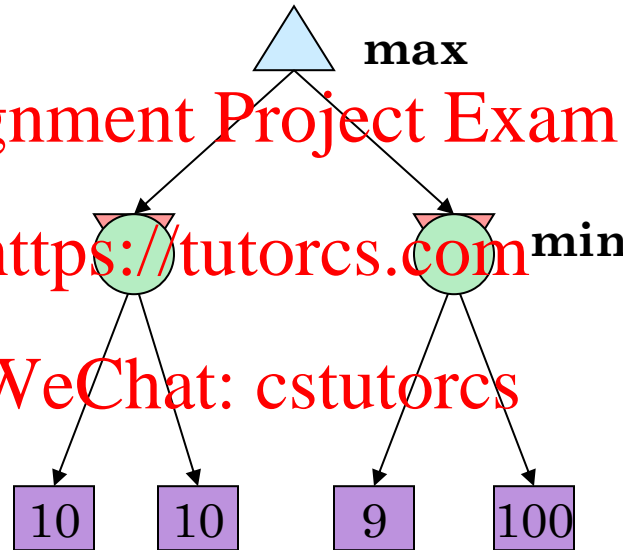
# Worst-Case vs. Average Case



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Idea: Uncertain outcomes controlled by chance, not an adversary!



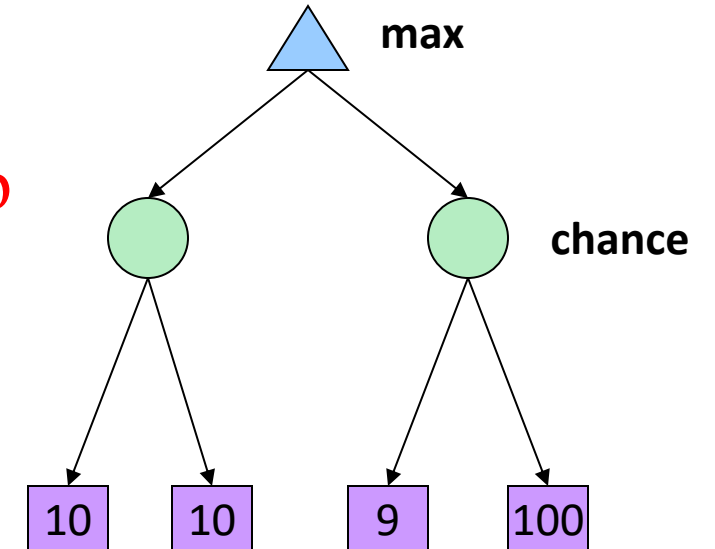
# Expectimax Search

- Why wouldn't we know what the result of an action will be?
  - Explicit randomness: rolling dice
  - Unpredictable opponents: the ghosts respond randomly
  - Actions can fail: when moving a robot, wheels might slip

- Values should now reflect average-case (expectimax) outcomes, not worst-case (minimax) outcomes

- Expectimax search:** compute the average score under optimal play
  - Max nodes as in minimax search
  - Chance nodes are like min nodes but the outcome is uncertain
  - Calculate their **expected utilities**
  - I.e. take weighted average (expectation) of children

- Later, we'll learn how to formalize the underlying uncertain-result problems as **Markov Decision Processes**



# Expectimax Pseudocode

```
def value(state):
```

```
    if the state is a terminal state: return the state's utility
```

```
    if the next agent is MAX: return max_value(state)
```

```
    if the next agent is EXP: return exp_value(state)
```

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```
def max_value(state):
```

```
    initialize v =  $-\infty$ 
```

```
    for each successor of state:
```

```
        v = max(v, value(successor))
```

```
    return v
```

```
def exp_value(state):
```

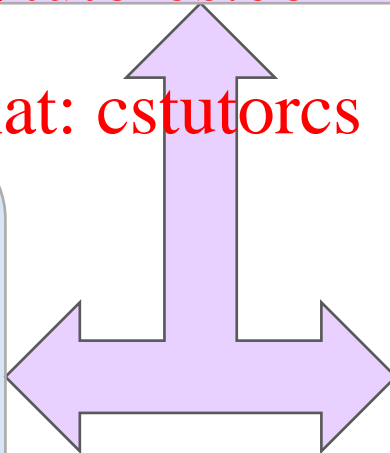
```
    initialize v = 0
```

```
    for each successor of state:
```

```
        p = probability(successor)
```

```
        v += p * value(successor)
```

```
    return v
```



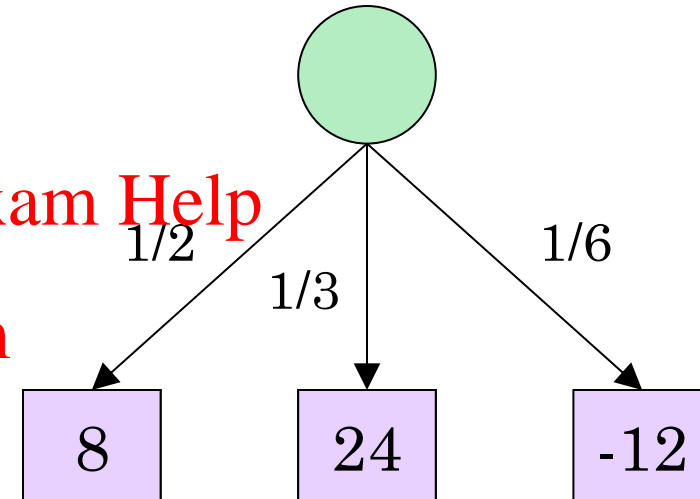
# Expectimax Pseudocode

```
def exp-value(state):  
    initialize v = 0  
    for each successor of state:  
        p = probability(successor)  
        v += p * value(successor)  
    return v
```

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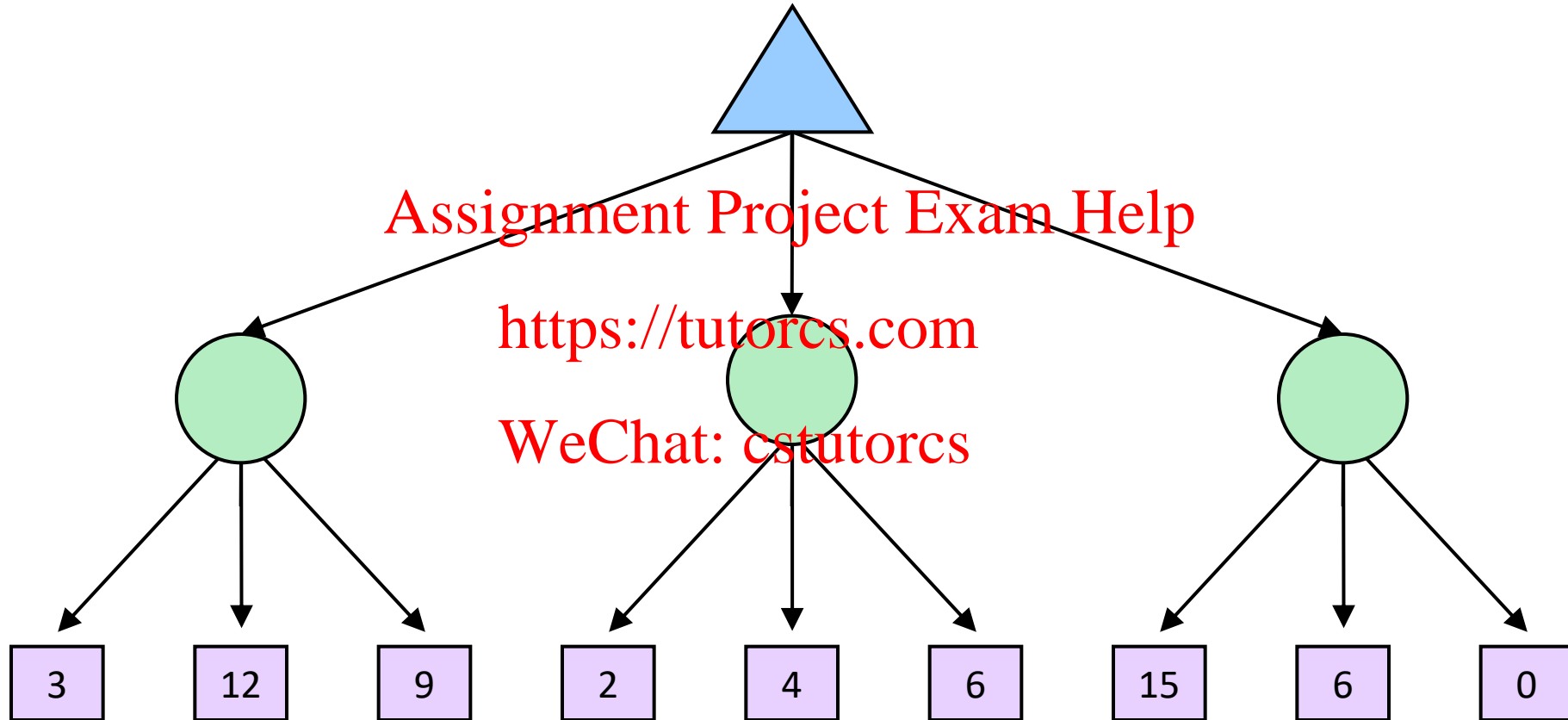
$$v = (1/2) (8) + (1/3) (24) + (1/6) (-12) = 10$$



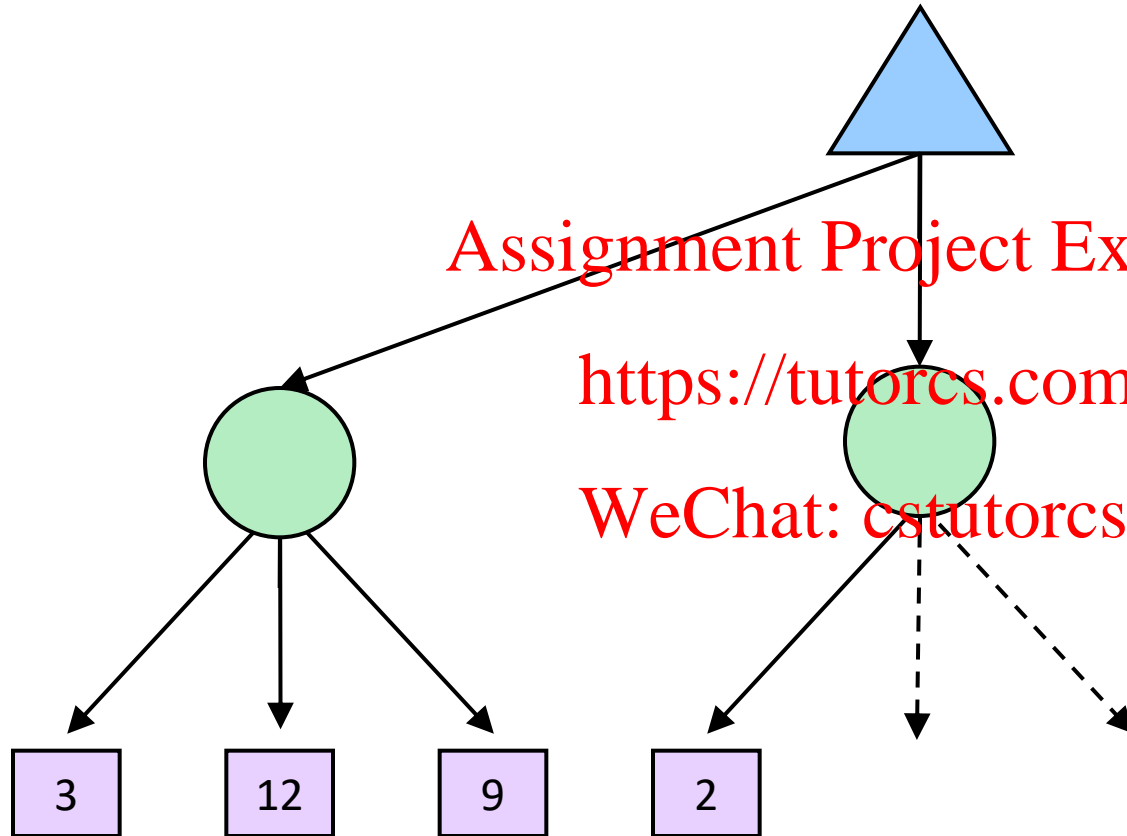


# Expectimax Example

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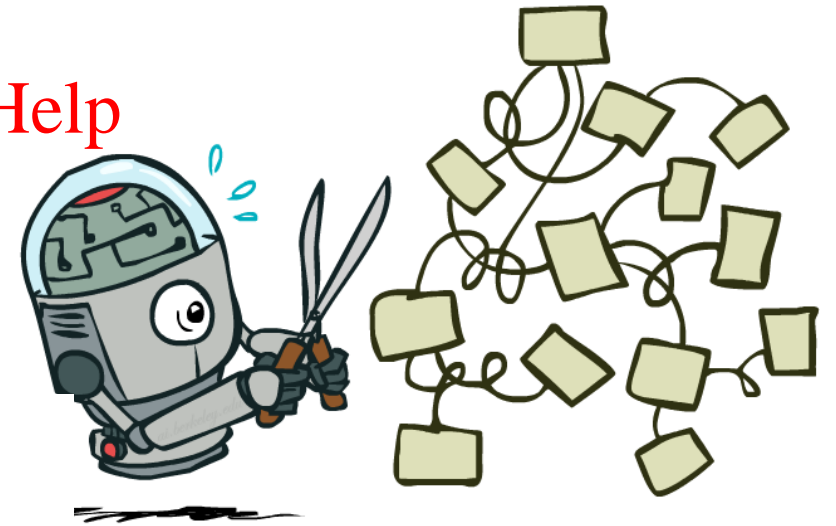
# Expectimax Pruning?



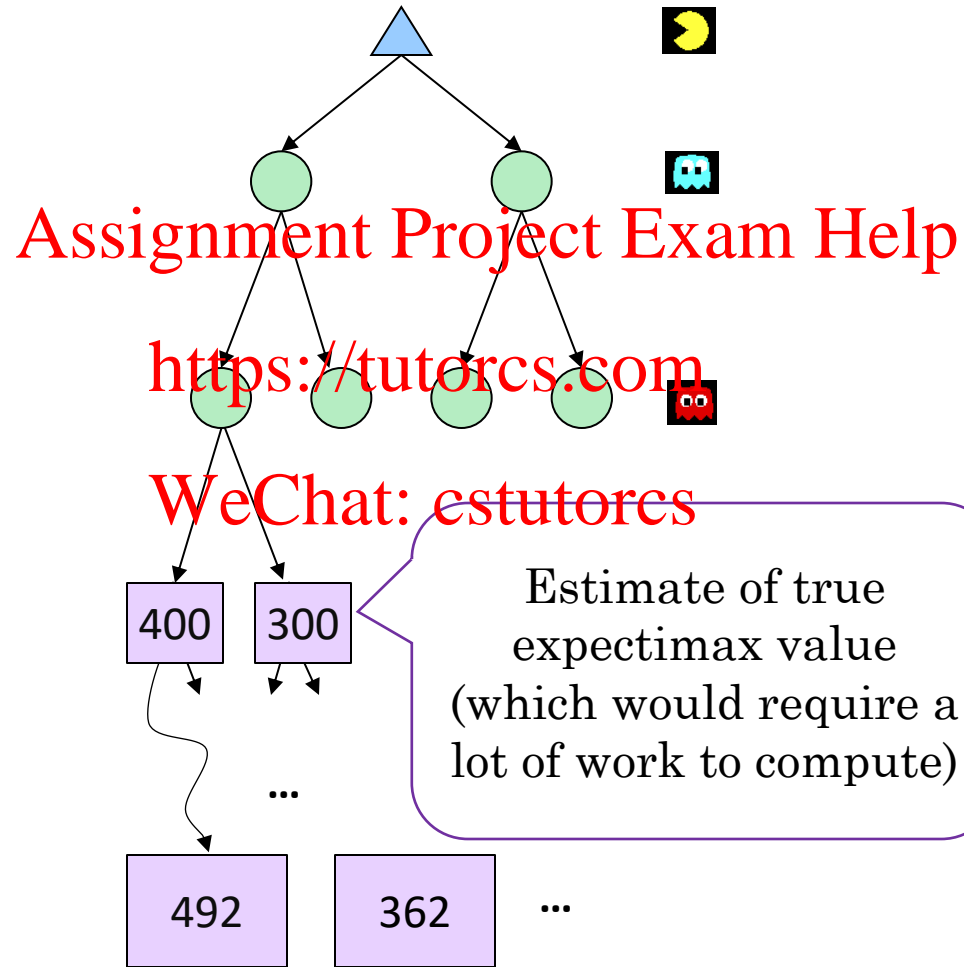
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# Depth-Limited Expectimax



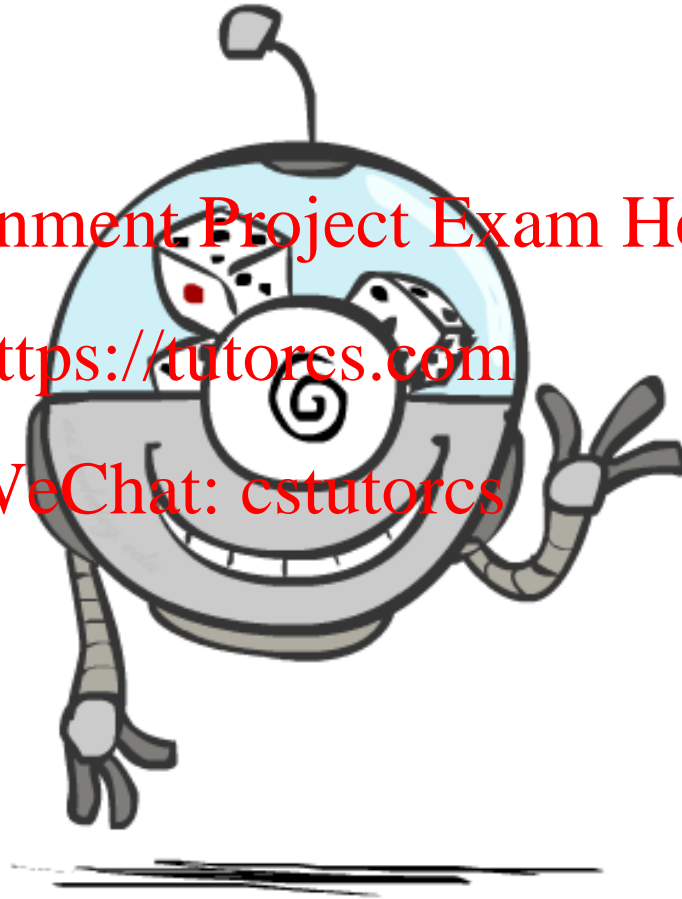
# Probabilities

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# Reminder: Probabilities

- A **random variable** represents an event whose outcome is unknown
- A **probability distribution** is an assignment of weights to outcomes

- Example: Traffic on freeway

- Random variable:  $T$  = whether there's traffic
- Outcomes:  $T$  in {none, light, heavy}
- Distribution:  $P(T=\text{none}) = 0.25$ ,  $P(T=\text{light}) = 0.50$ ,  $P(T=\text{heavy}) = 0.25$

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- Some laws of probability (more later):
  - Probabilities are always non-negative
  - Probabilities over all possible outcomes sum to one
- As we get more evidence, probabilities may change:
  - $P(T=\text{heavy}) = 0.25$ ,  $P(T=\text{heavy} \mid \text{Hour}=8\text{am}) = 0.60$
  - We'll talk about methods for reasoning and updating probabilities later



0.25



0.50



0.25



# Reminder: Expectations

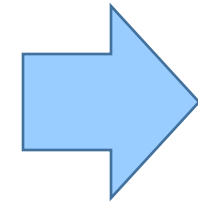
- The expected value of a function of a random variable is the average, weighted by the probability distribution over outcomes

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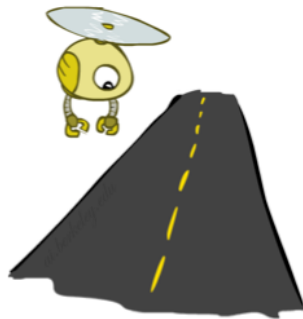
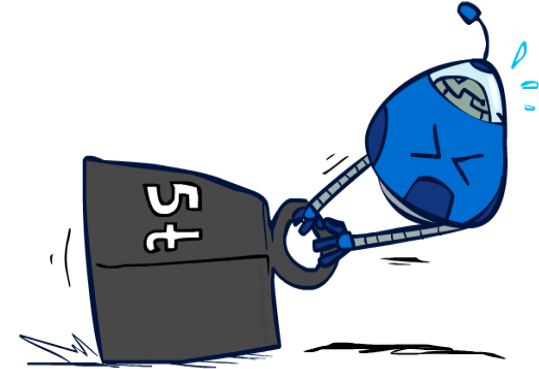
- Example: How long to get to the airport?

Time:	20 min	30 min	60 min
	x	x	x
Probability:	0.25	0.50	0.25

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35 min

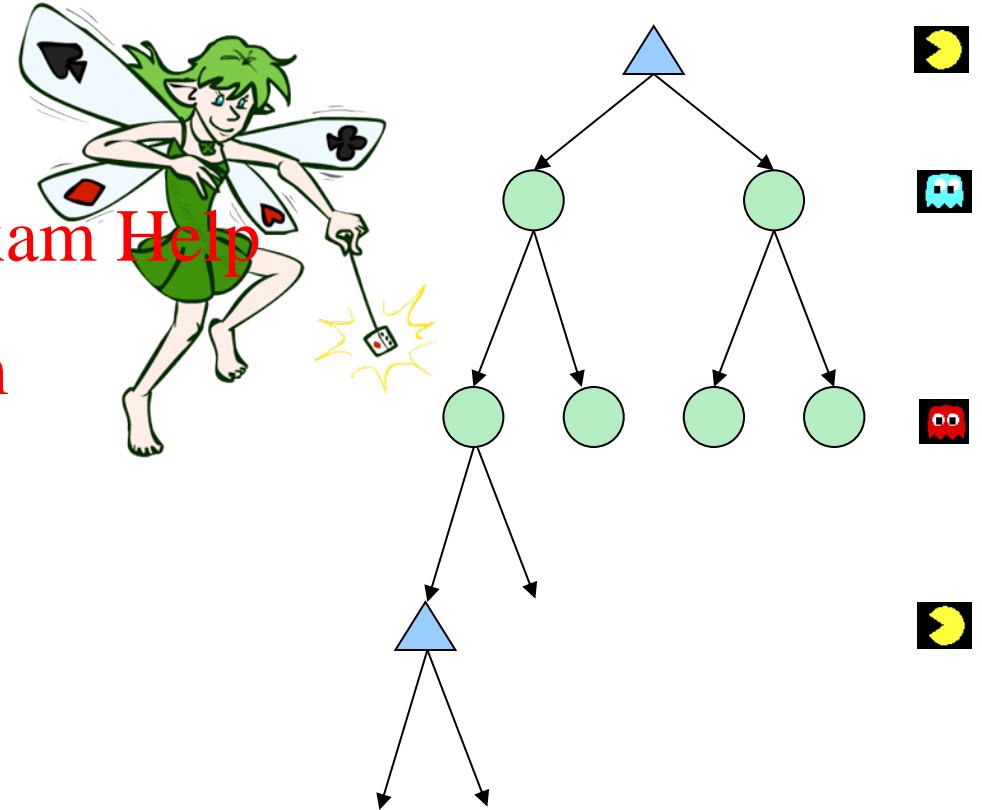


# What Probabilities to Use?

- In expectimax search, we have a probabilistic model of how the opponent (or environment) will behave in any state

- Model could be a simple uniform distribution (roll a die)
- Model could be sophisticated and require a great deal of computation
- We have a chance node for any outcome out of our control: opponent or environment
- The model might say that adversarial actions are likely!

- For now, assume each chance node magically comes along with probabilities that specify the distribution over its outcomes



*Having a probabilistic belief about another agent's action does not mean that the agent is flipping any coins!*

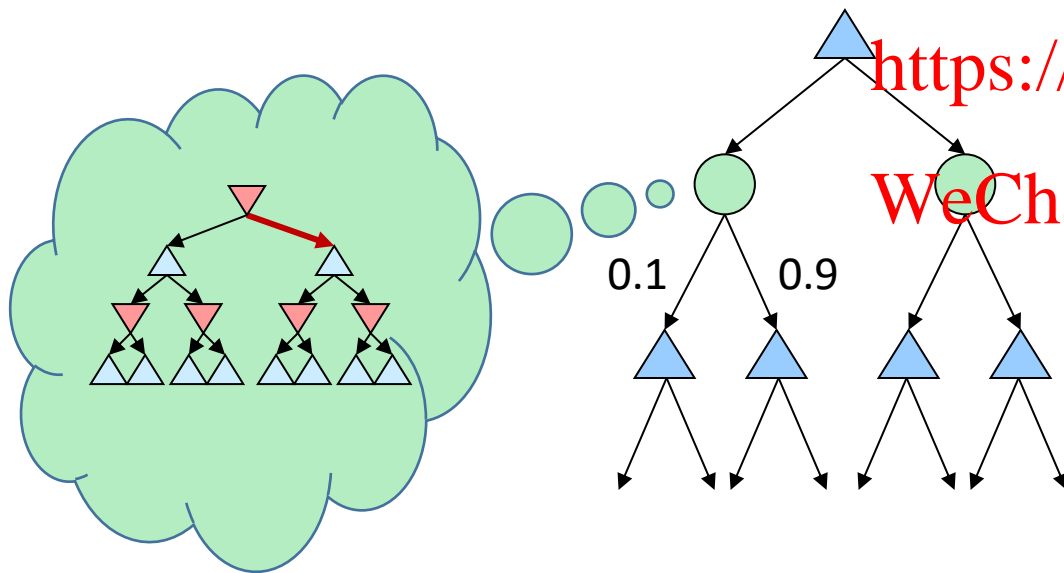
# Quiz: Informed Probabilities

- Let's say you know that your opponent is actually running a depth 2 minimax, using the result 80% of the time, and moving randomly otherwise
- Question: What tree search should you use?

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- To figure out EACH chance node's probabilities, you have to run a simulation of your opponent
- This kind of thing gets very slow very quickly
- Even worse if you have to simulate your opponent simulating you...
- ... except for minimax, which has the nice property that it all collapses into one game tree





# Modeling Assumptions

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# The Dangers of Optimism and Pessimism

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## Dangerous Optimism

Assuming chance when the world is adversarial



## Dangerous Pessimism

Assuming the worst case when it's not likely



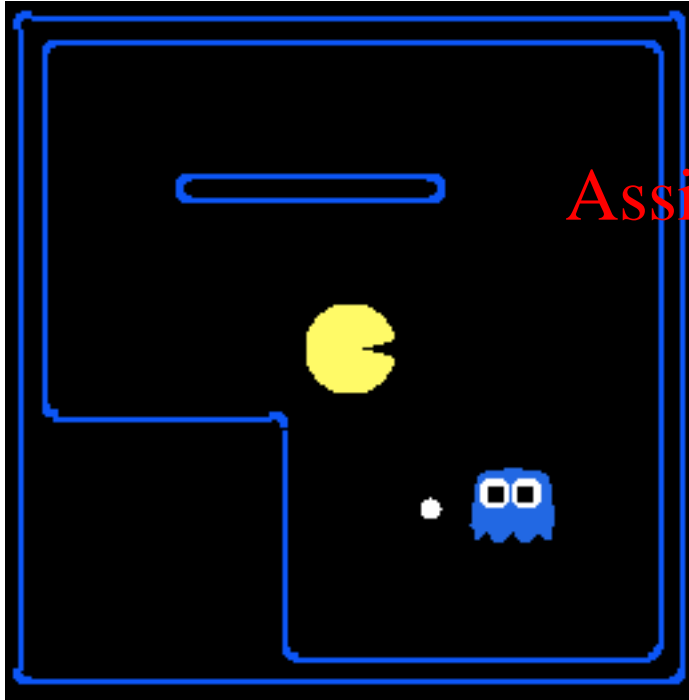
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# Assumptions vs. Reality



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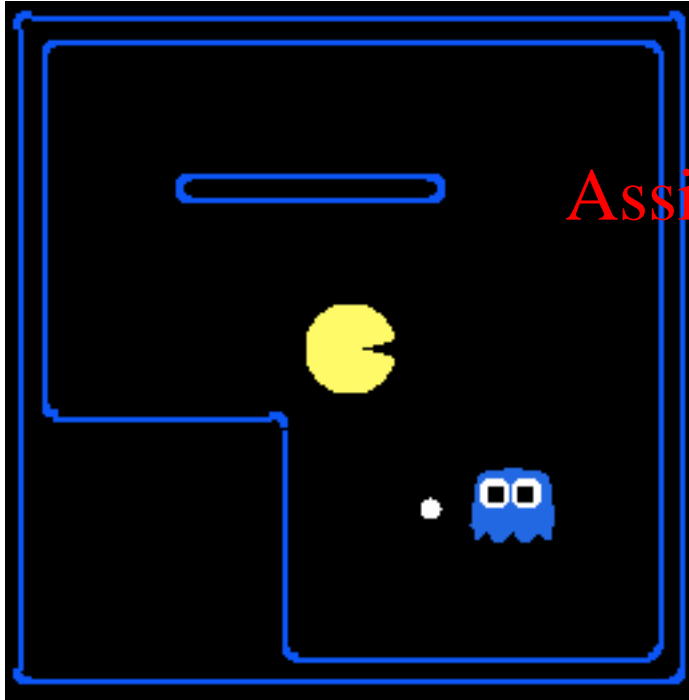
	Adversarial Ghost	Random Ghost
Minimax Pacman	1	3
Expectimax Pacman	1	1

Results from playing 5 games

Pacman used depth 4 search with an eval function that avoids trouble  
Ghost used depth 2 search with an eval function that seeks Pacman



# Assumptions vs. Reality



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	Adversarial Ghost	Random Ghost
Minimax Pacman	Won 5/5 Avg. Score: 483	Won 5/5 Avg. Score: 493
Expectimax Pacman	Won 1/5 Avg. Score: -303	Won 5/5 Avg. Score: 503

Results from playing 5 games

Pacman used depth 4 search with an eval function that avoids trouble  
Ghost used depth 2 search with an eval function that seeks Pacman



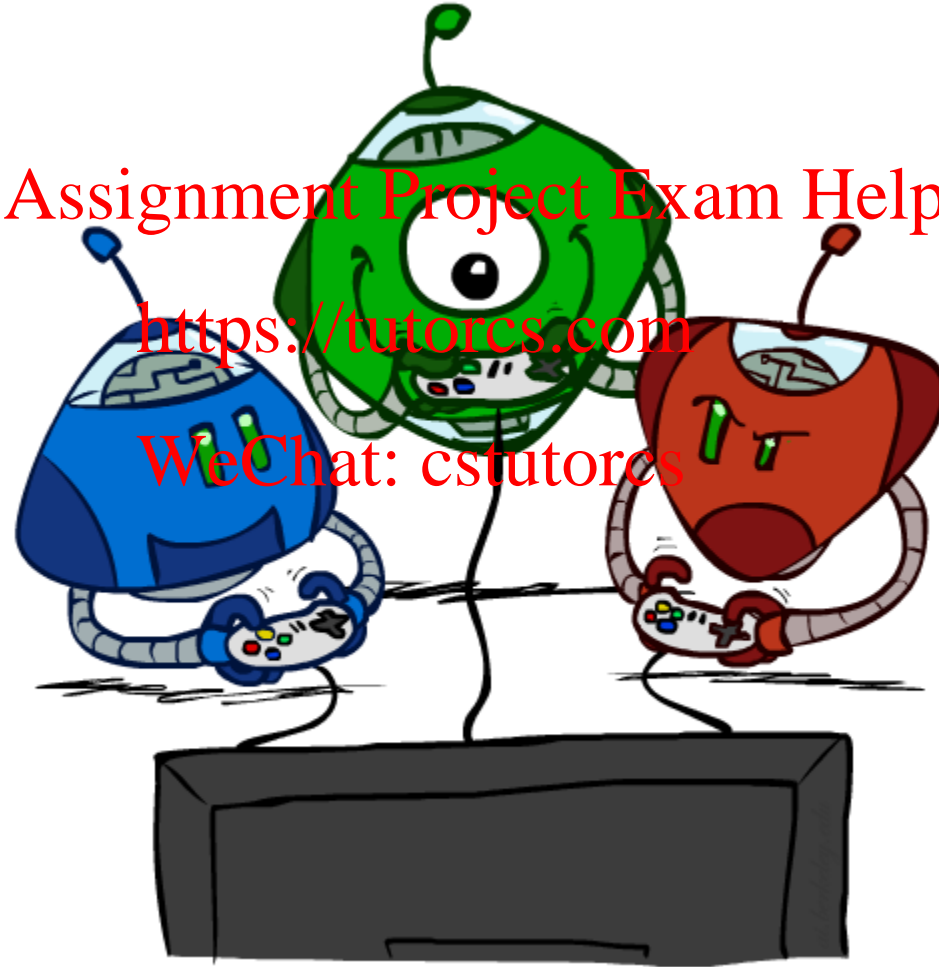
# Other Game Types

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# Mixed Layer Types

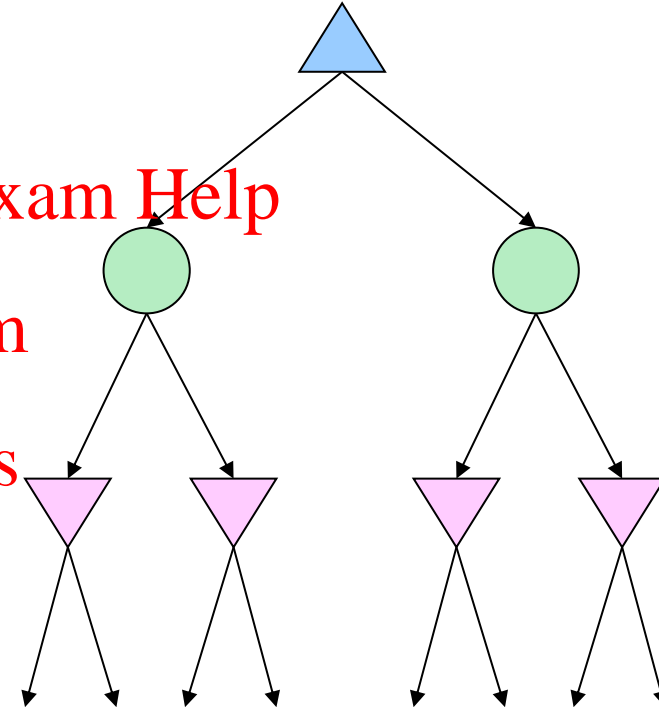
- E.g. Backgammon
- Expectiminimax
  - Environment is an extra “random agent” player that moves after each min/max agent
  - Each node computes the appropriate combination of its children



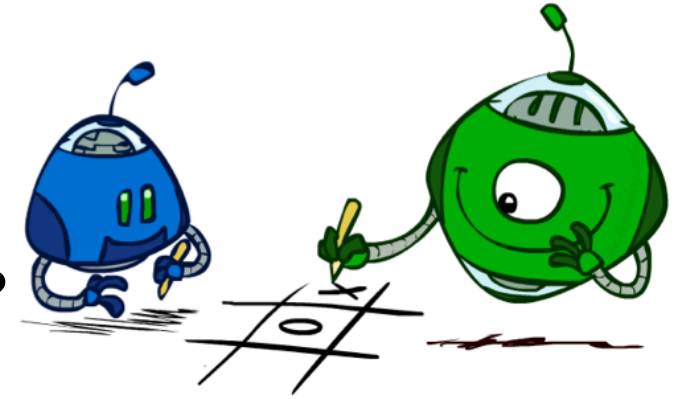
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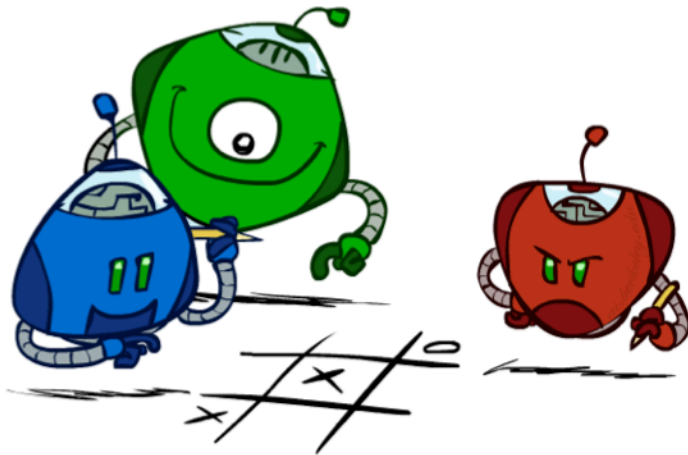
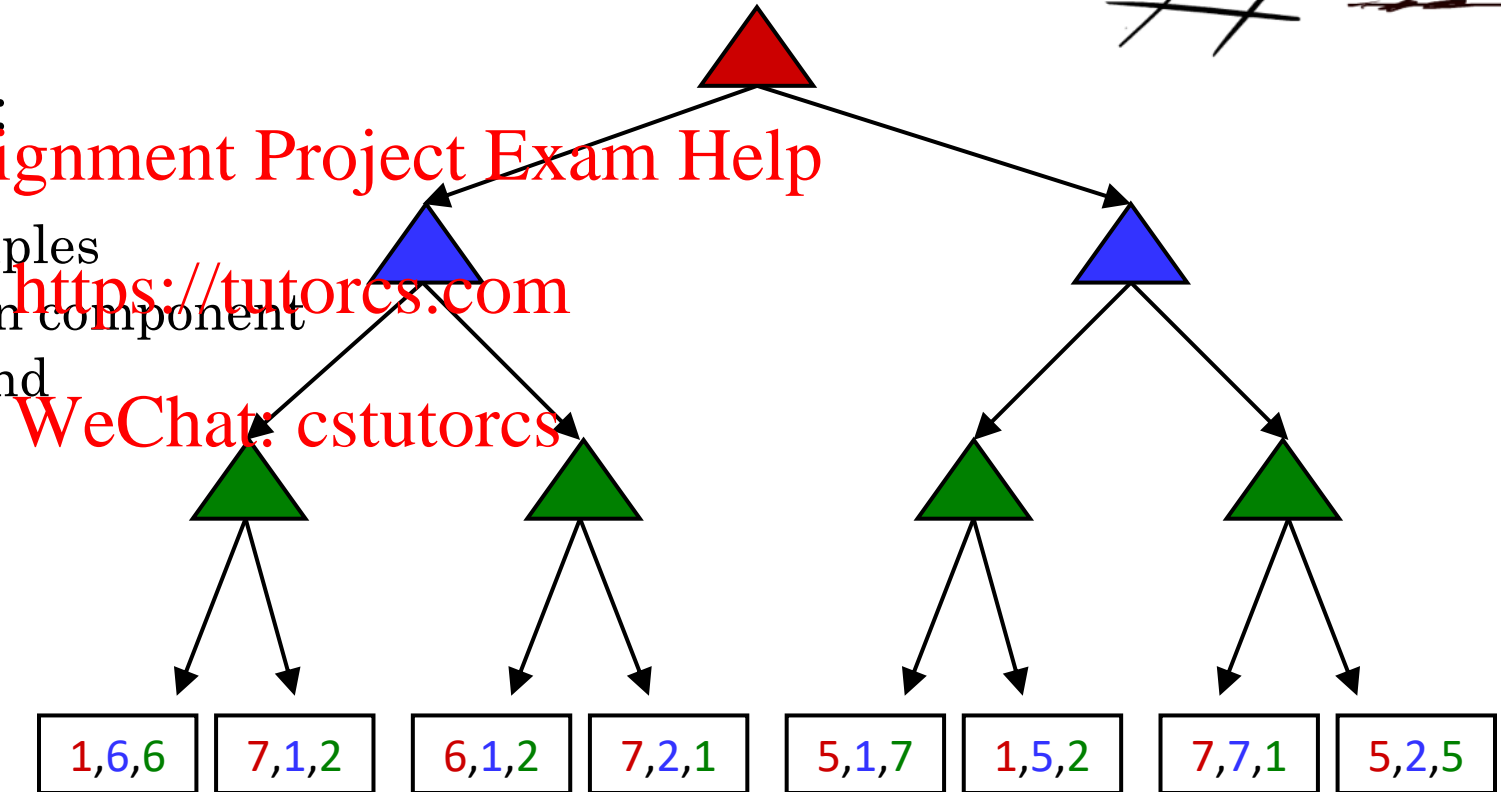
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# Multi-Agent Utilities

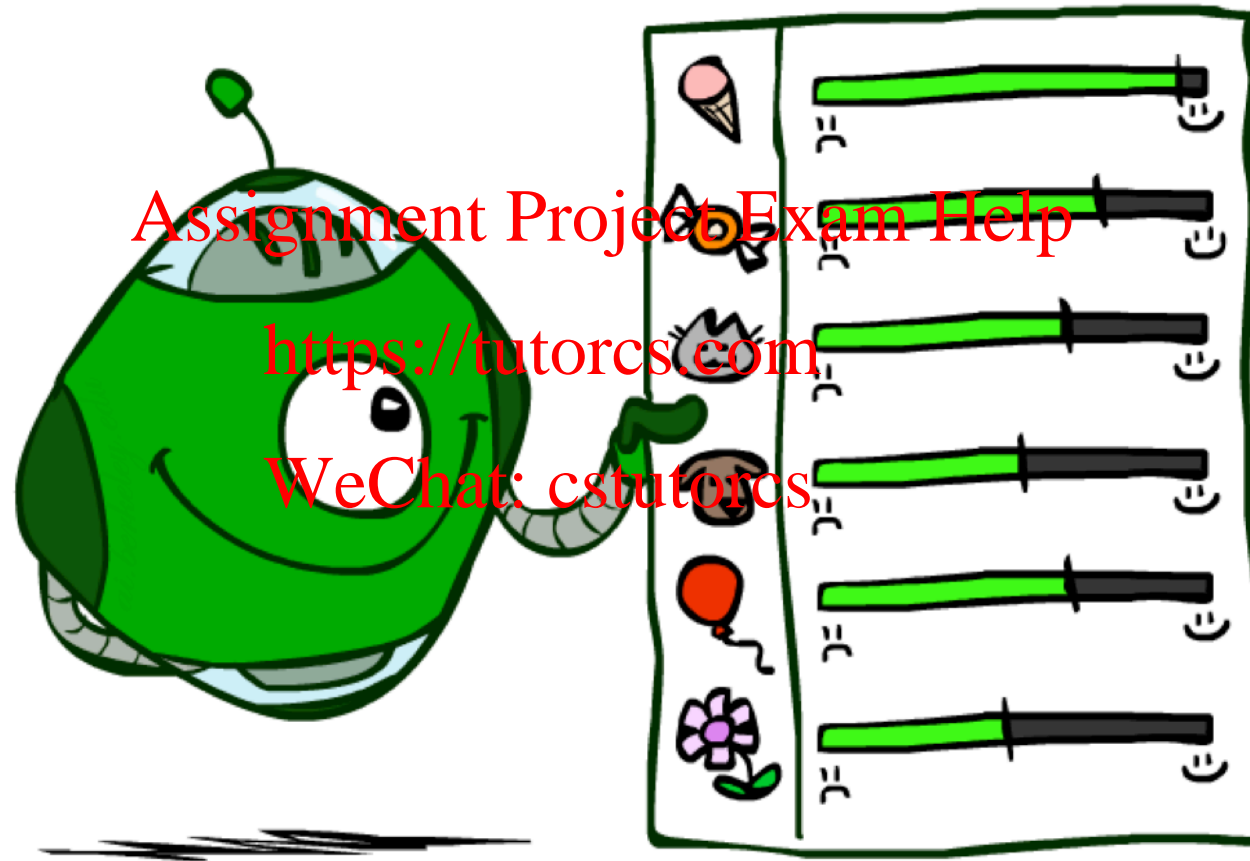


- What if the game is not zero-sum, or has multiple players?
- Generalization of minimax:
  - Terminals have utility tuples
  - Node values are also utility tuples
  - Each player maximizes its own component
  - Can give rise to cooperation and competition dynamically...



# Utilities

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# Maximum Expected Utility

- Why should we average utilities? Why not minimax?

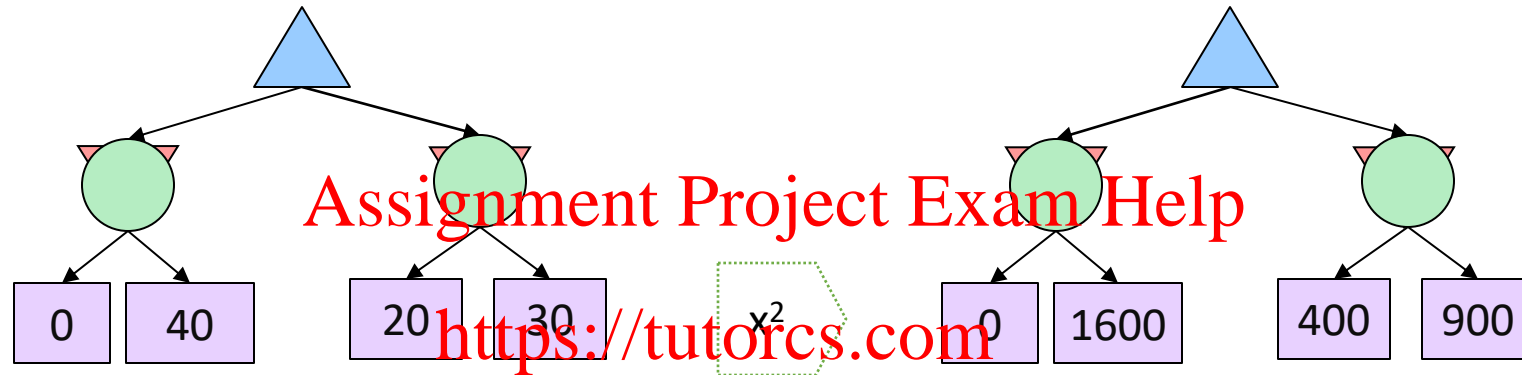
- Principle of maximum expected utility:
  - A rational agent should choose the action that maximizes its expected utility, given its knowledge

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- Questions:
  - Where do utilities come from?
  - How do we know such utilities even exist?
  - How do we know that averaging even makes sense?
  - What if our behavior (preferences) can't be described by utilities?



# What Utilities to Use?



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- For worst-case minimax reasoning, terminal function scale doesn't matter
  - We just want better states to have higher evaluations (get the ordering right)
  - We call this **insensitivity to monotonic transformations**
- For average-case expectimax reasoning, we need *magnitudes* to be meaningful



# Utilities

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- Utilities are functions from outcomes (states of the world) to real numbers that describe an agent's preferences

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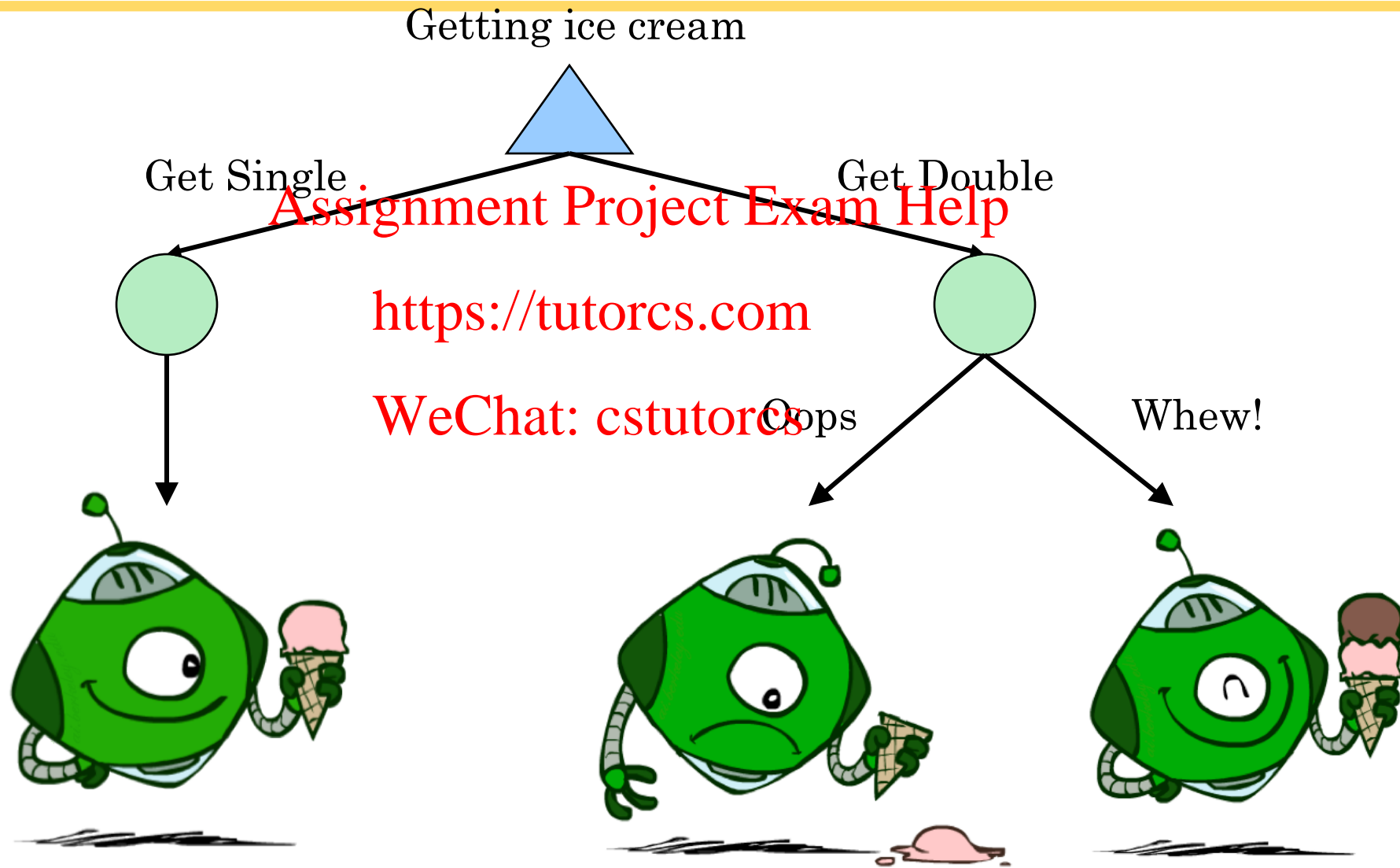
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- Where do utilities come from?

- In a game, may be simple (+1/-1)
- Utilities summarize the agent's goals
- Theorem: any “rational” preferences can be summarized as a utility function



# Utilities: Uncertain Outcomes



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# Preferences

- An agent must have preferences among:

- Prizes:  $A$ ,  $B$ , etc.
- Lotteries: situations with uncertain prizes

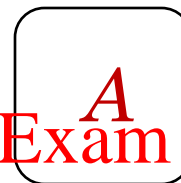
$$L = [p, A; (1 - p), B]$$

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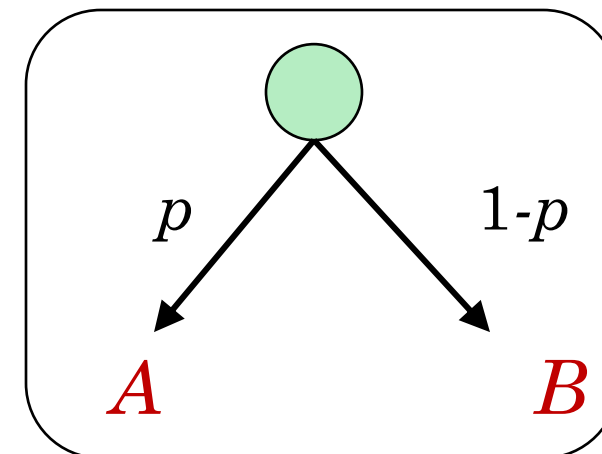
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A Prize



A Lottery



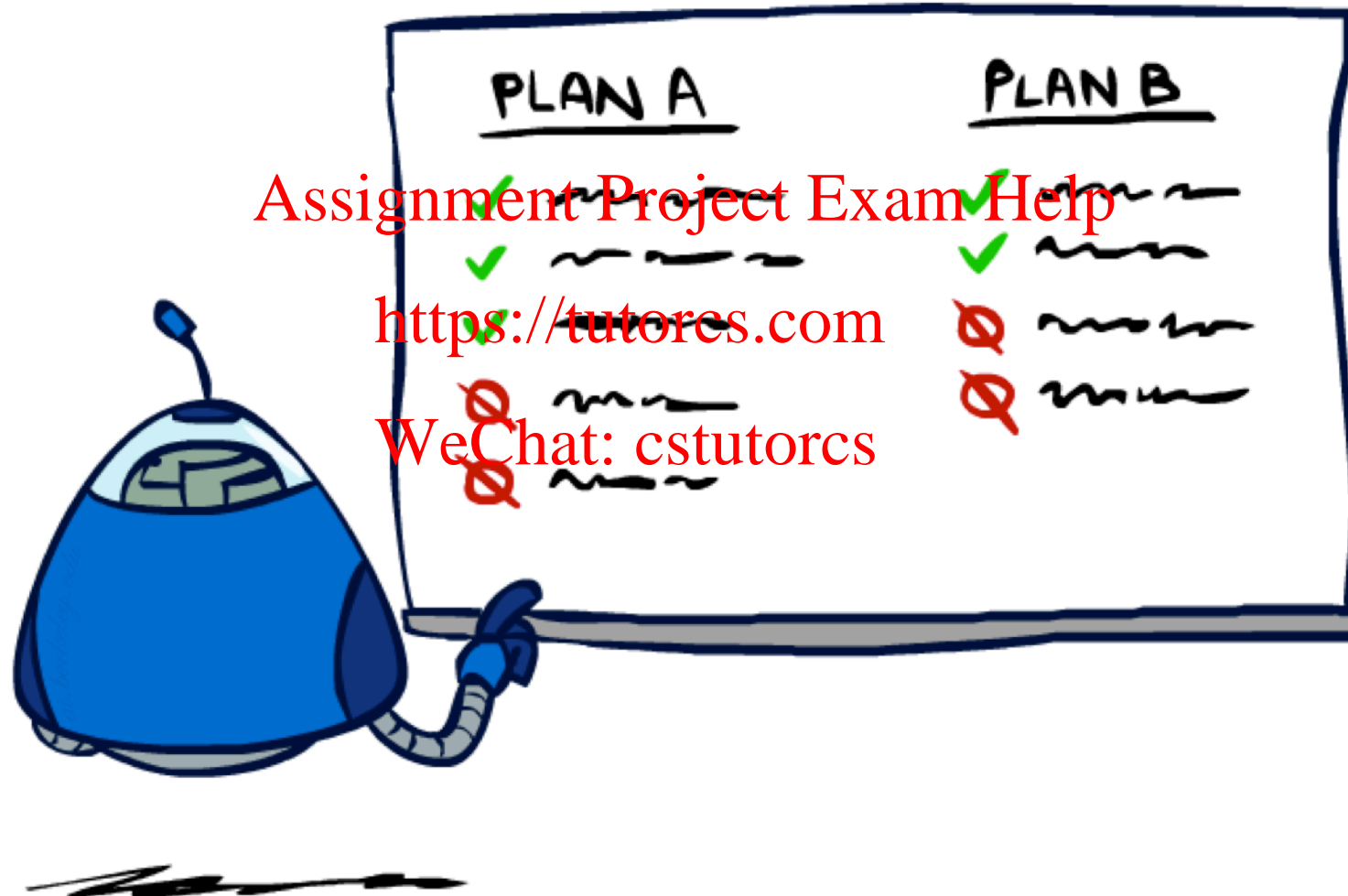
- Notation:

- Preference:  $A \succ B$
- Indifference:  $A \sim B$



# Rationality

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# Rational Preferences

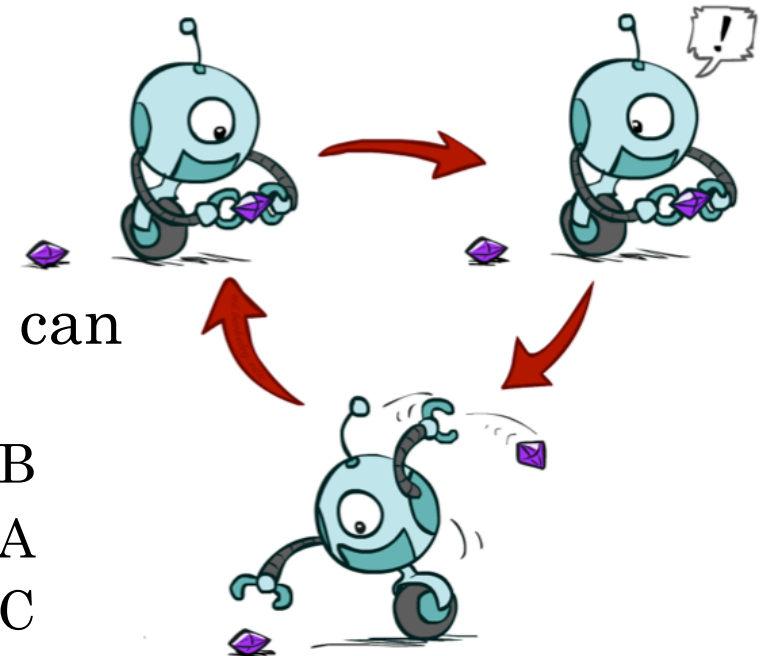
- We want some constraints on preferences before we call them rational, such as:

Axiom of Transitivity:  $(A \succ B) \wedge (B \succ C) \Rightarrow (A \succ C)$

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- For example: an agent with **intransitive preferences** can be induced to give away all of its money
  - If  $B \succ C$ , then an agent with  $C$  would pay (say) 1 cent to get  $B$
  - If  $A \succ B$ , then an agent with  $B$  would pay (say) 1 cent to get  $A$
  - If  $C \succ A$ , then an agent with  $A$  would pay (say) 1 cent to get  $C$



# Rational Preferences

## The Axioms of Rationality

### Orderability

$$(A \succ B) \vee (B \succ A) \vee (A \sim B)$$

### Transitivity

$$(A \succ B) \wedge (B \succ C) \Rightarrow (A \succ C)$$

### Continuity

$$A \succ B \succ C \Rightarrow \exists p [p, A; 1 - p, C] \sim B$$

### Substitutability

$$A \sim B \Rightarrow [p, A; 1 - p, C] \sim [p, B; 1 - p, C]$$

### Monotonicity

$$A \succ B \Rightarrow (p \geq q \Leftrightarrow [p, A; 1 - p, B] \succeq [q, A; 1 - q, B])$$

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Theorem: Rational preferences imply behavior describable as maximization of expected utility





# MEU Principle

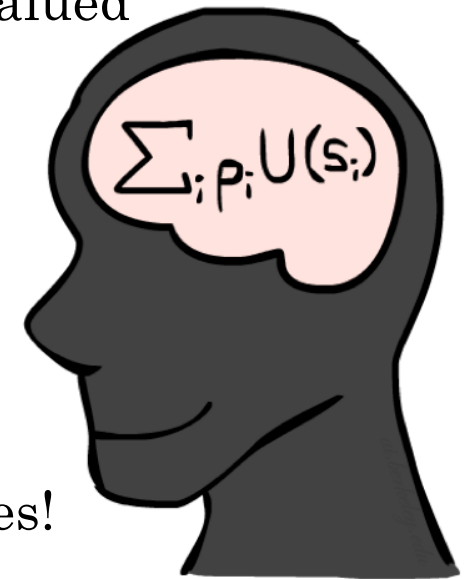
- Theorem [Ramsey, 1931; von Neumann & Morgenstern, 1944]
  - Given any preferences satisfying these constraints, there exists a real-valued function  $U$  such that:

$$U(A) \geq U(B) \Leftrightarrow A \succeq B$$

$$U([p_1, S_1; \dots; p_n, S_n]) = \sum_i p_i U(S_i)$$

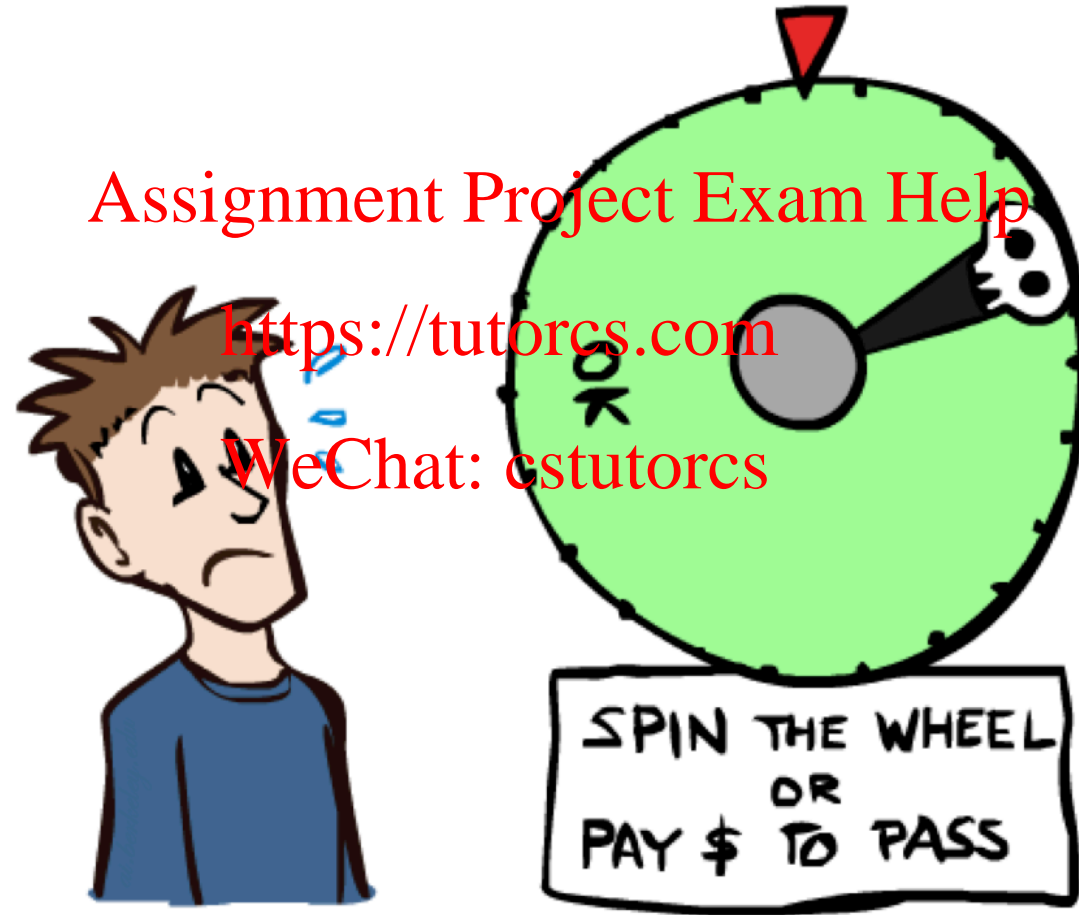
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- I.e. values assigned by  $U$  preserve preferences of both prizes and lotteries!
- Maximum expected utility (MEU) principle:
  - Choose the action that maximizes expected utility



# Human Utilities

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# Human Utilities

- Utilities map states to real numbers. Which numbers?
- Standard approach to assessment (elicitation) of human utilities:
  - Compare a prize  $A$  to a standard lottery  $L_p$  between
    - “best possible prize”  $u_+$  with probability  $p$
    - “worst possible catastrophe”  $u_-$  with probability  $1-p$
  - Adjust lottery probability  $p$  until indifference:  $A \sim L_p$
  - Resulting  $p$  is a utility in  $[0,1]$



# Human Utilities: Example

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- A person is given the choice between 2 scenarios:
  - Guaranteed scenario: the person receives \$50
  - Uncertain scenario: a coin is flipped to decide the person receive \$100 or not.
- Which choice would that person make?

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# Risk Aversion

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- **Risk averse**: would accept the guaranteed payment of (less than) \$50 rather than take the gamble

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- **Risk neutral**: indifferent between the bet and the guaranteed \$50 payment

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- **Risk seeking**: would accept the bet even when the guaranteed payment is more than \$50

# Prospect Theory: Utility Function

- **Risk aversion:** convexity

- Risk averse regarding gain
- Risk seeking regarding loss

- **Loss aversion**

- Losses are felt more strongly than gains

- **Endowment effect**

- We value things we own more highly
- Reference point: differentiate gains and loss

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