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# CIS 471/571 (Fall 2020): Introduction to Artificial Intelligence

Assignment Project Exam Help

## Lecture 15: Bayes Nets - Inference

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Source: <http://ai.berkeley.edu/home.html>

# Reminder

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- Homework 4: Bayes Nets
  - Deadline: Nov 24<sup>th</sup>, 2020

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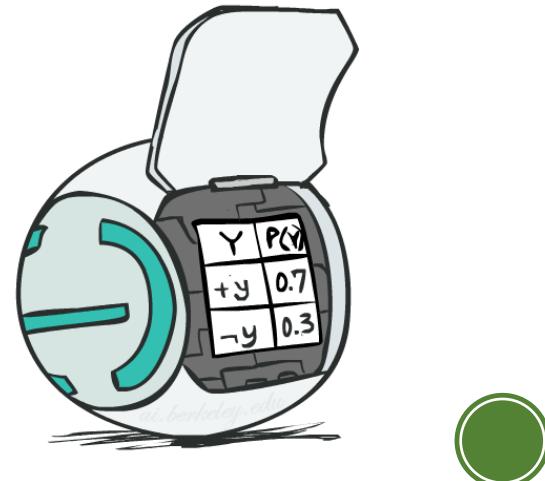
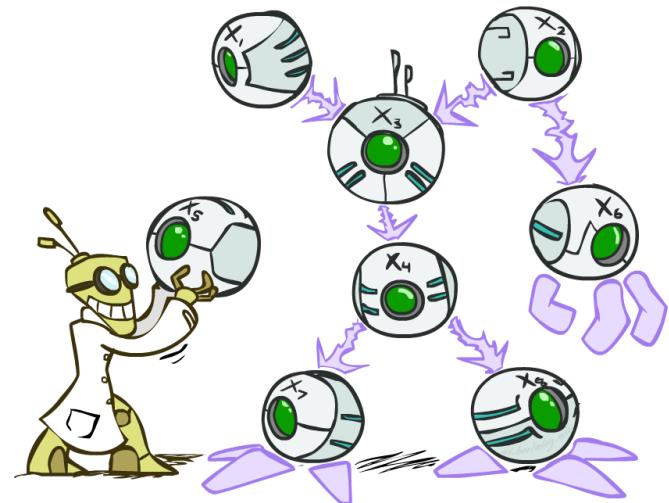
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# Bayes' Net Representation

- A directed, acyclic graph, one node per random variable
  - A conditional probability table (CPT) for each node
    - A collection of distributions over  $X$ , one for each combination of parents' values
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- Bayes' nets implicitly encode joint distributions
    - As a product of local conditional distributions
    - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

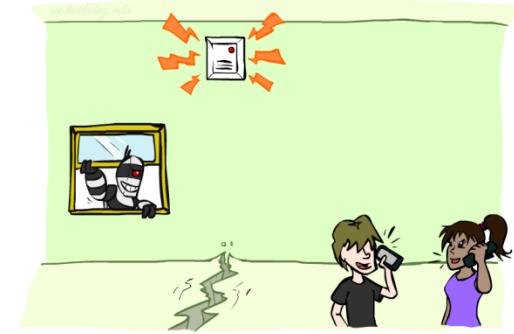


# Example: Alarm Network

| B  | P(B)  |
|----|-------|
| +b | 0.001 |
| -b | 0.999 |



| E  | P(E)  |
|----|-------|
| +e | 0.002 |
| -e | 0.998 |



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| A  | J  | P(J A) |
|----|----|--------|
| +a | +j | 0.9    |
| +a | -j | 0.1    |
| -a | +j | 0.05   |
| -a | -j | 0.95   |

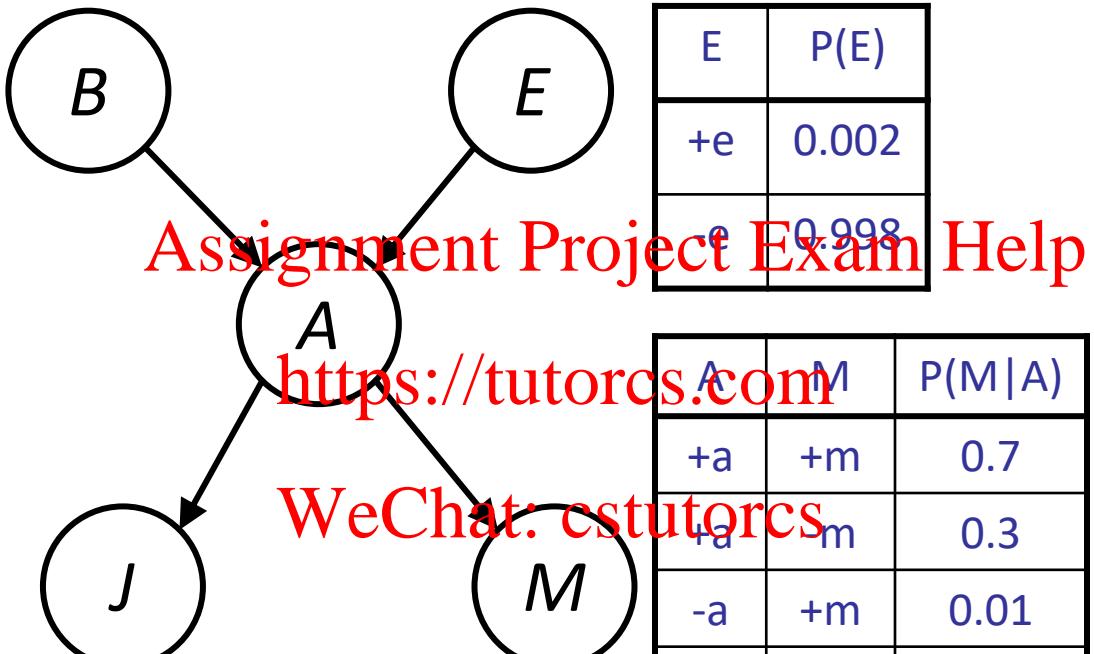
| A  | M  | P(M A) |
|----|----|--------|
| +a | +m | 0.7    |
| +a | -m | 0.3    |
| -a | +m | 0.01   |
| -a | -m | 0.99   |

| B  | E  | A  | P(A B,E) |
|----|----|----|----------|
| +b | +e | +a | 0.95     |
| +b | +e | -a | 0.05     |
| +b | -e | +a | 0.94     |
| +b | -e | -a | 0.06     |
| -b | +e | +a | 0.29     |
| -b | +e | -a | 0.71     |
| -b | -e | +a | 0.001    |
| -b | -e | -a | 0.999    |



# Example: Alarm Network

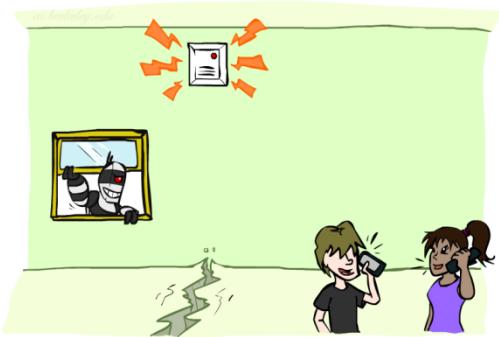
| B  | P(B)  |
|----|-------|
| +b | 0.001 |
| -b | 0.999 |



| E  | P(E)  |
|----|-------|
| +e | 0.002 |
| -e | 0.998 |

| A  | J  | P(J A) |
|----|----|--------|
| +a | +j | 0.9    |
| +a | -j | 0.1    |
| -a | +j | 0.05   |
| -a | -j | 0.95   |

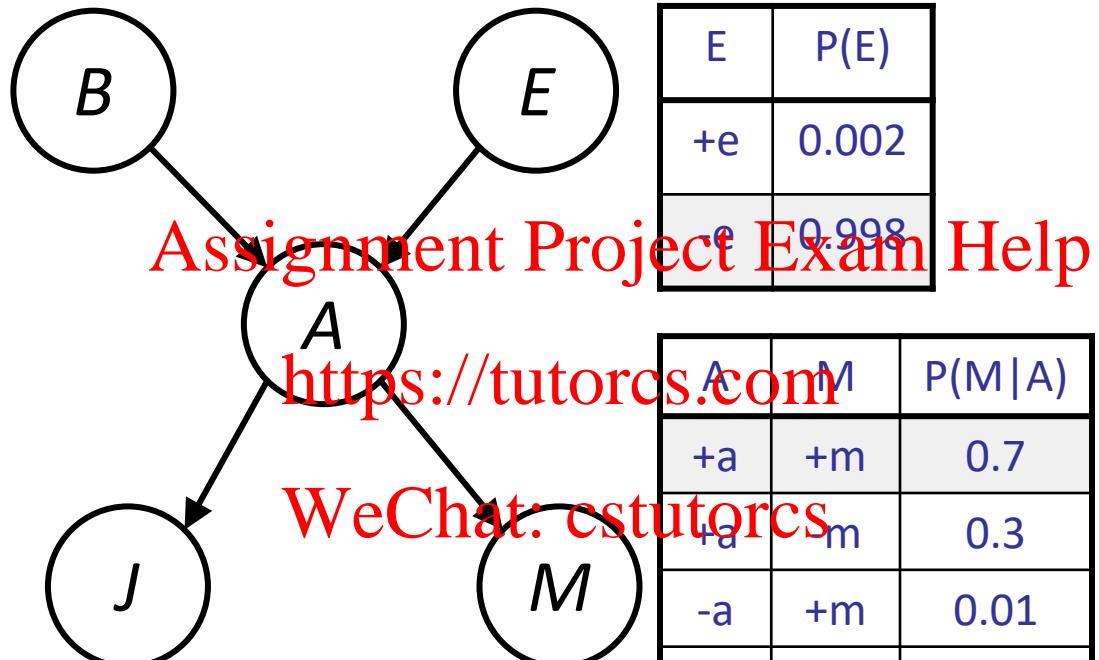
$$P(+b, -e, +a, -j, +m) = \\ P(+b)P(-e)P(+a|+b, -e)P(-j|+a)P(+m|+a) =$$



| B  | E  | A  | P(A B,E) |
|----|----|----|----------|
| +b | +e | +a | 0.95     |
| +b | +e | -a | 0.05     |
| +b | -e | +a | 0.94     |
| +b | -e | -a | 0.06     |
| -b | +e | +a | 0.29     |
| -b | +e | -a | 0.71     |
| -b | -e | +a | 0.001    |
| -b | -e | -a | 0.999    |

# Example: Alarm Network

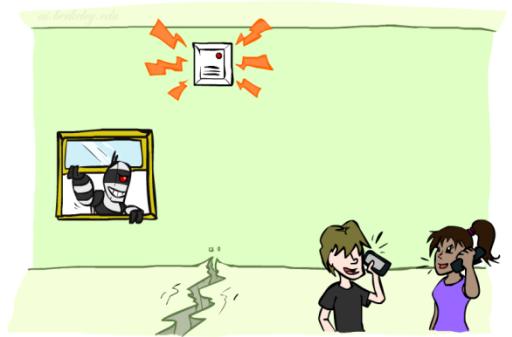
| B  | P(B)  |
|----|-------|
| +b | 0.001 |
| -b | 0.999 |



| E  | P(E)  |
|----|-------|
| +e | 0.002 |
| -e | 0.998 |

| A  | J  | P(J A) |
|----|----|--------|
| +a | +j | 0.9    |
| +a | -j | 0.1    |
| -a | +j | 0.05   |
| -a | -j | 0.95   |

| A  | M  | P(M A) |
|----|----|--------|
| +a | +m | 0.7    |
| +a | -m | 0.3    |
| -a | +m | 0.01   |
| -a | -m | 0.99   |



$$\begin{aligned}
 P(+b, -e, +a, -j, +m) &= \\
 P(+b)P(-e)P(+a|+b, -e)P(-j|+a)P(+m|+a) &= \\
 0.001 \times 0.998 \times 0.94 \times 0.1 \times 0.7
 \end{aligned}$$

| B  | E  | A  | P(A B,E) |
|----|----|----|----------|
| +b | +e | +a | 0.95     |
| +b | +e | -a | 0.05     |
| +b | -e | +a | 0.94     |
| +b | -e | -a | 0.06     |
| -b | +e | +a | 0.29     |
| -b | +e | -a | 0.71     |
| -b | -e | +a | 0.001    |
| -b | -e | -a | 0.999    |



# Bayes' Nets

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✓ Representation

✓ Conditional Independences

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- Probabilistic Inference
  - Enumeration (exact, exponential complexity)
  - Variable elimination (exact, worst-case exponential complexity, often better)
  - Inference is NP-complete
  - Sampling (approximate)
- Learning Bayes' Nets from Data

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# Inference

- Inference: calculating some useful quantity from a joint probability distribution

- Examples:

- Posterior probability

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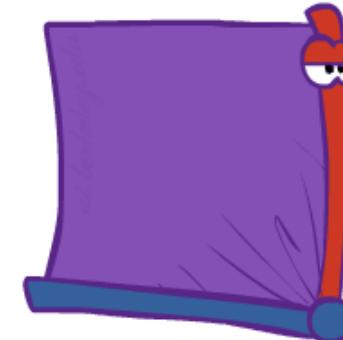
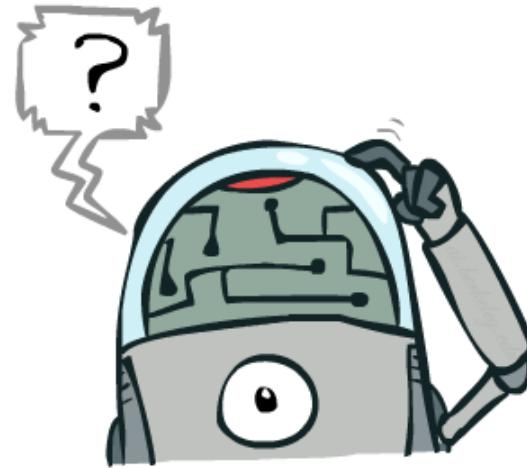
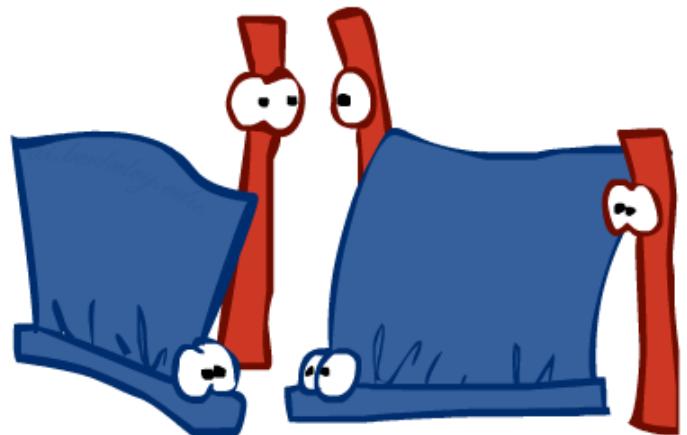
$$P(Q|E_1 = e_1, \dots, E_k = e_k)$$

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- Most likely explanation:

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$$\operatorname{argmax}_q P(Q = q | E_1 = e_1 \dots)$$



# Inference by Enumeration

- General case:

- Evidence variables:  $E_1 \dots E_k = e_1 \dots e_k$
- Query\* variable:  $Q$
- Hidden variables:  $H_1 \dots H_r$

$$\left. \begin{array}{l} E_1 \dots E_k = e_1 \dots e_k \\ Q \\ H_1 \dots H_r \end{array} \right\} X_1, X_2, \dots X_n$$

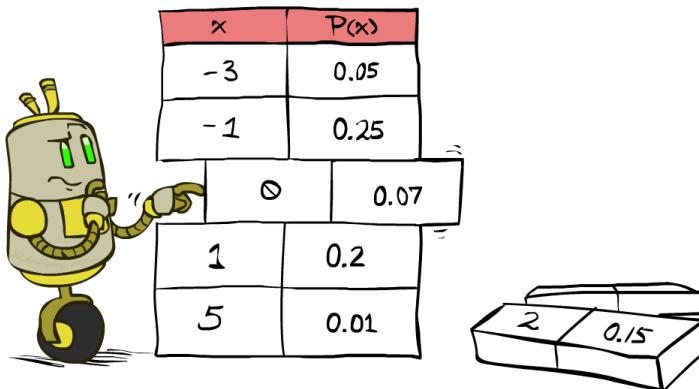
*All variables*

- We want:

\* Works fine with multiple query variables, too

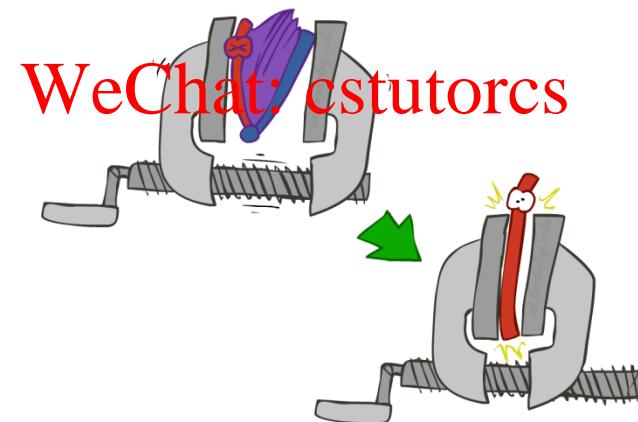
$$P(Q|e_1 \dots e_k)$$

- Step 1: Select the entries consistent with the evidence



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- Step 2: Sum out H to get <https://cstutorcs.com>



$$\times \frac{1}{Z}$$

$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} \underbrace{P(Q, h_1 \dots h_r, e_1 \dots e_k)}_{X_1, X_2, \dots X_n}$$

$$Z = \sum_q P(Q, e_1 \dots e_k)$$

$$P(Q|e_1 \dots e_k) = \frac{1}{Z} P(Q, e_1 \dots e_k)$$

# Inference by Enumeration in Bayes' Net

- Given unlimited time, inference in BNs is easy

- Reminder of inference by enumeration by example:

$$P(B \mid +j, +m) \propto_B P(B, +j, +m)$$

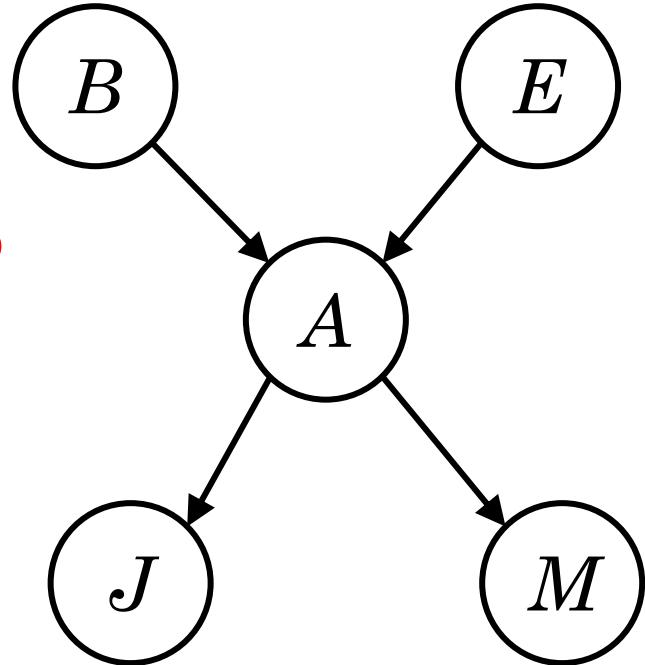
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$$= \sum_{e,a} P(B, e, a, +j, +m)$$

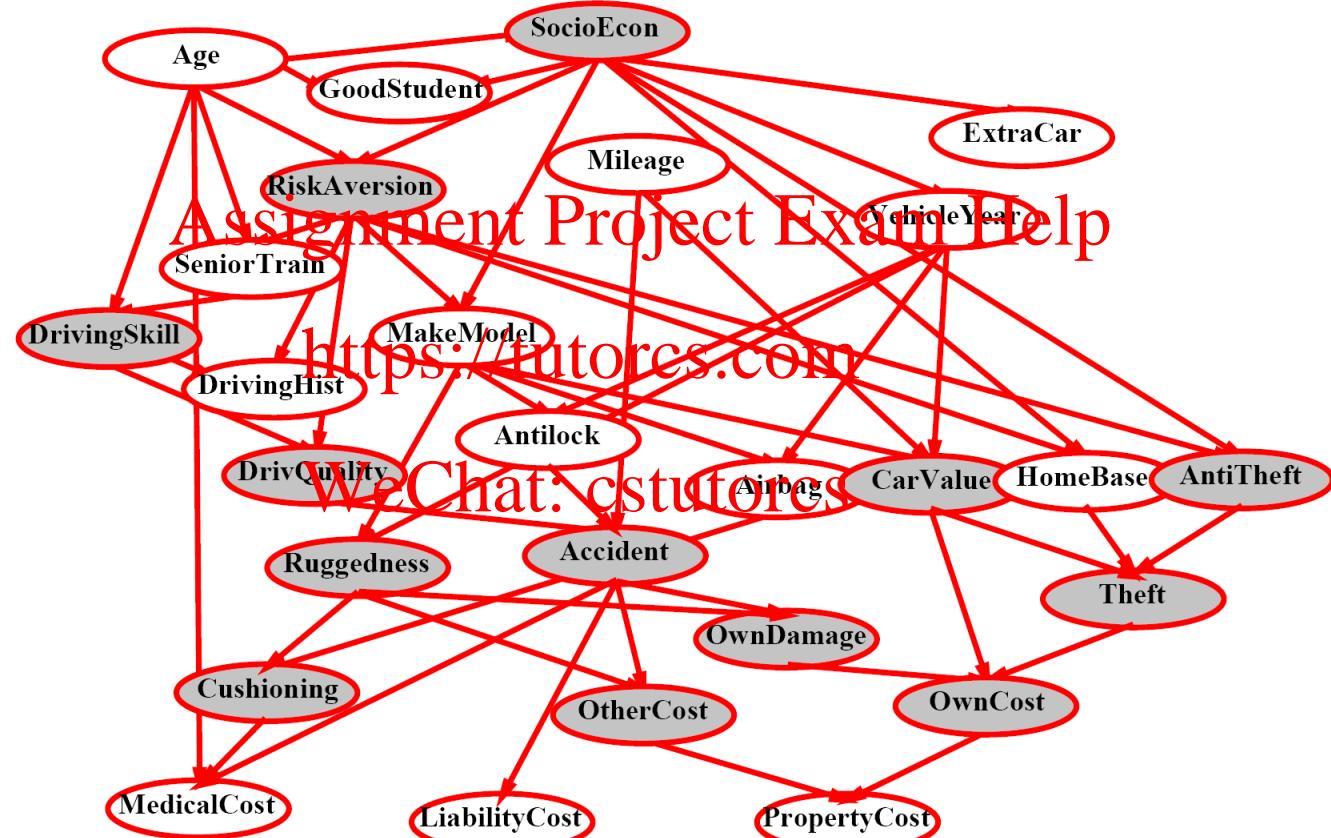
$$= \sum_{e,a} P(B)P(e)P(a|B, e)P(+j|a)P(+m|a)$$

$$= P(B)P(+e)P(+a|B, +e)P(+j|+a)P(+m|+a) + P(B)P(+e)P(-a|B, +e)P(+j|-a)P(+m|-a)$$

$$P(B)P(-e)P(+a|B, -e)P(+j|+a)P(+m|+a) + P(B)P(-e)P(-a|B, -e)P(+j|-a)P(+m|-a)$$

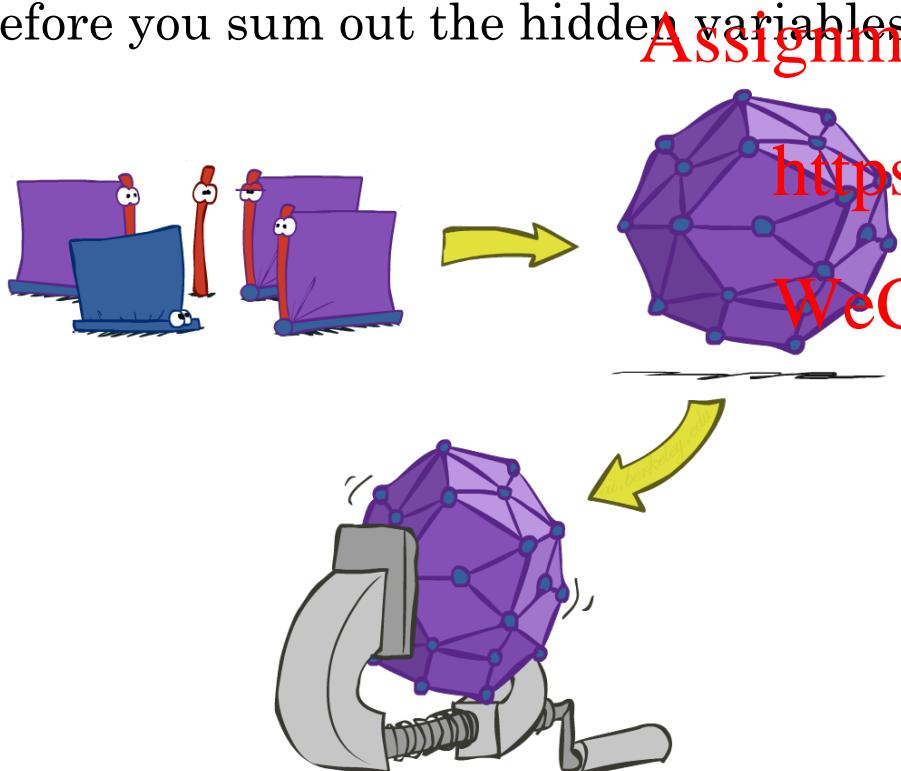


# Inference by Enumeration?



# Inference by Enumeration vs. Variable Elimination

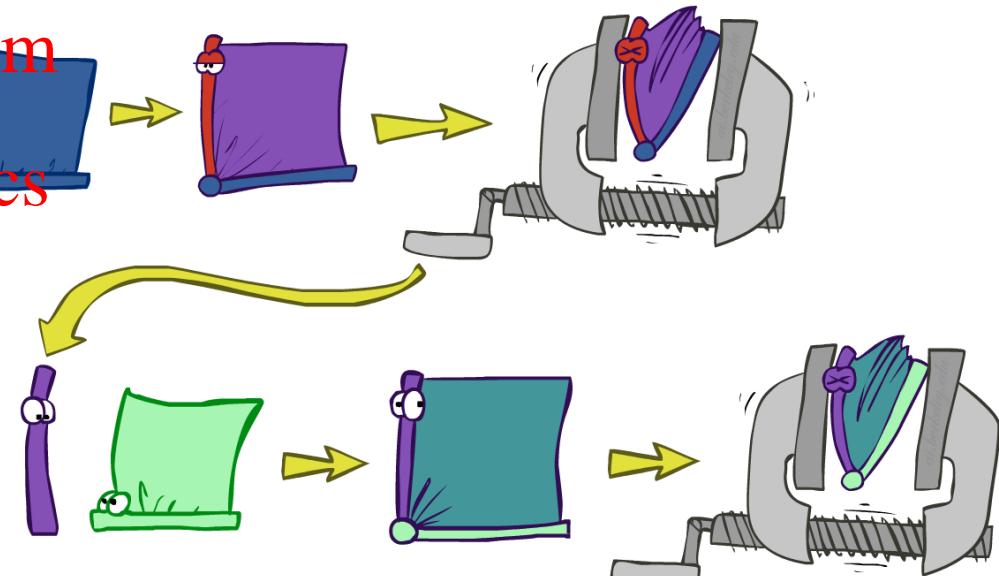
- Why is inference by enumeration so slow?
  - You join up the whole joint distribution before you sum out the hidden variables



- Idea: interleave joining and marginalizing!
  - Called “Variable Elimination”
  - Still NP-hard, but usually much faster than inference by enumeration

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- First we'll need some new notation: factors

# Factor Zoo

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# Factor Zoo I

- Joint distribution:  $P(X, Y)$ 
  - Entries  $P(x, y)$  for all  $x, y$
  - Sums to 1
- Selected joint:  $P(x, Y)$ 
  - A slice of the joint distribution
  - Entries  $P(x, y)$  for fixed  $x$ , all  $y$
  - Sums to  $P(x)$
- Number of capitals = dimensionality of the table

$$P(T, W)$$

| T    | W    | P   |
|------|------|-----|
| hot  | rain | 0.1 |
| cold | sun  | 0.2 |
| cold | rain | 0.3 |

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$$P(\text{cold}, W)$$

| T    | W    | P   |
|------|------|-----|
| cold | sun  | 0.2 |
| cold | rain | 0.3 |



# Factor Zoo II

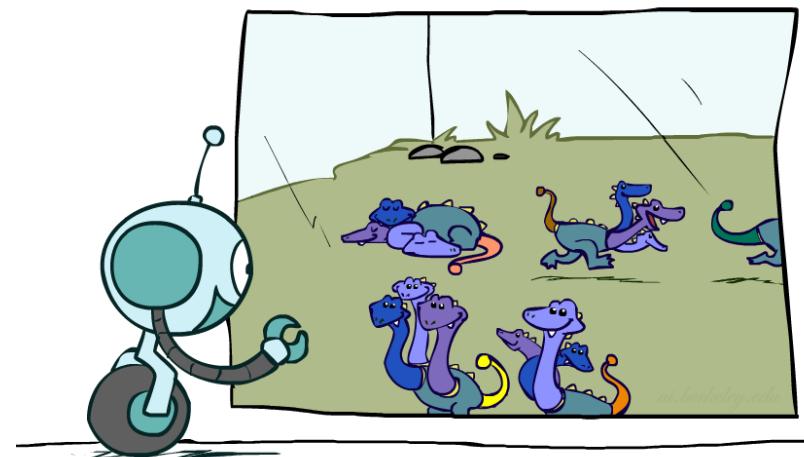
- Single conditional:  $P(Y | x)$ 
  - Entries  $P(y | x)$  for fixed  $x$ , all  $y$
  - Sums to 1



- Family of conditionals:

$P(Y | X)$

- Multiple conditionals
- Entries  $P(y | x)$  for all  $x, y$
- Sums to  $|X|$



$P(W|cold)$

| T    | W    | P   |
|------|------|-----|
| cold | sun  | 0.4 |
| cold | rain | 0.6 |

$P(W|T)$

| T    | W    | P   |
|------|------|-----|
| hot  | sun  | 0.8 |
| hot  | rain | 0.2 |
| cold | sun  | 0.4 |
| cold | rain | 0.6 |

$P(W|hot)$

$P(W|cold)$

# Factor Zoo III

- Specified family:  $P(y | X)$ 
  - Entries  $P(y | x)$  for fixed  $y$ ,  
but for all  $x$
  - Sums to ... who knows!

$P(rain|T)$

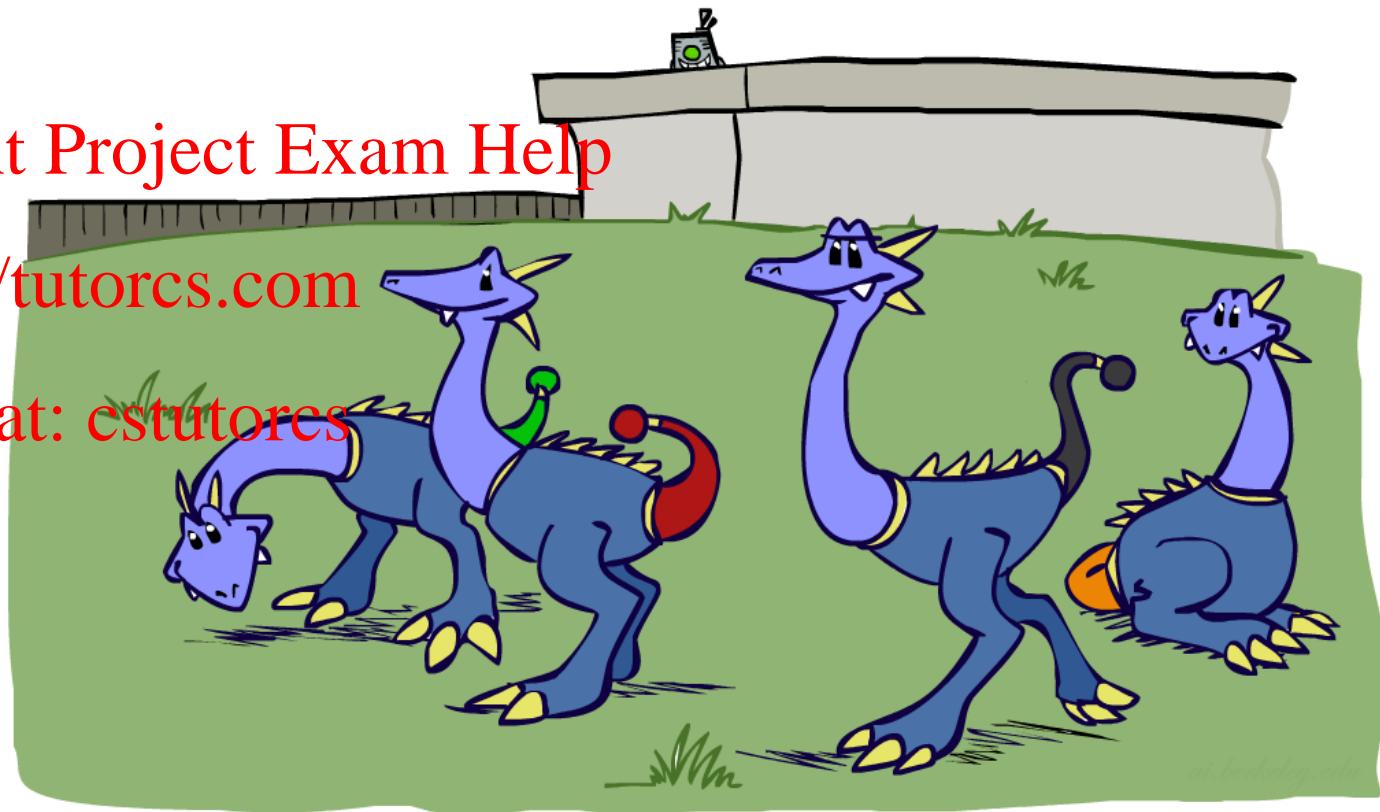
| T    | W    | P   |
|------|------|-----|
| hot  | rain | 0.2 |
| cold | rain | 0.6 |

$$\left. \begin{array}{l} P(rain|hot) \\ P(rain|cold) \end{array} \right\}$$

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# Factor Zoo Summary

- In general, when we write  $P(Y_1 \dots Y_N | X_1 \dots X_M)$

- It is a “factor,” a multi-dimensional array

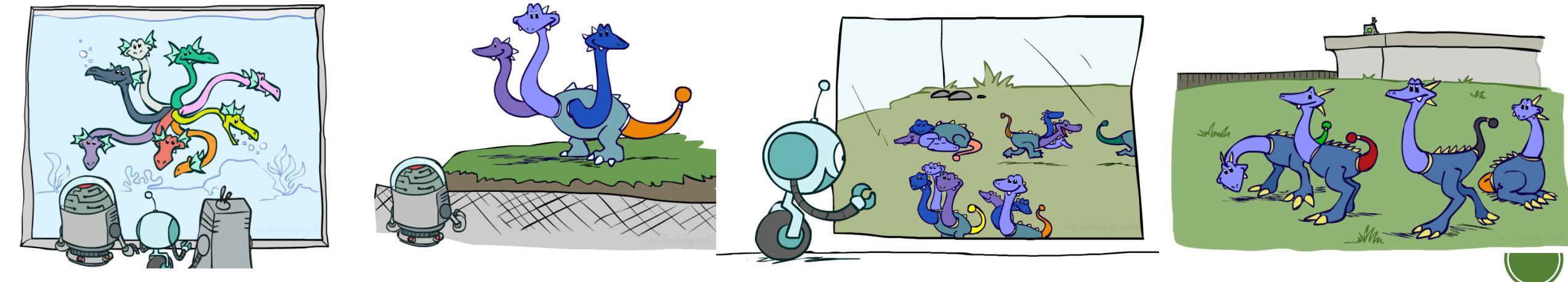
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- Its values are  $P(y_1 \dots y_N | x_1 \dots x_M)$

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- Any assigned (=lower-case) X or Y is a dimension missing (selected) from the array

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# Example: Traffic Domain

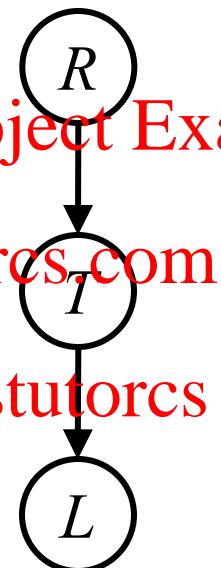
- Random Variables

- R: Raining
- T: Traffic Assignment Project Exam Help
- L: Late for class!

$$P(L) = ?$$

$$= \sum_{r,t} P(r,t,L)$$

$$= \sum_{r,t} P(r)P(t|r)P(L|t)$$



$$P(R)$$

|    |     |
|----|-----|
| +r | 0.1 |
| -r | 0.9 |

$$P(T|R)$$

|    |    |     |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

$$P(L|T)$$

|    |    |     |
|----|----|-----|
| +t | +l | 0.3 |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |



# Inference by Enumeration: Procedural Outline

- Track objects called **factors**
- Initial factors are local CPTs (one per node)

$$P(R)$$

|    |     |
|----|-----|
| +r | 0.1 |
| -r | 0.9 |

$$P(T|R)$$

|    |    |     |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

$$P(L|T)$$

|    |    |     |
|----|----|-----|
| +t | +l | 0.3 |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |

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- Any known values are selected
- E.g. if we know  $L = +\ell$  the initial factors are

$$P(R)$$

|    |     |
|----|-----|
| +r | 0.1 |
| -r | 0.9 |

$$P(T|R)$$

|    |    |     |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

$$P(+\ell|T)$$

|    |    |     |
|----|----|-----|
| +t | +l | 0.3 |
| -t | +l | 0.1 |

- Procedure: Join all factors, eliminate all hidden variables, normalize

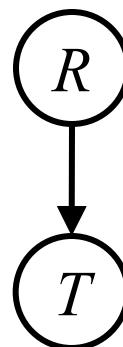
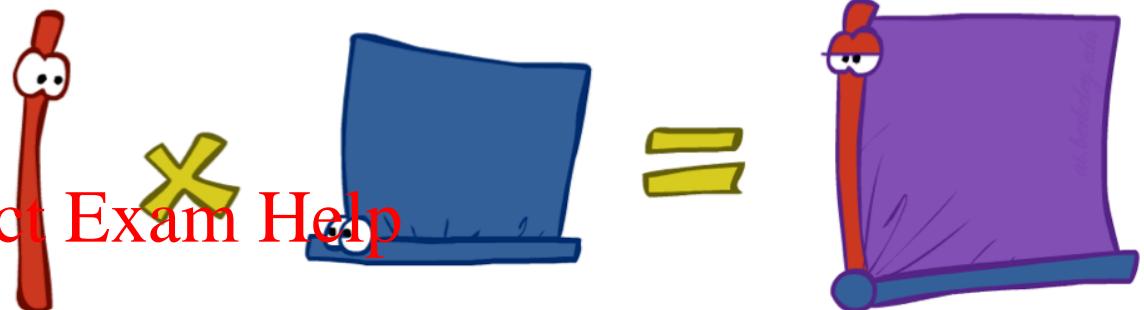


# Operation 1: Join Factors

- First basic operation: joining factors
- Combining factors:
  - Just like a database join
  - Get all factors over the joining variable
  - Build a new factor over the union of the variables involved
- Example: Join on R

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$$P(R)$$

|    |     |
|----|-----|
| +r | 0.1 |
| -r | 0.9 |

$$P(T|R)$$

|    |    |     |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

$$P(R, T)$$

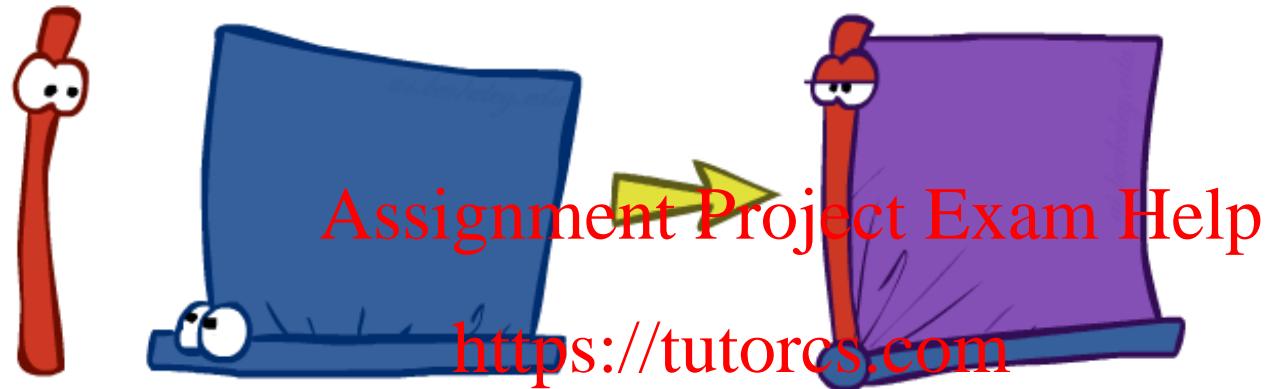
|    |    |      |
|----|----|------|
| +r | +t | 0.08 |
| +r | -t | 0.02 |
| -r | +t | 0.09 |
| -r | -t | 0.81 |



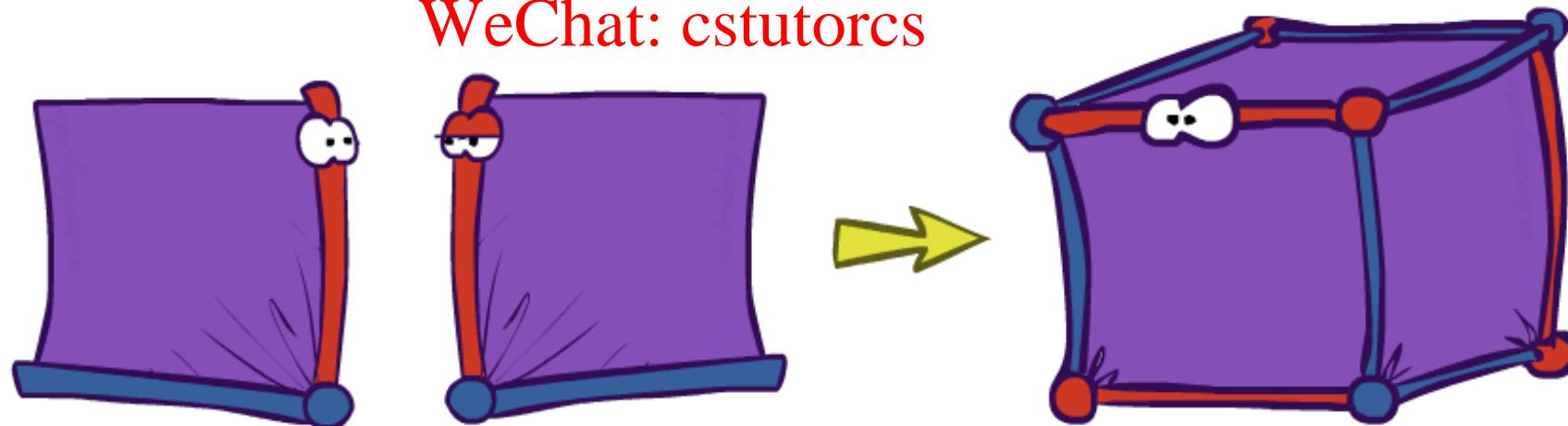
- Computation for each entry: pointwise products  $\forall r, t : P(r, t) = P(r) \cdot P(t|r)$

# Example: Multiple Joins

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# Example: Multiple Joins

|     | $P(R)$ |     |
|-----|--------|-----|
| $R$ | +r     | 0.1 |
|     | -r     | 0.9 |

|     | $P(T R)$ |     |
|-----|----------|-----|
| $T$ | +t       | 0.8 |
|     | -t       | 0.2 |
| $R$ | +r       | 0.1 |
|     | -r       | 0.9 |

|     | $P(L T)$ |     |
|-----|----------|-----|
| $L$ | +l       | 0.3 |
|     | -l       | 0.7 |
| $T$ | +t       | 0.1 |
|     | -t       | 0.9 |



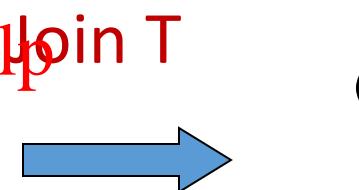
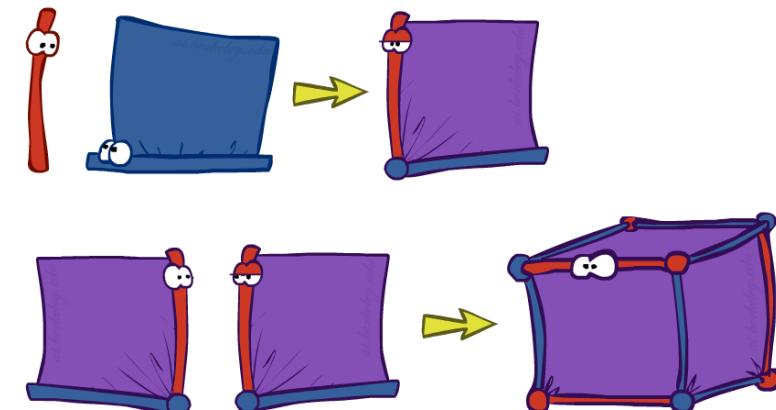
$P(R, T)$

| +r | +t | 0.08 |
|----|----|------|
| +r | -t | 0.02 |
| -r | +t | 0.09 |
| -r | -t | 0.81 |

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$P(L|T)$

| +t | +l | 0.3 |
|----|----|-----|
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |



$R, T$

$L$

$P(R, T, L)$

| +r | +t | +l | 0.024 |
|----|----|----|-------|
| +r | +t | -l | 0.056 |
| +r | -t | +l | 0.002 |
| +r | -t | -l | 0.018 |
| -r | +t | +l | 0.027 |
| -r | +t | -l | 0.063 |
| -r | -t | +l | 0.081 |
| -r | -t | -l | 0.729 |

# Operation 2: Eliminate

- Second basic operation:  
marginalization

- Take a factor and sum

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- Shrinks a factor to a smaller one

- A projection operation

- Example:

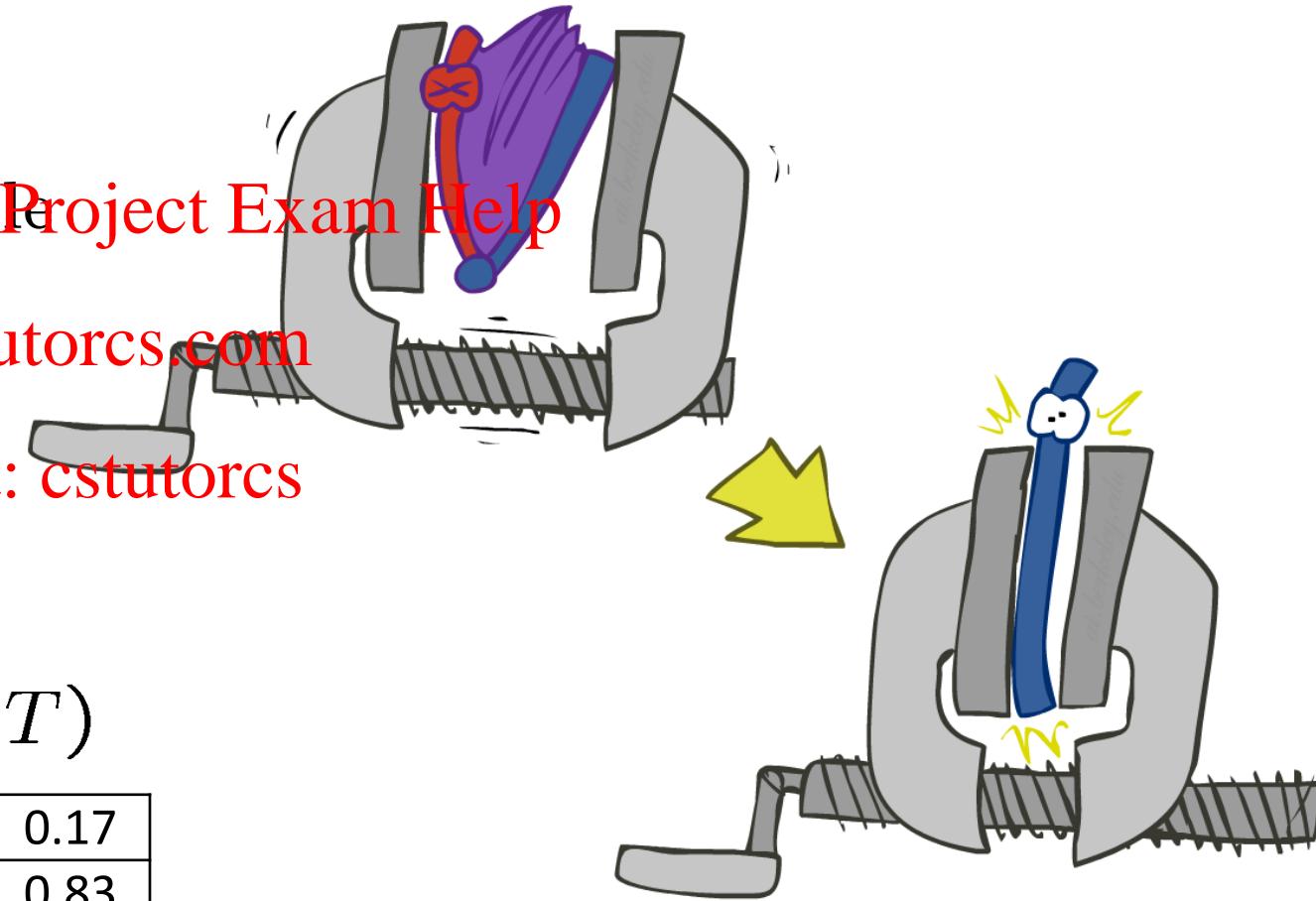
$$P(R, T)$$

|    |    |      |
|----|----|------|
| +r | +t | 0.08 |
| +r | -t | 0.02 |
| -r | +t | 0.09 |
| -r | -t | 0.81 |

sum  $R$

$$P(T)$$

|    |      |
|----|------|
| +t | 0.17 |
| -t | 0.83 |



# Multiple Elimination

$P(R, T, L)$

| $+r$ | $+t$ | $+l$ | $P(R, T, L)$ |
|------|------|------|--------------|
| $+r$ | $+t$ | $+l$ | 0.024        |
| $+r$ | $+t$ | $-l$ | 0.056        |
| $+r$ | $-t$ | $+l$ | 0.002        |
| $+r$ | $-t$ | $-l$ | 0.018        |
| $-r$ | $+t$ | $+l$ | 0.027        |
| $-r$ | $+t$ | $-l$ | 0.063        |
| $-r$ | $-t$ | $+l$ | 0.081        |
| $-r$ | $-t$ | $-l$ | 0.729        |

$R, T, L$

$T, L$

$L$

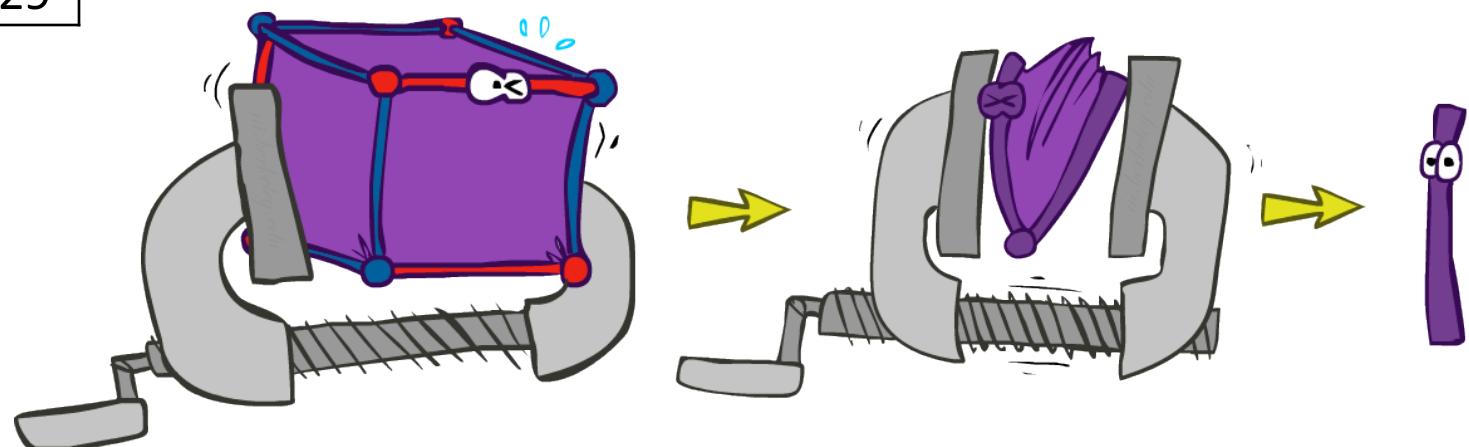
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Sum out R      Sum out T

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| $+t$ | $+l$ | $P(T, L)$ |
|------|------|-----------|
| $+t$ | $+l$ | 0.051     |
| $+t$ | $-l$ | 0.119     |
| $-t$ | $+l$ | 0.083     |
| $-t$ | $-l$ | 0.747     |

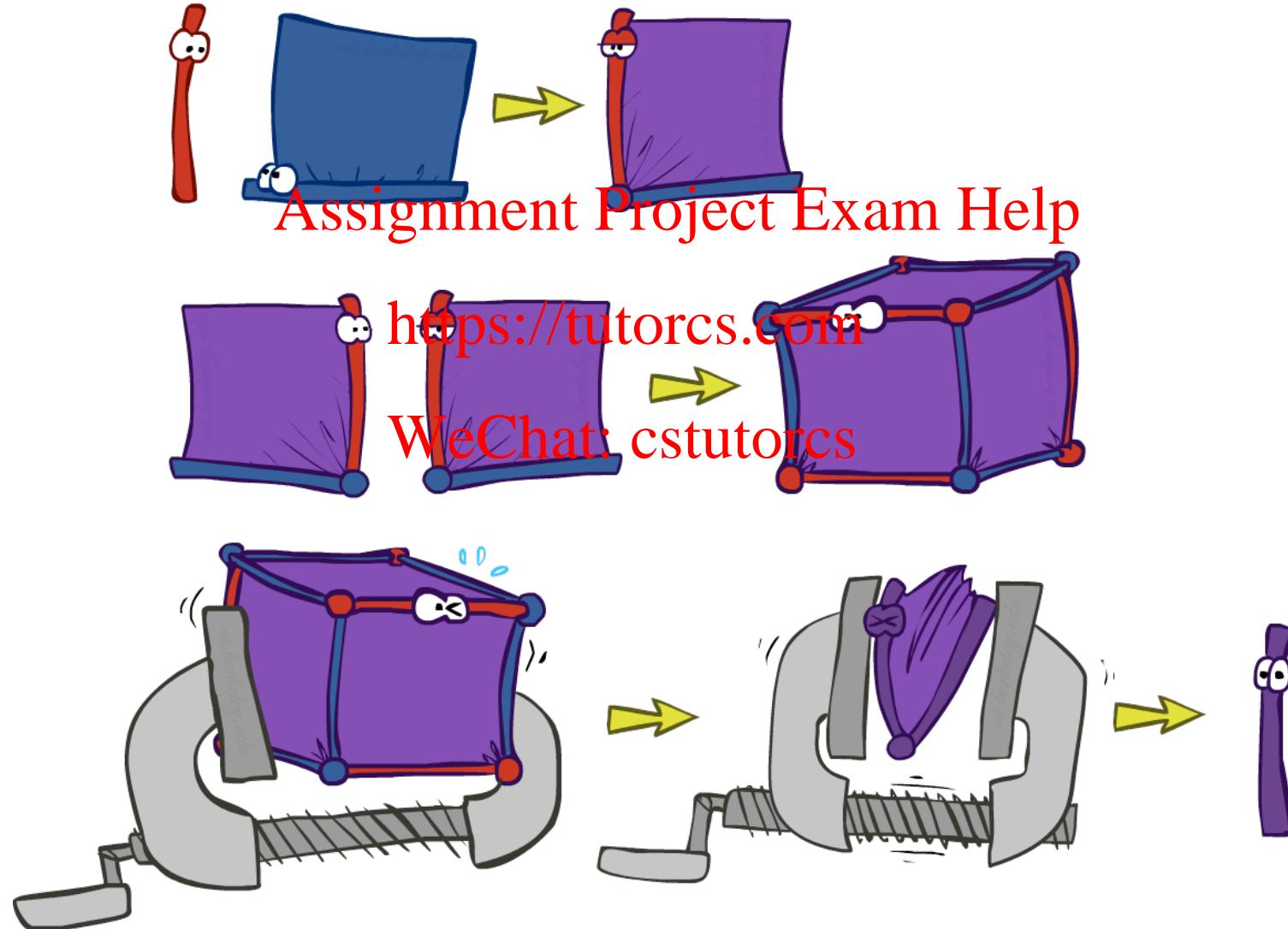
$P(L)$

|      |       |
|------|-------|
| $+l$ | 0.134 |
| $-l$ | 0.886 |

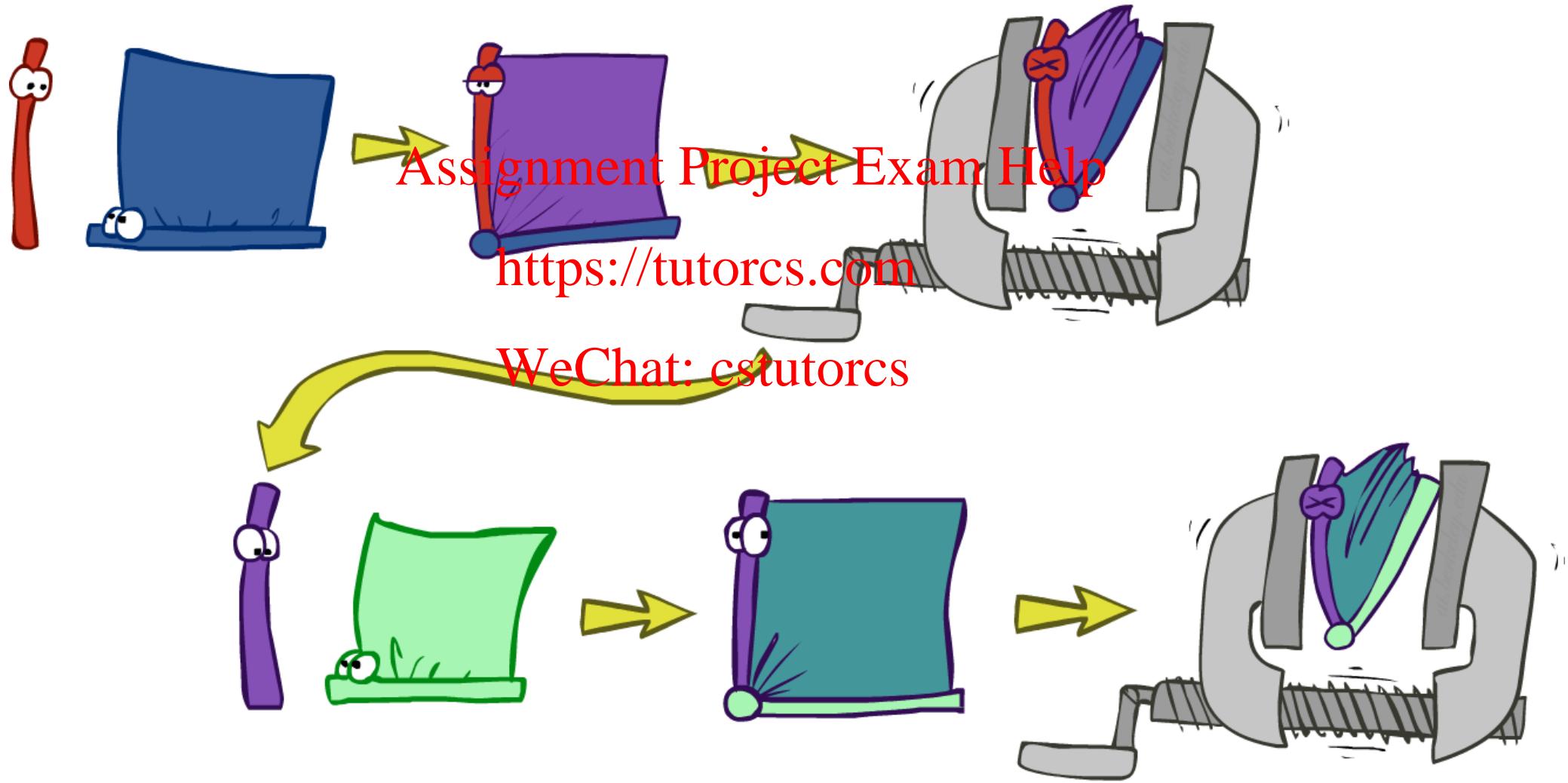


# Thus Far: Multiple Join, Multiple Eliminate (= Inference by Enumeration)

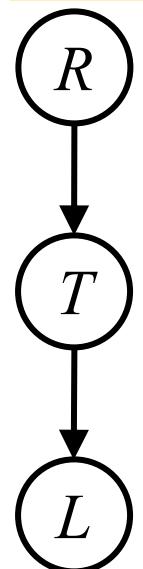
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# Marginalizing Early (= Variable Elimination)



# Traffic Domain



$$P(L) = ?$$

- Inference by Enumeration

$$= \sum_t \sum_r P(L|t)P(r)P(t|r)$$

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Join on r

Join on t

Eliminate r

Eliminate t

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$$= \sum_t P(L|t) \sum_r P(r)P(t|r)$$

Join on r

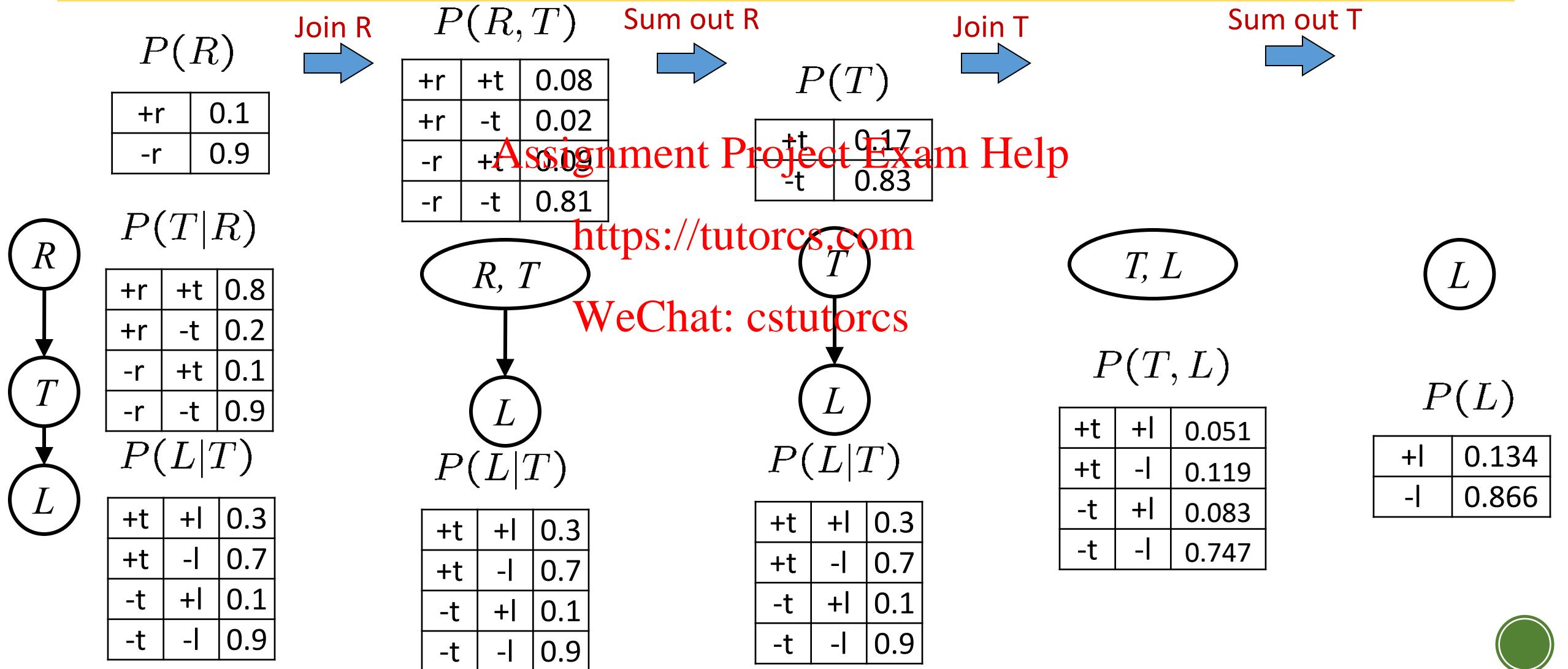
Eliminate r

Join on t

Eliminate t



# Marginalizing Early! (aka VE)



# Evidence

- If evidence, start with factors that select that evidence
  - No evidence uses these initial factors:

| $P(R)$ |     |
|--------|-----|
| +r     | 0.1 |
| -r     | 0.9 |

| $P(T R)$ |    |
|----------|----|
| +r       | +t |
| +r       | -t |
| -r       | +t |
| -r       | -t |

| $P(L T)$ |    |
|----------|----|
| +t       | +l |
| +t       | -l |
| -t       | +l |
| -t       | -l |

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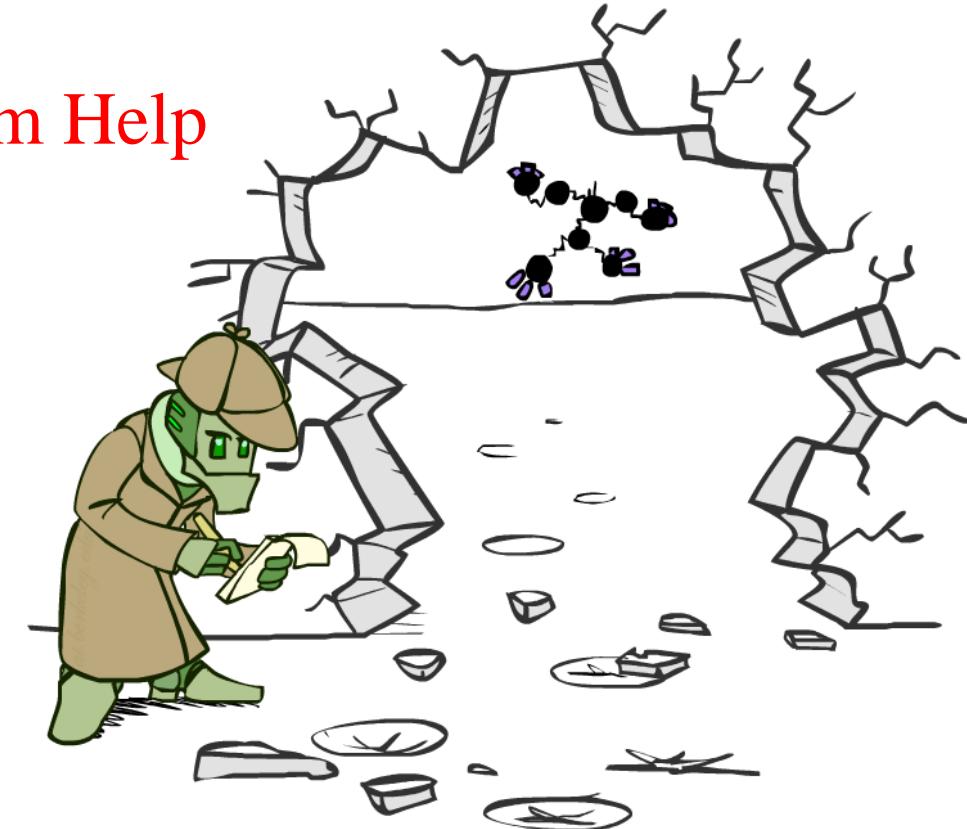
- Computing  $P(L|r)$  the initial factors become

| $P(+r)$ |     |
|---------|-----|
| +r      | 0.1 |

| $P(T +r)$ |    |
|-----------|----|
| +r        | +t |
| +r        | -t |

| $P(L T)$ |    |
|----------|----|
| +t       | +l |
| +t       | -l |
| -t       | +l |
| -t       | -l |

- We eliminate all vars other than query + evidence



# Evidence II

- Result will be a selected joint of query and evidence
  - E.g. for  $P(L | +r)$ , we would end up with:

$P(+r, L)$

|    |    |       |
|----|----|-------|
| +r | +l | 0.026 |
| +r | -l | 0.074 |

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$P(L | +r)$

Normalize  
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- To get our answer, just normalize this!
- That's it!



# General Variable Elimination

- Query:  $P(Q|E_1 = e_1, \dots, E_k = e_k)$

- Start with initial factors:

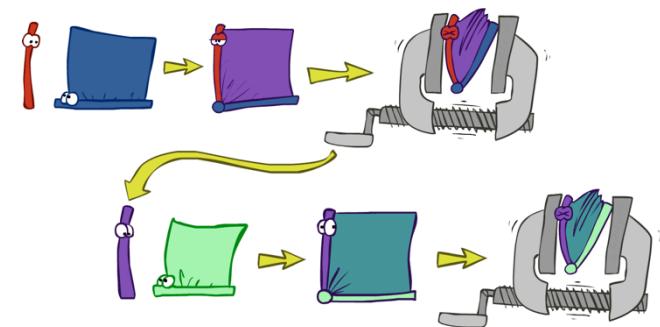
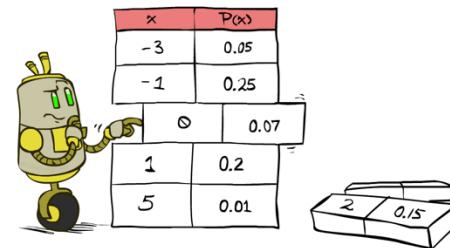
- Local CPTs (but instantiated by evidence)

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- While there are still hidden variables (not Q or evidence):

- Pick a hidden variable H
  - Join all factors mentioning H
  - Eliminate (sum out) H

- Join all remaining factors and normalize



$$\left( \text{blue} \times \text{purple} \right) = \text{purple} \quad \times \frac{1}{Z}$$



# Example

$$P(B|j, m) \propto P(B, j, m)$$

|        |        |             |          |          |
|--------|--------|-------------|----------|----------|
| $P(B)$ | $P(E)$ | $P(A B, E)$ | $P(j A)$ | $P(m A)$ |
|--------|--------|-------------|----------|----------|

<https://tutorcs.com>

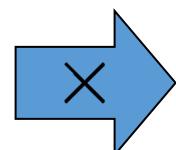
Choose A

$$P(A|B, E)$$

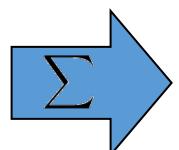
$$P(j|A)$$

$$P(m|A)$$

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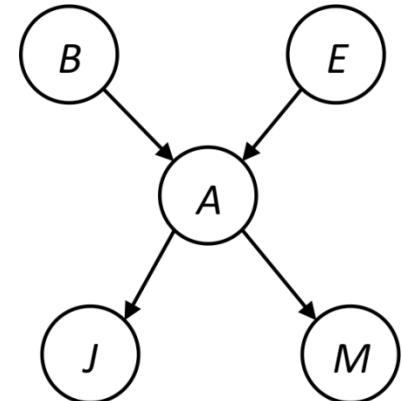


$$P(j, m, A|B, E)$$



$$P(j, m|B, E)$$

|        |        |                |
|--------|--------|----------------|
| $P(B)$ | $P(E)$ | $P(j, m B, E)$ |
|--------|--------|----------------|



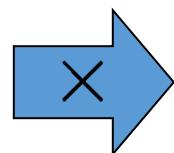
# Example

|        |        |                |
|--------|--------|----------------|
| $P(B)$ | $P(E)$ | $P(j, m B, E)$ |
|--------|--------|----------------|

Choose E

$$\begin{aligned} P(E) \\ P(j, m|B, E) \end{aligned}$$

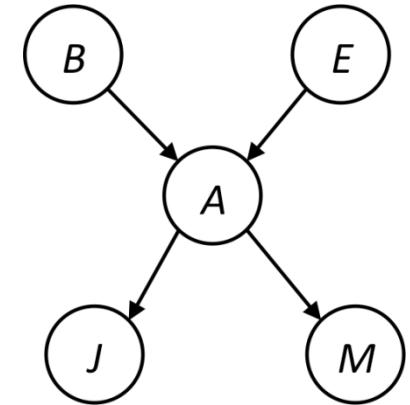
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$$P(j, m|E|B)$$

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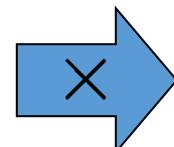
$$P(j, m|B)$$



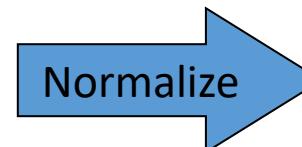
|        |             |
|--------|-------------|
| $P(B)$ | $P(j, m B)$ |
|--------|-------------|

Finish with B

$$\begin{aligned} P(B) \\ P(j, m|B) \end{aligned}$$



$$P(j, m, B)$$



$$P(B|j, m)$$



# Another Variable Elimination Example

Query:  $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

$$p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$$

Eliminate  $X_1$ , this introduces the factor  $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$ , and we are left with:

$$p(Z)f_1(Z, y_1)p(X_2|Z)p(X_3|Z)p(y_2|X_2)p(y_3|X_3)$$

Eliminate  $X_2$ , this introduces the factor  $f_2(Z, y_2) = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$ , and we are left with:

$$p(Z)f_1(Z, y_1)f_2(Z, y_2)p(X_3|Z)p(y_3|X_3)$$

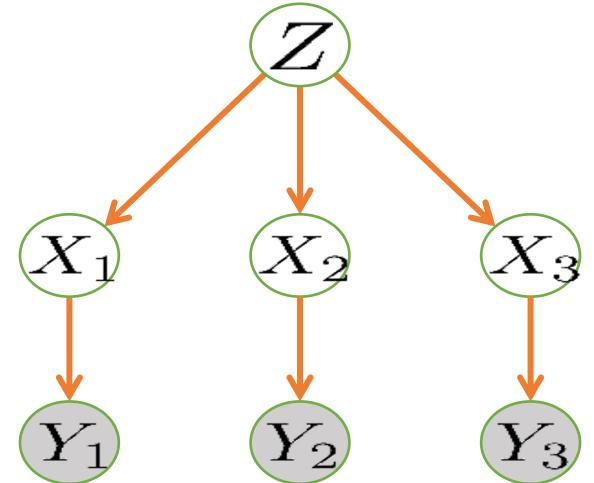
Eliminate  $Z$ , this introduces the factor  $f_3(y_1, y_2, X_3) = \sum_z p(z)f_1(z, y_1)f_2(z, y_2)p(X_3|z)$ , and we are left:

$$p(y_3|X_3), f_3(y_1, y_2, X_3)$$

No hidden variables left. Join the remaining factors to get:

$$f_4(y_1, y_2, y_3, X_3) = P(y_3|X_3)f_3(y_1, y_2, X_3).$$

Normalizing over  $X_3$  gives  $P(X_3|y_1, y_2, y_3)$ .

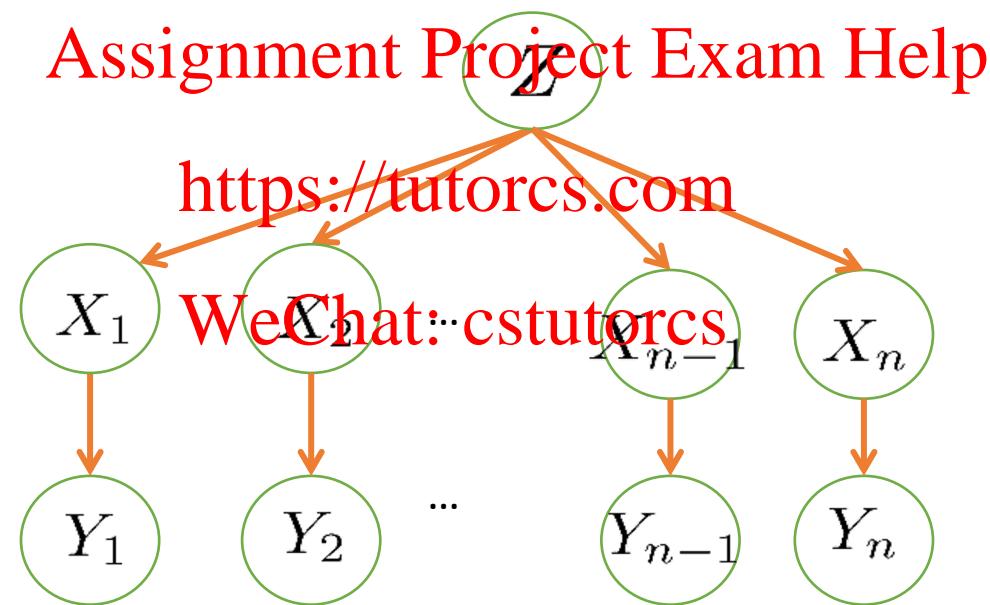


Computational complexity critically depends on the largest factor being generated in this process. Size of factor = number of entries in table. In example above (assuming binary) all factors generated are of size 2 --- as they all only have one variable (Z, Z, and  $X_3$  respectively).



# Variable Elimination Ordering

- For the query  $P(X_n | y_1, \dots, y_n)$  work through the following two different orderings as done in previous slide:  $Z, X_1, \dots, X_{n-1}$  and  $X_1, \dots, X_{n-1}, Z$ . What is the size of the maximum factor generated for each of the orderings?



- Answer:  $2^{n+1}$  versus  $2^2$  (assuming binary)
- In general: the ordering can greatly affect efficiency.



# VE: Computational and Space Complexity

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- The computational and space complexity of variable elimination is determined by the largest factor

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- The elimination ordering can greatly affect the size of the largest factor.  
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  - E.g., previous slide's example  $2^n$  vs. 2

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- Does there always exist an ordering that only results in small factors?
  - No!



# Worst Case Complexity?

- CSP:

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_1 \vee x_3 \vee \neg x_4) \wedge (x_2 \vee \neg x_2 \vee x_4) \wedge (\neg x_3 \vee \neg x_4 \vee \neg x_5) \wedge (x_2 \vee x_5 \vee x_7) \wedge (x_4 \vee x_5 \vee x_6) \wedge (\neg x_5 \vee x_6 \vee \neg x_7) \wedge (\neg x_5 \vee \neg x_6 \vee x_7)$$

$$P(X_i = 0) = P(X_i = 1) = 0.5$$

$$Y_1 = X_1 \vee X_2 \vee \neg X_3$$

$$Y_8 = \neg X_5 \vee X_6 \vee X_7$$

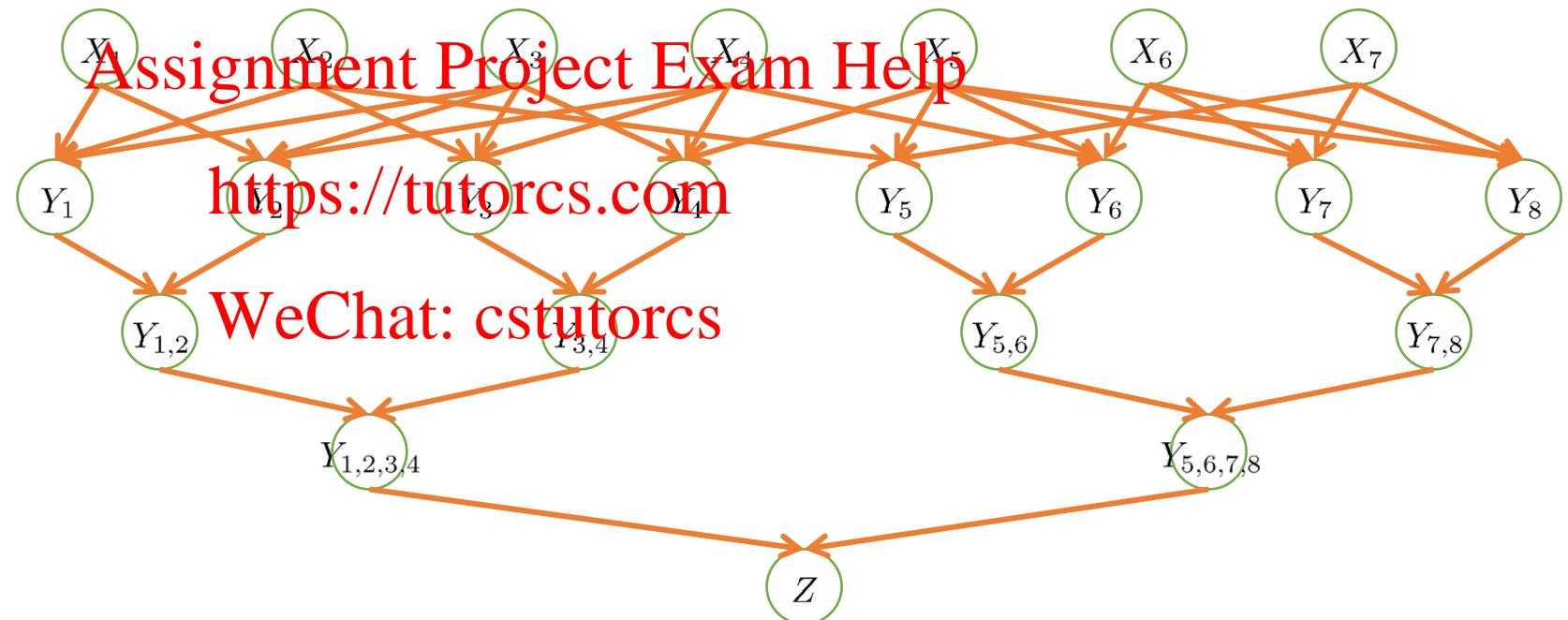
$$Y_{1,2} = Y_1 \wedge Y_2$$

$$Y_{7,8} = Y_7 \wedge Y_8$$

$$Y_{1,2,3,4} = Y_{1,2} \wedge Y_{3,4}$$

$$Y_{5,6,7,8} = Y_{5,6} \wedge Y_{7,8}$$

$$Z = Y_{1,2,3,4} \wedge Y_{5,6,7,8}$$



- If we can answer  $P(z)$  equal to zero or not, we answered whether the 3-SAT problem has a solution.
- Hence inference in Bayes' nets is NP-hard. No known efficient probabilistic inference in general.



# Polytrees

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- A polytree is a directed graph with no undirected cycles
- For poly-trees you can always find an ordering that is efficient
  - Try it!! [Assignment Project Exam Help  
https://tutorcs.com](https://tutorcs.com)
- Cut-set conditioning for Bayes' net inference
  - Choose set of variables such that if removed only a polytree remains
  - Exercise: Think about how the specifics would work out!



# Bayes' Nets

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- ✓ Representation
- ✓ Conditional Independences
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- Probabilistic Inference
  - ✓ Enumeration (exact, exponential complexity)
  - ✓ WeChat: cstutorcs Variable elimination (exact, worst-case exponential complexity, often better)
  - ✓ Inference is NP-complete
    - Sampling (approximate)
- Learning Bayes' Nets from Data

