



程序代写
作业
CS编程辅导

COMP4121 Advanced Algorithms

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Assignment Project Exam Help

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Recommender Systems

Recommender Systems

- Main purpose: the nob~~g~~ goal of selling you as much stuff as possible, regardless of whether you need it or not.



- Examples of recommender systems:

- Netflix's, to recommend to you which movie to see next.
- Amazon's, to recommend to you which book to buy next.
- Kogan's to recommend which gizmo to buy next.
- IEEE's Xplore: to recommend which articles might be of interest to you, given what article you have just look at.

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- Two major kinds of recommender systems:

- content based **Email: tutorcs@163.com** similarity (i.e., similar properties, qualities, kind etc.)
For example a book might be recommended because you bought a book on a similar topic)
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- collaborative filtering. Items are recommended based on some similarity measure between users and between items based on ratings of items by the community of users.
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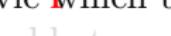
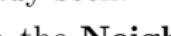
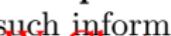
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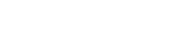
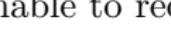
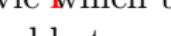
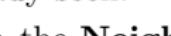
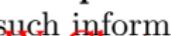
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- (II) based on similarity of items:

- assume it happened that two movies M_1 and M_2 received similar ratings by most users;
- a user has seen movie M_1 and liked it;
- then it is reasonable to recommend movie M_2 to such a user.



- Note that in both approaches, movies are not categorised and compared by their “intrinsic” features but we rely only on the “wisdom of the crowd”.

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- This is an example of *Collaborative Filtering*.

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- We now want to explore how such similarities of users and of items are measured in a most interesting way.

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- We can construct a sparsely populated table of ratings R ; the rows will correspond to movies, the columns to users. The entry $r(j, i)$ of the table, if non empty, represents the rating user U_i gave to movie M_j (in general, item M_j).

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- Usually, such a rating is the “number of stars”, in range 0 – 5 (or a similar, relatively small rating range, usually with at most 10 or so levels).

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Neighbourhood Method

- We replace these integers with more informative numbers.
- A more informative number can be obtained by computing the mean \bar{r} of all ratings of all users for movie M (thus, the mean of all numbers in our partial table of ratings R)
- We now obtain from the new table \bar{R} by replacing all ratings $r(j, i)$ in R by the values $r^*(j, i) =$



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- Now numbers $r^*(j, i)$ are already more informative: if $r^*(j, i) > 0$ this means, in a sense, that user U_j has liked movie M_i above the “global average”.
- The fact that numbers $r^*(j, i)$ can be both positive and negative with about equal likelihood is important for the subsequent steps to be taken.
- Some users are more generous and tend to give higher scores than the average user; some are more critical and tend to give lower scores.
- We are not interested in evaluating generosity of users, we want to assess only the “taste” of users: what they like and what they like less.
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- For that reason we want to remove the “systematic biases” of both the users and the movies, thus taking out the individual “generosity” of each user and the “hype” of each movie.
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$$S(\vec{v}, \vec{\mu}) = \sum_{(j,i) \in R} (r^*(j,i) - v_i - \mu_j)^2$$

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- Note that μ 's are constant shifts of rows (each row corresponding to a movie) and v 's are constant shifts of columns (each column corresponding to a user)
- We chose such constant shifts of each row and of each column which minimise the residuals.
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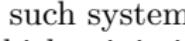
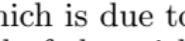
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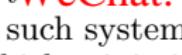
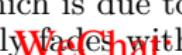
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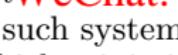
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$$= -2 \sum_{(j,i) \in R} (r^*(j,i) - v_i - \mu_j) = 0$$

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$$S(\vec{v}, \vec{\mu}, \lambda) = \sum_{(j,i) \in R} (r^*(j, i) - v_i - \mu_j)^2 + \lambda \left(\sum_i v_i^2 + \sum_j \mu_j^2 \right)$$

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where λ is a suitably chosen small positive constant, usually $10^{-10} \leq \lambda \leq 10^{-2}$.

- Optimal value of λ can be “learned” in a way to be described later.
- We now obtain from table R by replacing all $r^*(j, i)$ in \bar{R} with values $\tilde{r}(j, i) = r^*(j, i) - v_i - \mu_j$ where v 's and μ 's were obtained by our regularised least squares.
- Having removed the systematic biases of users and trendiness of movies, we are now ready to estimate similarities of users and similarities of movies.

Neighbourhood Method

- Unfortunately, Least Squares fits usually suffer from overfitting: they often minimise the objective function by choosing excessively large values for the variables, relying on many relations of positive and negative terms.
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Neighbourhood Method - similarity of users

- One of the most frequently used measure of similarity of users is the *cosine similarity measure*.
- Let us first compare two users U_i and U_k . We find all movies that both users have ranked and delete all other entries $\tilde{r}(j, i)$ and $\tilde{r}(j', k)$ in the corresponding columns of these two users. This gives us a partial table \tilde{R} (thus, we remove ratings of movies which only one of the two users have seen and all the blank spaces).
- In this way we obtain two column vectors \vec{u}_i and \vec{u}_k such that the coordinates of vector \vec{u}_i are the rankings of user U_i and the coordinates of vector \vec{u}_k are rankings of user U_k of all the movies seen by both users.
- The similarity of the two users is measured by the cosine of the angle between these two vectors.
- Intuitively, these two users have similar tastes if the two vectors point in “similar directions”.
- Recall that

$$\text{QQ: 749389476} \\ \cos(u_i, u_k) = \frac{\langle \vec{u}_i, \vec{u}_k \rangle}{\|\vec{u}_i\| \cdot \|\vec{u}_k\|}$$

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where $\langle \vec{u}_i, \vec{u}_k \rangle = \sum_p (\vec{u}_i)_p (\vec{u}_k)_p$ is the scalar product of vectors \vec{u}_i and \vec{u}_k and $\|\vec{u}_k\| = \sqrt{\sum_p (u_k)_p^2}$ is the norm (the “length”) of vector \vec{u}_k .

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- Thus we define the similarity of users U_i and U_k as



$$\text{sim}(U_i, U_k) = \frac{\langle \vec{u}_i, \vec{u}_k \rangle}{\|\vec{u}_i\| \cdot \|\vec{u}_k\|}$$

- To explain why we divide the scalar product $\langle \vec{u}_i, \vec{u}_k \rangle$ by the product $\|\vec{u}_i\| \cdot \|\vec{u}_k\|$ of the norms of the two vectors, note that these norms are likely to depend on the dimension of vectors \vec{u}_i and \vec{u}_k , which in turn depends on the number of the movies these two users have both seen.
- This is not a good feature; $\text{sim}(U_i, U_k)$ should depend only on the “intrinsic similarity” of tastes of the two users, and should not depend on irrelevant things such as the number of movies they have both seen.
- Dividing the scalar product by the product of their norms results in a quantity depending only on the angle between the two vectors, which more properly reflects similarity of the tastes of the two users.
- Determining the values of $\text{sim}(U_i, U_k)$ for every pair of users is a “preprocessing” step which can be updated every few days as new ratings from users are received.
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Neighbourhood Method - similarity of users

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- Among all users who have seen movie M_j pick L many users U_{k_l} with L largest values of $|\text{sim}(U_i, U_{k_l})|$
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$$\text{pred}(j, i) = \bar{r} + v_i + \mu_j + \frac{\sum_{1 \leq l \leq L} \text{sim}(U_i, U_{k_l}) \tilde{r}(j, k_l)}{\sum_{l=1}^L |\text{sim}(U_i, U_{k_l})|}$$

- We then recommend to add v_i movies when the predicted rating $\text{pred}(j, i)$ is the highest.
- Note that “the hype factor μ_j ” is brought back into the equation when deciding what to recommend.
- Factor v_i is constant across movies so it is insignificant; adding it is mostly for test purposes because it will more realistically predict the possible rating of user U_i of movie M_j allowing easy comparison in tests.

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$$\text{pred}(j, i) = \bar{r} + v_i + \mu_j + \frac{\sum_{1 \leq l \leq L} \text{sim}(U_i, U_{k_l}) \tilde{r}(j, k_l)}{\sum_{1 \leq l \leq L} |\text{sim}(U_i, U_{k_l})|}$$

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- We then recommend to user U_i movie M_j for which the predicted rating $\text{pred}(j, i)$ is the highest.
- Note that “the hype factor” μ_j is brought back into the equation when deciding what to recommend.
- Factor v_i is constant across movies so it is insignificant; adding it is mostly for test purposes because it will more realistically predict the possible rating of user U_i of movie M_j allowing easy comparison in tests.

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Neighbourhood Method - similarity of movies

- We can in a similar way estimate similarity of movies working on columns of table \tilde{R} (instead of rows).

- For any two movies M_j and M_n consider all users which have rated both movies and form two vectors \vec{m}_j and \vec{m}_n with coordinates which are the ratings of the form $\tilde{r}(j, l)$ and $\tilde{r}(n, l)$ where l ranges over all users who rated both movies.

- We can now define the similarity between these two movies as

$$\text{WeChat: cstutorcs} \frac{\langle \vec{m}_j, \vec{m}_n \rangle}{\| \vec{m}_j \| \cdot \| \vec{m}_n \|}$$

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- If we now want to predict how a user U_i would rank a movie M_j we would pick among all the movies M_{nl} from I those for which $|\text{sim}(M_j, M_{nl})|$ are the largest.
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$$\text{pred}(j, i) = \frac{\sum_{1 \leq l \leq L} \text{sim}(M_j, M_{nl}) \tilde{r}(n_l, i)}{\sum_{1 \leq l \leq L} |\sum_{1 \leq l \leq L} \text{sim}(M_j, M_{nl})|}$$

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Latent Factor Method

- A very different commonly used method is the Latent Factor Method.
- Heuristics behind the method:
 - One can argue that there is only a relatively small number (up to a few hundreds) of features a movie might possess to various extents which appeal to user's tastes and which determine how much a particular user would like such a movie.
 - Examples of such features are “action movie”, “romantic movie”, “famous actors”, “special effects”, “violence”, “humour”, etc.
 - Let us enumerate all of these features as f_1, f_2, \dots, f_N where N is of the order of a few tens to a few hundreds.
 - A movie can have a rating r_{ij} for feature f_i to an extent e_i , where e_i is, say, between 0 and 10.
 - Thus, to each movie M_j corresponds a vector \vec{e}^j of length N such that its i^{th} coordinate $(\vec{e}^j)_i$ represents the extent to which movie M_j has feature f_i .
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Latent Factor Method

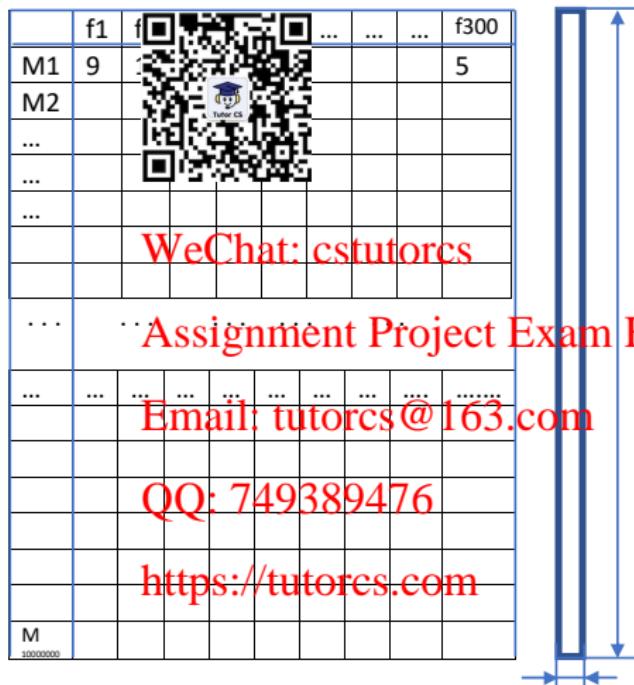
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Latent Factor Method

- Thus, if feature f_1 is “action movie” and if $F(1, 1) = 9$ this would mean that the first movie on our list has a very significant action component.

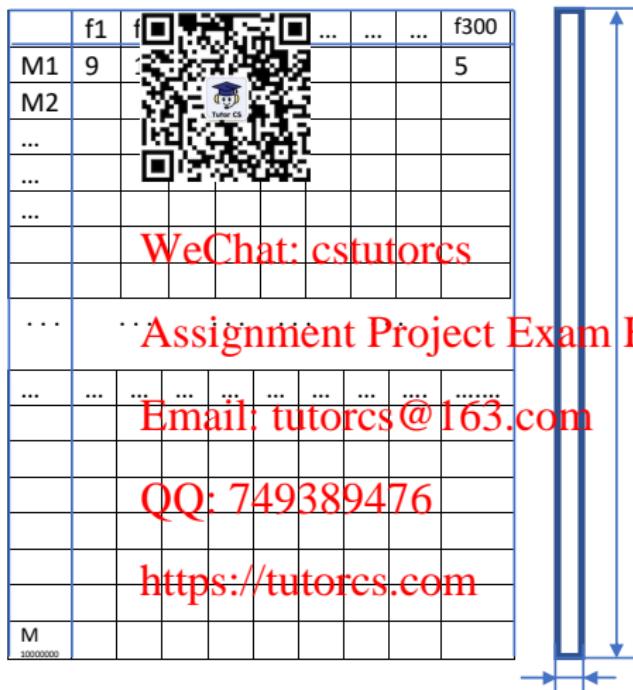


A few hundreds
of features



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- Thus, for example, if feature f_1 is “action movie” and if for user U_1 the value of $(\vec{l}^1)_1$ is 9, this would mean that user U_1 likes very much movies with a lot of action.
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- If feature f_m is “special effects” and entry $L(m, i)$ in m^{th} row and i^{th} column is, say, 5, this would mean that user U_i is ambivalent towards feature f_m : he neither likes nor dislikes movies which have lots of special effects.



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Latent Factor Method

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- If feature f_1 is “action” and feature f_2 is “romantic movie” and if $L(1, 1) = 9$ and $L(2, 1) = 1$, it could mean that the first user on our list likes movies with lots of action but does not like movies with lots of romance.



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hundreds of thousands of users

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- Assume for a moment that somehow we have access to matrix F which specifies for each movie M_i to what degree it has each feature f_m and matrix L which specifies for each feature f_m how important each feature f_m is.

- Let us fix a movie M_j and its feature content vector \vec{e}^j .
- Thus, for every feature f_m the coordinate $(\vec{e}^j)_m$ of \vec{e}^j specifies how much of feature f_m the movie M_j has.
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- Then for every user U_i and every movie M_j it would be easy to predict how much U_i would like M_j .

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$$E(j,i) = \sum_{1 \leq m \leq N} (\vec{l}^i)_m (\vec{e}^j)_m = \langle \vec{e}^j, \vec{l}^i \rangle.$$

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- Let us also fix a user U_i and its feature importance vector \vec{l}^i .
- Thus, for every feature f_m the coordinate $(\vec{l}^i)_m$ of \vec{l}^i specifies how important is that a movie has feature f_m .
- Then for every user U_i and every movie M_j it would be easy to predict how much U_i would like M_j .

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$$E(j,i) = \sum_{1 \leq m \leq N} (\vec{e}^j)_m (\vec{l}^i)_m = \langle \vec{e}^j, \vec{l}^i \rangle.$$

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- But note that $E(j,i)$ is precisely the entry of the matrix $E = F \times L$ in j^{th} row and i^{th} column:

Latent Factor Method

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- Assume for a moment that somehow we have access to matrix F which specifies for each movie M_i to what degree it has each feature f_m and matrix L which specifies for each feature f_m how important each feature f_m is.
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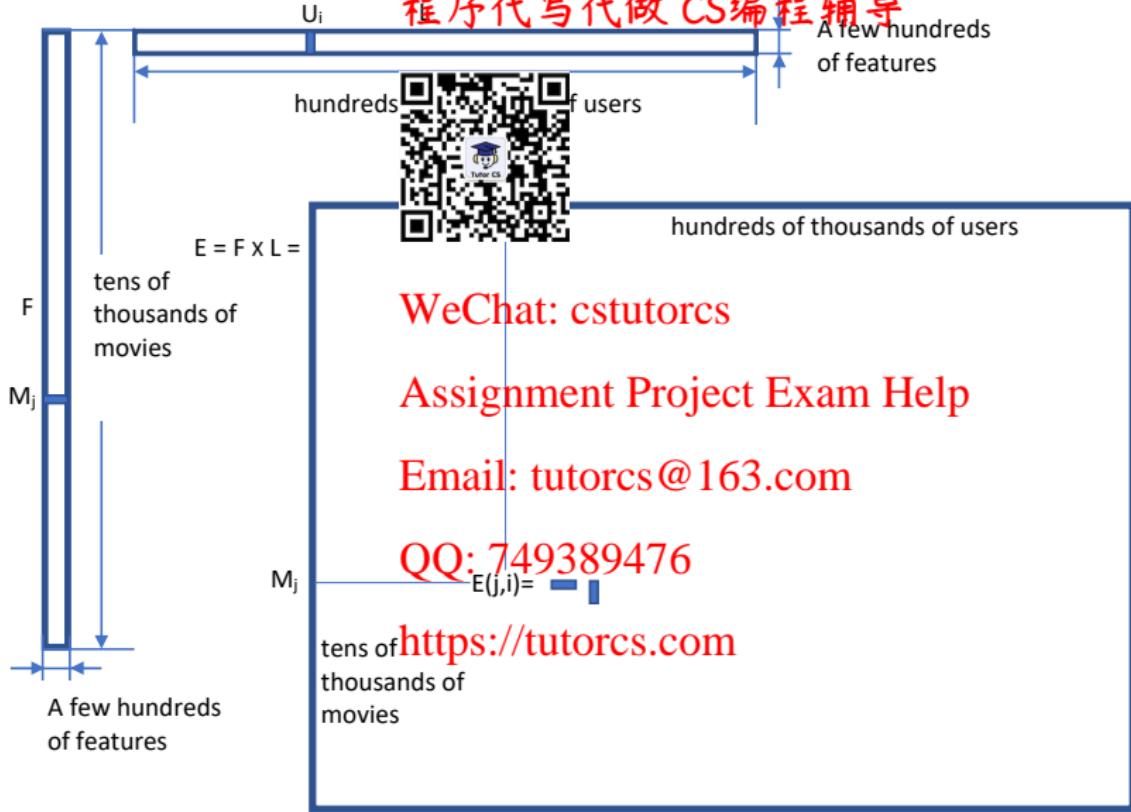
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- However, there is a very serious problem with such an approach to prediction how much would a user like movie M_j .
- How can we determine which are the relevant few dozens to few hundreds of features needed to describe a movie exhaustively?



- Who would assess each movie objectively according to how much of each feature such a movie has?

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- Even worse, how would we determine objectively how much each feature is important to each user?

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- Solution: all of these should be “learned” from the partial table of the existing ratings of movies!

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- We even do not need to know what all features are or what they mean.

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Latent Factor Method

- Let N be the number of “features” we want to let emerge (with no meaning assigned whatsoever). In applications N ranges between 20 and up to 200.
 - Let $\#M$ be the number of features in the database and $\#U$ be the number of users.
 - Idea:** Fill matrices F $\times N$ and L of size $N \times \#U$ with variables $F(j, m)$ and $L(m, i)$ which yet have to be determined.
 - Solve the following least squares problem in the variables



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- Note that the total number of variables is $(\#M + \#U) \times N$.
 - So N should be chosen so that $(\#M + \#U) \times N$ is a fraction of the total number of existing entries in the partially filled table R of user's ratings.
 - Note that if we manage to find $F(j, m)$'s and $L(m, i)$'s which "optimally model" data, we have no way of figuring out what are the "features" these numbers are representing; they simply "emerged" from the data.

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$$S(\vec{F}, \vec{L}) = \sum_{(j, i): R(j, i) \text{ exists}} \left(\sum_{1 \leq m \leq N} F(j, m) \cdot L(m, i) - R(j, i) \right)^2$$

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- However, there is a serious problem with this approach: setting the partial derivatives of the objective $S(\vec{F}, \vec{L})$ with respect to all variables to zero results in the following system of equations:

$$\frac{\partial}{\partial F(j, m)} S(\vec{F}, \vec{L})$$



$$= \frac{\partial}{\partial F(j, m)} \sum_{i: R(j, i) \text{ exists}} \left(\sum_{1 \leq m \leq N} F(j, m) \cdot L(m, i) - R(j, i) \right)^2$$

$$= 2 \sum_{i: R(j, i) \text{ exists}} \left(\sum_{1 \leq m \leq N} F(j, m) \cdot L(m, i) - R(j, i) \right) L(m, i) = 0;$$

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$\frac{\partial}{\partial L(m, i)} S(\vec{F}, \vec{L})$ <https://tutorcs.com>

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Latent Factor Method

- This is a huge system of cubic equations and cannot be solved feasibly.
- Worse, such an optimisation problem is often non-convex, so search for the optimal solution can end up in a local minimum.
- We apply an iterative process to find an approximate solution.
- Note that we apply such an iterative process directly to “raw data” - no de-biasing like the one we performed in the Nearest Neighbour Method.
- Steps:



- We initially set all variables $F(j, m)$ to the same value $F^{(0)}(j, m)$, say a median value.
- We now solve the following Least Squares problem in variables $\{L(m, i) : 1 \leq m \leq M\}$.

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$$\sum_{(j,i):R(j,i) \text{ exists}} \left(\sum_{1 \leq m \leq N} F^{(0)}(j, m) \cdot L(m, i) - R(j, i) \right)^2$$

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- Note that, since $F^{(0)}(j, m)$ are concrete numbers rather than variables, such a Least Squares problem does reduce to a system of linear equations after we find the partials and set them to zero.
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QQ: 749389476
<https://tutorcs.com>

- Note that, since $F^{(0)}(j, m)$ are concrete numbers rather than variables, such a Least Squares problem does reduce to a system of linear equations after we find the partials and set them to zero.
- This Least Squares can also be regularised just as previously.

Latent Factor Method

- This is a huge system of cubic equations and cannot be solved feasibly.
- Worse, such an optimisation problem is even not convex, so search for the optimal solution can end up in a local minimum.
- We apply an iterative  find an approximate solution.
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- Steps:

- We initially set all variables $F(j, m)$ to the same value $F^{(0)}(j, m)$, say a median value.

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- we now solve the following Least Squares problem in variables $\{L(m, i) : 1 \leq m \leq M\}$

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minimize

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Latent Factor Method

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- Steps (continued):

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minimize

$$\sum_{(j,i):R(j,i)} \left(\sum F(j, m) \cdot L^{(0)}(m, i) - R(j, i) \right)^2$$

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- Note that, since $L^{(0)}(m, i)$ are numbers (obtained as the solutions of the previous Least Squares problem) rather than variables, such a Least Squares problem again reduces to a system of linear equations after we find the partials and set them to zero.
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Latent Factor Method

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Latent Factor Method

- Steps (continued):

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- minimize

$$\sum_{(j,i):R(j,i)} \left[F^{(1)}(j,m) \cdot L(m,i) - R(j,i) \right]^2$$


- We keep alternating between taking either $\{F(j, m) : 1 \leq m \leq N\}$ or $\{L(m, i) : 1 \leq m \leq N; 1 \leq i \leq \#U\}$ as free variables, fixing the values of the other variables to the solution to the corresponding Least Squares problem.
 - This method is sometimes called “*Method of Alternating Projections*”.
 - We stop such iterations when

$$\sum_{(j,m)} (F^{(k)}(j,m) - F^{(k-1)}(j,m))^2 + \sum_{(i,m)} (L^{(k)}(m,i) - L^{(k-1)}(m,i))^2$$

becomes smaller than an accuracy threshold $\varepsilon > 0$.

Latent Factor Method

- Steps (continued):

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Latent Factor Method

- Steps (continued): 程序代写代做 CS编程辅导

- After we obtain the values $F^{(k)}(j, m)$ and $L^{(k)}(m, i)$ from the last iteration k , we can construct corresponding matrices F of size $\#M \times N$ and L of size $N \times \#U$.



$$\tilde{F} = \left(F^{(k)}(j, m) : 1 \leq j \leq \#M; 1 \leq m \leq N \right);$$
$$\tilde{L} = \left(L^{(k)}(m, i) : \text{WeChat: cstutorcs} \leq N; 1 \leq i \leq \#U; \right).$$

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- We finally set $E = F \times L$ as the final matrix of predicted ratings of all movies by all users where E_{ij} is the prediction of the rating of movie M_j by user U_i .
- Each of N “features” QQ: 749389476 which $F(j, m)$ is supposed to “measure” in a movie M_j is a “latent factor” which we have no way of describing.
- Some computer scientists say it doesn’t work but the recommender systems based on the Latent Factor Method perform remarkably well in many domains.
- Most likely this is because they are able to leverage the “global information”, based on the relationship of ALL ratings, more effectively than the Neighbourhood Methods which use ratings in a more “localised way”.

Latent Factor Method

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 - After we obtain the values $F^{(k)}(j, m)$ and $L^{(k)}(m, i)$ from the last iteration k , we form corresponding matrices \tilde{F} of size $\#M \times N$ and \tilde{L} of size $N \times \#U$.
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Recommender Systems - conclusions

- So we presented two kinds of recommender systems:

- the Neighbourhood Method (in two flavours, one based on the similarity of users, another based on similarity of movies)
- the Latent Factor Model which can be deployed with different number N of “latent factors” (in applications usually between 20 and 200)



- So how do we decide which method to use in a particular application?
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- How can we evaluate how effective a particular choice of a recommender system is?
Assignment Project Exam Help
- **Idea:** We use real existing data. As an example we use the *Netflix Challenge* competition.
Email: tutorcs@163.com
- Netflix provided approximately 100 million actual ratings of 480,000 users, rating 17,770 movies.
QQ: 749389476
- The competition was to stay open till a submission was able to beat the Netflix's own recommendation system by more than 10% and then all the competitors had 30 days to submit an algorithm which was the final entry.
- The team with the best performing algorithm would get a prize of 1 million US dollars.

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- The team with the best performing algorithm would get a prize of 1 million US dollars.

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Recommender Systems - conclusions

- So we presented two kinds of recommender systems:
 - the Neighbourhood Method (in two flavours, one based on the similarity of users, the other based on similarity of movies)
 - the Latent Factor Model which can be deployed with different number N of “latent factors” (in applications usually between 20 and 200)

- So how do we decide which one we should use in a particular application?

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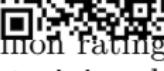
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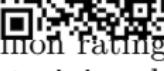
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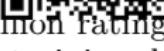
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- But instead of picking one recommender system over another one, we can also combine several recommender systems as follows.
- Let $P_k(j, i)$ be the predicted ratings of a recommender system S_k , $1 \leq k \leq B$, where we have B many recommender systems.
- We can now form a combined prediction as a weighted average



$$= \sum_{1 \leq k \leq B} w_k P_k(j, i)$$

where $\sum_{1 \leq k \leq B} w_k = 1$ are positive weight factors.

- But how do we determine optimal weights w_k , and also optimal values of other parameters such as the regularisation factor λ and the number N of Latent Factors?
- The answer is pretty mundane: by an arduous trial and error procedure:
- If we have a massive training data set as in the case of the Netflix prize, we can remove quite a few smaller testing subsets T_q of ratings and then use the algorithm with different values of the parameters to predict these removed test ratings.
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Recommender Systems - conclusions

- In fact, the best performing algorithms at the Netflix competition were combinations of dozens of components with empirically tuned parameters.
- Further improvements in performance can be achieved by giving lower weights to older ratings of movies, also introducing the temporal dimension.
- Conclusion:
- The Recommender Systems, just as the Google PageRank algorithm, exemplify a design paradigm:
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- The ingredient “baseline” algorithms have a sound basis employing increasingly sophisticated mathematical concepts and theorems.
- However, the final product is an empirically obtained “tweak” of such component algorithms.
- Unlike Physics, Computer Science cannot seek “definitive”, exact methods and theories, especially for applications which involve subjective human factors such as taste or human opinion.
- We look for good approximations of complex and “noisy” reality, obtained from mathematically based components through empirical testing and tweaking.
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- The ingredient “baseline” algorithms have a sound basis employing increasingly sophisticated mathematical concepts and theorems.
- However, the final product is an empirically obtained “tweak” of such component algorithms
- Unlike Physics, Computer Science cannot seek “definitive”, exact methods and theories, especially for applications which involve subjective human factors such as taste or human opinion.
- We look for good approximations of complex and “noisy” reality, obtained from mathematically based components through empirical testing and tweaking.
- In most of engineering fields the only real criterion of the success of a new design is the commercial impact of such a design!

Recommender Systems - conclusions

- In fact, the best performing algorithms at the Netflix competition were combinations of dozens of components with empirically tuned parameters.
- Further improvements can be achieved by giving lower weights to older ratings of movies so introducing the temporal dimension.
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