



程序代写代做 CS编程辅导



UNSW
SYDNEY



MP4161

Advanced Topics in Software Verification

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Last Time

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- Syntax of a simple language
- Operational semantics
- Program proof on operational semantics
- Hoare logic rules
- Soundness of Hoare logic



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Content

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→ Foundations & Principles

- Intro, Lambda natural deduction [1,2]
- Higher Order (part 1) [2,3^a]
- Term rewriting [3,4]



→ Proof & Specification Techniques

- Inductively defined sets, rule induction [4,5]
- Datatype induction, primitive recursion [5,7]
- General recursive functions, termination proofs [7^b]
- Proof automation (part 2) [8]
- Hoare logic, proofs about programs, invariants [8,9]
- C verification [9,10]
- Practice, questions, exam prep [10^c]

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^aa1 due; ^ba2 due; ^ca3 due

Automation?

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Last time: Hoare reasoning is nicer than using operational semantics.



BUT:

- it's still kind of tedious
- it seems boring & mechanical

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Invariant

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Problem: While – no activity to find right (invariant) P

Solution:

- annotate program with invariants
- then, Hoare rules can be applied automatically

Example:

$\{M = 0 \wedge N = 0\}$
WHILE $M \neq a$ INV $\{N = M * b\}$ DO $N := N + b; M := M + 1$ OD
 $\{N = a * b\}$

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Weakest Preconditions

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$\text{pre } c \ Q = \exists P \text{ such that } \{P\} \ c \ \{Q\}$

With annotated invariant, try to get:

$\text{pre SKIP } Q = Q$

$\text{pre } (x := a) \ Q = \lambda \sigma. Q(\sigma(x := a\sigma))$

$\text{pre } (c_1; c_2) \ Q = \text{pre } c_1 \ (\text{pre } c_2 \ Q)$

$\text{pre } (\text{IF } b \ \text{THEN } c_1 \ \text{ELSE } c_2) \ Q = (b \rightarrow \text{pre } c_1 \ Q \ \sigma) \wedge (\neg b \rightarrow \text{pre } c_2 \ Q \ \sigma)$

$\text{pre } (\text{WHILE } b \ \text{INV } I \ \text{DO } c \ \text{OD}) \ Q = I$

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Verification Conditions

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$\{\text{pre } c \ Q\} \ c \ \{\text{Q}\}$ only true under certain conditions



These are called **verification conditions** $\text{vc } c \ Q$:

$\text{vc SKIP } Q = \text{True}$

$\text{vc } (x := a) \ Q = \text{True}$

$\text{vc } (c_1; c_2) \ Q = \text{vc } c_2 \ Q \wedge (\text{vc } c_1 \ (\text{pre } c_2 \ Q))$

$\text{vc } (\text{IF } b \ \text{THEN } c_1 \ \text{ELSE } c_2) \ Q = \text{vc } c_1 \ Q \vee \text{vc } c_2 \ Q$

$\text{vc } (\text{WHILE } b \ \text{INV } I \ \text{DO } c \ \text{OD}) \ Q = (\forall \sigma. I \sigma \wedge b \sigma \longrightarrow \text{pre } c \ I \ \sigma) \wedge$
 $(\forall \sigma. I \sigma \wedge \neg b \sigma \longrightarrow Q \ \sigma) \wedge$
 $\text{vc } c \ I$

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$\text{vc } c \ Q \wedge (P \implies \text{pre } c \ Q) \implies \{P\} \ c \ \{Q\}$

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Syntax Tricks

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- $x := \lambda\sigma. 1$ instead of $x := 1$ sucks
- $\{\lambda\sigma. \sigma x = n\}$  $\{x = n\}$ sucks as well

Problem: program variables are functions, not values

Solution: distinguish program variables syntactically

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Choices:

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- declare program variables with each Hoare triple
 - nice, usual syntax.
 - works well if you state full program and only use vcg
- separate program variables from Hoare triple (use extensible records),
indicate usage as function syntactically
 - more syntactic overhead
 - program pieces compose nicely

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Arrays

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Depending on language, model arrays as functions:

→ Array access = function application:

$a[i] = a$

→ Array update = function update:

$a[i] := v \quad = \quad a := a(i := v)$

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Use lists to express length:

→ Array access = nth:

$a[i] = a$

→ Array update = list update:

$a[i] := v \quad = \quad a := a[i := v]$

→ Array length = list length:

$a.length = \text{length } a$

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Pointers

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Choice 1

datatype	ref		Null
types	heap		val
datatype	val		= nat int Bool bool Struct_x int int bool ...

- hp :: heap, p :: ref
- Pointer access: $*p = \text{the_Int } (hp \text{ (the_addr } p))$
- Pointer update: $*p := v = hp := hp \text{ ((the_addr } p) := v)$
- a bit klunky
- gets even worse with structs
- lots of value extraction (the_Int) in spec and program

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Pointers

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Choice 2 (Burstall '72, Bornat '00)

Example: struct with pointer and element



datatype ref int | Null

types next_hp = int \Rightarrow ref

types elem_hp = int \Rightarrow int

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→ next :: next_hp, elem_hp \Rightarrow ref

→ Pointer access: $p \rightarrow \text{next} = \text{next} (\text{the_addr } p)$

→ Pointer update: $p \rightarrow \text{next} := v = \text{next} := \text{next} ((\text{the_addr } p) := v)$

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In general:

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→ a separate heap for each struct field

→ buys you $p \rightarrow \text{next} \neq p \rightarrow \text{elem}$ automatically (aliasing)

→ still assumes type safe language

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We have seen today ...

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- Weakest precondition
- Verification condition
- Example program
- Arrays, pointers



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