

# COMP 251

程序代写代做 CS编程辅导



Algorithms Structures (Winter 2021)

Algorithm Paradigms – DP3 + Greedy

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# Announcements

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# Outline

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- Complete Search
- Divide and Conquer
- Dynamic Programming
  - Introduction.
  - Examples.
- Greedy.
  - Introduction.
  - Examples.



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# DP—Activity-selection Problem

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- Input: Set  $S$  of  $n$  activities  $a_1, a_2, \dots, a_n$ .

- $s_i$  = start time of activity  $a_i$
- $f_i$  = finish time of activity  $a_i$



- Output: Subset  $A$  of maximum **number** of compatible activities.

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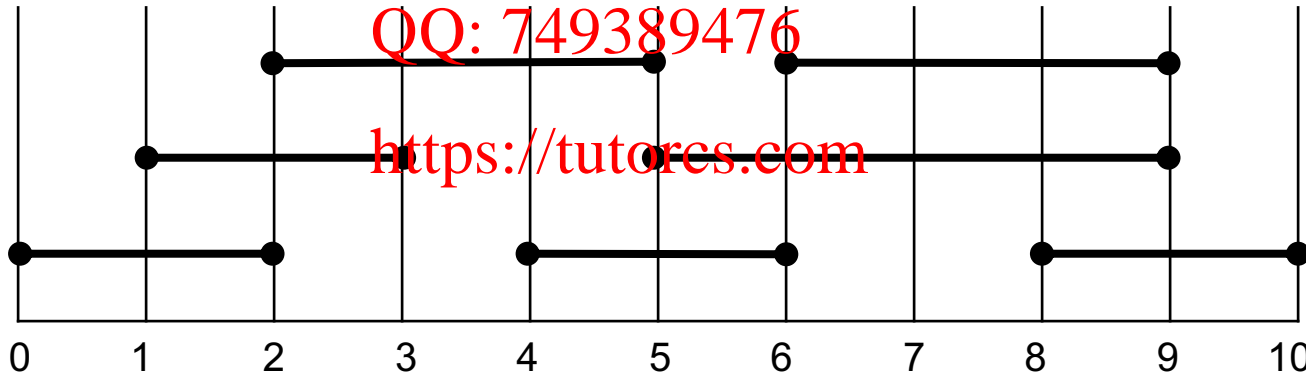
- 2 activities are compatible, if their intervals do not overlap.

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Example:

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Activities in each line are compatible.



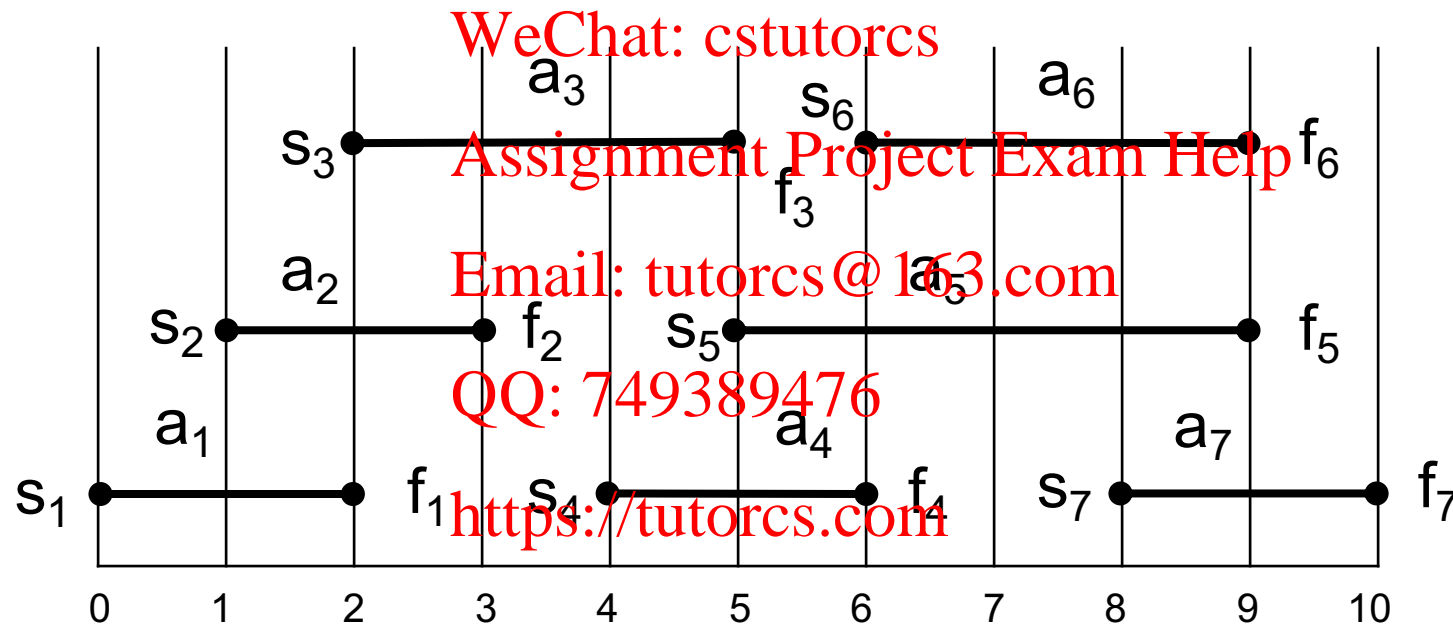
# DP— Activity-selection Problem

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i	1	2	3	4	5	6	7
$s_i$	0	2	3	4	5	6	8
$f_i$	2	3	5	6	9	9	10



Activities sorted by finishing time.



Optimal compatible set:  $\{ a_1, a_3, a_5 \}$

# DP—Activity-selection Problem

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**Step 1:** Identify the problems (in words).



**Step 1.1:** Identify the problems.

- Let  $S_{ij}$  = subset of activities in  $S$  that start after  $a_i$  finishes and finish before  $a_j$  starts.

$$S_{ij} = \{a_k \in S : \forall i, j \quad f_i \leq s_k < f_k \leq s_j\}$$

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- $A_{ij}$  = optimal solution to  $S_{ij}$

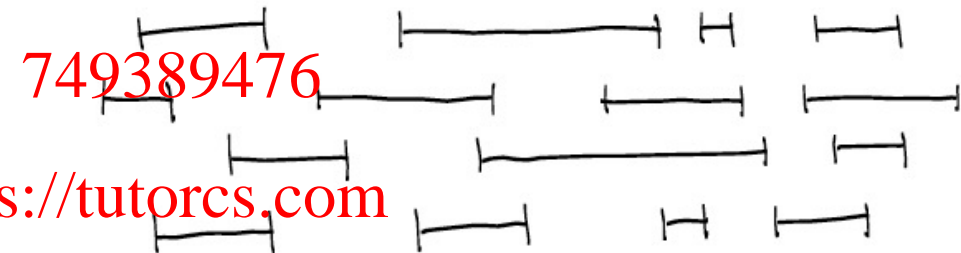
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- $A_{ij} = A_{ik} \cup \{a_k\} \cup A_{kj}$

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- $c[i, j]$  = size of  $A_{ij}$

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time

# DP—Activity-selection Problem

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Step 2: Find the recurrence.

Step 2.1: What decision to make at every step?

- Which activity  $a_k$  must take for the optimal set.

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# DP– Activity-selection Problem

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**Step 2:** Find the recurrence.

**Step 2.1:** What decision do we make at every step?.

- Which activity  $a_k$  must we take for the optimal set.
  - Subproblem: Selecting the maximum number of mutually compatible activities from  $S_{ij}$ .
  - Let  $c[i, j]$  = size of maximum-size subset of mutually compatible activities in  $S_{ij}$ .

$$c[i, j] = \begin{cases} 0 & \text{if } S_{ij} = \emptyset \\ \max_{\substack{k: i \leq k < j \text{ and } a_k \in S_{ij}}} \{c[i, k] + c[k, j] + 1\} & \text{if } S_{ij} \neq \emptyset \end{cases}$$

**Note:** We do not know (yet) which  $k$  to use for the optimal solution.



# DP—Activity-selection Problem

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## Step 2: Find the recurrence.

- Which activity  $a_k$  is best for the optimal set.

$$c[i, j] = \begin{cases} 0 & \text{if } S_{ij} = \emptyset \\ \max_{i < k < j \text{ and } a_k \in S_{ij}} \{c[i, k] + c[k, j] + 1\} & \text{if } S_{ij} \neq \emptyset \end{cases}$$

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# DP—Activity-selection Problem

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**Step 3:** Recognize and solve the base cases.

**Step 4:** Implement a methodology.

- We could then develop a recursive algorithm and memoize it, or we could work bottom-up and fill in table entries as we go along. But we would be overlooking another important characteristic of the activity-selection problem that we can use to great advantage.
- What if we could choose an activity to add to our optimal solution without having to first solve all the subproblems? That could save us from having to consider all the choices inherent in recurrence.
  - we need consider only one choice: the greedy choice



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# Greedy– Activity-selection Problem

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## Intuition:



- We should choose an activity that leaves the resource available for as many other activities as possible.
- Of the activities we end up choosing, one of them must be the first one to finish.
- Choose the activity in  $S$  with the earliest finish time

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# Greedy– Activity-selection Problem

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## Theorem:

Let  $S_{ij} \neq \emptyset$ , and let  $a_m$  be an activity in  $S_{ij}$  with the earliest finish time  $f_m = \min\{f_i \mid a_i \in S_{ij}\}$ . Then:



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# Greedy– Activity-selection Problem

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## Proof:

(1)  $a_m$  is used in some maximum-size subset of mutually compatible activities.



- Let  $A_{ij}$  be a maximum-size subset of mutually compatible activities in  $S_{ij}$  (i.e. an optimal solution of  $S_{ij}$ ).
- Order activities in  $A_{ij}$  in monotonically increasing order of finish time, and let  $a_k$  be the first activity in  $A_{ij}$ .
- If  $a_k = a_m \Rightarrow$  done.
- Otherwise, let  $A'_{ij} = A_{ij} - \{a_k\} \cup \{a_m\}$ .
- $A'_{ij}$  is valid because  $a_m$  finishes before  $a_k$ .
- Since  $|A_{ij}| = |A'_{ij}|$  and  $A_{ij}$  maximal  $\Rightarrow A'_{ij}$  maximal too.

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# Greedy–Activity-selection Problem

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## Proof:

(2)  $S_{im} = \emptyset$ , so that  $a_m$  leaves  $S_{mj}$  as the only nonempty subproblem.



If there is  $a_k \in S_{im}$  then  $f_j \leq s_k < f_k \leq s_m < \mathbf{f_m} \Rightarrow f_k < f_m$  which contradicts the hypothesis that  $a_m$  has the earliest finishing time.

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# Greedy– Activity-selection Problem

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# subproblems in optimal solution

# choices to consider

Before theorem	After theorem
2	1
1	1

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We can now solve the problem  $S_{ij}$  top-down:

- Choose  $a_m \in S_{ij}$  with the earliest finish time (greedy choice).
- Solve  $S_{mj}$ .

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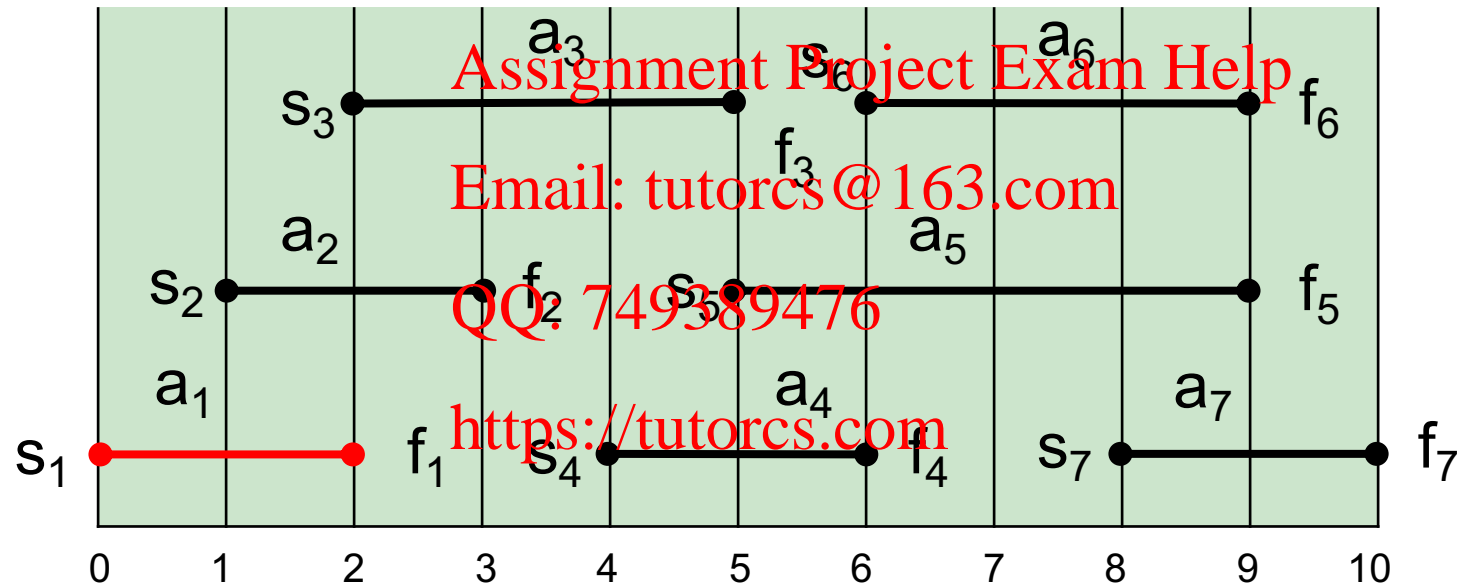
# Greedy– Activity-selection Problem

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i	1		4	5	6	7
$s_i$	0		4	5	6	8
$f_i$	2		6	9	9	10

Activities sorted by finishing time.

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# Greedy–Activity-selection Problem

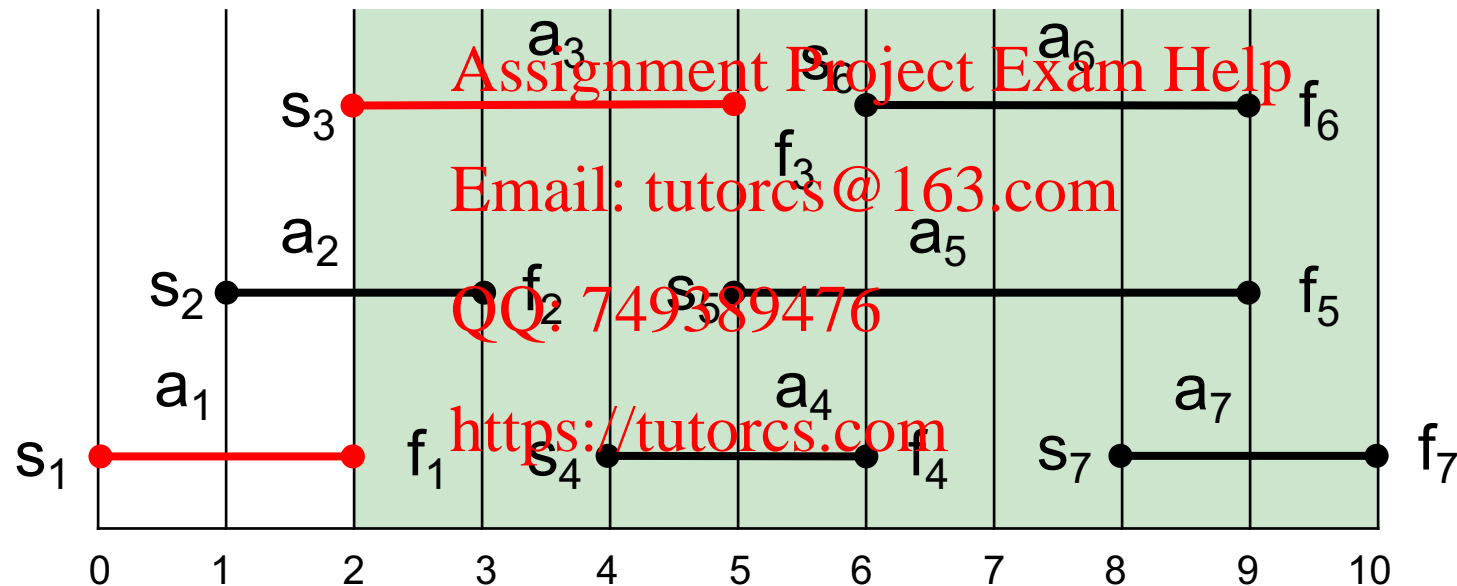
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# Greedy–Activity-selection Problem

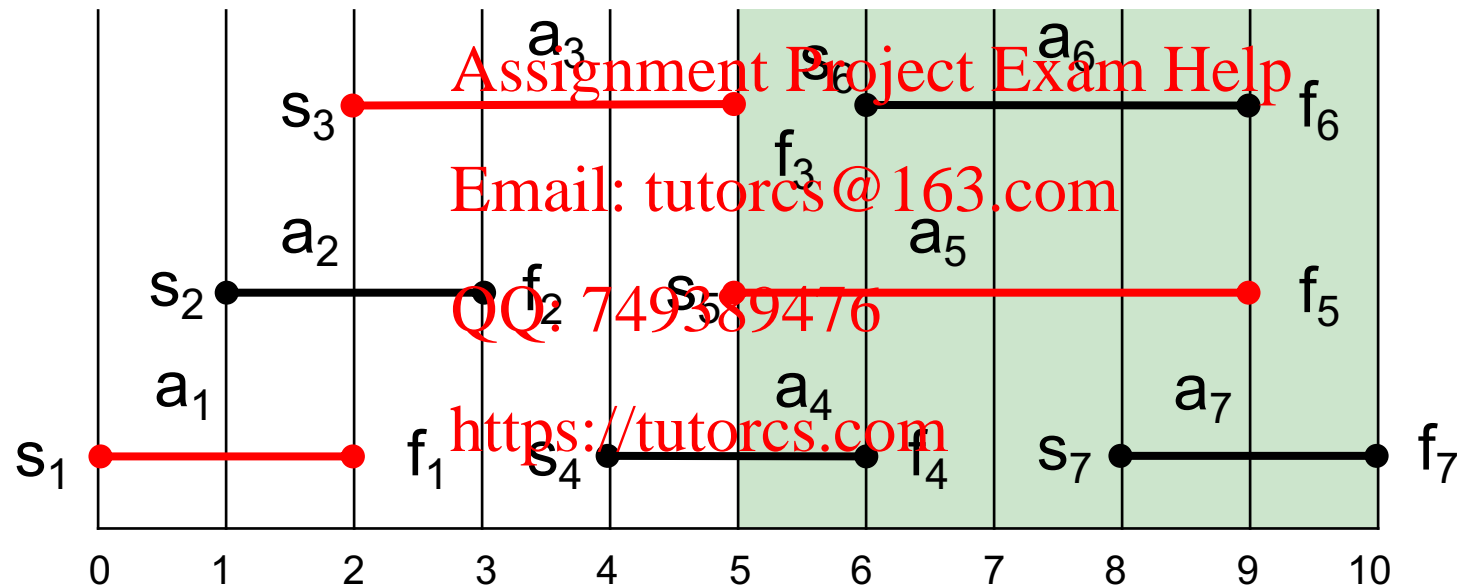
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Activities sorted by finishing time.

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# Greedy– Activity-selection Problem

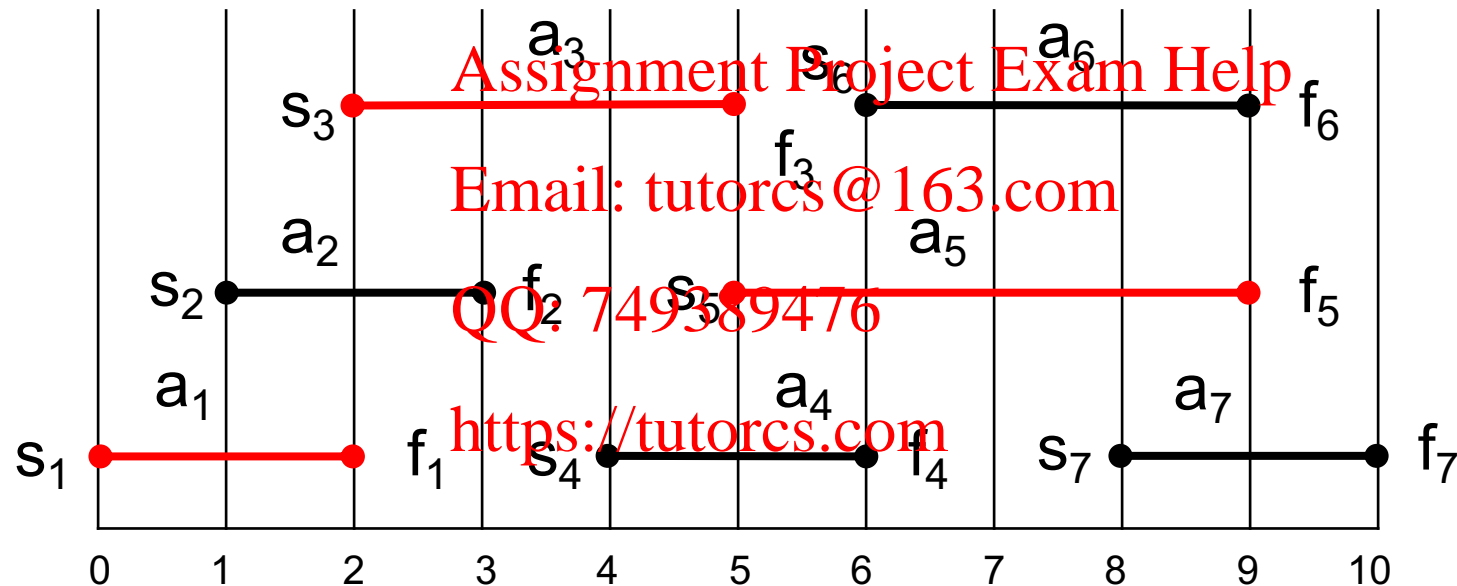
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Activities sorted by finishing time.


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# Greedy– Activity-selection Problem

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## Recursive-Selector (s, f, i, n)



1.  $m \leftarrow i+1$   
2. **while**  $m < f_i$  // Find first activity in  $S_{i,n+1}$   
3.     **do**  $m \leftarrow m+1$   
4.     **if**  $m \leq n$   
5.         **then return**  $\{a_i\} \cup$   
              Recursive-Activity-Selector( $s, f, m, n$ )  
6.     **else return**  $\emptyset$

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Recursive-Activity-Selector( $s, f, m, n$ )

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Initial Call: Recursive-Activity-Selector ( $s, f, 0, n+1$ )

Complexity:  $\Theta(n)$  <https://tutorcs.com>

Note 1: We assume activities are already ordered by finishing time.

Note 2: Straightforward to convert the algorithm to an iterative one.

# Greedy– Activity-selection Problem

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GREEDY-ACTIVITY-SELECTOR( $s, f$ )

1  $n \leftarrow \text{length}(A)$

2  $A \leftarrow A$

3  $k \leftarrow 1$

4 for  $m \leftarrow 2$  to  $n$

5     if  $s[m] \geq f[k]$

6          $A \leftarrow A \cup \{a_m\}$

7          $k \leftarrow m$

8 return  $A$

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Note 1: We assume activities are already ordered by finishing time.

Note 2: Straightforward to convert the algorithm to an iterative one.

# Greedy – Activity-selection Problem

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- Greedy template. Consider jobs in some natural order.
- Take each job provided it is compatible with the ones already taken.
- [Earliest start time] Consider jobs in ascending order of  $s_j$ .

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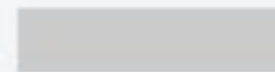
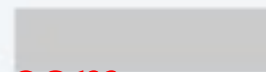
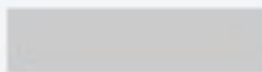
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counterexample for earliest start time



# Greedy – Activity-selection Problem

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- Greedy template. Consider jobs in some natural order.
- Take each job provided it is compatible with the ones already taken.
- [Shortest interval] Jobs in ascending order of  $f_j - s_j$ .

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counterexample for shortest interval

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# Greedy – Activity-selection Problem

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- Greedy template. Consider jobs in some natural order.
- Take each job provided it is compatible with the ones already taken.
- [Fewest conflicts] For each job  $j$ , count the number of conflicting jobs  $c_j$ . Schedule in ascending order of  $c_j$ .



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counterexample for fewest conflicts

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# Greedy – Similar to Activity-selection Problem

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- Problem:

- Lecture  $j$  starts at  $s_j$  and ends at  $f_j$ .
- Goal: find minimum number of classrooms to schedule all lectures so that no two lectures conflict the same time in the same room.
- Ex. This schedule uses 4 classrooms to schedule 10 lectures.

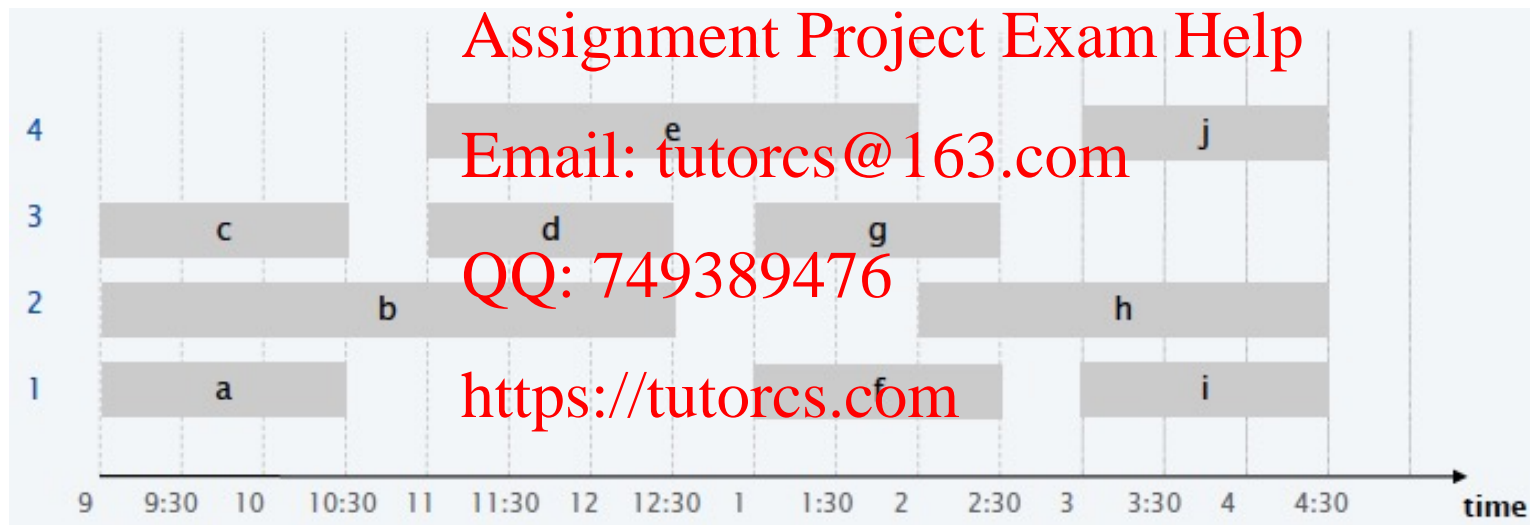
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# Greedy – Similar to Activity-selection Problem

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- Problem:

- Lecture  $j$  starts at  $s_j$  and ends at  $f_j$ .
- Goal: find minimum number of classrooms to schedule all lectures so that no two lectures conflict (i.e. same time in the same room).
- Ex. This schedule uses 3 classrooms to schedule 10 lectures.

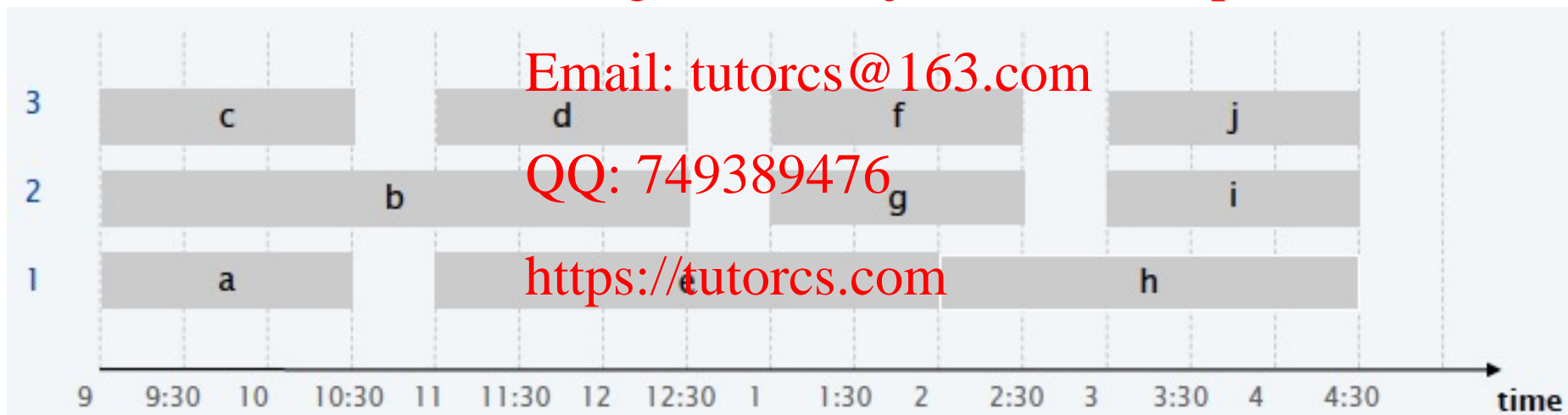
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# Greedy – Similar to Activity-selection Problem

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- Greedy template. Consider lectures in some natural order.
- Assign each lecture to an available classroom (which one?); allocate a new class if none are available.
- [Earliest finish time] Consider lectures in ascending order of  $f_j$ . (solution of the previous example.)

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counterexample for earliest finish time

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# Greedy – Similar to Activity-selection Problem

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- Greedy template. Consider lectures in some natural order.
- Assign each lecture to an available classroom (which one?); allocate a new class if none are available.
- [Shortest interval] Consider lectures in ascending order of  $f_j - s_j$ .

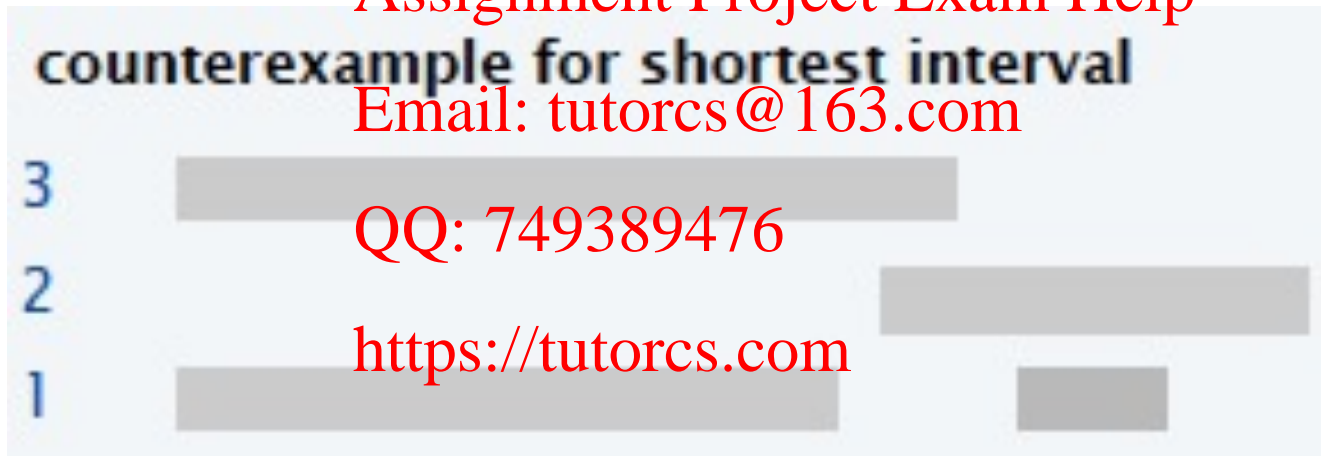
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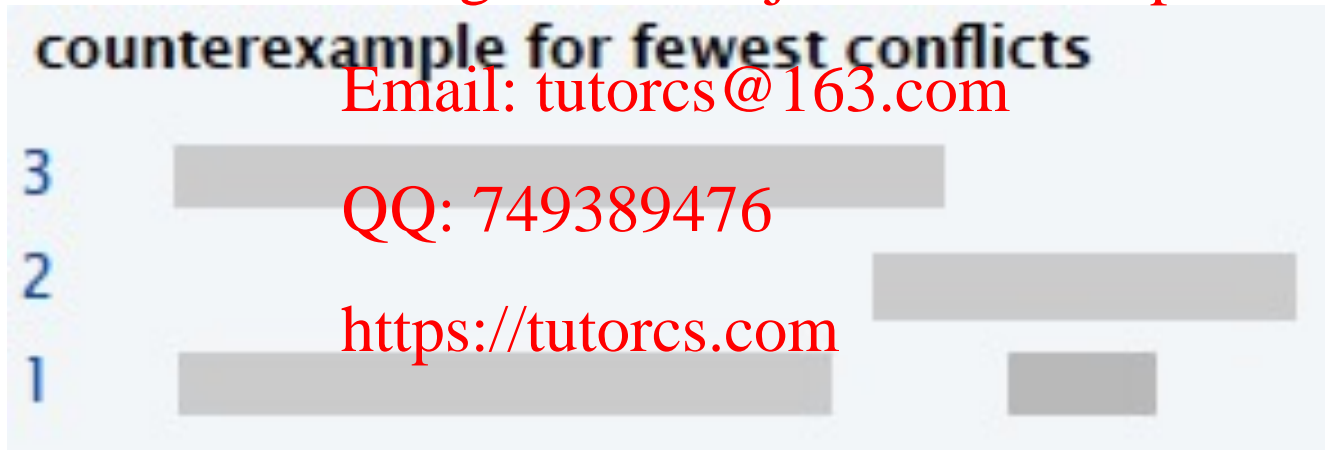


# Greedy – Similar to Activity-selection Problem

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- Greedy template. Consider lectures in some natural order.
- Assign each lecture to an available classroom (which one?); allocate a new class if none are available.
- [Fewest conflicts] For each lecture  $j$ , count the number of conflicting lectures  $c_j$ . Schedule in ascending order of  $c_j$ .

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# Greedy – Similar to Activity-selection Problem

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- Greedy template. Consider lectures in some natural order.
- Assign each lecture to an available classroom (which one?); allocate a new classroom if none are available.
- [Earliest start time] Consider lectures in ascending order of  $s_j$ .



EARLIEST-START-TIME-FIRST ( $n, s_1, s_2, \dots, s_n, f_1, f_2, \dots, f_n$ )

SORT lectures by start time so that  $s_1 \leq s_2 \leq \dots \leq s_n$ .

$d \leftarrow 0$  ← number of allocated classrooms

FOR  $j = 1$  TO  $n$

IF lecture  $j$  is compatible with some classroom

Schedule lecture  $j$  in any such classroom  $k$ .

ELSE

Allocate a new classroom  $d + 1$ .

Schedule lecture  $j$  in classroom  $d + 1$ .

$d \leftarrow d + 1$

RETURN schedule.

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# Greedy– Definitions

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Kleinberg and Tardos: "... builds up a solution in small steps, choosing a decision at each step *myopic* (short sighted) to optimize some underlying criterion."



Cormen, Leiserson, Rivest makes the choice that looks best in the moment... it makes a locally optimal choice in the hope that the choice will lead to a globally optimal solution"

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Levitin: "... choice must be (1) feasible i.e. satisfy the problem constraints, (2) the best local choice among all feasible choices available at that step, and (3) **irrevocable**".

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Hackerearth "...If we make a choice that seems best at the moment and solve the remaining subproblems later, we still reach optimal solution. We never have to reconsider our previous choices".

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# Greedy– Typical Steps

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- Cast the optimization problem as one in which we make a choice and are left with a subproblem to solve.
- Prove that there is an optimal solution that makes the greedy choice (greedy choice is safe).
- Show that greedy choice and optimal solution to subproblem  $\Rightarrow$  optimal solution to the problem.
- Make the greedy choice and **solve top-down**.
- You may have to preprocess input to put it into greedy order (e.g. sorting activities by finish time).



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# Greedy— Elements

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No general way to tell if a greedy algorithm is optimal, but two key ingredients are:

- Greedy-choice Principle

- We can build a globally optimal solution by making a locally optimal (greedy) choice.

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- Optimal Substructure

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