## 程序系统·易战战RGS编程辅导

Fall 2023 Homework 3



Figure 1: Vtrees over variables A, B, C.

## 1. [12 pts] Consider the function of the funct

- (6pt) What is the compressed  $(\mathbf{X}, \mathbf{Y})$ -partition of function f, where  $\mathbf{X} = \{A, B\}$  and  $\mathbf{Y} = \{C\}$ ?
- (3pt) To construct an SDD justing the (X, Y) partition that you desired in the previous question, which of the vtrees in Figure 1 should be used?
- (3pt) Which vtrees in Figure 1 will lead to an SDD that corresponds to an OBDD?
- 2. [16 pts] Consider the following Authorian  $Q = (A \land B) \lor (B \land C) \lor (C \land D)$ .
  - (8pt) Construct the compressed  $(\mathbf{X}, \mathbf{Y})$ -partitions for f and  $\neg f$ , where  $\mathbf{X} = \{A, C\}$  and  $\mathbf{Y} = \{B, D\}$ .
  - (8pt) Derive a general present function of function of function f: (8pt) partition for any function f:

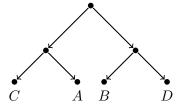
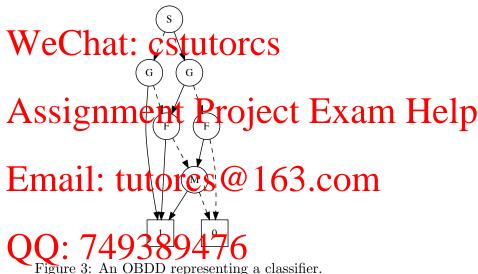


Figure 2: A vtree over variables A, B, C, D.

- 3. [14 pts] Construct an SDD for the function  $f = (A \land \neg B) \lor (\neg B \land C) \lor (C \land D)$  based on the vtree in Figure 2.
- 4. [12 pts] Consider a structured space which corresponds to selecting k or more items from a set of n items, where  $n \ge 1$  and  $0 \le k \le n$ . A Boolean formula  $\Delta$  captures this space iff there is a one-to-one correspondence between the possible selections and the satisfying assignments of  $\Delta$ . Suppose we use the Boolean variable  $A_i$  to indicate whether item i is selected.

- (4pt) Describe a DNF that captures this structured space. How many terms does the DNF have in terms of n and k.
- (4pt) Can you can be space more efficiently using an OBDD? If so, describe the OBDD of n and k.
- 5. [12 pts] Conside  $\Delta = (\neg A \lor I)$  (8pt) List the pr
  - (4pt) List the pr



 $C) \wedge (A \vee \neg B \vee \neg C) \wedge (A \vee \neg B \vee C) \wedge (A \vee B \vee C).$ 

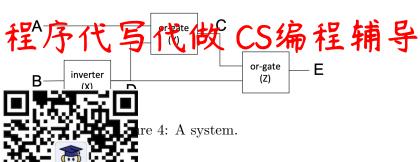
- 6. [14 pts] Consider a model that predicts a movie's box success based on four binary features, S (Original Screenplay), S (Great cinemategraphy), P (Famous Cast), and M (Marketing). The OBDD in Figure 3 describes the classification function, i.e. a feature configuration is evaluated to 1 iff the corresponding movie is predicted to be a success. Please answer the
  - (4pt) **Prime Implicant Explanation:** Consider a movie that is an original screenplay and has poor cinematography, a famous cast, and good marketing  $\{S=1, G=0, F=1, M=1\}$ . Identify a smallest set of features  $\alpha$  that renders the remaining features  $\beta$  irrelevant to the decision on this instance. That is, if we fix features  $\alpha$  to their current values, we can change the values of features  $\beta$  arbitrarily without changing the current decision.
  - (4pt) Complete Reason: The class formula for the positive class is

following explanation queries on the OBDD.

$$[G \wedge (\neg S \vee F)] \vee (F \wedge M) \vee [(\neg S \vee G) \wedge (F \vee M)].$$

Compute the complete reason for the decision on instance  $I = \{S = 0, G = 1, F = 0, M = 1\}.$ 

(6pt) **Sufficient and Necessary Reasons:** Compute the sufficient reasons and necessary reasons for this decision. That is, compute the prime implicants and prime implicates of the complete reason.



- 7. [20 pts] Consider I and I are represented by I and I are I and I and I are I and I are
  - (5pt) Write the specific and a CNF.

Suppose the system input is  $A=1,\,B=0$  and the system output is E=0. Answer the following questions under this system observation.

- (8pt) Construct the health condition for the system using directed resolution.
- (4pt) List the kernel diagnoses.
- (3pt) List the minary sidge it riverent. Project Exam Help

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