

Chapter 2. Fourier Representation of Signals and Systems –~~Review~~ 程序代写代做 CS 编程辅导

Summary: Time- and frequency-domain representations of signals, properties of signals, time-frequency analysis, frequency-domain analysis of systems (signal transmission), Fourier transform, Fourier series.



Textbook coverage:

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2.1 Fourier Transform ([Haykin & Moher 2.1](#))

2.2 Properties of Fourier Transform ([Haykin & Moher 2.2](#))

2.3 Fourier Series and Fourier Transform of Periodic Signals ([Haykin & Moher 2.4 and 2.5](#))

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2.4 Transmission of Signals through Linear Time-Invariant Systems ([Haykin & Moher 2.6](#))

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2.5 Filters ([Haykin & Moher 2.7 and more](#))

2.6 Energy Spectral Density and Autocorrelation Function for Energy Signals ([Haykin & Moher 2.8](#))

2.7 Power Spectral Density and Autocorrelation Function for Power Signal ([Haykin & Moher 2.9 and more](#))

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Signal: A set of data that is functions of one or more independent variables.

- Examples: speech signal, pressure as a function of time, etc.
- Focus on single-variable signal: A function of time $g(t)$.



Fundamental signals:

- Dirac delta function: $\delta(t) = 0$ for $t \neq 0$ and $\int_{-\infty}^{\infty} \delta(t) dt = 1$

$$\int_{-\infty}^{\infty} g(t)\delta(t-t_0)dt = g(t_0)$$

- Signum function: $\text{sgn}(t) = \begin{cases} 1, & t > 0 \\ 0, & t = 0 \\ -1, & t < 0 \end{cases}$

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- Unit step function: $u(t) = \begin{cases} 1/2, & t = 0 \\ 0, & t < 0 \end{cases}$

$$u(t) = \begin{cases} 1, & t > 0 \\ 0, & t \leq 0 \end{cases}$$

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Fundamental signals (cont.)

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- Unit rectangular function



$$x(t) = \begin{cases} 1, & -\frac{1}{2} \leq t \leq \frac{1}{2} \\ 0, & t < -\frac{1}{2} \text{ or } t > \frac{1}{2} \end{cases}$$

- Unit triangle function

$$x(t) = \begin{cases} 0 & |t| \geq \frac{1}{2} \\ 1 - 2|t| & |t| < \frac{1}{2} \end{cases}$$

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- Sinc function: $\text{sinc}(t) = \frac{\sin(\pi t)}{\pi t}$

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- Complex exponential function: $x(t) = e^{jw_0 t} = \cos(w_0 t) + j\sin(w_0 t)$

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Periodic signal: $g(t) = g(t + nT)$

- T : fundamental period (smallest period) of signal $g(t)$

Symmetric signal

- Even signal: $g(t) = g(-t)$
- Odd signal: $g(t) = -g(-t)$

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Q: is $x(t) = e^{jw_0 t}$ a periodic signal?
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Signal: A set of data that is functions of one or more independent variables.

- Examples: speech signal, pressure as a function of time, etc.
- Focus on single-variable signal: A function of time $g(t)$.



Signal energy & power

- Energy: $E_g = \int_{-\infty}^{\infty} |g(t)|^2 dt$
- Power: $P_g = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |g(t)|^2 dt = \lim_{T \rightarrow \infty} (E_g/T)$
- Energy signal: $0 < E_g < \infty$
- Power signal: $0 < P_g < \infty$

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Q1: Are periodic signals energy signals?

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Q2: Is there any signal that is both energy signal and power signal?

Q3: Is there any signal that is neither energy signal nor power signal?

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System: An entity that processes its inputs to produce outputs.

input $g(t)$ → System → output $y(t)$

- Processing the input signal to modify it or to extract information from it.
- Focus on single-input, single-output, linear time-invariant (LTI) systems.

A system is linear if the principle of superposition holds, i.e., its response to the weighted sum of a number of inputs is equal to the weighted sum of its responses when each input is applied individually.

If $g_1(t) \rightarrow y_1(t)$, $g_2(t) \rightarrow y_2(t)$,

then for any a_1, a_2 , $a_1g_1(t) + a_2g_2(t) \rightarrow a_1y_1(t) + a_2y_2(t)$.

Q: Are following systems linear?

(a) $g(t) \rightarrow e^{g(t)}$

(b) $g(t) \rightarrow g(t) + 1$

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A system is **time invariant** if its response to a time-shifted input by any amount of time is equal to the time-shift of its response to the input with the same amount of time.

If $g(t) \rightarrow y(t)$, then for a  $\rightarrow y(t - T)$.

Q: Are following systems time invariant? $x(t)$ and $y(t)$ represent input and output of the system.

(a) $g(t) \rightarrow g(t) + 1$

(b) $g(t) \rightarrow \sin(t)g(t)$

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A system is linear time-invariant (LTI) system if both conditions hold.

example: $g(t) \rightarrow g(t) + 1$ is not a LTI system as it is non-linear.

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Consider linear time-invariant (LTI) systems.

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The unit impulse response of a system, $h(t)$, is its output when the input is the unit impulse function $\delta(t)$.



For an LTI system, its output $y(t)$ to any input $g(t)$ is the **convolution** of the input and its unit impulse response:

$$y(t) = g(t) * h(t) = \int_{-\infty}^{\infty} g(\tau)h(t - \tau)d\tau$$

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A system is **Causal** if it does not respond before the excitation is applied.

- For a causal LTI system, $h(t) = 0$ for $t < 0$.

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A system is **stable** if the output is bounded for all bounded input.

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- For a stable LTI system, $\int_{-\infty}^{\infty} |h(t)|dt < \infty$

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Why frequency-domain representation/analysis?
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- Understand a signal via its frequency components (Fourier transform, Fourier series)
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- Understand a system's response for different frequency components
(Frequency response)
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Why frequency-domain representation/analysis? 程序代与代做CS编程辅导

- Understand a signal via its frequency components (Fourier transform, Fourier series)
- Understand a system's response for different frequency components (Frequency response).



Example from R. Nowak "Intro to digital image processing".

2.1 Fourier Transform

Represent a non-periodic signal as a continuous sum of infinitesimal ‘simple’ exponential functions



Def. The Fourier transform of a nonperiodic signal $g(t)$ (if Fourier transformable) is:

$$G(f) = \int_{-\infty}^{\infty} g(t) \exp(-j2\pi ft) dt.$$

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Given the Fourier transform $G(f)$, the original time-domain signal can be recovered by the following inverse Fourier transform

$$g(t) = \int_{-\infty}^{\infty} G(f) \exp(j2\pi ft) df.$$

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$g(t)$ and $G(f)$ constitute a Fourier transform pair.

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f : frequency in Hertz (Hz).

$\omega = 2\pi f$: frequency in radian/second (rad/sec).

$$G(f) = \int_{-\infty}^{\infty} g(t) \exp(-j2\pi ft) dt. \xrightarrow{\text{程序代写代做 CS 编程辅导}} g(t) = \int_{-\infty}^{\infty} G(f) \exp(j2\pi ft) df.$$

Notation:

$$G(f) = \mathbf{F}[g(t)] = \mathbf{F}^{-1}[G(f)] \quad g(t) \rightleftharpoons G(f)$$

Lower case letter: time



Upper case letter: frequency

Q1: Please compute $\mathbf{F}[\delta(t)]$.

Q2: Given $G(f) = \delta(f)$, Assignment Project Exam Help

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$$G(f) = \int_{-\infty}^{\infty} g(t) \exp(-j2\pi ft) dt. \xrightarrow{\text{程序代写代做 CS 编程辅导}} g(t) = \int_{-\infty}^{\infty} G(f) \exp(j2\pi ft) df.$$

Time-domain	Fourier transform pairs
1	$\delta(f)$
$\delta(t)$	1
$u(t)$	$\frac{1}{2}[\delta(f) + \frac{1}{j2\pi f}]$
$\text{rect}\left(\frac{t}{T}\right)$	$T\text{sinc}(fT)$
$2W\text{sinc}(2Wt)$	$\text{rect}\left(\frac{f}{2W}\right)$
$\Delta\left(\frac{t}{T}\right)$	$\frac{T}{2}\text{sinc}\left(\frac{fT}{2}\right)$
$e^{-at}u(t) \quad (a > 0)$	$\frac{1}{a+j2\pi f}$
$e^{-a t } \quad (a > 0)$	$\frac{2a}{a^2+(2\pi f)^2}$
$\sin(2\pi f_c t)$	$\frac{1}{2j}[\delta(f - f_c) - \delta(f + f_c)]$
$\cos(2\pi f_c t)$	$\frac{1}{2}[\delta(f - f_c) + \delta(f + f_c)]$



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$\frac{2a}{a^2+(2\pi f)^2}$

$\frac{1}{2j}[\delta(f - f_c) - \delta(f + f_c)]$

$\frac{1}{2}[\delta(f - f_c) + \delta(f + f_c)]$

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$G(f)$: Generally, a complex function of frequency f

$$G(f) = |G(f)| \exp^{j\theta(f)}$$



Amplitude spectrum ($|G(f)|$)

Phase spectrum: $\angle\theta(f)$

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Prove: for a real-value function $g(t)$,

- $G(-f) = G^*(f) \rightarrow$ conjugate symmetry

- $|G(-f)| = |G(f)| \rightarrow$ even function of f

- $\theta(-f) = -\theta(f) \rightarrow$ odd-symmetric w.r.t. f

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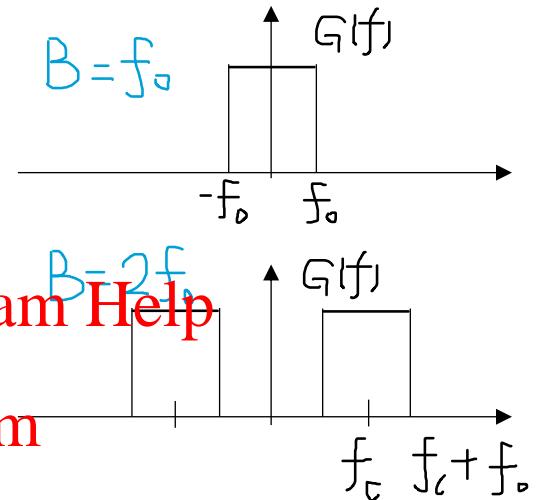
Bandwidth of a signal: The difference between the highest and lowest frequencies of the spectral components of a signal.

- It is convention to state the bandwidth as the range of **positive** frequencies.
- A signal cannot be stored in both time and frequency.



For band-limited signals:

- Baseband signal: energy centered around zero-frequency.
- Bandpass signal: energy centered around a frequency far away from zero.



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For pulse-like signals:

- main lobe bandwidth for symmetric signals
- 3-dB bandwidth
- 95% essential bandwidth of a signal: Range of the frequency that contains 95% of the energy.

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2.2 Properties of Fourier Transform

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1. Linearity: $c_1 g_1(t) + c_2 g_2(t) \rightleftharpoons c_1 G_1(f) + c_2 G_2(f)$
2. Time scaling: $g(at) \rightleftharpoons \frac{1}{|a|} G\left(\frac{f}{a}\right)$ (Dilation)
 $a \neq 0$
3. Conjugation: $g^*(t) \rightleftharpoons G^*(-f)$
4. Duality: $g(t) \rightleftharpoons G(f)$ then $G(t) \rightleftharpoons g(-f)$
5. Time shifting: $g(t - t_0) \rightleftharpoons e^{-j2\pi f_0 t_0} G(f)$
6. Frequency shifting: $g(t) \exp(j2\pi f_c t) \rightleftharpoons G(f - f_c)$ for any constant f_c .

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7. Areas under $g(t)$ and $G(f)$: 做 CS 编程辅导

$$\int_{-\infty}^{+\infty} g(t)dt \text{ and } \int_{-\infty}^{+\infty} G(f)df = g(0)$$



8. Differentiation

$$\frac{d}{dt}g(t) \rightleftharpoons j2\pi fG(f) \text{ and } \int_{-\infty}^t g(\tau)d\tau \rightleftharpoons \frac{1}{j2\pi f}G(f) + \frac{1}{2}G(0)\delta(f)$$

9. Convolution and Modulation:

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$$g_1(t) * g_2(t) \rightleftharpoons G_1(f) \cdot G_2(f) \text{ and } g_1(t) \cdot g_2(t) \rightleftharpoons G_1(f) * G_2(f)$$

10. Parseval's theorem:

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$$E_g = \int_{-\infty}^{+\infty} |g(t)|^2 dt = \int_{-\infty}^{+\infty} |G(f)|^2 df$$

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Energy Spectral Density & Autocorrelation Function for Energy Signals

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For an energy signal $g(t)$, i.e. $E_g = \int_{-\infty}^{\infty} |g(t)|^2 dt < \infty$, its energy spectral density is de

$$\Psi_g(f) = \frac{1}{E_g} \int_{-\infty}^{\infty} g(t) e^{-j2\pi ft} dt, \text{ where } g(t) \Leftrightarrow G(f).$$



Wiener-Khitchine Relation: energy signals autocorrelation function and energy spectral density function form a Fourier transform pair:

$$R_g(t) \Leftrightarrow \Psi_g(f),$$

where the autocorrelation function $R_g(\tau) = \int_{-\infty}^{\infty} g(t)g^*(t - \tau)dt$.

Energy spectral density $\Psi_g(f)$ tells how signal energy spreads over frequencies, so we have the Parseval's Theorem:

$$E_g = \int_{-\infty}^{\infty} |G(f)|^2 df = \int_{-\infty}^{\infty} \Psi_g(f) df = R_g(0) = \int_{-\infty}^{\infty} |g(t)|^2 dt$$

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Parseval's Power theorem & Power Spectral Density of Power Signals

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For a power signal $g(t)$, if $\lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |g(t)|^2 dt < \infty$, define

$$g_T(t) = \begin{cases} \frac{T}{2} & -\frac{T}{2} \leq t \leq T/2 \\ 0 & \text{otherwise} \end{cases}$$

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Then $g_T(t)$ is an energy signal.

From $g_T(t) \Rightarrow G_T(f)$, Parseval's power theorem is

$$\begin{aligned} P_g &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |g(t)|^2 dt = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-\infty}^{\infty} |G_T(f)|^2 df \\ &= \int_{-\infty}^{\infty} \lim_{T \rightarrow \infty} \frac{1}{T} |G_T(f)|^2 df = \int_{-\infty}^{\infty} S_g(f) df \end{aligned}$$

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Define **power spectral density (PSD)** of $g(t)$ as:



$$\lim_{T \rightarrow \infty} \frac{1}{T} |G_{T_0}(f)|^2$$

PSD tells how signal spreads over frequencies.

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The auto-correlation function of power signal $g(t)$ is

$$R_g(\tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} g(t) g^*(t - \tau) dt$$

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Similarly, we have $R_g(\tau) \rightleftharpoons S_g(f)$ and $P_g = \int_{-\infty}^{\infty} S_g(f) df = R_g(0)$

2.3 Fourier Series and Fourier Transform of Periodic Signals

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$g_{T_0}(t)$: A periodic signal with period T_0 .

Fundamental frequency $f_0 = \frac{1}{T_0}$

A periodic signal $g_{T_0}(t)$ can be represented as a sum of complex exponential (complex exponential Fourier series):

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$$g_{T_0}(t) = \sum_{n=-\infty}^{+\infty} c_n \exp(j2\pi n f_0 t)$$

where $c_n = \frac{1}{T_0} \int_{-\frac{T_0}{2}}^{\frac{T_0}{2}} g_{T_0}(t) e^{-j2\pi n f_0 t} dt$.

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Fourier transform of $g_{T_0}(t)$ is:

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$$G_{T_0}(f) = \sum_{n=-\infty}^{+\infty} c_n \delta(f - n f_0)$$

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For periodic signal $g(t)$ with period T_0

$$\text{Fundamental freq. } f_0 = \frac{1}{T_0}$$

$$\text{FS: } g_{T_0}(t) = \sum_{n=-\infty}^{\infty} C_n e^{j2\pi n f_0 t} + \int_{-T_0/2}^{T_0/2} g(t) e^{-j2\pi n f_0 t} dt$$

$$\Rightarrow \text{FT: } G_{T_0}(f) = \sum_{n=-\infty}^{\infty} C_n \delta(f - n f_0)$$

To find C_n for $\cos(2\pi f_0 t)$

$$\begin{aligned} C_n &= \frac{1}{T_0} \int_{-T_0/2}^{T_0/2} \cos(2\pi f_0 t) e^{-j2\pi n f_0 t} dt \\ &= \frac{1}{T_0} \int_{-T_0/2}^{T_0/2} \frac{1}{2} [e^{j2\pi f_0 t} + e^{-j2\pi f_0 t}] e^{-j2\pi n f_0 t} dt \\ &= \frac{1}{2T_0} \int_{-T_0/2}^{T_0/2} e^{j2\pi f_0 (1-n)t} + e^{-j2\pi f_0 (1+n)t} dt \end{aligned}$$

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$$\begin{aligned} &= \frac{1}{2T_0} \left[\int_{-T_0/2}^{T_0/2} e^{j2\pi f_0 (1-n)t} dt + \int_{-T_0/2}^{T_0/2} e^{-j2\pi f_0 (1+n)t} dt \right] \\ &= \frac{1}{2T_0} \left[\frac{e^{j2\pi f_0 (1-n)T_0/2} - e^{j2\pi f_0 (1-n)(-T_0/2)}}{j2\pi f_0 (1-n)} + \frac{e^{-j2\pi f_0 (1+n)T_0/2} - e^{-j2\pi f_0 (1+n)(-T_0/2)}}{j2\pi f_0 (1+n)} \right] \end{aligned}$$

$$\begin{aligned} f_0 = \frac{1}{T_0} \Rightarrow f T_0 = 1 &\Rightarrow \frac{1}{2T_0} \left[\frac{e^{j2\pi f_0 (1-n)T_0/2} - e^{j2\pi f_0 (1-n)(-T_0/2)}}{j2\pi f_0 (1-n)} - \frac{e^{-j2\pi f_0 (1+n)T_0/2} - e^{-j2\pi f_0 (1+n)(-T_0/2)}}{j2\pi f_0 (1+n)} \right] \\ &= \frac{1}{2T_0} \left[\frac{e^{j\pi(1-n)} - e^{-j\pi(1-n)}}{j2\pi f_0 (1-n)} - \frac{e^{-j\pi(1+n)} - e^{j\pi(1+n)}}{j2\pi f_0 (1+n)} \right] \end{aligned}$$

$$= \frac{1}{2T_0} \left[\frac{2j \sin[\pi(1-n)]}{j2\pi f_0 (1-n)} - \frac{2j \sin[\pi(1+n)]}{j2\pi f_0 (1+n)} \right]$$

$$= \frac{\sin[\pi(1-n)]}{2\pi(1-n)} + \frac{\sin[\pi(1+n)]}{2\pi(1+n)}$$

$$= \begin{cases} 0 & n \neq \pm 1 \\ \frac{\sin[\pi(1-n)]}{2\pi(1-n)} & n=1 \\ 0 + \frac{\sin[\pi(1+n)]}{2\pi(1+n)} & n=-1 \end{cases}$$

$$= \begin{cases} 0 & n \neq \pm 1 \\ \frac{-\pi \cos[\pi(1-n)]}{2\pi} & n=1 \\ \frac{\pi \cos[\pi(1+n)]}{2\pi} & n=-1 \end{cases}$$

$$= \begin{cases} 0 & n \neq \pm 1 \\ \frac{1}{2} & n=1 \\ \frac{1}{2} & n=-1 \end{cases}$$

$$\Rightarrow \cos(2\pi f_0 t) = \sum_{n=-\infty}^{\infty} C_n e^{j2\pi n f_0 t} = \frac{1}{2} e^{j2\pi f_0 t} + \frac{1}{2} e^{-j2\pi f_0 t}$$

$$\Rightarrow F[\cos(2\pi f_0 t)] = \sum_{n=-\infty}^{\infty} C_n \delta(f - n f_0) = \frac{1}{2} \delta(f - f_0) + \frac{1}{2} \delta(f + f_0) \quad !!.$$



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Relation between FT and FS

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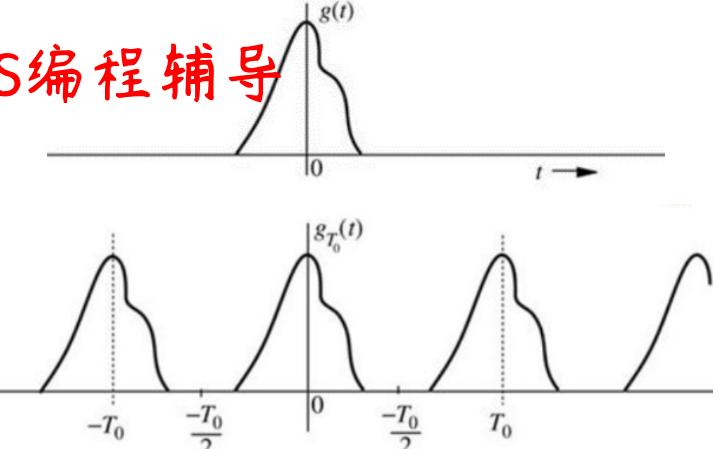
Define two signals $g(t)$ and $g_{T_0}(t)$:

$$g_{T_0}(t) = \sum_{m=-\infty}^{\infty} g\left(\frac{t - mT_0}{2}\right)$$

$$g(t) = \begin{cases} g_{T_0}(t) & -\frac{T_0}{2} \leq t \leq \frac{T_0}{2} \\ 0 & \text{otherwise} \end{cases}$$



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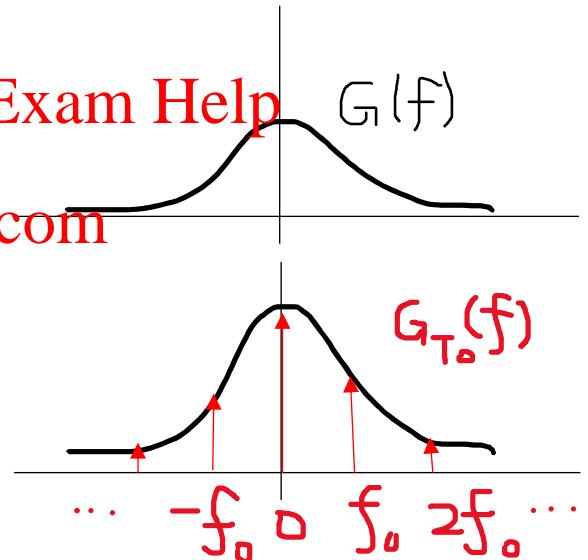
Let $g(t) \Rightarrow G(f)$ $g_{T_0}(t) \Rightarrow G_{T_0}(f)$

we have $c_n = \frac{1}{T_0} G(nf_0) = f_0 G(nf_0)$.

That is,

$$G_{T_0}(f) = f_0 \sum_{n=-\infty}^{\infty} G(nf_0) \delta(f - nf_0).$$

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 Repetition in the time domain results
 in sampling in the frequency domain.



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Power spectral density for periodic signal $g_{T_0}(t)$ with period T_0 .

$$G_{T_0}(f) = f_0 \sum_{n=-\infty}^{\infty} G(nf_0) \delta(f - nf_0). \quad f_0 = \frac{1}{T_0}$$


Then its power spectral density is

$$S_{g_{T_0}}(f) = \sum_{n=-\infty}^{\infty} |c_n|^2 \delta(f - nf_0) = \sum_{n=-\infty}^{\infty} f_0^2 |G(nf_0)|^2 \delta(f - nf_0)$$

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Parseval's power theorem for periodic signal:

$$\frac{1}{T} \int_{-T/2}^{T/2} |g(t)|^2 dt = \sum_{n=-\infty}^{\infty} |c_n|^2$$

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2.4 Transmission of signals through LTI systems

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System: An entity that processes its inputs to produce outputs.

input $g(t)$ → output $y(t)$

- Processing the input signal to modify it or to extract information from it.
- Focus on single-input-single-output, linear time-invariant (LTI) system.

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The unit impulse response of a system, $h(t)$, is its output when the input is the unit impulse function $\delta(t)$.

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 $\delta(t) \rightarrow h(t)$

For an LTI system, its output to any input $g(t)$ is the **convolution** of the input and its unit impulse response:

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$$y(t) = g(t) * h(t) = \int_{-\infty}^{+\infty} g(\tau)h(t - \tau)d\tau$$

For an LTI system, its ~~frequency response~~ 编程辅导 of its unit impulse response:

$$H(f) = \int_{-\infty}^{\infty} h(2\pi ft) dt. \quad h(t) \rightleftharpoons H(f)$$

- Magnitude response
- Phase response $\theta(f)$, or $\angle H(f)$



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The output of an LTI system with any input $g(t)$ in the domain:

$$Y(f) = H(f)G(f) \rightleftharpoons y(t) = g(t) * h(t) :$$

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Given any LTI system's input-output pair $g(t) \rightarrow y(t)$, the impulse response of the system can be specified in two steps;

- Step 1: $H(f) = \frac{Y(f)}{G(f)}$
- Step 2: $h(t) = \mathcal{F}^{-1}(H(f))$

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Filters

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- Filters are systems that are designed to remove some unwanted components from a signal.
 - Low-pass filter
 - High-pass filter
 - Band-pass filter
 - Band-reject or notch filters



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- Cutoff frequencies: frequencies beyond which the filter will not pass the signal components.
 - 3-dB frequencies: the frequency at which the power-transfer ratio of the filter drops to half of the maximum, i.e., the energy spectral density (or PSD) at this frequency is half (3dB drop) of its maximum.

Effect of filtering (LTI system) on energy spectral density

$$g(t) \xrightarrow{h(t)} y(t)$$

$$Y(f) = H(f) \Psi_g(f) \quad S_y(f) = |H(f)|^2 \Psi_g(f).$$

The energy spectral density of the output equals the energy spectral density of the input multiplied by the squared amplitude of frequency response of the LTI system.

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Effect of filtering (LTI system) on power spectral density

$$g(t) \xrightarrow{h(t)} y(t)$$

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$$S_y(f) = |H(f)|^2 S_g(f)$$