Solution to Homework Assignment 1

Solution to Problem 1: 程序代写代做 CS编程辅导

 $G(f) = \begin{cases} e^{-j2\pi ft_0} & f \in [-f_0, f_0] \\ 0 & \text{elsewhere} \end{cases}$ By using the definition $f(t) = \int_{-f_0}^{f_0} e^{j2\pi f(t-t_0)} df = \frac{1}{j2\pi (t-t_0)} e^{j2\pi f(t-t_0)} \Big|_{-f_0}^{f_0}$ $= \int_{-f_0}^{g_0} e^{j2\pi f(t-t_0)} df = \frac{1}{j2\pi (t-t_0)} e^{j2\pi f(t-t_0)} \Big|_{-f_0}^{f_0}$

(b) $G(f) = \text{rect}\left(\frac{f}{2f_0}\right)$. Thus $g(t) = 2f_0 \text{sinc}(2f_0t)$. Or from the definition of the erserge G(f) and G(f) are G(f) and G(f) are G(f) are G(f) and G(f) are G(f) and G(f) are G(f) are G(f) and G(f) are G(f) are G(f) are G(f) and G(f) are G(f) are G(f) and G(f) are G(f) are G(f) are G(f) are G(f) are G(f) are G(f) and G(f) are G(f) are

$$f(t) = \int_{-f_0}^{f_0} e^{j2\pi ft} df = \frac{1}{j2\pi t} e^{j2\pi ft} \Big|_{-f_0}^{f_0} = \frac{\sin(2\pi f_0 t)}{\pi t} = 2f_0 \text{sinc}(2f_0 t).$$

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Solution to Problem 2: Iron the piol: tutores@163.com

$$g_1(t) = \sin t[u(t) - u(t - \pi)].$$

By definition: **QQ**: 749389476

$$\mathbf{htp}_{0}^{\pi} \sin(t)e^{-j2\pi ft}dt$$

$$\mathbf{htp}_{0}^{\pi} \frac{1}{2} \int_{2}^{\pi} \cot \mathbf{cos}(t) dt$$

$$= -\cos(t)e^{-j2\pi ft} \Big|_{0}^{\pi} + \int_{0}^{\pi} \cos(t)de^{-j2\pi ft}$$

$$= 1 + e^{-j2\pi^{2}f} + (-j2\pi f) \int_{0}^{\pi} \cos(t)e^{-j2\pi ft}dt$$

$$= 1 + e^{-j2\pi^{2}f} + (-j2\pi f) \int_{0}^{\pi} e^{-j2\pi ft}d\sin(t)$$

$$= 1 + e^{-j2\pi^{2}f} + (-j2\pi f) \left[\sin(t)e^{-j2\pi ft} \Big|_{0}^{\pi} - \int_{0}^{\pi} \sin(t)de^{-j2\pi ft} \right]$$

$$= 1 + e^{-j2\pi^{2}f} - (-j2\pi f)^{2} \int_{0}^{\pi} \sin(t)e^{-j2\pi ft}dt$$

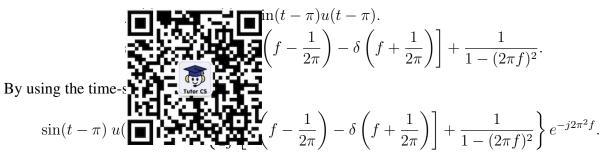
$$= 1 + e^{-j2\pi^{2}f} + 4\pi^{2}f^{2}G_{1}(f)$$

After move the $4\pi^2 f^2 G_1(f)$ to the left of the equation, we get

$$G_1(f) - 4\pi^2 f^2 G_1(f) = 1 + e^{-j2\pi^2 f}.$$

Hence,

程序代写代码^(f) 被^{4元(f)} 编程辅导 By properties: Notice that



By linearity of FT, we have

$$G(f) = \underbrace{\begin{cases} \mathbf{Y} & \mathbf{E} \\ 2j & \mathbf{E} \end{cases}}_{\mathbf{Y}} \underbrace{\begin{cases} \mathbf{E} \\ 2\pi \end{cases}}_{\mathbf{Y}} - \underbrace{\begin{cases} \mathbf{E} \\ \mathbf{E} \\ 2\pi \end{cases}}_{\mathbf{Y}} \underbrace{\begin{cases} \mathbf{E} \\ \mathbf{E} \\ \mathbf{E} \end{cases}}_{\mathbf{Y}} \underbrace{\begin{cases} \mathbf{E} \\ \mathbf{E} \\ \mathbf{E} \end{cases}}_{\mathbf{Y}} \underbrace{\begin{cases} \mathbf{E} \\ \mathbf{E} \\ \mathbf{E} \end{cases}}_{\mathbf{Y}} - \underbrace{\begin{cases} \mathbf{E} \\ \mathbf{E} \\ \mathbf{E} \end{cases}}_{\mathbf{Y}} \underbrace{\begin{cases} \mathbf{E} \\ \mathbf{E} \\ \mathbf{E} \end{cases}}_{\mathbf{E} \end{bmatrix}}_{\mathbf{Y}} \underbrace{\begin{cases} \mathbf{E} \\ \mathbf{E} \\ \mathbf{E} \end{bmatrix}}_{\mathbf{Y}} \underbrace{\begin{cases} \mathbf{E} \\ \mathbf{E} \end{bmatrix}$$

As
$$\delta (f \pm \frac{1}{2\pi}) (1 + e^{-j2\pi^2 f}) = \delta (f \pm \frac{1}{2\pi}) (1 + e^{\pm j\pi}) = 0$$
, we have $F(\omega) = \frac{1 + e^{-j2\pi^2 f}}{1 - 4\pi^2 f^2}$.

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$$g_2(t) = e^{-at}[u(t) - u(t - T)].$$

By definition,

$$G_2(f) = \int_0^\infty e^{-at} e^{-j2\pi ft} dt = -\frac{1 - e^{-(a+j2\pi f)t}}{a + j2\pi f} \Big|_0^T = \frac{1 - e^{-(a+j2\pi f)T}}{a + j2\pi f}$$

Notice that

https://tutorcs.com

$$g_2(t) = e^{-at}u(t) - e^{-aT}e^{-a(t-T)}u(t-T).$$

$$e^{-at}u(t) \iff \frac{1}{a+j2\pi f}.$$

By using the time-shifting property,

$$e^{-a(t-T)}u(t-T) \Longleftrightarrow \frac{1}{a+i2\pi f}e^{-j2\pi fT}.$$

By the linearity of FT, we have

$$F(\omega) = \frac{1 - e^{-(a+j2\pi f)T}}{a + j2\pi f}.$$

Solution to Problem 3:

(a) Since

$$g(t)\sin(2\pi f_c t) = \frac{1}{2j}g(t)\left[e^{j2\pi f_c t} - e^{-j2\pi f_c t}\right],$$

from frequency-shifting property and linearity,

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(b) Since $2 + \cos(2\pi f_0 t) \rightleftharpoons 2\delta(f) + \frac{1}{2}\delta(f - f_0) + \frac{1}{2}\delta(f + f_0)$, by using the property in (a), we have $S(\underbrace{\frac{1}{2}\delta(f - f_0)}_{\text{Tabor cs}}) + \frac{1}{2}\delta(f - f_0) + \frac{1}{2}\delta($



Figure 1: Spectra for Problem 3. https://tutorcs.com

Solution to Problem 4:

(a) The signals u(t), u(t), u(t) are represented by the following figure 样子代与代数 CS编程辅导



(b)We have

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