CASE WESTERN RESERVE UNIVERSITY Fase School of Engineering State of Electrical Computer and Systems Engineering F ECSE 281. Logic Design and Computer Organization (4)

Assignment #11

me extra credits. Please upload your homework our .asm file and a single pdf file containing your

Due: May 4, 2023

This is a required hon solutions to Canvas. ' screenshots.

50 pts + 50 pts Extra Ci

In order to get the extra credit, your code should be working properly, and you need to upload both your asm code and the pdf containing the screenshots.

This state machine has 4 inputs and 6 outputs. Students should use the PIC16F84A. The required pin assignments are given in the following table.

Ema	Required Pin Inputs		Assignments Right Outputs		3.com
	Function	PIC	Function	PIC	
00.	71/19	2RQ	1476	RB0	
44.	G2	RA1	L2	RB1	
	G3	RA2	L3	RB2	
https	s4/tu	ter	CS.CC)ftg	
1			ERR	RB4	
			WIN	RB5	

A high output is used to turn on a light while a low output signifies that the light is off.

Programs should initialize to state S1 and include a delay of \sim 1.0 second from one state to the next in the rotating light pattern. This delay could be created in different ways, for example, using a simple program loop, or using a timer with or without interrupts. It need not be precise, but should be accurate to \pm 0.05 seconds. You may choose your processor clock frequency to adjust the state delay.

The program should be tested using a stimulus workbook ("guessing_game_stimuli_Spring2023.sbs") that has been posted on Canvas with this assignment. This external stimulus is applied using

Stimulus → open a stimulus workbook (from icons to the left of the Stimulus window)

being sure to "Apply" the stimulus before you start debugging your code.

Your solution to this homework should include your documented assembly language code and watch window to demonstrate that your game responds properly to stimulus. This example shows a watch window following the first wrong guess. Your solution should show this watch window following each state change. This can be done most easily by setting breakpoints immediately following each state change in

your code, then running the processor, which will automatically stop at each state change. You need to use a processor frequency of 100 Hz (instruction frequency of 500 Hz) 100 Hz (instruction frequenc

 Name
 Type
 Address
 Value

 □ ✓ PORTB
 □ 0x6
 □ 0x10

 □ ✓ PORTA
 □ 0x5
 □ 0x06

 □ <Enter new watch>
 □ 0x5
 □ 0x06

Hints and Suggested

Computation of the nextended of the next

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