

程序代写代做 CS编程辅导



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**Wireless Sensing**  
Assignment Project Exam Help

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# 程序代写 Overview



1. Motivation of Wireless Sensing
2. Principle of Wireless Sensing
3. WiFi Sensing
4. Radar Sensing

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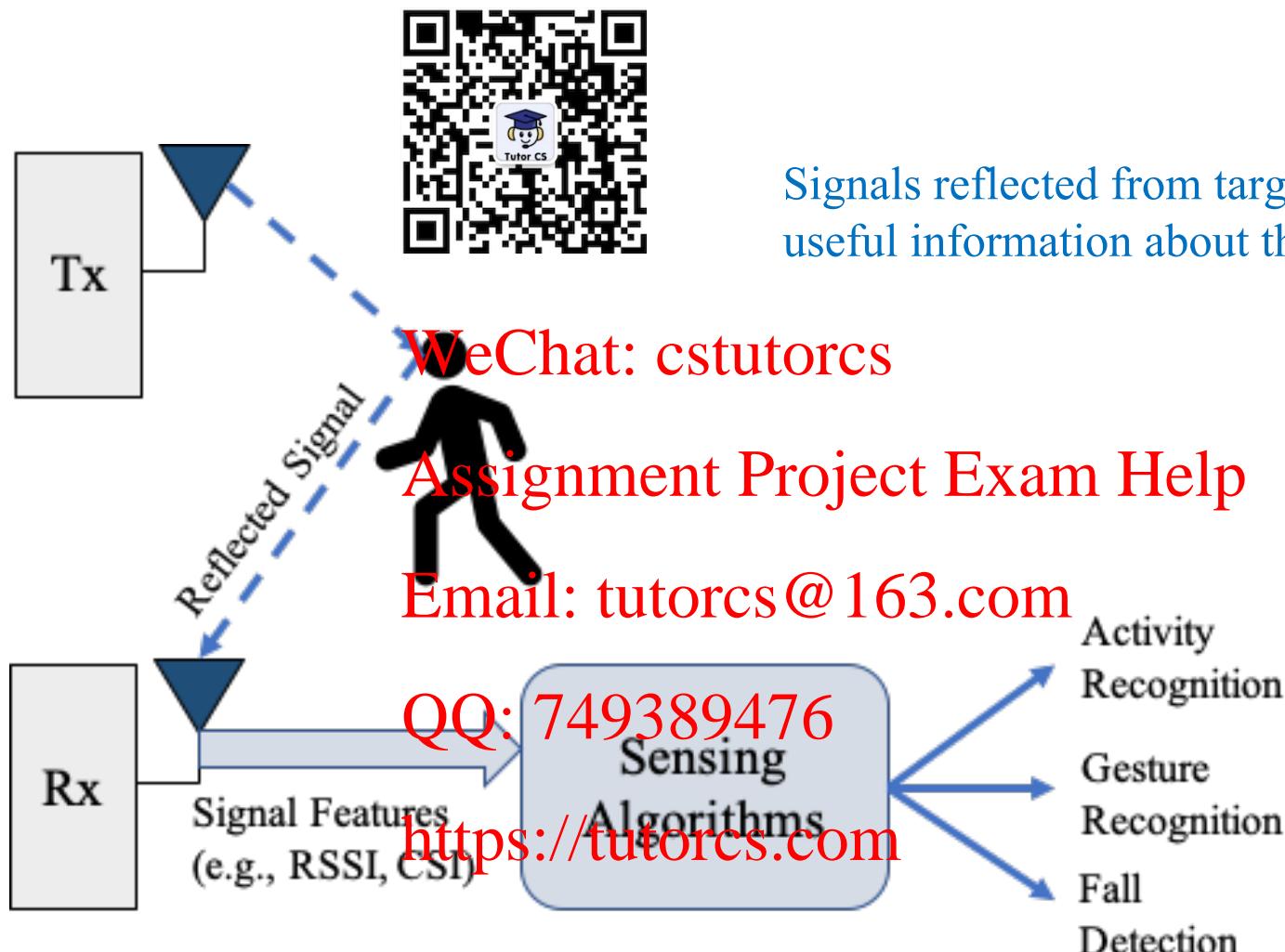
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# Motivation of Wireless Sensing

- ❑ Wireless signals good for both communication and remote sensing  
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- ❑ Sensing becoming indispensable in modern living
  - Wearable sensor: heart rate, heartrate, activity, ...
  - Camera: monitoring behaviour, surveillance, ...
- ❑ Wearable is obtrusive: does not work in the dark/fog and has privacy concerns
- ❑ Wireless sensing works remotely (nonobtrusively) without privacy concerns and works in the dark/fog too
- ❑ Wireless sensing becoming commercial success: sleep monitoring, vital sign monitoring, fall detection, localization and tracking, activity monitoring, people counting, and so on.
  - <https://www.celeno.com/wifi-doppler-imaging>
  - <https://www.emeraldinno.com/>
  - <https://walabot.com/walabot-home>
  - <https://www.originwirelessai.com/wirelessai>
  - <https://xkcorp.com/>



# Principle of Wireless Sensing



# Types of Sensing



- WiFi Sensing:  
existing wireless  
signals and equipment  
used for sensing
- Radar Sensing:  
Specialised wireless  
signals and equipment

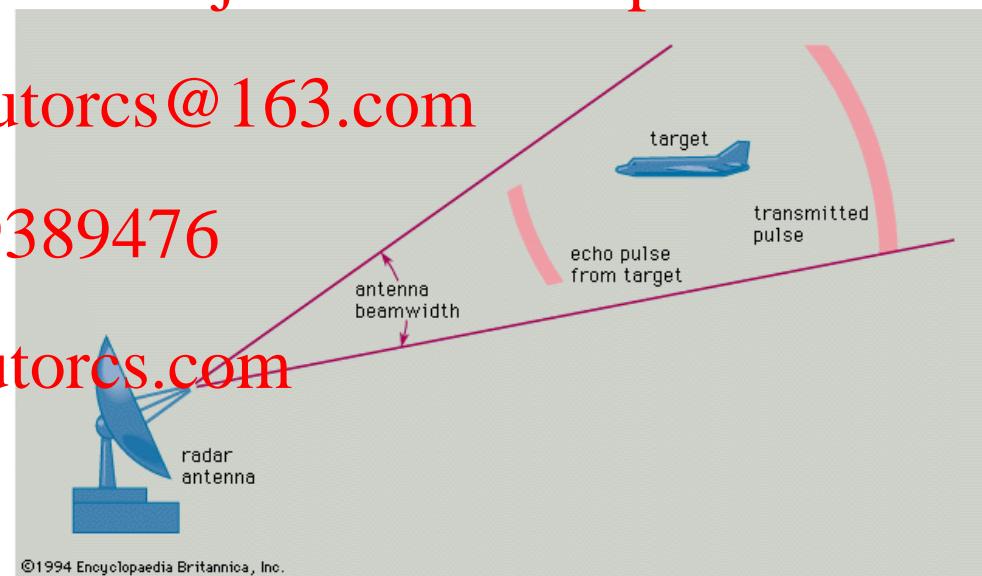
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# WiFi Signal Information used for Sensing

- Two typical WiFi signals used for sensing:
  - RSS: easy to access, limited sensing capability
  - CSI (channel state information): difficult to obtain, but enables fine-grained and more accurate sensing

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# Sensing with RSS

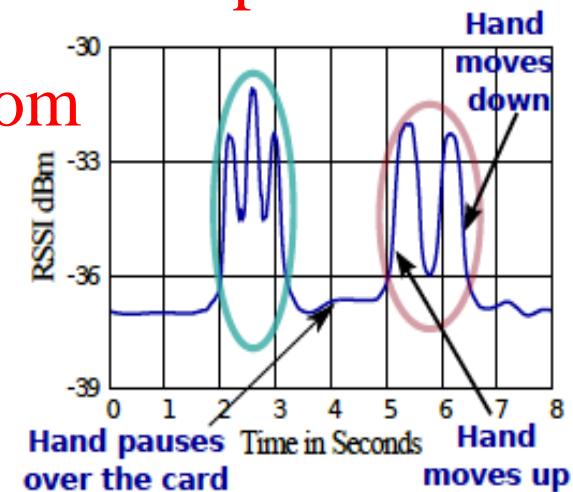
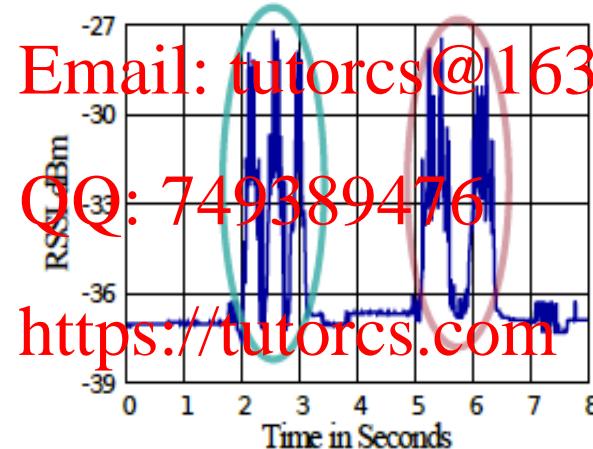
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- Single scalar value (in dBm) reported for the whole WiFi channel
- Pros: Widely available: most device hardware/OS report the RSS for each packet received
- Cons: Coarse and unstable; difficult to achieve fine-grained sensing



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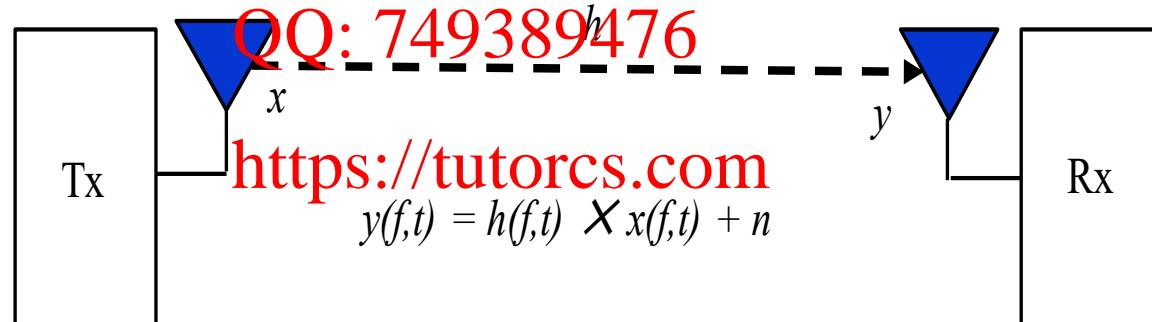


# WiFi Sensing with CSI



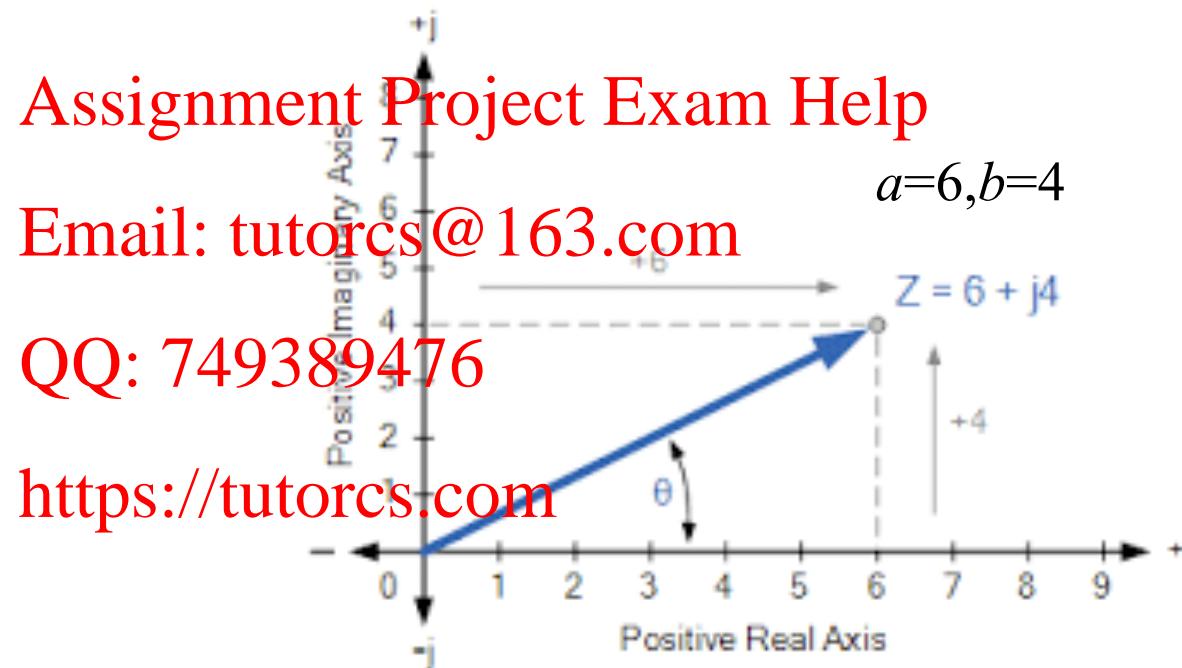
- ❑ RSS averages signal amplitude over the entire channel bandwidth; cannot reveal the channel response. CSI can show the amplitude and phase changes for different frequencies within the channel; RSS therefore is good only for **coarse** sensing and unsuitable for **detailed** sensing tasks
- ❑ Signal **phase** changes when the reflector moves or changes location; changes in path length will cause phase change (why?)
- ❑ CSI refers to known channel properties, i.e., how the channel affect the amplitude and phase of the transmitted signal, between a Tx and Rx

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# Mathematical Representation of CSI

- CSI tells us how much the channel will attenuate the amplitude and how much it will shift the transmitted signal
- CSI is a **complex number** which can be represented as either
  - $Ae^{j\theta}$  ( $A$ =amplitude,  $\theta$ =phase,  $j=\sqrt{-1}$ ), or
  - $a+jb$  (Amplitude =  $\sqrt{a^2 + b^2}$ , Phase =  $\tan^{-1} \frac{b}{a}$ )



# Use of CSI in Wireless Communication



- CSI is used at the PH
- CSI is used in the PH WiFi and cellular networks to estimate the channel (quality) and improve communication reliability and data rates
- In WiFi, the packet preamble contains known signals, which is compared with the received signals to estimate CSI at the receiver; the receiver then uses the CSI to decode the data symbols in the packet payload; the Rx may also provide CSI feedback to the Tx, e.g., in 802.11n, so the Tx can adjust the data rates (modulation and coding) or configure MIMO transmission parameters

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# Human Sensing with CSI

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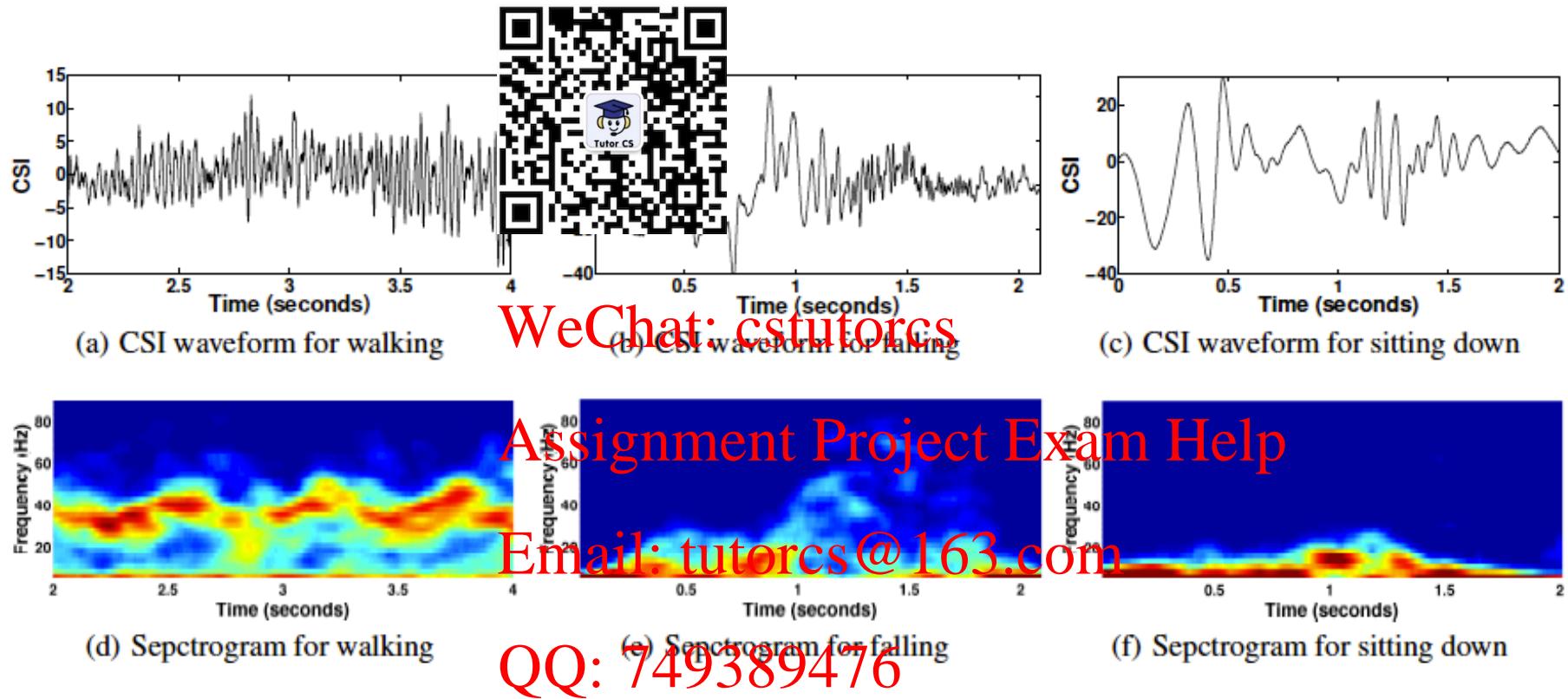
- ❑ Signal phase changes reflector moves or changes location; changes in path length phase change (why?)
- ❑ CSI returns both amplitude and phase for each subcarrier of WiFi OFDM; e.g., up to 52 amplitude values for 20MHz channel for each packet received
- ❑ **CSI time series:** by configuring a Tx to transmit packets at a fixed rate, a receiver can obtain a time series of CSI at a target rate, e.g., 100 packets/s leads to CSI sampling at 100Hz
- ❑ Patterns for different human activities, such as a fall, can be learnt from the CSI time series
- ❑ The phase values in CSI are often very noisy in WiFi due to low-cost hardware; hence only the amplitude value of the CSI is typically used for sensing (future WiFi devices may provide more accurate phase values as they need to implement high QAM modulations that require accurate detection of large number of different phase values)



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# Example of CSI-based Sensing



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Source: Wang, Liu, Shahzad, Ling, and Lu: *Understanding and Modeling of WiFi Signal Based Human Activity Recognition*  
MOBICOM 2015

# CSI Extraction Tools



- ❑ CSI is generated and controlled at the PHY layer, but human sensing algorithms execute at the application layer
- ❑ How to access CSI from application layer?
- ❑ Firmware of most WiFi chipsets can be modified to extract CSI
- ❑ Example of a freely available CSI extraction tool: **nexmon**  
([https://github.com/seemoo-lab/nexmon\\_csi](https://github.com/seemoo-lab/nexmon_csi))

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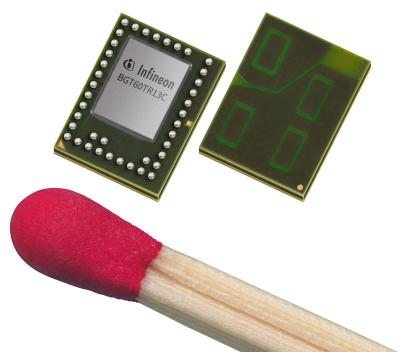
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# Radar

- RAdio Detecting And Ranging CS编程辅导
- Detects objects and estimates the range/distance
- Traditional radars are movement/antenna; designed to detect objects at far, such as ships, aircrafts, ...
- New trends in radar sensors



60GHz radar chip  
from Infineon  
5mmx5.5mm



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# principle of Radar Sensing

- Range, i.e., distance can be calculated if we can measure time of flight (ToF)
  - $\text{Range} = \text{ToF} \times \text{speed}$
- Radar: a fundamental sensing technique that estimates ToF and range by generating a wireless signal and then measuring the reflected signal

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**Time of Flight** = time for the signal to reach the object and come back

# Range vs Resolution 程序与代码编程辅导

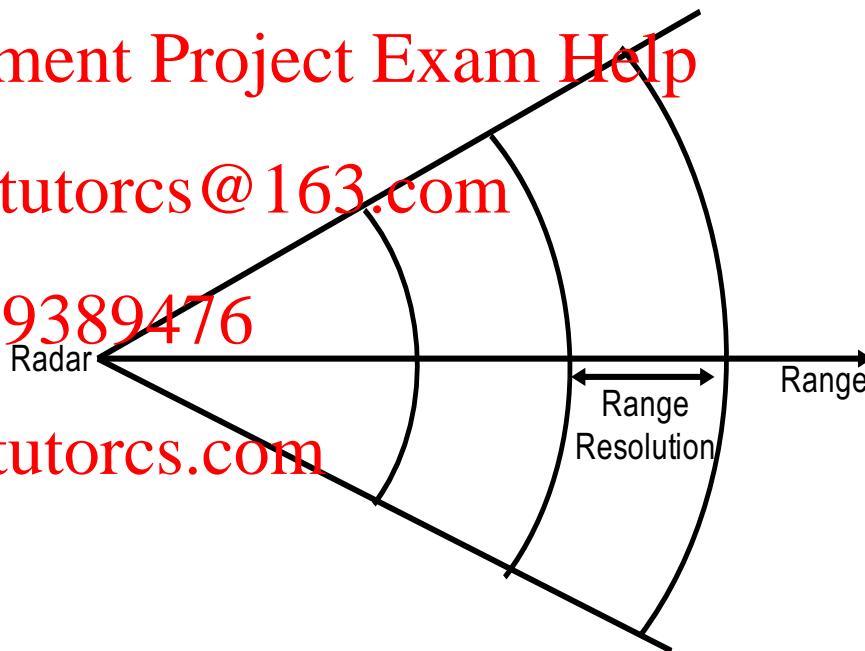
- ❑ Range: the maximum distance from which a radar can reliably detect and estimate the range of an object (how far a radar can see)
- ❑ Resolution: ability to separate more targets at different ranges within the same bearing (how clearly a radar can see)
- ❑ longer range radars have lower resolution and vice-versa.
- ❑ Both range and resolution measured in units of distance, e.g., in meters
- ❑ Resolution =  $c/2B$  meter;  $c$  = speed of light

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# Example

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**Question:** What is the resolution of a 24GHz radar operating within the ISM band from 24 GHz to 24.25 GHz



**Solution:**

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$$\text{Bandwidth (B)} = 24.25 - 24 = 0.25 \text{ GHz}$$

$$\text{Speed of light } c = 3 \times 10^8 \text{ m/s}$$

$$\text{Resolution} = c/2B = (3 \times 10^8) / (0.25 \times 10^9) = 1.2 \text{ m}$$

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# Types of Radar

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- Pulse: long range detection, heavy, power-hungry, used in large infrastructure, e.g., weather station, control tower, etc.
- FMCW (Frequency Modulated Continuous Wave): light-weight, energy efficiency, low cost, suitable for mobile devices (e.g., smartphones) and IoTs

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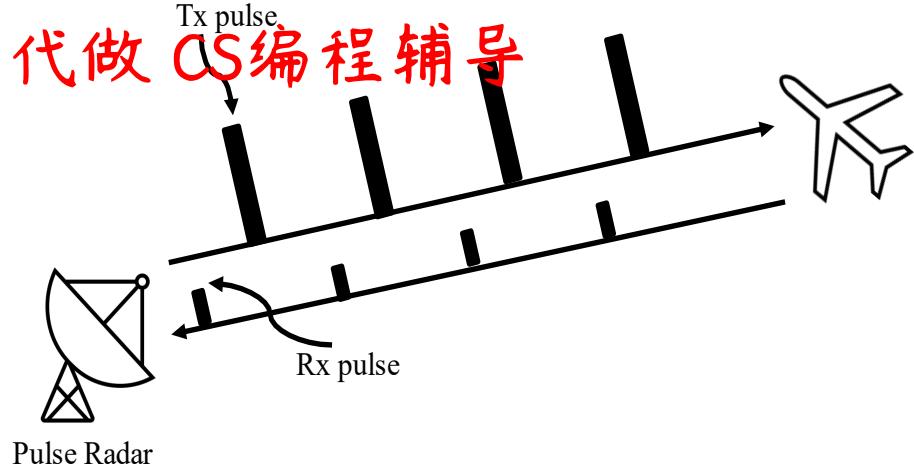
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## Pulse Radar



- Very short pulses:  $\mu\text{s}$  or  $\text{ns}$
- Very high peak power:  $\text{kW}$  or  $\text{MW}$
- Suitable for long range applications: e.g., aircraft detection
- Highly directional; rotates continuously to cover  $360^\circ$
- 10-100 pulses per sec., silent in between; low average power
- Received pulses are very weak (due to long distance)
- Bandwidth ( $B$ ) =  $1/w$  ( $w$  = pulse width); Resolution =  $c/2B = (cxw)/2$ .
- Better resolution with narrower pulses. wider pulses contain more energy; hence they provide longer detection range, but echoes from multiple objects can overlap yielding lower resolution

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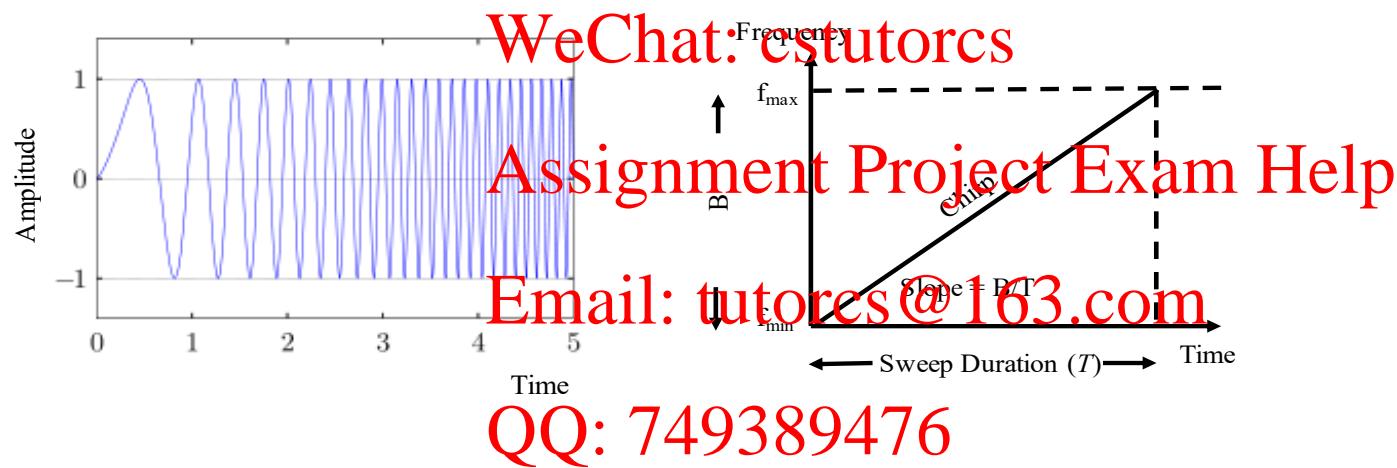
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# FMCW Radars 程序代写代做CS编程辅导

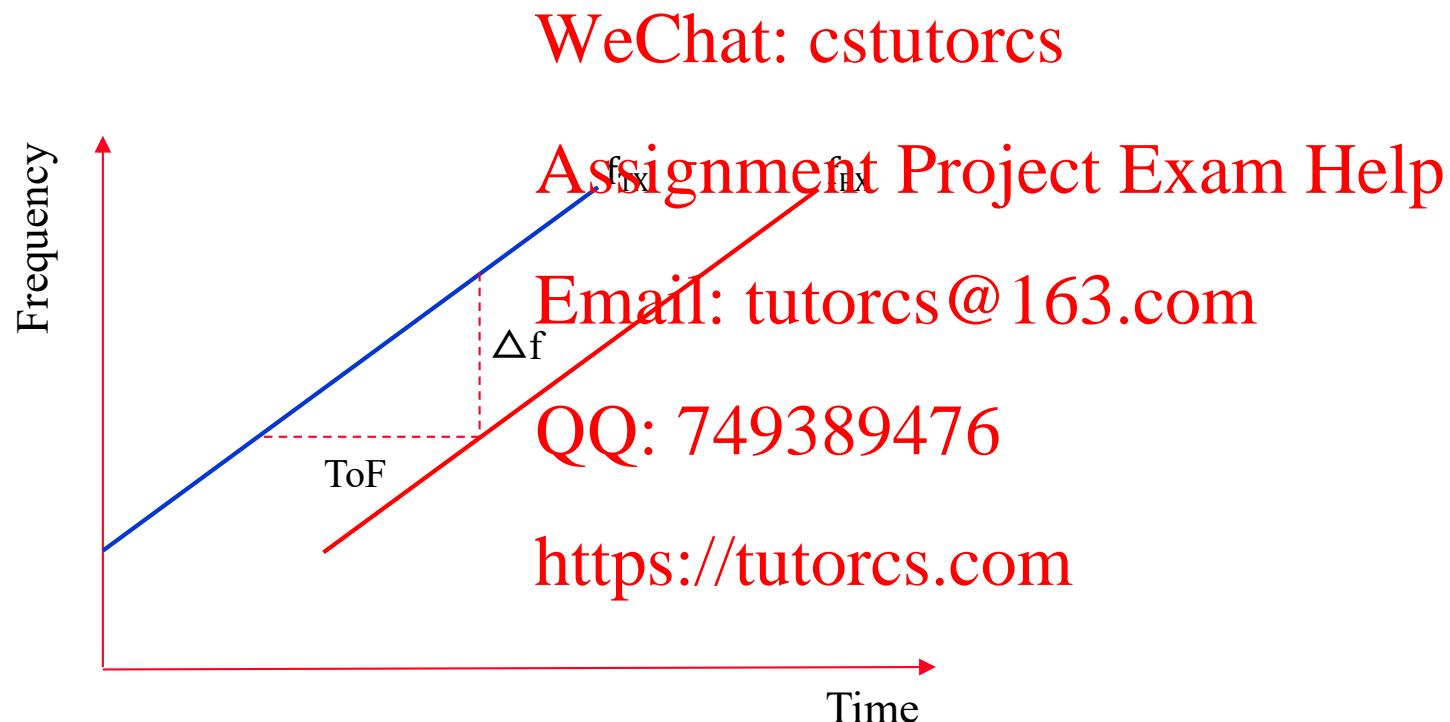
- Unlike pulses, FMCW transmits continuous wave (CW)
- Frequency of the CW is increasing linear upchirp



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# Range Estimation with EMCW

- Instantaneous frequency
- $ToF = \Delta f/S$
- $Range = ToF \times c = (\Delta f)$

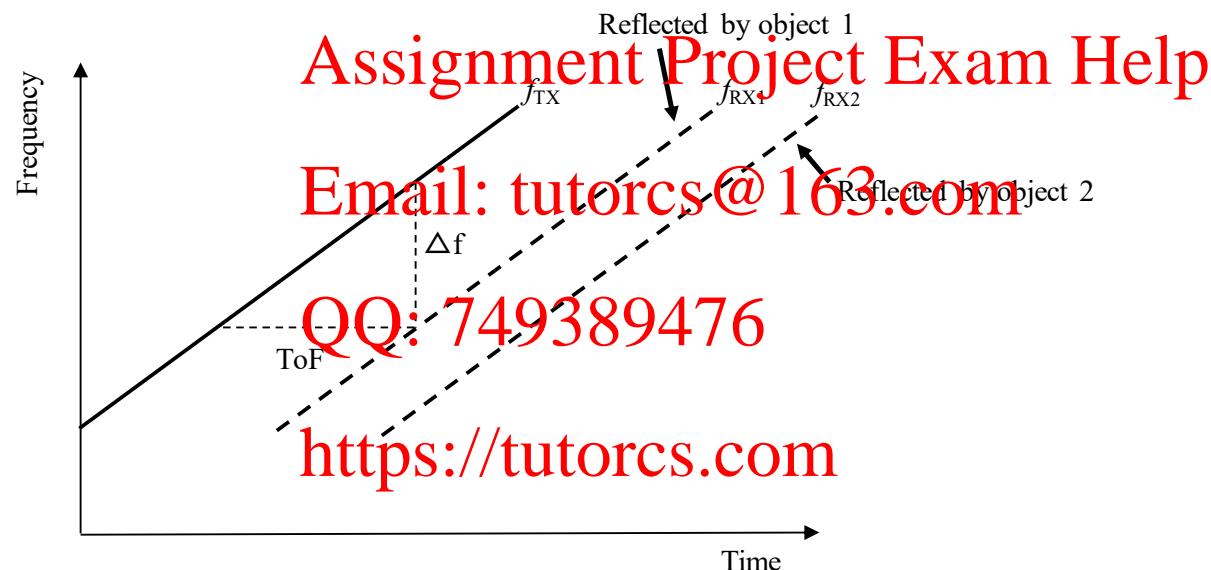


# Detecting Multiple Objects with EMCW

- Two objects located at different distances from the receiver would produce two reflected chirps with slight delays between them.



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# Resolution of EMCSW 程序代写与EMCSW编程辅导

- Assume 2 objects located bearing but  $\Delta d$  from each other
- $\Delta f = \text{instantaneous frequency difference between the 2 received chirps}$
- $(\Delta f)/(2\Delta d/c) = S = B/T$  *the difference between RTT of 2 objects*
- Two frequencies within  $\Delta f$  can be distinguished if  $\Delta f > 1/T$  (law of FFT)
- For  $\Delta f = 1/T$ , we have  $\Delta d = c/2B$

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# Summary 程序代写代做ES编程辅导

1. Wireless signals are used for both communication and sensing
2. Two major types of wireless sensing: WiFi Sensing and Radar Sensing
3. Using RSS and CSI, wireless signals can be used for many human sensing and monitoring applications
4. RSS is readily available, but cannot provide fine-grain sensing  
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5. CSI can provide fine-grain sensing, but modifications required to access CSI in commodity WiFi devices  
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6. Radar can provide accurate range and motion information; more sophisticated sensing applications are possible with radars, but they require dedicated infrastructure for sensing
7. Millimeter wave FMCW radars have emerged as a popular IoT sensing device with applications in many IoT domains: health, smart home, smart industry, smart transport, ...  
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