```
osse::collaborate::
       Scheduler
   # clock
   # nodes
   + Scheduler()
   + Update()
   + NextVisitor()
   + FindRoute()
   + AllLos()
   + AllDist()
   # RestoreNodes()
   # SaveTree()
osse::collaborate::
    SchedulerAlpha
- flag
+ SchedulerAlpha()
+ SchedulerAlpha()
+ Update()
+ PredictChargeChange()
+ NextVisitor()
+ FindRoute()
NodeSensorDistance()
MakeRoute()
FindGainsFrom()
Confirm()
- GetRouteLoa()
```