1) Reachable nodes using BFS

```
#include<stdio.h>
#include<stdlib.h>
int visited[100], queue[100], front = -1, rear = -1, n, i, j;
int adj[100][100];
void bfs(int v){
  while(front<=rear){
    v=queue[front++];
    for(int i=0;i<n;i++){
       if(adj[v][i] && !visited[i]){
         queue[rear++]=i;
         visited[i]=1;
      }
    }
  }
}
int main(){
  int v;
  printf("Enter the no. of vertices: ");
  scanf("%d",&n);
  printf("\nEnter the matrix: \n");
  for(i=0;i< n;i++){
    for(j=0;j< n;j++){
       scanf("%d",&adj[i][j]);
    }
  }
  printf("\nEnter the starting vertex: ");
  scanf("%d",&v);
  for(i=0;i<n;i++){
    queue[i]=0;
    visited[i]=0;
  }
  bfs(v);
  for(i=0;i< n;i++){
    if(visited[i]){
       printf("->%d",i);
```

```
}
else{
    printf("Not possible");
}
```

2)Topological sort

```
#include <stdio.h>
#include <stdlib.h>
int s[100],res[100];
int j;
void adjacency(int a[100][100],int n){
  printf("Enter the elements: \n");
  for(int i=0;i<n;i++){
    for(int j=0;j< n;j++)\{
       scanf("%d",&a[i][j]);
    }
  }
}
void dfs(int u,int n,int a[100][100]){
  s[u]=1;
  int v;
  for(v=0;v<n;v++){
     if(a[u][v]\&\& !s[v]){
       dfs(v,n,a);
     }
  }
  res[j--]=u;
}
void topological(int n, int a[100][100]){
  int i,u;
  for(i=0;i< n;i++){
     s[i]=0;
  }
  j=n-1;
  for(u=0;u< n;u++){}
    if(!s[u]){
       dfs(u,n,a);
     }
  }
```

```
int main()
{
  int a[100][100],n,i,j;
  printf("Enter the no. of vertices: ");
  scanf("%d",&n);
  adjacency(a,n);
  for(i=0;i<n;i++){
    for(j=0;j< n;j++){
       printf("%d\t",a[i][j]);
    }
    printf("\n");
  }
  printf("Topological Order: \n");
  topological(n,a);
  for(i=0;i< n;i++)\{
    printf("->%d",res[i]);
  }
  return 0;
}
```

3)Johnson Trotter

```
#include <stdio.h>
#include <stdlib.h>
#include<stdbool.h>
void printt(int perm[],int n){
  for (int i=0;i< n;i++){
    printf("%d",perm[i]);
  printf("\n");
}
void johnsontrotter(int n)
  int perm[n],dir[n];
  for(int i=0;i< n;i++){
    perm[i]=i+1;
    dir[i]=-1;
  }
  printt(perm,n);
  while(true){
    int mobile=-1, mobileindex=-1;
    for(int i=0;i< n;i++){
      if(dir[i]==-1 \&\& i>0 \&\& perm[i]>perm[i-1]){
         if(perm[i]>mobile){
           mobile=perm[i];
           mobileindex=i;
         }
      if(dir[i]==1 && i<n-1 && perm[i]>perm[i+1]){
         if(perm[i]>mobile){
           mobile=perm[i];
           mobileindex=i;
         }
      }
    }
    if(mobileindex==-1){break;}
    int swapindex=mobileindex+dir[mobileindex];
```

```
int temp=perm[mobileindex];
    perm[mobileindex]=perm[swapindex];
    perm[swapindex]=temp;
    temp=dir[mobileindex];
    dir[mobileindex]=dir[swapindex];
    dir[swapindex]=temp;
    for(int i=0;i<n;i++){
      if(perm[i]>mobile){
        dir[i]=-dir[i];
      }
    }
    printt(perm,n);
  }
}
int main()
{
  int n=3;
 johnsontrotter(n);
  return 0;
}
```

4)Merge Sort

```
#include <stdio.h>
#include <stdlib.h>
#include<time.h>
int count=0;
void merge(int arr[], int l,int mid,int r){
  int an=mid-l+1;
  int bn=r-mid;
  int a[an];
  int b[bn];
  for(int i=0;i<an;i++){</pre>
    a[i]=arr[l+i];
  }
  for(int j=0;j<bn;j++){
    b[j]=arr[mid+1+j];
  }
  int i=0,j=0,k=l;
  while(i<an && j<bn){
       count++;
    if(a[i] < b[j]){
       arr[k++]=a[i++];
    }
    else{
       arr[k++]=b[j++];
    }
  }
  while(i<an){
    arr[k++]=a[i++];
  }
  while(j<bn){
    arr[k++]=b[j++];
  }
}
void mergesort(int arr[],int l,int r){
  if(l>=r){}
```

```
return;
  }
  int mid=(l+r)/2;
  mergesort(arr,l,mid);
  mergesort(arr,mid+1,r);
  merge(arr,l,mid,r);
}
void printarray(int a[],int n){
  for(int i=0;i<n;i++){
    printf("%d\t",a[i]);
  }
}
int main() {
  int n;
  printf("Enter the no. of elements: ");
  scanf("%d", &n);
  int aa[n], ad[n], ar[n];
  srand(time(0));
  for (int i = 0; i < n; i++) {
    aa[i] = i + 1;
    ad[i] = n - i;
    ar[i] = (rand() % n) + 1;
  }
  printf("Before Sorting\n");
  printf("Ascending:\n");
  printarray(aa, n);
  printf("\nDescending:\n");
  printarray(ad, n);
  printf("\nRandom:\n");
  printarray(ar, n);
  clock_t start, end;
  double time_taken;
  // Ascending array sort
```

```
start = clock();
mergesort(aa, 0, n - 1);
end = clock();
time_taken = ((double)(end - start)) / CLOCKS_PER_SEC;
printf("\nTime taken for Ascending: %f seconds", time_taken);
printf("\nCount: %d\n", count);
// Reset count for next sort
count = 0;
// Descending array sort
start = clock();
mergesort(ad, 0, n - 1);
end = clock();
time_taken = ((double)(end - start)) / CLOCKS_PER_SEC;
printf("\nTime taken for Descending: %f seconds", time_taken);
printf("\nCount: %d\n", count);
// Reset count for next sort
count = 0;
// Random array sort
start = clock();
mergesort(ar, 0, n - 1);
end = clock();
time_taken = ((double)(end - start)) / CLOCKS_PER_SEC;
printf("\nTime taken for Random: %f seconds", time_taken);
printf("\nCount: %d\n", count);
printf("\nAfter Sorting:\n");
printf("Ascending:\n");
printarray(aa, n);
printf("\nDescending:\n");
printarray(ad, n);
printf("\nRandom:\n");
printarray(ar, n);
```

```
return 0;
```

5)Quick Sort

```
#include <stdio.h>
#include <stdlib.h>
int count=0;
void swap(int *a, int *b){
  int temp=*a;
  *a=*b;
  *b=temp;
}
int partition(int arr[],int low,int high){
  int pivot=arr[low];
  int i=low+1;
  int j=high;
  while(1){
    while(arr[i]<=pivot && i<=high){
      count++;
      i++;
    }
    while(arr[j]>pivot && j>=low){
       count++;
      j--;
    }
    if(i < j){
      swap(&arr[i],&arr[j]);
    }
    else{
      arr[low]=arr[j];
      arr[j]=pivot;
       return j;
    }
  }
```

```
}
void quicksort(int a[],int l,int r){
  if (l<=r){
    int p=partition(a,l,r);
    quicksort(a,l,p-1);
    quicksort(a,p+1,r);
  }
}
void printarray(int a[],int n){
  for(int i=0;i<n;i++){
    printf("%d\t",a[i]);
  }
}
int main(){
  int n;
  printf("Enter the no. of elements: ");
  scanf("%d",&n);
  int aa[n],ad[n],ar[n];
  srand(time(0));
  for(int i=0;i<n;i++)\{
    aa[i]=i+1;
    ad[i]=n-i;
    ar[i]=(rand()%n)+1;
  }
  printf("Before Sorting\n");
  printf("Ascending:\n");
  printarray(aa,n);
  printf("\nDescending:\n");
  printarray(ad,n);
  printf("\nRandom:\n");
  printarray(ar,n);
  printf("\n");
  quicksort(aa,0,n-1);
  printf("\nCount= %d",count);
```

```
count=0;
quicksort(ad,0,n-1);
printf("\nCount= %d",count);

count=0;
quicksort(ar,0,n-1);
printf("\nCount= %d",count);

printf("\nAfter Sorting:\n");
printf("Ascending:\n");
printarray(aa,n);
printf("\nDescending:\n");
printarray(ad,n);
printf("\nRandom:\n");
printarray(ar,n);
```

6)Heap Sort

```
#include <stdio.h>
#include <stdlib.h>
int count=0;
void swap(int *a, int *b){
  int temp=*a;
  *a=*b;
  *b=temp;
void heapify(int arr[],int n,int i){
  int largest=i;
  int left=2*i+1;
  int right=2*i+2;
  count++;
  if(left<n && arr[left]>arr[largest]){
    largest=left;
  }
  if(right<n && arr[right]>arr[largest]){
    largest=right;
  }
  if(largest!=i){
    swap(&arr[i],&arr[largest]);
    heapify(arr,n,largest);
  }
}
void heapsort(int arr[],int n){
  for(int i=n/2-1;i>=0;i--){
    heapify(arr,n,i);
  }
  for(int i=n-1;i>0;i--){
    swap(&arr[0],&arr[i]);
    heapify(arr,i,0);
  }
}
void printarray(int arr[], int n){
  for(int i=0;i<n;i++){
```

```
printf("%d ",arr[i]);
  }
  printf("\n");
}
int main()
{
  int n,i;
  printf("Enter the no. of elements: ");
  scanf("%d",&n);
  int arrA[n],arrD[n],arrR[n];
  srand(time(0));
  for(i=0;i<n;i++){
    arrA[i]=i+1;
    arrD[i]=n-i;
    arrR[i]=(rand()%n)+1;
  }
  printf("Before Sorting\n");
  printf("Ascending:\n");
  printarray(arrA,n);
  printf("\nDescending:\n");
  printarray(arrD,n);
  printf("\nRandom:\n");
  printarray(arrR,n);
  printf("\n");
  heapsort(arrA,n);
  printf("\nCount= %d",count);
  count=0;
  heapsort(arrD,n);
  printf("\nCount= %d",count);
  count=0;
  heapsort(arrR,n);
  printf("\nCount= %d",count);
```

```
printf("\nAfter Sorting:\n");
printf("Ascending:\n");
printarray(arrA,n);
printf("\nDescending:\n");
printarray(arrD,n);
printf("\nRandom:\n");
printarray(arrR,n);
return 0;
}
```

7)Knapsack

```
#include <stdio.h>
#include <stdlib.h>
int max(int a,int b){
  if(a>b){return a;}
  else{return b;}
int knapsack(int n, int C,int w[],int p[]){
  int v[n+1][C+1];
  int i,j;
  for(i=0;i<=n;i++){
    for(j=0;j<=C;j++){
      if(i==0 | j==0)
         v[i][j]=0;
       }
       else if(w[i-1]>j){
         v[i][j]=v[i-1][j];
       }
       else{
         v[i][j]=max(v[i-1][j],p[i-1]+v[i-1][j-w[i-1]]);
       }
    }
  }
  return v[n][C];
}
int main(){
  int n,w[50],p[50],i,C,a;
  printf("Enter the no. of items: ");
  scanf("%d",&n);
  printf("\nEnter the weight and profit: \n");
  for(i=0;i<n;i++){
    scanf("%d %d",&w[i],&p[i]);
  }
```

```
printf("\nEnter the size of kanpsack: ");
scanf("%d",&C);
a=knapsack(n,C,w,p);
printf("%d",a);
return 0;
}
```

8) Floyd's Algorithm

```
#include <stdio.h>
#include <stdlib.h>
#define INF 99999
void print(int distance[100][100],int n){
  printf("Shortest distance between every pair of vertices: \n");
  for(int i=0;i<n;i++){
    for(int j=0;j< n;j++){
       if(distance[i][j]==INF){
         printf("%7s","INF");
       }
       else{
         printf("%7d",distance[i][j]);
       }
    }
    printf("\n");
  }
}
void Floyd(int graph[100][100],int n){
  int distance[100][100];
  for(int i=0;i< n;i++){
    for(int j=0;j<n;j++){
       distance[i][j]=graph[i][j];
    }
  }
  for(int k=0;k< n;k++){
    for(int i=0;i< n;i++){
       for(int j=0;j<n;j++){
         if(distance[i][j] > distance[i][k]+distance[k][j]){
            distance[i][j]=distance[i][k]+distance[k][j];
         }
       }
    }
  }
  print(distance,n);
```

```
int main()
{
  int n;
  printf("Enter the no. of vertices: ");
  scanf("%d",&n);
  int graph[100][100];
  printf("\nEnter the adjacency matrix:\n ");
  for(int i=0;i<n;i++){
    for(int j=0;j<n;j++){
      scanf("%d", &graph[i][j]);
    }
}
Floyd(graph,n);
  return 0;</pre>
```

}

}

9) Connected using DFS

```
#include <stdio.h>
#include <stdlib.h>
int n,visited[100],adj[100][100];
void dfs(int u){
  int v;
  visited[u]=1;
  for(v=0;v< n;v++){}
    if(adj[u][v] && !visited[v]){
         printf("%d->%d\n",u,v);
       dfs(v);
    }
  }
int main()
{
  int i,j,count=0;
  printf("Enter the no. of vertices: ");
  scanf("%d",&n);
  for(i=0;i< n;i++){
    visited[i]=0;
  }
  for(j=0;j< n;j++){}
    adj[i][j]=0;
  }
  printf("\nEnter the elements in array: \n");
  for(i=0;i<n;i++){
    for(j=0;j< n;j++){
       scanf("%d",&adj[i][j]);
    }
  }
  dfs(0);
  printf("\n");
  for(i=0;i< n;i++){
    if(visited[i]){
       count++;
```

```
}

if(count==n){
    printf("\nConnected");
}

else{
    printf("Not connected");
}

return 0;
}
```

10)Prims Algorithm

```
#include <stdio.h>
#include <stdbool.h>
#include <limits.h>
#define V 5 // Number of vertices in the graph
int minKey(int key[], bool mstSet[]) {
  int min = INT_MAX, min_index;
  for (int v = 0; v < V; v++) {
    if (mstSet[v] == false \&\& key[v] < min) {
       min = key[v];
       min_index = v;
    }
  }
  return min_index;
}
void primMST(int graph[V][V]) {
  int parent[V]; // Array to store constructed MST
  int key[V]; // Key values used to pick minimum weight edge in cut
  bool mstSet[V]; // To represent set of vertices included in MST
  // Initialize all keys as INFINITE
  for (int i = 0; i < V; i++) {
    key[i] = INT_MAX, mstSet[i] = false;
  }
  // Always include the first vertex in MST.
  // Make key 0 so that this vertex is picked as first vertex.
  key[0] = 0; // First vertex is always picked as root of MST
  parent[0] = -1; // First node is always root of MST
  // The MST will have V vertices
  for (int count = 0; count < V - 1; count++) {
    // Pick the minimum key vertex from the set of vertices
```

```
// not yet included in MST
    int u = minKey(key, mstSet);
    // Add the picked vertex to the MST Set
    mstSet[u] = true;
    // Update key value and parent index of the adjacent vertices
    // of the picked vertex. Consider only those vertices which are
    // not yet included in MST
    for (int v = 0; v < V; v++) {
       // graph[u][v] is non zero only for adjacent vertices of m
       // mstSet[v] is false for vertices not yet included in MST
       // Update the key only if graph[u][v] is smaller than key[v]
       if (graph[u][v] \&\& mstSet[v] == false \&\& graph[u][v] < key[v]) {
         parent[v] = u, key[v] = graph[u][v];
       }
    }
  }
  // Calculate the total minimum cost of the MST
  int minCost = 0;
  for (int i = 1; i < V; i++) {
    minCost += graph[i][parent[i]];
  }
  // Print the total minimum cost of the MST
  printf("Minimum Cost of MST: %d\n", minCost);
int main() {
  int graph[V][V] = {
    \{0, 2, 0, 6, 0\},\
    \{2, 0, 3, 8, 5\},\
    \{0, 3, 0, 0, 7\},\
    {6, 8, 0, 0, 9},
    \{0, 5, 7, 9, 0\}
```

}

```
};

// Find and print the minimum cost of the Minimum Spanning Tree (MST)
primMST(graph);

return 0;
}
```