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What are u and v ?

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Change / shift
in x

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Quick Detour

Taylor Expansion

$$I(x + \Delta x, y + \Delta y)$$

$$\approx I(x, y) + I_x(x, y) \Delta x + I_y(x, y) \Delta y$$

+ higher order terms

Quick Detour

Taylor Expansion

$$I(x + \Delta x, y + \Delta y)$$

$$\approx I(x, y) + \underline{I_x}(x, y) \Delta x + \underline{I_y}(x, y) \Delta y$$

Partial Derivatives

in x and y directions.

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$$E[\Delta x, \Delta y] = \sum_{x,y} w(x,y) [I(x+\Delta x, y+\Delta y) - I(x,y)]^2$$

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$$\approx \sum_{x,y} w(x,y) [I(x,y) + I_x(x,y)\Delta x + I_y(x,y)\Delta y - I(x,y)]^2$$

$$I(x+\Delta x, y+\Delta y)$$

$$\approx I(x,y) + I_x(x,y)\Delta x + I_y(x,y)\Delta y$$

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$$= \sum_{x,y} w(x,y) [I_x(x,y) \Delta x + I_y(x,y) \Delta y]^2$$

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$$= \sum_{x,y} w(x,y) [I_x(x,y) \Delta x + I_y(x,y) \Delta y]^2$$

$$= \sum_{x,y} w(x,y) \left[(\Delta x)^2 I_x^2(x,y) + (\Delta y)^2 I_y^2(x,y) + 2 \Delta x \Delta y I_x(x,y) I_y(x,y) \right]$$

Auto Correlation (Correlation with itself)

$$\begin{aligned} E[\Delta x, \Delta y] &= \sum_{x,y} w(x,y) [I(x+\Delta x, y+\Delta y) - I(x,y)]^2 \\ &= \sum_{x,y} w(x,y) \left[(\Delta x)^2 I_x^2(x,y) + (\Delta y)^2 I_y^2(x,y) \right. \\ &\quad \left. + 2 \Delta x \Delta y I_x(x,y) I_y(x,y) \right] \end{aligned}$$

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$$= \sum_{x,y} w(x,y) [\Delta x \quad \Delta y] \begin{bmatrix} I_x^2(x,y) & I_x(x,y) I_y(x,y) \\ I_x(x,y) I_y(x,y) & I_y^2(x,y) \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix}$$

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→ independent of x, y

Auto Correlation (Correlation with itself)

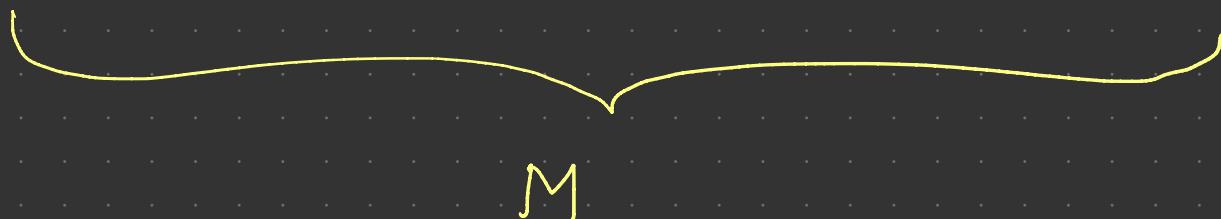
$$E[\Delta x, \Delta y]$$

$$= [\Delta x \quad \Delta y] \sum_{x,y} w(x,y) \begin{bmatrix} I_x^2(x,y) & I_x(x,y)I_y(x,y) \\ I_x(x,y)I_y(x,y) & I_y^2(x,y) \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix}$$

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$$E[u, v] = [u \ v] M \begin{bmatrix} u \\ v \end{bmatrix}, \quad M = \sum_{x,y} \begin{bmatrix} I_x^2 w & I_x I_y w \\ I_x I_y w & I_y^2 w \end{bmatrix}$$

Eigen Decomposition

$$M = R^{-1} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} R$$

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λ_1, λ_2 are eigen values

Rows of R are eigen vectors.

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$$\text{Cornerness Value, } C = \lambda_1 \lambda_2 - \alpha (\lambda_1 + \lambda_2)^2$$

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if this value is higher, λ_1 and λ_2 are large

$$E[u, v] = [u \ v] M \begin{bmatrix} u \\ v \end{bmatrix}$$

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$$C = \lambda_1 \lambda_2 - \alpha (\lambda_1 + \lambda_2)^2$$

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$$M = R^{-1} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} R$$

$$\begin{aligned} C &= \lambda_1 \lambda_2 - \propto (\lambda_1 + \lambda_2)^2 \\ &= \det(A) - \propto \text{trace}(A) \end{aligned}$$

A

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We still have to compute eigenvalues.

$$E[u, v] = [u \ v] M \begin{bmatrix} u \\ v \end{bmatrix}$$

$$M = R^{-1} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} R$$

$$C = \lambda_1 \lambda_2 - \propto (\lambda_1 + \lambda_2)^2$$

\underbrace{A}_{A}

$$= \det(A) - \propto \text{trace}(A)$$

We still have to compute eigenvalues.

↳ Costly operation.

How to reduce time complexity?

Again Detour.

$$M = R^{-1} A R$$

Again Detour. $M = R^{-1} A R$

- $\det(M) = \det(R^{-1} A R)$
 $= \det(R^{-1}) \det(A) \det(R)$

Again Detour. $M = R^{-1} A R$

$$\begin{aligned}\bullet \det(M) &= \det(R^{-1} A R) \\ &= \det(R^{-1}) \det(A) \det(R) \\ &= \frac{1}{\det(R)} \det(A) \det(R)\end{aligned}$$

Again Detour. $M = R^{-1} A R$

$$\begin{aligned}\bullet \det(M) &= \det(R^{-1} A R) \\ &= \det(R^{-1}) \det(A) \det(R) \\ &= \frac{1}{\det(R)} \det(A) \det(R) \\ &= \det(A)\end{aligned}$$

Again Detour. $M = R^{-1} A R$

- $\det(M) = \det(A)$
- $\text{trace}(M) = ?$

Again Detour. $M = R^{-1} A R$

• $\det(M) = \det(A)$

• $\text{trace}(M) = ?$

↳ Detour again (Detour Inception
↳ Deception)

B, C are two square matrices

$$\# BC_{ij} = \sum_{k=1}^n B_{ik} C_{kj}$$

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B, C are two square matrices

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B, C are two square matrices

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$$\# \text{trace}(CB) = \sum_{i=1}^n CB_{ii} = \sum_{i=1}^n \sum_{k=1}^n C_{ik} B_{ki}$$

$$\therefore \text{trace}(BC) = \text{trace}(CB)$$

Again Detour. $M = R^{-1} A R$

- $\det(M) = \det(A)$
- $\text{trace}(M) = \text{trace}(R^{-1} A R)$
= $\text{trace}(R^{-1} (A R))$
= $\text{trace}((A R) R^{-1})$
= $\text{trace}(A R R^{-1})$
= $\text{trace}(A)$

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$\underbrace{\quad}_{A}$

$$= \det(A) - \alpha \operatorname{trace}(A)$$

$$= \det(M) - \alpha \operatorname{trace}(M)$$

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$$= \det(M) - \alpha \operatorname{trace}(M)$$

$$M = \sum_{x,y} w(x,y) \begin{bmatrix} I_x^2(x,y) & I_x(x,y) I_y(x,y) \\ I_x(x,y) I_y(x,y) & I_y^2(x,y) \end{bmatrix}$$

